

# Better Decremental and Fully Dynamic Sensitivity Oracles for Subgraph Connectivity

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# Decremental v.s. Fully Dynamic

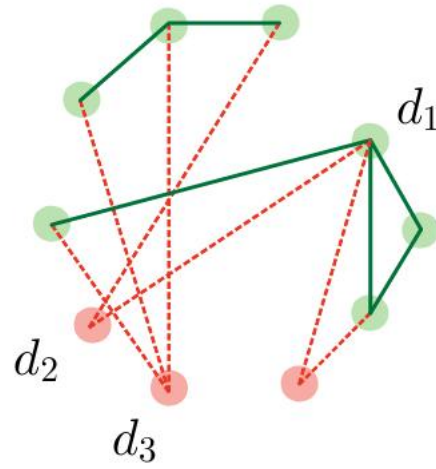
- **Decremental Setting (Vertex-Failure)**

- There are no inactivated vertices initially, i.e.,  $V_{\text{off}} = \emptyset$ .

- **Fully Dynamic Setting**

- No constraints

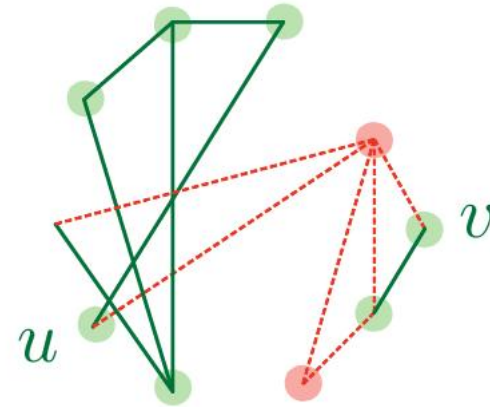
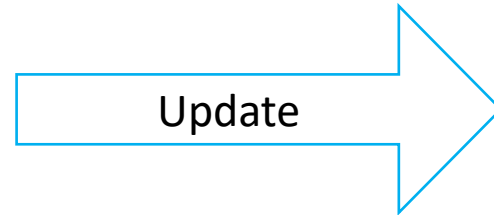
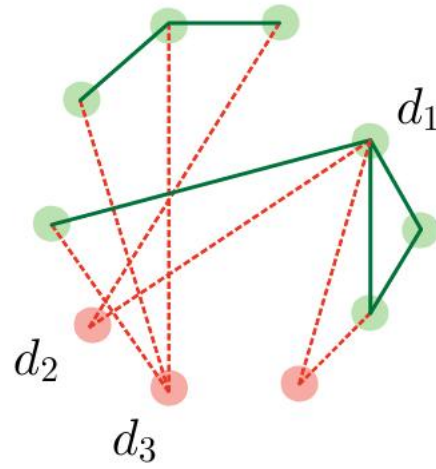
# Example



