# Introduction to MPI for Python with MPI4Py

Pascal Paschos, PhD
Sr. HPC Specialist
pascal.paschos@northwestern.edu

Alper Kinaci, PhD Sr. Computational Specialist akinaci@northwestern.edu

Research Computing Services



## Message Passing Interface (MPI)

- A standard library interface for coding on distributed memory systems
- Only message passing library that can be considered a standard
- It is supported on virtually all HPC platforms
- C, C++, Fortran, Python, Java and R bindings
- Different implementations exist: OpenMPI, MPICH, Intel MPI etc.
- The programmer is responsible for correctly identifying parallelism and implementing parallel algorithms

## Advantages of Message Passing

- Universality: The model works on separate processors connected by any network
- Performance/Scalability:
  - As core counts increase, management of memory becomes a key performance factor
  - Each message passing process directly uses only its local data, avoiding the complexities and possible conflicts of shared data model

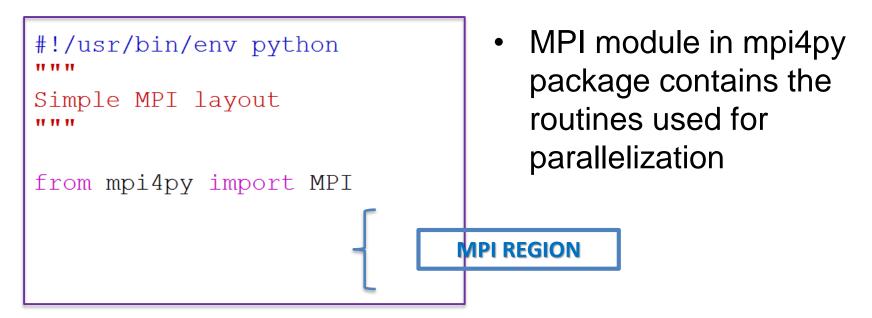
### Layout in Fortran & C

#### **FORTRAN**

```
PROGRAM mpilayout
                                              #include <mpi.h>
USE MPI ! f90 designation
! include "mpif.h" ! f77 designation
integer ierr
                               NON-MPI
CALL MPI INIT(ierr)
                               MPI CALL
                                             MPI Finalize();
CALL MPI FINALIZE (ierr)
                               NON-MPI
END PROGRAM mpilayout
```

```
int main (int argc, char **argv)
MPI Init(&argc, &argv);
```

## Layout of an Python Code with mpi4y



- MPI\_Init is called when mpi4py is imported
- MPI\_Finalize is called when script exits

## Running mpi4py on Quest

- Load python module
- > module load python
- Run the MPI code
- > mpirun -np 2 python <script.py>

#### Hello World

```
#!/usr/bin/env python
"""
Hello World, serial
"""
import sys
sys.stdout.write("Hello, World!"+"\n")
```



```
#!/usr/bin/env python
"""
Hello World, parallel
"""

from mpi4py import MPI
import sys
sys.stdout.write("Hello, World!"+"\n")
```

## A Simple Python MPI Code

```
#!/usr/bin/env python
Hello World, parallel
from mpi4py import MPI
import sys
comm = MPI.COMM WORLD
size = MPI.COMM WORLD.Get size()
rank = MPI.COMM WORLD.Get rank()
name = MPI.Get processor name()
sys.stdout.write(
    "Hello, World! I am process %d of %d on %s.\n"
    % (rank, size, name))
```

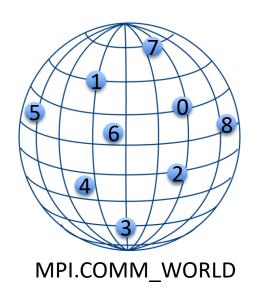
Minimal or no message communication: Embarrassingly parallel

#### MPI Environment

**Python** | co

comm=MPI.COMM WORLD

- Communicator: a structure in which we identify a group of processes
- COMM\_WORLD: constant which includes the whole activated communicator processes in an instance. It is a standard communicator object of MPI module in mpi4y



#### MPI Environment

Python MPI.COMM\_WORLD.Get\_size()

Size: the number of processes in a communicator

Python MPI.COMM\_WORLD.Get\_rank()

 Rank: Within the communicator, each processes is assigned to an integer from 0 to size-1

#### **MPI** Communication

As understood from the name, MPI processes communicate by passing messages



Point-to-Point Communication

#### **MPI** Communication

Message (data+envelope)

A message contains the data and its envelope

DATA	ENVELOPE
Buffer, initial address	Communicator
Count	Source
Data type	Destination
	Tag

#### **MPI** Communication

## **Point-to-Point Communication**

Message is passed from one process to another

- Blocking (Comm.send, Comm.receive)
- Non-blocking (Comm.isend, Comm.irecv)

## **Collective Communication**

Message passes to all processes in a communicator

- Blocking versus non-blocking:
  - Blocking routines do not return until it is safe to use the routine's buffer (i.e. variables)
    - safe: the buffer has been copied to system or receiver buffer
  - Non-blocking routines do not wait for communication to complete
  - Non-blocking routines allow the overlap of computation and communication in order to gain performance

- Usual communication methods are included in Comm class of MPI module
- Comm.send(buf, dest, tag)

#### Data Envelope

Variable	Definition
buf	Address of send buffer
dest	Rank of destination
tag	Message tag

Comm.recv(buf,source,tag,status)

Data Envelope

Variable	Definition
buf	Address of receive buffer
source	Rank of source
tag	Message tag
status	Status object (sender rank, tag, length)

Deadlock: Message passing cannot be completed.

```
if rank == 0:
    comm.send(..., dest=1, ...)
    comm.recv(..., source=1, ...)
elif rank == 1:
    comm.send(..., dest=0, ...)
    comm.recv(..., source=0, ...)
```

