## Online Computation, Ex 3.

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**ex1.** Consider the experts setting with gains:  $g_{i,t} \in [0,1]$  is **ex2.** Show a lower bound of  $\Omega\left(\sqrt{T}\right)$  in the experts setting the gain of expert i at step t. Hedge updates:

$$P_{i,t+1} = \frac{e^{\eta G_{i,t}}}{\sum_{j} e^{\eta G_{j,t}}}$$

where  $G_{i,t} = \sum_{s \leq t} g_{i,t}$ . Prove that the regret of Hedge at time T is  $O(\sqrt{T \log n})$ , for a good choice of the learning rate  $\eta$ , against the adaptive adversary.

**Solution.** Let  $g_t$  be the random variable which counts the gain at time step t and by  $G_t = \sum_{t=0}^{T} g_t$ . Recall that for any pair of random variables X, Y such that  $X \geq Y$  holds that  $\mathbf{E}[X] \geq \mathbf{E}[Y]$ . Also notice that for x restricted to some range [-r, r] there are constants  $c_0, c_1$  depend on r such that  $e^{x}-1-x \le c_{0}x^{2}$  and  $1+x+c_{0}x^{2} \le e^{x+c_{1}x^{2}}$ . Namely, the exponent is bounded by quadric approximation (second Tylor series order). By the monotonous property of the expectation, for any random variable X that maps to bounded range [-r, r], it holds that:

$$\mathbf{E}\left[e^{x}\right] \le \mathbf{E}\left[1 + x + c_{0}x^{2}\right] \le e^{\mathbf{E}\left[x + c_{1}x^{2}\right]}$$

Define the potential  $\psi(t) = \sum_{i} e^{\eta G_{i,t}}$  and notice that:

- 1.  $\frac{\psi(t+1)}{\psi(t)} = \mathbf{E}\left[e^{\eta g_t}\right]$  relatives to the distribution  $P_{i,t+1}$ .
- 2.  $\psi(t) \geq e^{\eta G_{t,j}}$  for any t and j in particular the j which maximizes the gain.

Therefore we obtain that:

$$\psi\left(T\right) = \frac{\psi\left(T\right)}{\psi\left(0\right)}\psi\left(0\right) = \prod_{t=0}^{T} \frac{\psi\left(t+1\right)}{\psi\left(t\right)}\psi\left(0\right) \le n \prod_{t=0}^{T} \mathbf{E}\left[e^{\eta g_{t}}\right] \le n \prod_{t=0}^{T} \mathbf{E}\left[1 + \eta g_{t} + c_{\pm}\left(\eta g_{t}\right)^{2}\right]$$

$$n \prod_{t=0}^{T} 1 + \mathbf{E}\left[\eta g_{t} + c_{\pm}\left(\eta g_{t}\right)^{2}\right] \le n \prod_{t=0}^{T} e^{\mathbf{E}\left[\eta g_{t} + c_{\pm}\left(\eta g_{t}\right)^{2}\right]} \le n e^{\mathbf{E}\left[\sum \eta g_{t} + c_{\pm}\left(\eta g_{t}\right)^{2}\right]}$$

On the other hand, by the second property, it follows that for any j:

$$e^{\eta G_{j,T}} < ne^{\mathbf{E}[\sum \eta g_t] + \mathbf{E}[c_{\pm}(\eta g_t)^2]}$$

By dividing at  $e^{\mathbf{E}[\sum \eta g_t]}$ , extracting the logarithm and combine the fact that  $g_t^2 = g_t$  (indicator) we have that:

$$R_T \le \frac{1}{\eta} \log\left(n\right) + c_+ \eta T$$

And by choosing  $\eta = \sqrt{\log(n)/T}$  we complete the proof.

on the regret of any online algorithm against the oblivious adversary.

Solution. Consider an adversarial which draw the values of  $g_{i,t}$  uniformly random, in particular  $g_{i,t}$ 's are independent. Fix an online algorithm for the problem and denote by  $g_t$ the gain that earns by it at time step t. As  $g_{i,t}$  are independent, the sum  $G_T = \sum g_t$  is a summation of independent variables with the same exception and variance. Therefore we know that  $(G_T - T\mu)/\sqrt{T} \sim G(0, \sigma)$  where  $\mu$  and  $\sigma$  do not depends on T. Denote that Gaussian by X.

On the other hand, a run in which the optimal gain  $T\mu + \frac{1}{2}\sqrt{T}$  might occur with positive probability. Using that event, we infer that the regret has to be at least:

$$R_T \ge T\mu + \frac{1}{2}\sqrt{T} - \mathbf{E}\left[G_t\right] = \frac{1}{2}\sqrt{T}$$

**ex3.** Consider a system of linear inequalities  $Ax \geq b$ , where  $A \in [0,\infty]^{m \times n}, b \in [0,\infty]^m$ , and unknown  $x \in [0,\infty]^n$ . (we are seeking a non-negative solution). An  $\varepsilon$ -approximate solution  $x \geq 0$  satisfies  $Ax \geq b - \varepsilon 1$ . Suppose we have an efficient procedure for the following problem: Given  $p \in$  $[0,1]^m, \sum_{i\in[m]} p_i = 1$ , decide if exists  $x \geq 0, p^{\top} Ax \geq p^{\top} b$ . Show how to find an  $\varepsilon$ -approximate solution to  $Ax \geq b$ . Analyze the run-time.

**Solution.** I think that a misunderstood occurred, and the restriction of A>0 was written by mistake. Because otherwise, One could pick x to be the vector  $x_i=\frac{\max b}{\min A}$  for any i, where the minimum is taken over all the non-zero values of A. Notice that on the one hand,  $x \geq 0$  and on the other hand, the inequality is satisfied. For see that, consider non-zero row  $a_i$  of A, there is must to be at least one entry  $A_{ij'\in a_i}$  which is nonzero, Hence we have that:

$$(Ax)_i = \sum_{\substack{A_{ij} \text{ max } b \\ \min A}} \ge \frac{A_{ij'}}{\min A} \max b \ge b_i$$

Also, the above proves that the inequalities system has no solution only if a coordinate exists for which  $b_i > 0$  and the ith row contains only zero values. One can Compute x by doing at most one iteration over the input. So the total running time is at most O(mn). If A isn't restricted to holding only positive values, then the problem is equivalence to solving an arbitrary LP.

**ex4.** Recall that we showed, for EXP updates, that w.p  $1 - \delta$ 

$$RT \le \beta nT + \gamma T + (1+\beta)\eta + \frac{\ln(\delta^{-1}n)}{\beta} + \frac{\ln n}{\eta}$$

Infer that for the right choice of  $\beta, \gamma, \eta$ 

$$\mathbf{E}\left[R_T\right] = O\left(\sqrt{Tn\ln n}\right)$$

**Solution.** Let's choose  $\delta=2^{-Tn},\ \beta=\sqrt{\frac{logn}{nT}},\ \text{and}\ \gamma,\eta=\Theta\left(\beta\right)$  assume that  $T=\Omega(n)$  (which is reasonable assumption). Observes that the term  $\frac{\log\left(\delta^{-1}n\right)}{\beta}$  becomes  $\frac{log(n)}{\beta}+\frac{1}{nT\beta}$  and then we obtain that:

$$\mathbf{E}\left[R_T\right] \le \left(1 - 2^{-Tn}\right) \Theta\left(\sqrt{Tn\log n}\right) + 2^{-Tn} \cdot T = \Theta\left(\sqrt{Tn\log n}\right)$$