Red Vertices:  $V_{\text{off}}$

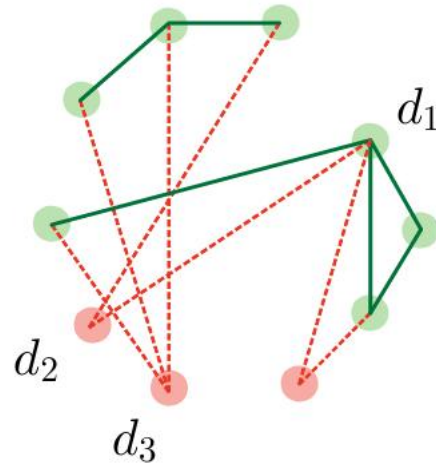
Green Vertices:  $V_{\text{on}}$

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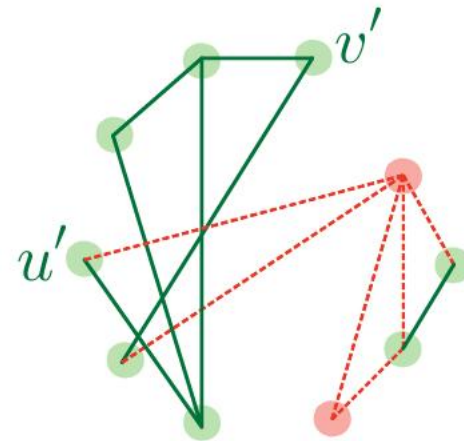
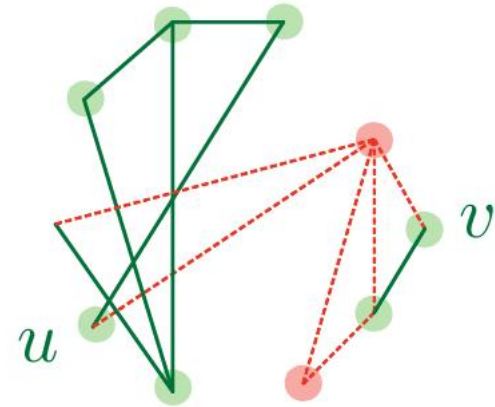
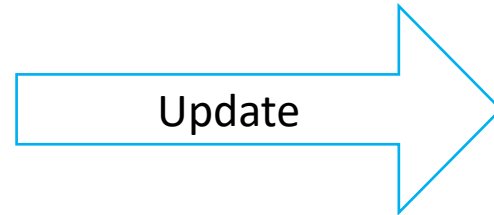


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Red Vertices:  $V_{\text{off}}$   
Green Vertices:  $V_{\text{on}}$



# History (Decremental)

	Det./ Rand.	Space	Preprocessing	Update	Query
Block trees, SQRT trees, and [KTDBC91] only when $d_\star \leq 3$	Det.	$O(n)$	$\tilde{O}(m)$	$O(1)$	$O(1)$
Duan & Pettie [DP10] for $c \geq 1$	Det.	linear in preprocessing time	$\tilde{O}(md_\star^{1-\frac{2}{c}}n^{\frac{1}{c}-\frac{1}{c\log(2d_\star)}})$	$\tilde{O}(d^{2c+4})$	$O(d)$
Duan & Pettie [DP20]	Det.	$O(md_\star \log n)$	$O(mn \log n)$	$O(d^3 \log^3 n)$	$O(d)$
	Rand.	$O(m \log^6 n)$	$O(mn \log n)$	$\bar{O}(d^2 \log^3 n)$ w.h.p.	$O(d)$
Brand & Saranurak [vdBS19]	Rand.	$O(n^2)$	$O(n^\omega)$	$O(d^\omega)$	$O(d^2)$
Pilipczuk et al. [PSS <sup>+</sup> 22]	Det.	$m2^{2^{O(d_\star)}}$	$mn^22^{2^{O(d_\star)}}$	$2^{2^{O(d_\star)}}$	$2^{2^{O(d_\star)}}$
	Det.	$n^2 \text{poly}(d_\star)$	$\text{poly}(n)2^{O(d_\star \log d_\star)}$	$\text{poly}(d_\star)$	$\text{poly}(d_\star)$
Long & Saranurak [LS22]	Det.	$O(m \log^3 n)$	$O(mn \log n)$	$\bar{O}(d^2 \log^3 n \log^4 d)$	$O(d)$
	Det.	$O(m \log^* n)$	$\hat{O}(m) + \tilde{O}(d_\star m)$	$\hat{O}(d^2)$	$O(d)$
Kosinas [Kos23]	Det.	$O(d_\star m \log n)$	$O(d_\star m \log n)$	$O(d^4 \log n)$	$O(d)$
<b>This paper</b>	Det.	$O(m \log^3 n)$	$\hat{O}(m) + O(d_\star m \log^3 n)$	$O(d^2(\log^7 n + \log^5 n \log^4 d))$	$O(d)$



# History (Fully Dynamic)

	Det./ Rand.	Space	Preprocessing	Update	Query
Henzinger & Neumann [HN16]	Det.	$\tilde{O}(n_{\text{off}}^2 m)$	$\hat{O}(n_{\text{off}}^2 m) + \tilde{O}(d_{\star} n_{\text{off}}^2 m)$	$\hat{O}(d^4)$	$O(d^2)$
Hu, Kosinas & Polak [HKP23]	Det.	$\tilde{O}((n_{\text{off}} + d_{\star})m)$	$\tilde{O}((n_{\text{off}} + d_{\star})m)$	$\tilde{O}(d^4)$	$O(d)$
<b>This paper</b>	Det.	$O(\min\{(n_{\text{off}} + d_{\star})m \log^2 n, n^2\})$	$\hat{O}(m) +$ $O(\min\{(n_{\text{off}} + d_{\star})m, n^{\omega}\} \log^2 n)$	$O(d^2 \log^7 n)$	$O(d)$

# Technique Overview

- **Low Degree Hierarchy**, which can be reduced to  $O(\log n)$  calls to the low-degree Steiner forest decomposition.[DP20, LS22]
- We say a forest  $F \subseteq E(G)$ , is a spanning forest of  $U$  in  $G$  if  $F$  spans the whole  $U$  (may also span vertices not in  $U$ ).

