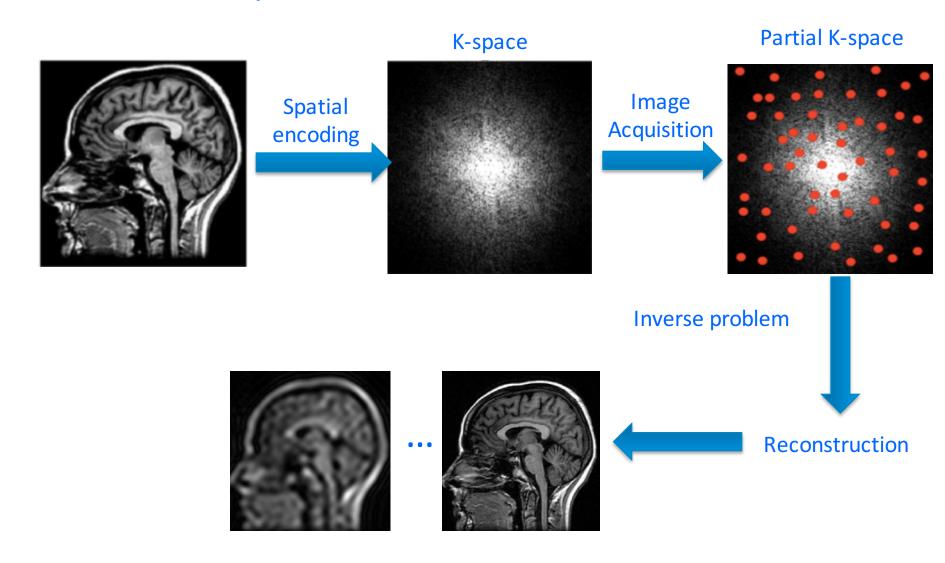
# Learning Pathway: One Month Internship Study

#### **OUTLINE**

- MRI: Inverse problem
- Wavelet Transform
  - Continuous Wavelet Transform
  - Discrete Wavelet Transform
  - Localization properties
  - Sparity
  - Denoising
- Compressed sensing
  - A new theory of sampling
  - Solving Underdetermined Systems
  - Incoherent sampling
  - Optimization Scheme
  - Demo



## MRI: Inverse problem





 CWT: The integral sum of the signal multiplied by the Dilations and translations of the wavelet functions:

$$C(scale, position) = \int_{-\infty}^{\infty} f(t) \Psi(scale, position, t) dt$$

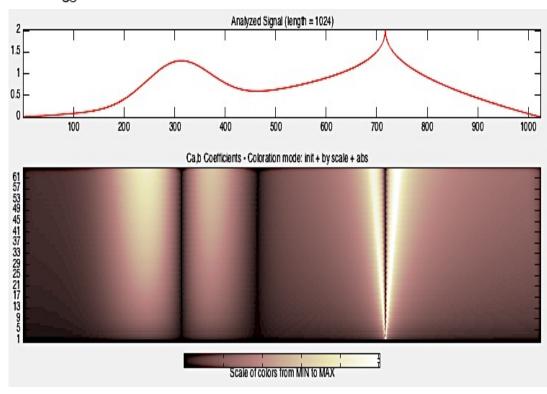
$$\psi_{\tau,s}(t) = \frac{1}{\sqrt{|s|}} \psi(\frac{t-\tau}{s})$$

• For a given wavelet function with fixed  $\tau$  and s,

$$C = \langle f(t), \psi_{\tau,s}(t) \rangle$$

 For a set of wavelet functions with fixed s,

$$C(\tau) = f(t) * \psi_{-\tau,s}(-t)$$





- A Wavelet is a waveform of effectively limited duration that has an average value of zero.
- Admissibility condition:

$$C_{\psi} = \int_{\mathbb{R}} \frac{|\Psi(\omega)|^2}{|\omega|} d\omega < \infty$$