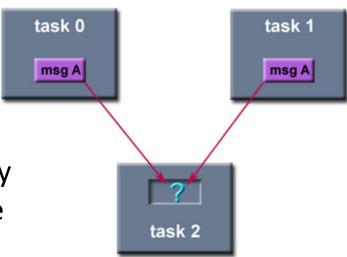


```
if rank == 0:
    comm.send(..., dest=1, ...)
    comm.recv(..., source=1, ...)
elif rank == 1:
    comm.recv(..., dest=0, ...)
    comm.send(..., source=0, ...)
```



- Order and Fairness
  - MPI keeps the order of send (or receive) requests from the same task
  - MPI does not guarantee fairness

If 2 different tasks send messages that match another tasks receive, only one send will be complete



## Communicating Objects & Arrays

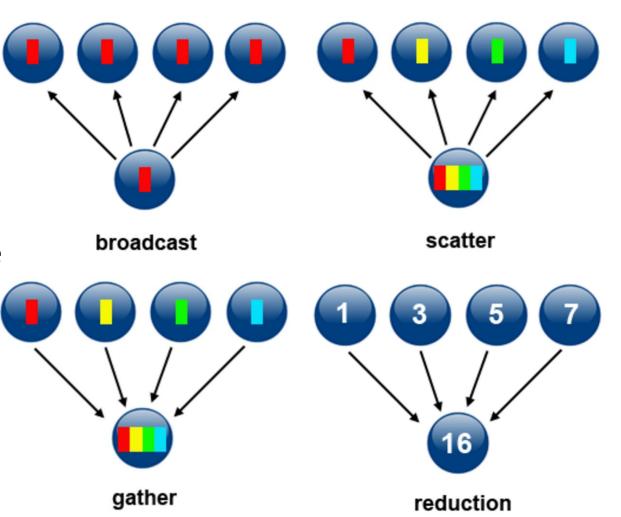
- mpi4py provides two sets of functions for communication:
  - All lower case methods (send, recv etc.) are for communicating generic python data objects. Can be slow.
  - Upper-case initial letter case (Send, Recvetc.) are for communicating array data (such as NumPy arrays) which occupies continuous memory blocks. Fast communication.

```
import numpy as np
from mpi4py import MPI
comm = MPI.COMM WORLD
message = np.arange(1)
comm.Barrier()
status = MPI.Status()
size = comm.size
rank = comm.rank
if rank == 0:
        message[0] = 48151623
        print 'process ', rank, ' sends ' , message
        comm.Send(message, dest=1)
        print ' '
elif rank == 1:
        comm.Recv(message, source=0, status=status)
        print ' '
        print 'process ', rank, ' receives ', message
```

A blocking communication between 2 processes for array data

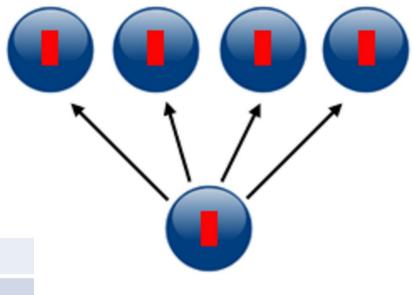
## **Types of Collective Communications**

- Synchronization
- Data Movement
- Collective Compute



#### Comm.Bcast (buf, root)

Broadcasts a message from one process to members in a communicator



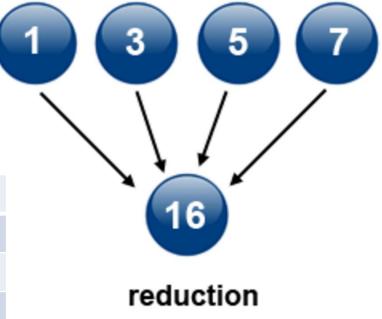
Variable	Definition
buf	Address of input buffer
root	Process id of root process

broadcast

#### Comm.Reduce (sendbuf,recbuf,op,root)

Performs a reduction operation to the vector of elements in the sendbuf of the group members and places the result in recvbuf on root

Variable	Definition
sendbuf	Address of send buffer
recvbuf	Address of receive buffer
ор	Operation (+,-,x,max,min,)
root	Process id of root process



Comm.barrier Comm.Barrier	All processes within a communicator will be blocked until all processes within the communicator have entered the call.
Comm.bcast Comm.Bcast	Broadcasts a message from one process to members in a communicator.
Comm.reduce Comm.Reduce	Performs a reduction operation to the vector of elements in the sendbuf of the group members and places the result in recvbuf on root.
Comm.gather Comm.Gather	Collects data from the sendbuf of all processes in comm and place them consecutively to the recybuf on root based on their process rank.
Comm.scatter Comm.Scatter	Distribute data in sendbuf on root to recvbuf on all processes in comm.
Comm.allreduce Comm.Allreduce	Same as MPI_REDUCE, except the result is placed in recvbuf on all members in a communicator.
Comm.allgather Comm.Allgather	Same as GATHER/GATHERV, except now data are placed in recvbuf on all processes in comm.
Comm.alltoall Comm.Alltoall	The j-th block of the sendbuf at process i is send to process j and placed in the i-th block of the recybuf of process j.

#### References

- https://computing.llnl.gov/tutorials/mpi/
- http://sc.tamu.edu/shortcourses/SC-MPI/mpi\_shortcourse\_v4.pdf
- http://mpi4py.scipy.org/docs/usrman/tutorial. html
- https://mpi4py.scipy.org/docs/apiref/mpi4py.
   MPI-module.html
- https://wiki.python.org/moin/ParallelProcessing