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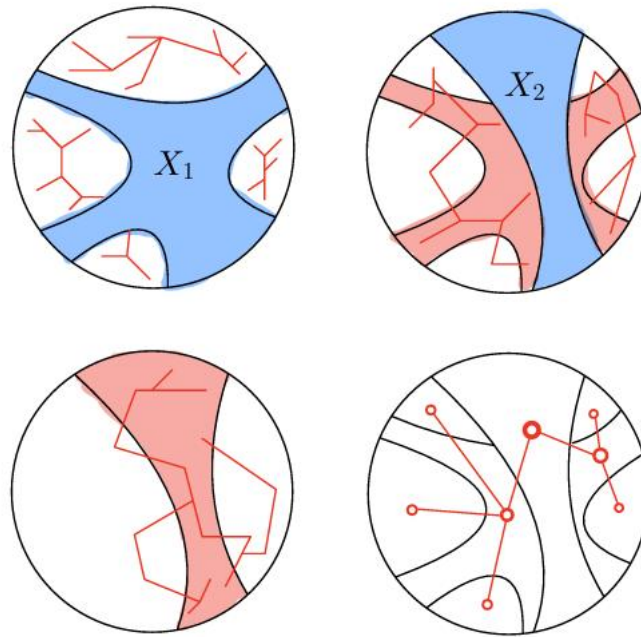
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# Low Degree Hierarchy

- Low Degree Hierarchy: a laminar set  $C$  of components.
- Components form a **tree** hierarchy.
- $X_i = \text{Decomp}(G, X_{i-1})$



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# Cut Matching Game

- Let  $G$  be a undirected graph with a terminal set  $U$ . Given a parameter  $\varphi$  and a partition  $(A, B)$  of  $U$ , there is a deterministic algorithm that computes either
- 1. A **vertex cut**  $(L, S, R)$  with  $|R \cap U| \geq |L \cap U| \geq \min\{|A|, |B|\}/3$  and  $|S| \leq \varphi \cdot |L \cap U|$
- 2. A **matching**  $M$  between  $A$  and  $B$  with size  $|M| \geq \min\{|A|, |B|\}/3$  s.t. there is an embedding of  $M$  into  $G$  with congestion  $O(1/\varphi)$

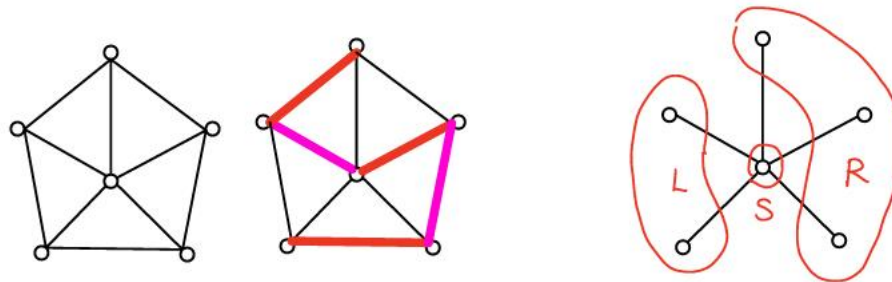


Figure **Left**: Low Degree Steiner Tree **Right**: Balanced Vertex Cut

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- Reason: It allows us to consider semi-bipartite graph. We can assume that  $G[V_{on}] = (L, R, E)$ , where there is no edge between  $R$ .