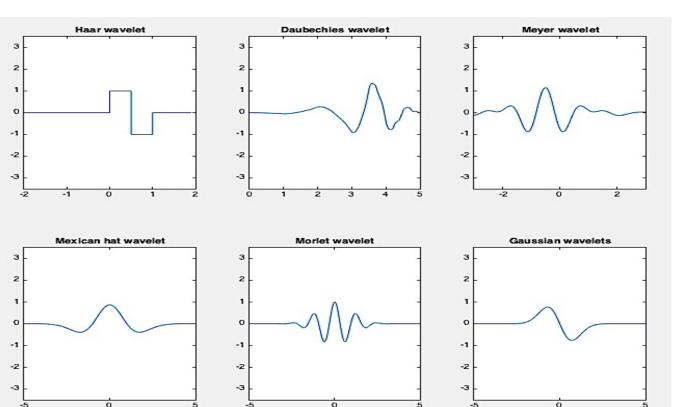


#### Zero mean:

$$\int_{-\infty}^{\infty} \Psi(t) \, \mathrm{d} \, t = 0$$

#### Finite energy:

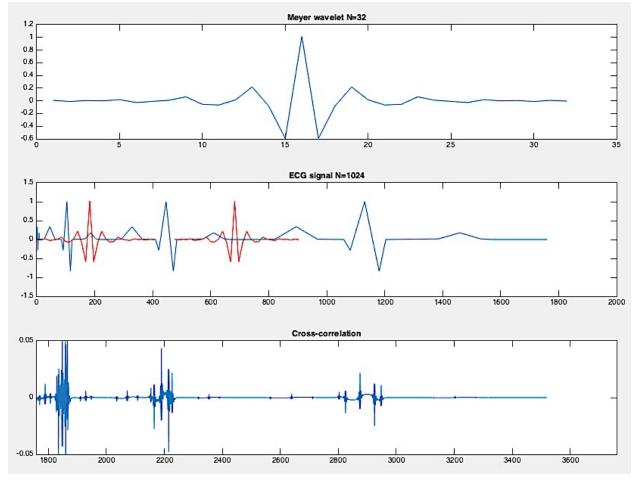
$$\int_{-\infty}^{\infty} |\Psi(t)|^2 \mathrm{d}\,t \le \infty$$





Think wavelet in different perspectives:

 Cross correlation (inner product): A measure of the similarity between the signal and the scaled and shifted wavelet.





 Band-pass filtering (convolution): For a fixed scale, the wavelet transform is the convolution of the signal and the time reversed wavelet.

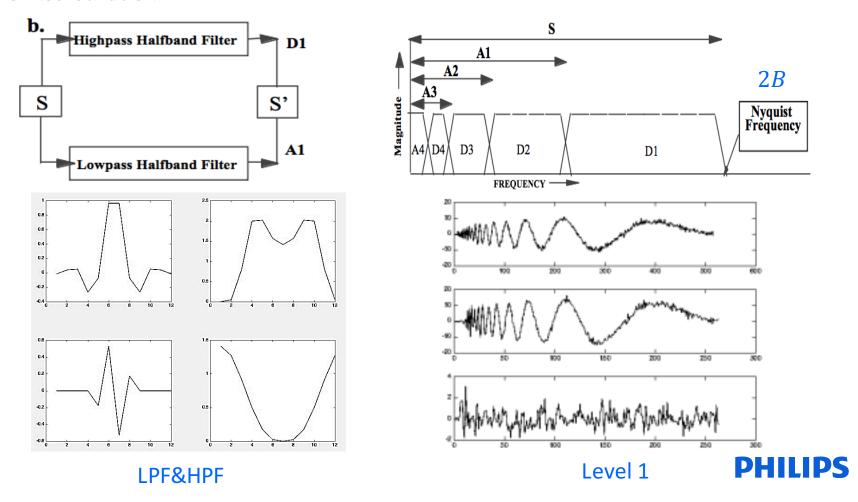
Shannon Wavelet Mexican hat Haar Morelet



#### Wavelet transform: Discrete Wavelet Transform

 DWT: Calculating the wavelets coefficients at only a subset of scales and shifted positions by splitting the signal to sub-bands:

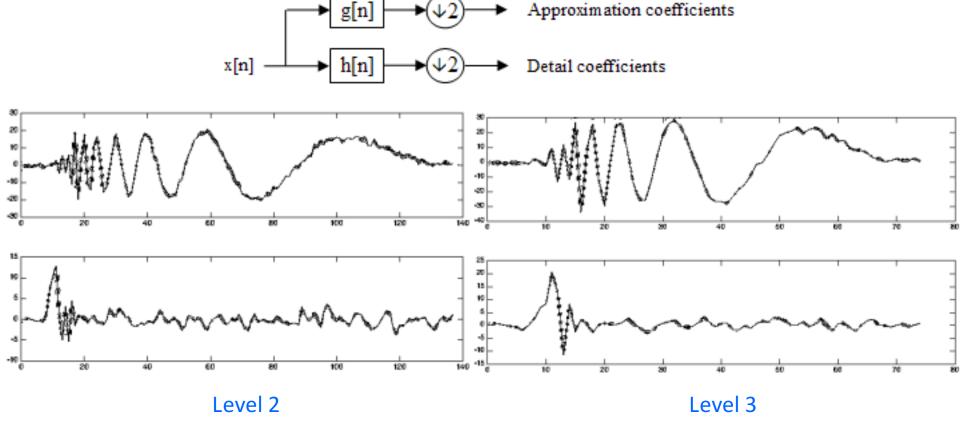
#### Scale Discretization:



#### Wavelet transform: Discrete Wavelet Transform

#### Shifted position Discretization:

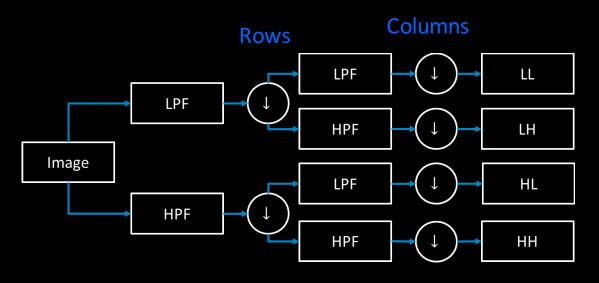
• According to Nyquist-Shannon sampling theorem:  $f_s>2B$ . Half of the samples can be discarded!

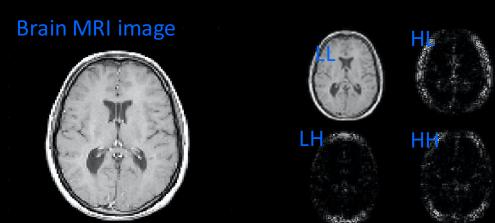




### Wavelet transform: Discrete Wavelet Transform

2D-DWT: Do 1D-DWT horizontally and vertically.





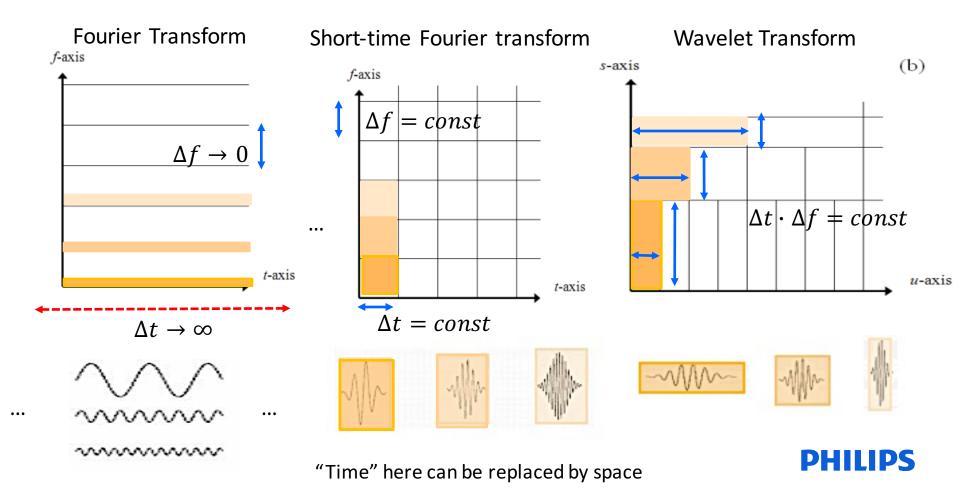
Approxi	Horizont
mation	al details
Vertical	Diagonal
details	details



