group86_best_algorithm1

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1 COMP5318 - Machine Learning and Data Mining: Assignment 2, Best Classifier CNN

```
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```

1.0.1 Hardware and software specifications

hardware: 1. CPU: Intel i
7-8700 K @ 3.70 GHz 2. RAM: 64 G DDR4 3000 MHz 3. Graphics: N
Vidia GeForce GTX 1080 Ti 4. Chipset: Z370

1.0.2 Software specifications

```
[1]: import os, platform
     print('OS name:', os.name, ', system:', platform.system(), ', release:', u
     →platform.release())
     import sys
     print("Anaconda version:")
     #!conda list anaconda
     print("Python version: ", sys.version)
     print("Python version info: ", sys.version_info)
     import PIL
     from PIL import Image
     print("PIL version: ", PIL.__version__)
     import matplotlib
     import matplotlib.pyplot as plt
     print("Matplotlib version: ", matplotlib.__version__)
     #import tensorflow as tf
     #print("Keras version:", tf.keras.__version__)
     import cv2
     print("OpenCV version: ", cv2.__version__)
     import numpy as np
     print("nump version: ", np.__version__)
```

```
OS name: nt , system: Windows , release: 10
Anaconda version:
Python version: 3.8.3 (default, Jul 2 2020, 17:30:36) [MSC v.1916 64 bit (AMD64)]
Python version info: sys.version_info(major=3, minor=8, micro=3, releaselevel='final', serial=0)
PIL version: 7.2.0
Matplotlib version: 3.2.2
OpenCV version: 4.4.0
nump version: 1.18.5
```

1.1 CODE RUNNING INSTRUCTIONS:

```
Instruction:
```

Simply change the switches in below blocks and run all.

```
Dataset directory:

Same directory as the jupyter notebook, in the format of:
---[current dir]
|----[This file]
|----[dataset]
|----test
|----train
```

The default parameters will used the saved model to run simple tests, and load confusion matrices, accuracies, etc. from disk and plot them for display purpose.

1.2 Section 0. Switches

Load saved model or run training?

```
[2]: load_saved_model = True
```

Run 10-fold cross validation? (Slow if turned on)

```
[3]: # Caution: Slow if turned on.
test_CNN_ten_fold = False
```

1.3 Section 1. Library and general functions

```
[4]: # Go to anaconda prompt to install package imblearn
# anaconda: conda install -c glemaitre imbalanced-learn
#pip install kmeans-smote

from skimage import io, transform
import matplotlib.pyplot as plt
import numpy as np
```

```
import pandas as pd
import cv2
import time
```

1.3.1 global variables

```
[5]: # choose one of below two line depend file location ******
     g_dataset_dir = "./dataset/"
     #g_dataset_dir = "../dataset/"
     a_random_file = "./dataset/train/1b1B1b2-2pK2q1-4p1rB-7k-8-8-3B4-3rb3.jpeg"
     \#a_random_file = ".../dataset/train/1b1B1b2-2pK2q1-4p1rB-7k-8-8-3B4-3rb3.jpeg"
     saved_model_path = "./saved_model/"
     abc_model_file = saved_model_path + "abc_dump.pkl"
     svc_model_file = saved_model_path + "svc_dump.pkl"
     cnn_model_file = saved_model_path + "cnn_weights"
     ten_fold_result_path = "./ten_fold_results/"
     # define global variable
     g_train_dir = g_dataset_dir + "/train/"
     g_test_dir = g_dataset_dir + "/test/"
     g_{inage_size} = 400
     g_grid_row = 8
     g_grid_col = 8
     g_grid_num = g_grid_row * g_grid_col
     g_grid_size = int(g_image_size / g_grid_row)
     #Processing 1 - scale down
     g_down_sampled_size = 200
     g_down_sampled_grid_size = int(g_grid_size / (g_image_size / ___
     →g_down_sampled_size))
     # global instance of mapping of char vs chess pieces
     # reference: Forsyth-Edwards Notation, https://en.wikipedia.org/wiki/
     → Forsyth%E2%80%93Edwards_Notation
```

```
\# pawn = "P", knight = "N", bishop = "B", rook = "R", queen = "Q" and king = "K"
# White pieces are designated using upper-case letters ("PNBRQK") while black
→pieces use lowercase ("pnbrqk")
# we use 0 to note an empty grid.
# 13 items in total.
g_piece_mapping = {
    "P" : "pawn",
    "N" : "knight",
    "B" : "bishop",
    "R" : "rook",
    "Q" : "queen",
    "K" : "king",
    "p" : "pawn",
    "n" : "knight",
    "b" : "bishop",
    "r" : "rook",
    "q" : "queen",
    "k" : "king",
    "0" : "empty_grid"
}
g_num_labels = len(g_piece_mapping)
g_labels = ["P",
"N",
"B".
"R",
"Q",
"K",
"p",
"n",
"b",
"r",
"q",
"k",
"0"]
```

1.3.2 Helper codes for label & board