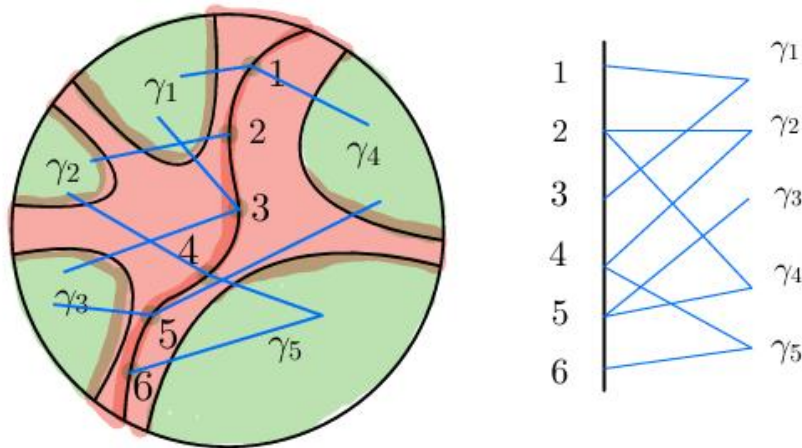
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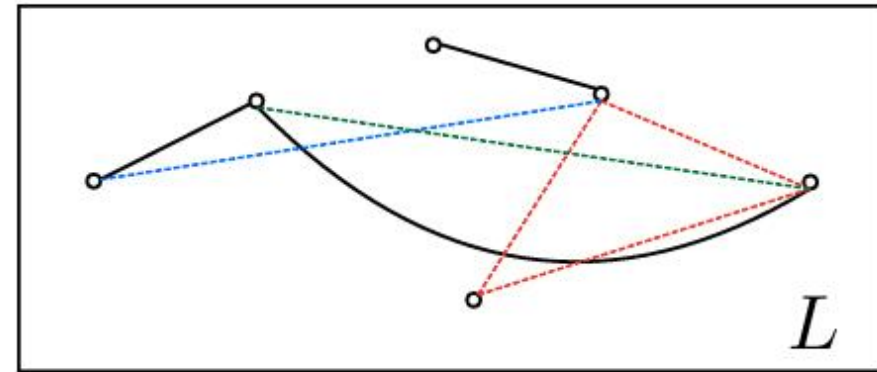
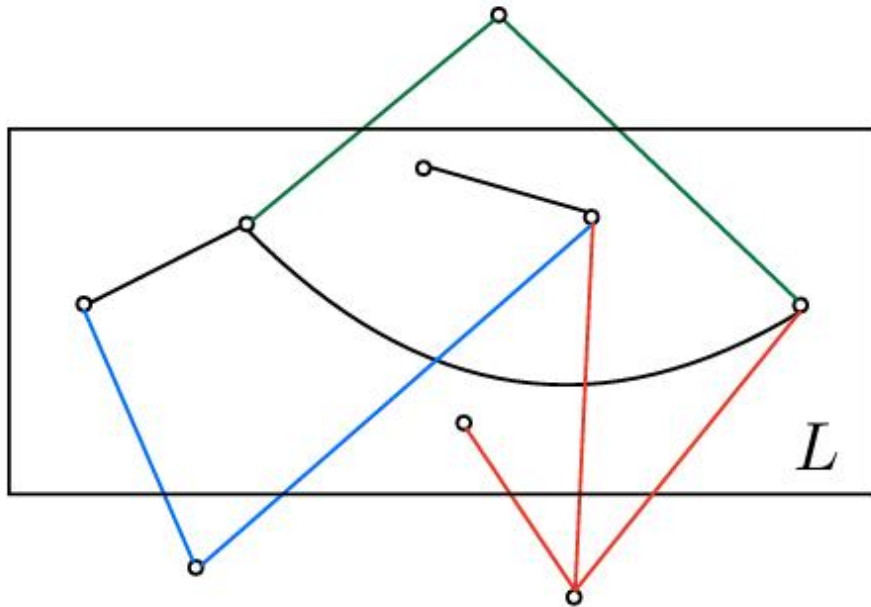
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# Abstract Graph

- High level idea: maintain all vertices in  $L$  and ignore the vertices in  $R$



----- artificial edges

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# Conditional Lower Bound

1. If  $t_u + t_p = f(d) \cdot n^{o(1)}$ , then  $S = \widehat{\Omega}(n^2)$ .
  2. If  $t_u + t_p = f(d) \cdot n^{o(1)}$ , then  $t_u = \widehat{\Omega}((n_{\text{off}} + d)m)$ . [HKP23]
  3. If  $t_u + t_p = f(d) \cdot n^{o(1)}$ , then  $t_u = \widehat{\Omega}(n^{\omega_{\text{bool}}})$ .
  4. If  $t_p = \text{poly}(n)$ , then  $t_u + t_q = \widehat{\Omega}(d^2)$ . [LS22]
  5. If  $t_p = \text{poly}(n)$  and  $t_u = \text{poly}(dn^{o(1)})$ , then  $t_q = \widehat{\Omega}(d)$ . [HKNS15]
- The  $f(d)$  above can be an arbitrary growing function, and  $\omega_{\text{bool}}$  is the exponent of Boolean matrix multiplication.

# Acknowledgement

- We thank Thatchaphol Saranurak for helpful discussions.

Thank you!