### Wavelet Transform: Localization properties

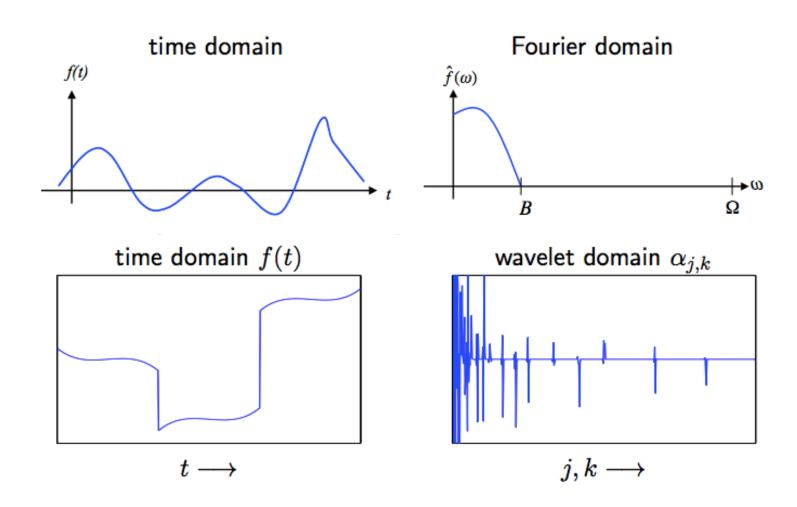
At the Time-frequency plane, the Heisenberg Uncertainty Principle told us:

