Lecture 7-2

Chap. 5 Network Layer, part II

Distance Vector Algorithm

Bellman-Ford Equation (dynamic programming)

Define

 $d_x(y) := cost of least-cost path from x to y$

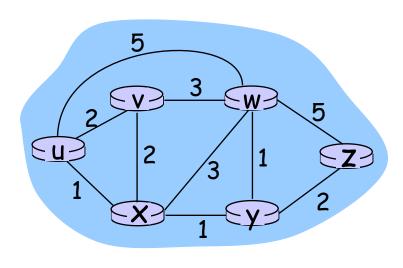
Then

$$d_x(y) = \min_{v} \{c(x,v) + d_v(y)\}$$

where min is taken over all neighbors v of x

Bellman-Ford example

Clearly,
$$d_v(z) = 5$$
, $d_x(z) = 3$, $d_w(z) = 3$



B-F equation says:

$$d_{u}(z) = \min \{ c(u,v) + d_{v}(z), \\ c(u,x) + d_{x}(z), \\ c(u,w) + d_{w}(z) \}$$

$$= \min \{ 2 + 5, \\ 1 + 3, \\ 5 + 3 \} = 4$$

Node that achieves minimum is next hop in shortest path → forwarding table

Distance Vector Algorithm (1)

- D_x(y) = estimate of least cost from x to y
- Distance vector: D_x = [D_x(y): y ∈ N]
- Node x knows cost to each neighbor v: c(x,v)
- Node x maintains D_x = [D_x(y): y ∈ N]
- Node x also maintains its neighbors' distance vectors
 - For each neighbor v, x maintains $D_v = [D_v(y): y \in N]$

Distance vector algorithm (2)

Basic idea:

- Each node periodically sends its own distance vector estimate to neighbors
- When a node x receives new DV estimate from neighbor, it updates its own DV using B-F equation:

$$D_x(y) \leftarrow \min_{v} \{c(x,v) + D_v(y)\} \quad \text{for each node } y \in N$$

• Under minor, natural conditions, the estimate $D_x(y)$ converge to the actual least cost $d_x(y)$

Distance Vector Algorithm (3)

Iterative, asynchronous: each local iteration caused by:

- local link cost change
- DV update message from neighbor

Distributed:

- each node notifies neighbors only when its DV changes
 - neighbors then notify their neighbors if necessary

Each node:

Wait for (change in local link cost or msg from neighbor) recompute estimates if DV to any dest has changed, *notify* neighbors

$$D_{x}(y) = \min\{c(x,y) + D_{y}(y), c(x,z) + D_{y}(y)\}$$

$$= \min\{2+0, 7+1\} = 2$$

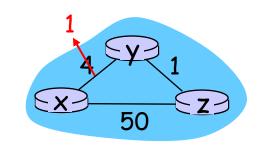
$$0 \text{ cost to}$$

$$0 \text$$

Distance Vector: link cost changes

Link cost changes:

- node detects local link cost change
- updates routing info, recalculates distance vector
- if DV changes, notify neighbors



"good news travels fast" At time t_0 , y detects the link-cost change, updates its DV, and informs its neighbors.

At time t_1 , z receives the update from y and updates its table. It computes a new least cost to x and sends its neighbors its DV.

At time t_2 , y receives z's update and updates its distance table. y's least costs do not change and hence y does not send any message to z.

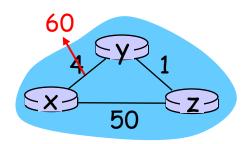
Distance Vector: link cost changes

Link cost changes:

- good news travels fast
- bad news travels slow "count to infinity" problem!
- 44 iterations before algorithm stabilizes: see text

Poisoned reverse:

- If Z routes through Y to get to X :
 - Z tells Y its (Z's) distance to X is infinite (so Y won't route to X via Z)
- will this completely solve count to infinity problem?



Comparison of LS and DV algorithms

Message complexity

- <u>LS:</u> with n nodes, E links, O(nE) msgs sent
- <u>DV:</u> exchange between neighbors only
 - convergence time varies

Speed of Convergence

- <u>LS:</u> O(n²) algorithm requires O(nE) msgs
 - may have oscillations
- <u>DV</u>: convergence time varies
 - may be routing loops
 - count-to-infinity problem

Robustness: what happens if router malfunctions?

<u>LS:</u>

- node can advertise incorrect link cost
- each node computes only its own table

<u>DV:</u>

- DV node can advertise incorrect path cost
- each node's table used by others
 - · error propagate thru network