

DLRW Stage3 Inserted IAF Formulae

Neha, Sumit, Jakob

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1 L_{ELBO}

The loss we want to minimize for a VAE is the L_{ELBO} :

$$\begin{aligned} L_{ELBO} &= \int q(z|x) \ln(p(x|z) \frac{p(z)}{q(z|x)}) dz \\ &= E_{q(z|x)} [\ln p(x|z) - \ln q(z|x) + \ln p(z)] \end{aligned} \quad (1)$$

2 Normalizing Flows

If z_0 is transformed to z_k via k normalizing flows then we have :

$$z_k = f_k \circ f_{k-1} \circ f_{k-2} \circ \dots \circ f_1(z_0) \quad (2)$$

Then in accordance with change of variables for probability densities, the probability distribution of z_k can be written as:

$$\begin{aligned} \ln q(z_k) &= \ln(q(z_0) \prod_{i=1}^k \left| \frac{\delta f_i}{\delta z_{i-1}} \right|^{-1}) \\ &= \ln q(z_0) + \sum_{i=1}^k \ln \left| \frac{\delta f_i}{\delta z_{i-1}} \right|^{-1} \end{aligned} \quad (3)$$

3 Time Series Data

Assumptions:

$$p(x_{0:T}|z_{0:T}) = \prod_{t=0}^T p(x_t|z_t) \quad \dots \text{likeli} \quad (4)$$

$$p(z_{0:T}|u_{0:T}) = p(z_0) \prod_{t=1}^T p(z_t|z_{t-1}, u_{t-1}) \quad \dots \text{prior} \quad (5)$$

$$q(z_{0:T}|x_{0:T}, u_{0:T}) = q(z_0|x_0) \prod_{t=1}^T q(z_t|x_t, z_{t-1}, u_{t-1}) \quad \dots \text{post} \quad (6)$$

$$z_{t,0} - > z_{t,1} \quad \text{iaf for each time step} \quad (7)$$

$$\Rightarrow q_{z_{t,1}}(z_{t,1}|x_t, z_{t-1}, u_{t-1}) = q_{z_{t,0}}(z_{t,0}|x_t, z_{t-1}, u_{t-1}) - \ln \left| \frac{\delta z_{t,1}}{\delta z_{t,0}} \right| \quad (8)$$

In the following equations, $z_t = z_{t,1}$ and $z_{t,0}$ is written as it is.

The loss for time series data in a VAE architecture with an IAF step inserted in each time step can be formulated as an L_{ELBO} loss:

$$\begin{aligned} L &= \int q(z_{0:T}|x_{0:T}) \ln \left(\frac{p(x_{0:T}|z_{0:T})}{q(z_{0:T}|x_{0:T})} \right) dz_{0:T} \\ &= \int q(z_0|x_0) \ln \left(\frac{p(x_0|z_0)}{q(z_0|x_0)} \right) dz_0 + \sum_{t=1}^T \int q(z_{0:t}|x_{0:t}) \ln \left(\frac{p(x_t|z_t)}{q(z_t|x_t, z_{t-1})} \right) dz_{0:t} \\ &= \int q(z_0|x_0) \ln \left(\frac{p(x_0|z_0)}{q(z_0|x_0)} \right) dz_0 \\ &\quad + \sum_{t=1}^T \int q(z_{0:t}|x_{0:t}) (\ln(p(x_t|z_t)) + \ln p(z_t|z_{t-1}) - \ln q(z_t|x_t, z_{t-1})) dz_{0:t} \\ &= \int q(z_0|x_0) \ln \left(\frac{p(x_0|z_0)}{q(z_0|x_0)} \right) dz_0 \\ &\quad + \sum_{t=1}^T \int q(z_{0:t}|x_{0:t}) (\ln(p(x_t|z_t)) + \ln p(z_t|z_{t-1}) - \ln q(z_{t,0}) + \ln \left| \frac{\delta z_t}{\delta z_{t,0}} \right|) dz_0 \\ &= E_{z_0 \sim q(z_0|x_0)} [\ln \left(\frac{p(x_0|z_0)}{q(z_0|x_0)} \right)] \\ &\quad + E_{z_{0:t} \sim q(z_{0:t}|x_{0:t})} \left[\sum_{t=1}^T [\ln(p(x_t|z_t)) + \ln p(z_t|z_{t-1}) - \ln q(z_{t,0}) + \ln \left| \frac{\delta z_t}{\delta z_{t,0}} \right|] \right] \end{aligned} \quad (9)$$

Additional assumption:

$$q(z_t|z_{t-1}, x_{0:T}, u_{0:T}) = q(z_t|z_{t-1}, x_t, u_{t-1}) \quad (10)$$