

Complex Network Analysis for Marine Models

Subtitle (optional)

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Test case to assess the implementation of the overturner model

This note is an adaptation of Eric Deleersnijder's working paper [Del11].

Governing equations

Let us consider a water domain, whose width is denoted $B(t, \mathbf{x})$, where t is the time and $\mathbf{x} = (y, z)$ is the position vector. The continuity equation is

$$\frac{\partial B}{\partial t} + \nabla \cdot (B\mathbf{u}) = 0, \quad (1)$$

where $\mathbf{u}(t, \mathbf{x})$ is the latitudinally-averaged meridional velocity. Assuming that mixing along the parallels is sufficiently efficient, we may study the concentration of a passive tracer by means of a two-dimensional model. The latitudinally-averaged concentration of the tracer $C(t, \mathbf{x})$ obeys the following partial differential equation :

$$\frac{\partial (BC)}{\partial t} + \nabla \cdot (B\mathbf{u}C) = Q\delta(\mathbf{x} - \mathbf{x}_1) + \nabla \cdot (B\mathbf{K} \cdot \nabla C), \quad (2)$$

where \mathbf{K} is the diffusivity tensor (symmetric and positive definite); δ is the Dirac delta function with $\delta(\mathbf{x} - \mathbf{x}_n) = \delta(x - x_n)\delta(y - y_n)$; $Q(t)$ is the rate of release of a lineic source on a segment of length B along the latitude direction located at $\mathbf{x} = \mathbf{x}_1$. If $C(t, \mathbf{x})$ represents the density of the tracer in water, then $Q(t)$ is the mass of tracer released per second by the source.

Equation (2) is the so-called conservative form of the model. The convective form is obtained by combining equations (1) and (2):

$$\frac{\partial C}{\partial t} + \mathbf{u} \cdot \nabla C = \frac{Q}{B}\delta(\mathbf{x} - \mathbf{x}_1) + \frac{1}{B}\nabla \cdot (B\mathbf{K} \cdot \nabla C). \quad (3)$$

An idealised model

Now we make some simplifying assumptions which will allow us to build an analytical solution. First, we consider an infinite domain, i.e.

$$-\infty < y < \infty, \quad -\infty < z < \infty. \quad (4)$$

We assume a constant width B and a constant velocity field

$$\mathbf{u}(t, \mathbf{x}) = v\mathbf{e}_y + w\mathbf{e}_z, \quad (5)$$

where \mathbf{e}_y and \mathbf{e}_z are the unit vectors associated respectively with the y - and z -coordinate axis. Furthermore, the diffusivity tensor is supposed constant and diagonal :

$$\mathbf{K} = \begin{pmatrix} K_{yy} & 0 \\ 0 & K_{zz} \end{pmatrix}, \quad (6)$$

where $K_{yy}, K_{zz} > 0$. Finally, we consider a sudden pointwise release of tracer at $t = 0$. Hence, $Q(t)$ is of the form :

$$Q(t) = M\delta(t), \quad (7)$$

where M is the mass of tracer released at $t = 0$.

Under these assumptions, equation (3) simplifies to :

$$\frac{\partial C}{\partial t} + v \frac{\partial C}{\partial y} + w \frac{\partial C}{\partial z} = \frac{M}{B} \delta(t) \delta(y - y_1) \delta(z - z_1) + K_{yy} \frac{\partial^2 C}{\partial y^2} + K_{zz} \frac{\partial^2 C}{\partial z^2}. \quad (8)$$

For the sake of simplicity, we can forget about the fact that our model is width-integrated and consider that it is a purely two-dimensional model with a point-source

$$Q := J\delta(t), \quad (9)$$

where $J := M/B$ can be regarded as the mass of tracer released by the sudden point source at $\mathbf{x} = \mathbf{x}_1$, if C now represents the two-dimensional density (i.e., in $[kg/m^2]$) of the tracer in water.¹ This is represented on figure 1. **On peut aussi simplement considérer $B = 1$. Attention, si on opte finalement pour cette option, un facteur B doit être présent pour le calcul de certains diagnostics.**