$$\Delta t \cdot \Delta f \ge \frac{1}{4\pi}$$



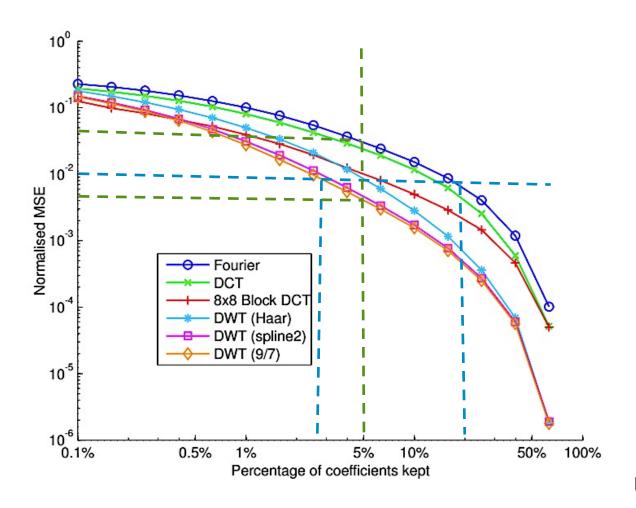
### Wavelet Transform: Sparity

Sparse: few large coeffs, many small coeffs





### Wavelet Transform: Sparity

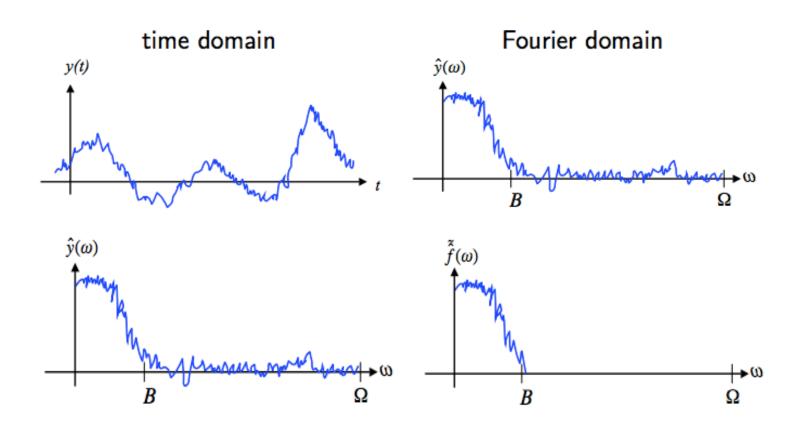


Guerquin-Kern EPFL,PhD thiesis



### Wavelet Transform: Denoising

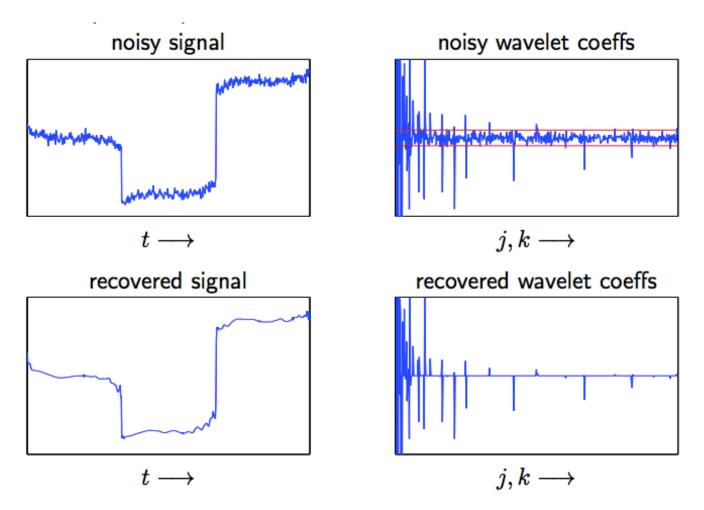
• Frequency domain: Denoising with low pass filtering:





### Wavelet Transform: Denoising

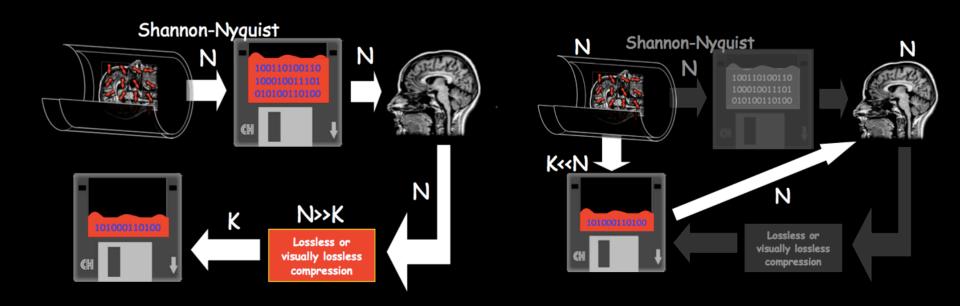
Wavelet denoising: denoising with soft thresholding:





## Compressed Sensing: A new theory of sampling

First compress, then reconstruct. Instead of first collect, then compress.



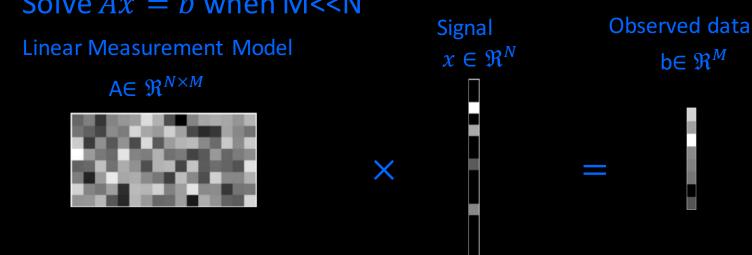
Standard approach

Compressed sensing



### Compressed Sensing: Solving Underdetermined Systems

Solve Ax = b when M<<N



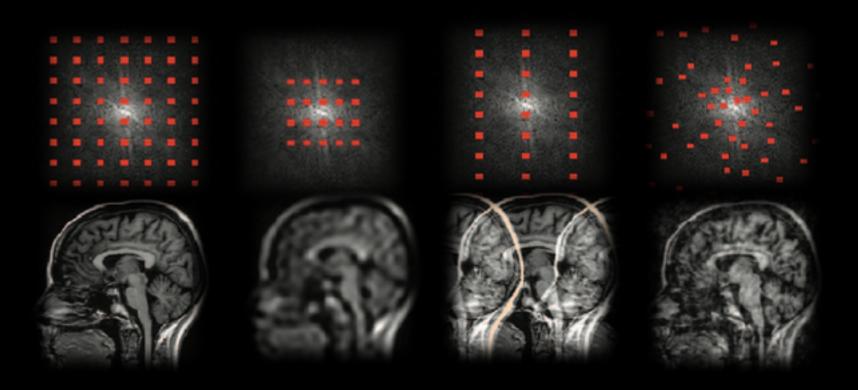
- Sparsity and Incoherency
  - X is a K-sparse signal (K<m<<n): At most K of the coefficients of x can be non-zero.
  - The sensing matrix A is incoherent:  $A^* \cdot A \approx I$





