Marginal probability of measurement/ track corres- pondence		Non-existent		inuing ucks 2	3	ew trac.	ks 5
Non-existent		0	0	0	0.8	0.6	0.1
Measurements	1	0	0.6	0.2	0.2	0	0
	2	0	0.2	0.4	0	0.4	0
	3	0	0	0.1	0	0	0.9
Missed detection	4	0.8	0.2	0	0	0	0
	5	0.7	0	0.3	0	0	0