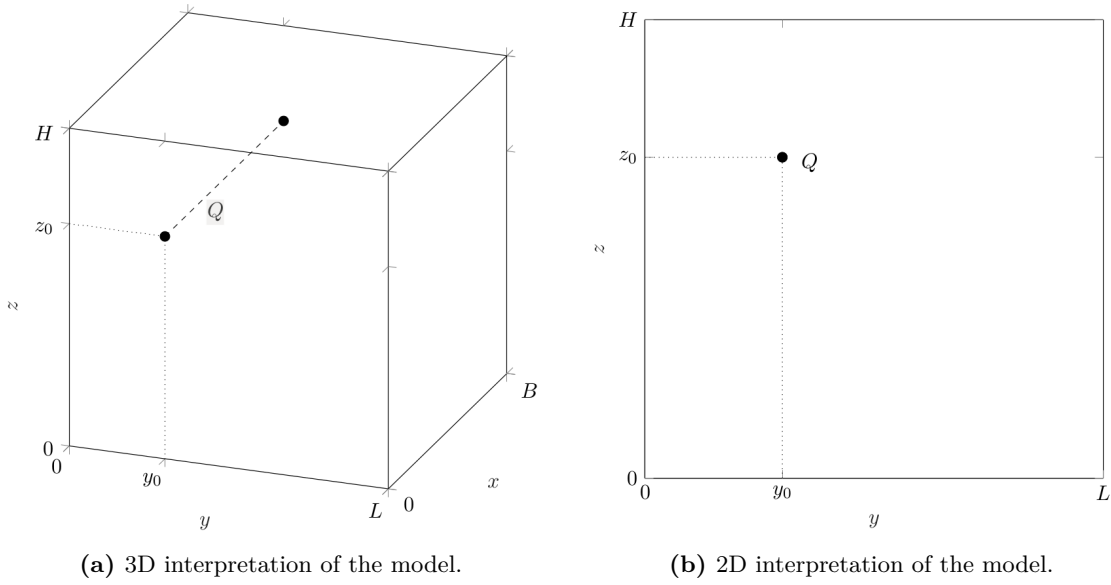
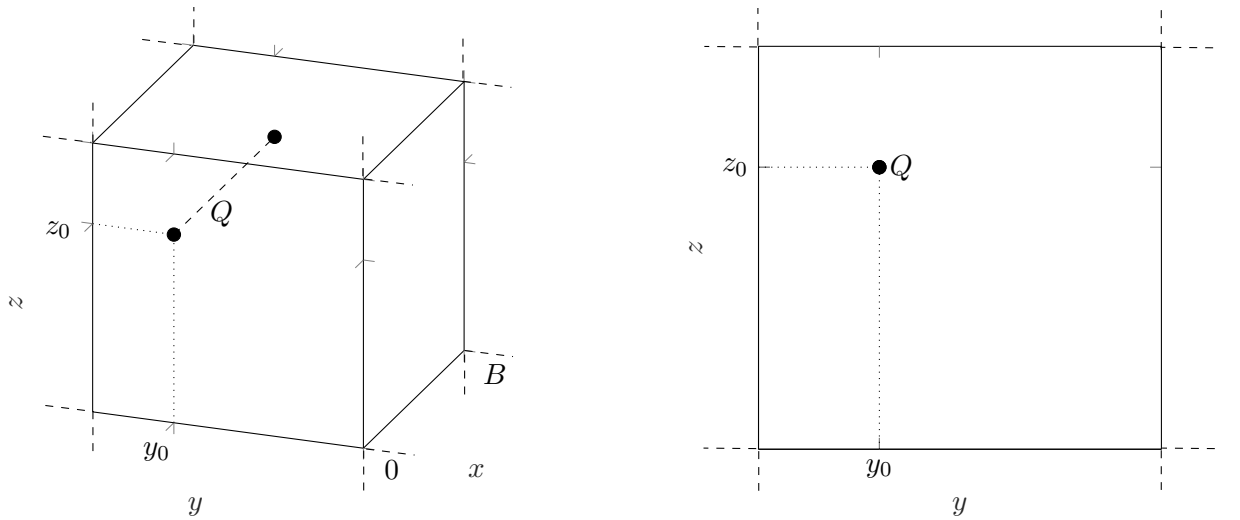


Figure 1 – Illustration of the 3D and 2D interpretations of the model.



¹This could be a bit confusing. As we switch from a 3-dimensional interpretation of the model to a 2-dimensional one, the meaning of the parameters changes. Hence, in the 3-dimensional interpretation, C represents a 3D density ($[kg/m^3]$) and M is a mass, whereas in the 2-dimensional interpretation, C is a 2D density ($[kg/m^2]$) and M has units of $[kg \cdot m]$.