## Compressed Sensing: Incoherent sampling

Applying inverse Fourier transform for reconstruction:



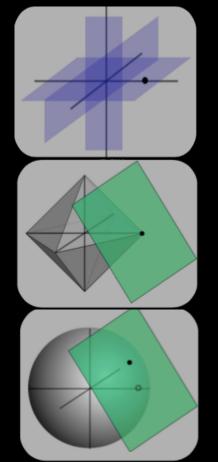


## Compressed Sensing: Optimization Scheme

• Minimizes  $l_p(x)$ , s.t.  $\overline{Ax = b}$ 

	Definition	Description
$l_0$	$x^{\#} = argmin_{X:Ax=b}   x  _{l^{0}}$ $  x  _{l^{0}} = \sum_{i=1}^{N}  x_{i} ^{0} = \#(1 \le i \le n, x_{i} \ne 0)$	NP-hard Problem
$l_1$	$x^{\#} = argmin_{X:Ax=b} \ x\ _{l^{1}}$ Solving non-linear convex optimization	Convex optimization Problem
$l_2$	$x^{\#} = argmin_{X:Ax=b}   x  _{l^{2}}$ $  x  _{l^{2}} = A^{*}(AA^{*})^{-1}b$	Least Squares Solution

Geometry Interpretation

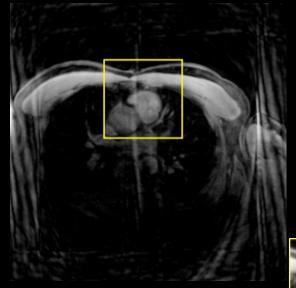




### Compressed Sensing: Optimization Scheme

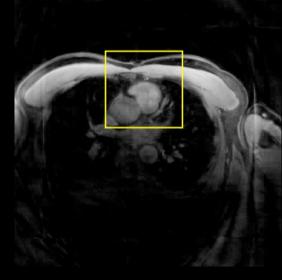
Reconstruction as an optimization problem

$$x^{\#} = argmin||y - Ax||_{2}^{2} + \lambda ||x||_{p}^{p}$$
Data consistency Regularization

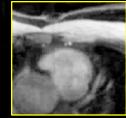


 $l_2$  regularization



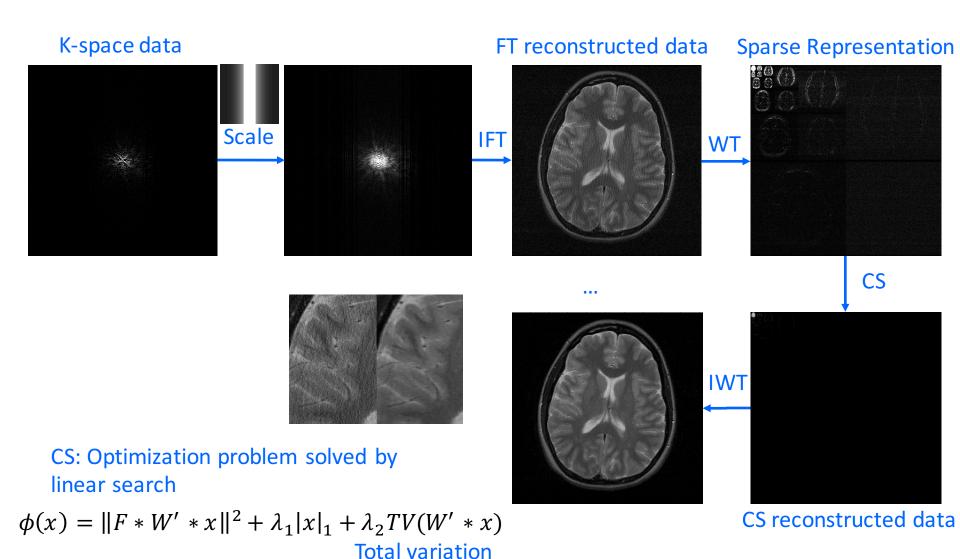


 $l_1$  regularization





### Compressed Sensing: Demo



# Thank you for your attention!

