view_frames Result

Recorded at time: 2289.835

odom

Broadcaster: /gazebo
Average rate: 100.201 Hz
Most recent transform: 2289.834 (0.001 sec old)
Buffer length: 4.980 sec

footprint

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (2289.835 sec old)
Buffer length: 0.000 sec

chassis

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (2289.835 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (2289.835 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 50.202 Hz
Most recent transform: 2289.822 (0.013 sec old)
Buffer length: 4.960 sec

Broadcaster: /robot_state_publisher
Average rate: 50.202 Hz
Most recent transform: 2289.822 (0.013 sec old)
Buffer length: 4.960 sec

link0

caster_wheel

left_wheel

right_wheel

Broadcaster: /robot_state_publisher
Average rate: 50.202 Hz
Most recent transform: 2289.822 (0.013 sec old)
Buffer length: 4.960 sec

link1

Broadcaster: /robot_state_publisher
Average rate: 50.202 Hz
Most recent transform: 2289.822 (0.013 sec old)
Buffer length: 4.960 sec

link2

Broadcaster: /robot_state_publisher
Average rate: 50.202 Hz
Most recent transform: 2289.822 (0.013 sec old)
Buffer length: 4.960 sec

link3

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (2289.835 sec old)
Buffer length: 0.000 sec

link4

Broadcaster: /robot_state_publisher
Average rate: 50.202 Hz
Most recent transform: 2289.822 (0.013 sec old)
Buffer length: 4.960 sec

link5

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (2289.835 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (2289.835 sec old)
Buffer length: 0.000 sec

camera

finger