Green's function

In order to build the analytical solution of the problem, we need to compute the Green's function $G(t, t', \mathbf{x})$ associated to this particular problem. $G(t, t', \mathbf{x})$ is zero for $t < t'$ and is the solution of

$$\begin{cases} \frac{\partial G}{\partial t} + v \frac{\partial G}{\partial y} + w \frac{\partial G}{\partial z} = K_{yy} \frac{\partial^2 G}{\partial y^2} + K_{zz} \frac{\partial^2 G}{\partial z^2} \\ G(t, t', y, z)|_{t=t'} = \delta(y)\delta(z) \end{cases} \quad (10)$$

for $t \geq 0$. This yields

$$G(t, t', y, z) = \frac{\exp \left[-\frac{(y-s_v)^2}{4K_{yy}\tau} - \frac{(z-s_w)^2}{4K_{zz}\tau} \right]}{4\pi \sqrt{K_{yy}K_{zz}}\tau}, \quad (11)$$

where $\tau = t - t'$ and

$$\mathbf{s}(t, t') = (s_v(t, t'), s_w(t, t')) = \left(\int_{t'}^t v d\xi, \int_{t'}^t w d\xi \right) = (v\tau, w\tau). \quad (12)$$

The Green's function has some interesting properties. The "mass" of the solution is

$$m(t, t') \equiv \int_{\mathbb{R}^2} G(t, t', \mathbf{x}) d\mathbf{x} = 1. \quad (13)$$

The "center of mass" is located at

$$\mathbf{r}(t, t') \equiv \frac{1}{m(t, t')} \int_{\mathbb{R}^2} \mathbf{x} G(t, t', \mathbf{x}) d\mathbf{x} = \mathbf{s}(t, t'). \quad (14)$$

The variance of the solution is

$$\sigma^2(t, t') \equiv \frac{1}{m(t, t')} \int_{\mathbb{R}^2} |\mathbf{x} - \mathbf{r}(t, t')|^2 G(t, t', \mathbf{x}) d\mathbf{x} = 2(K_{yy} + K_{zz})\tau. \quad (15)$$

Analytical solution and properties

The analytical solution of our test case is now obtained with the help of the Green's function derived above :

$$C(t, \mathbf{x}) = \int_{t'}^t \int_{\mathbb{R}^2} G(t, t', \mathbf{x} - \mathbf{x}') J \delta(t) \delta(\mathbf{x} - \mathbf{x}_1) d\mathbf{x}' dt'. \quad (16)$$

This expression simplifies to

$$C(t, \mathbf{x}) = J G(t, 0, \mathbf{x} - \mathbf{x}_1). \quad (17)$$

The number of tracer's particles present in the domain is

$$m(t) \equiv \int_{\mathbb{R}^2} C(t, \mathbf{x}) d\mathbf{x} = J. \quad (18)$$

Note that this number is independant of the transport processes.

The mass center is located at

$$\begin{aligned} \mathbf{r}(t) &\equiv \frac{1}{m(t)} \int_{\mathbb{R}^2} \mathbf{x} C(t, \mathbf{x}) d\mathbf{x} \\ &= \int_{\mathbb{R}^2} \mathbf{x} G(t, 0, \mathbf{x} - \mathbf{x}_1) d\mathbf{x} \\ &= \int_{\mathbb{R}^2} (\mathbf{x} - \mathbf{x}_1) G(t, 0, \mathbf{x} - \mathbf{x}_1) + \mathbf{x}_1 G(t, 0, \mathbf{x} - \mathbf{x}_1) d\mathbf{x} \\ &= \mathbf{x}_1 + \mathbf{s}(t, 0), \end{aligned} \quad (19)$$

where properties (13) and (14) are used to perform the last step.

Finally, the variance of the solution is

$$\begin{aligned}
\sigma^2(t) &= \frac{1}{m(t)} \int_{\mathbb{R}^2} |\mathbf{x} - \mathbf{r}(t)|^2 C(t, \mathbf{x}) d\mathbf{x} \\
&= \int_{\mathbb{R}^2} |(\mathbf{x} - \mathbf{x}_1) - \mathbf{s}(t, 0)|^2 G(t, 0, \mathbf{x} - \mathbf{x}_1) d\mathbf{x} \\
&= 2(K_{yy} + K_{zz})t,
\end{aligned} \tag{20}$$

where property (15) is used.

Bibliography

- [Del11] Eric Deleersnijder. Test cases for advection-diffusion equations with a first-order decay term. 2011. Available at <http://hdl.handle.net/2078.1/155372>.