```
[6]: #DataHelper.py
import os
```

```
import cv2
from skimage import io
import numpy as np
import glob
import h5py
# get clean name by a path, where in our case this gets the FEN conviniently
def GetCleanNameByPath(file name):
   return os.path.splitext(os.path.basename(file_name))[0]
# get full paths to the files in a directory.
def GetFileNamesInDir(path_name, extension="*", num_return = 0):
    if num_return == 0:
       return glob.glob(path_name + "/*." + extension)
   else:
       return glob.glob(path_name + "/*." + extension)[:num_return]
# get name list
def GetCleanNamesInDir(path_name, extension = "*", num_return = 0):
   names = GetFileNamesInDir(path_name, extension)
   offset = len(extension) + 1
   clean_names = [os.path.basename(x)[:-offset] for x in names]
   if num return == 0:
        return clean_names
       return clean_names[:num_return]
# read dataset
def ReadImages(file_names, path = "", format = cv2.IMREAD_COLOR):
   if path == "":
        return [cv2.imread(f, format) for f in file_names]
   else:
       return [cv2.imread(path + "/" + f, format) for f in file_names]
# read image by name
def ReadImage(file_name, gray = False):
   return io.imread(file_name, as_gray = gray)
# h5py functions
# read h5py file
# we assume the labels and
def ReadH5pyFile(file_name, data_name):
   h5_buffer = h5py.File(file_name)
   return h5_buffer[data_name].copy()
```

```
# write h5py file
def WriteH5pyFile(file_name, mat, data_name = "dataset"):
    with h5py.File(file_name, 'w') as f:
        f.create_dataset(data_name, data = mat)
```

```
[7]: #BoardHelper.py
     import re
     import string
     from collections import OrderedDict
     import numpy as np
     import skimage.util
     from skimage.util.shape import view_as_blocks
     #from ChessGlobalDefs import *
     #FEN TO LABELS OF SQUARES
     def FENtoL(fen):
         rules = {
            r"-": r"",
            r"1": r"0",
            r"2": r"00".
             r"3": r"000",
            r"4": r"0000".
             r"5": r"00000",
            r"6": r"000000",
            r"7": r"0000000",
            r"8": r"00000000",
         }
         for key in rules.keys():
             fen = re.sub(key, rules[key], fen)
         return list(fen)
     # Label array to char list:
     def LabelArrayToL(arr):
         rules = {
             0 : "P",
             1 : "N",
             2 : "B",
             3 : "R",
             4 : "Q",
             5 : "K",
```

```
6 : "p",
       7 : "n",
       8 : "b",
       9 : "r",
      10 : "q",
      11 : "k",
      12 : "0"
    }
   flattened = arr.flatten(order = "C")
    L = []
   for x in flattened:
        L.append(rules[x])
   return L
# char list to FEN
def LtoFEN(L):
   FEN = ""
   for y in range(8):
        counter = 0
        for x in range(8):
            idx = x + y * 8
            char = L[idx]
            if char == "0":
                counter += 1
                if x == 7:
                   FEN += str(counter)
            else:
                if counter:
                   FEN += str(counter)
                    counter = 0
               FEN += char
        if y != 7:
            FEN += "-"
    return FEN
```

```
# FEN to one-hot encoding, in our case, it returns an 64 by 13 array, with each
→row as a one-hot to a grid.
def FENtoOneHot(fen):
    # this rule is in the same format as g_piece_mapping
    \#rules = {
         "P" : np.array([1, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0]),
         "N" : np.array([0, 1, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0]),
    #
    #
         "B": np.array([0, 0, 1, 0, 0, 0, 0, 0, 0, 0, 0, 0]),
         "R" : np.array([0, 0, 0, 1, 0, 0, 0, 0, 0, 0, 0, 0]),
         "Q" : np.array([0, 0, 0, 0, 1, 0, 0, 0, 0, 0, 0, 0, 0]),
         "K" : np.array([0, 0, 0, 0, 0, 1, 0, 0, 0, 0, 0, 0]),
    #
    #
         "p": np.array([0, 0, 0, 0, 0, 0, 1, 0, 0, 0, 0, 0]),
         "n": np.array([0, 0, 0, 0, 0, 0, 1, 0, 0, 0, 0]),
    #
    #
         "b": np.array([0, 0, 0, 0, 0, 0, 0, 1, 0, 0, 0]),
    #
         "r": np.array([0, 0, 0, 0, 0, 0, 0, 0, 1, 0, 0]),
         "q": np.array([0, 0, 0, 0, 0, 0, 0, 0, 0, 1, 0, 0]),
    #
         "k": np.array([0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 1, 0]),
    #
    #
         "0": np.array([0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 1])
    #}
   rules = {
        "P" : 0,
        "N" : 1,
       "B" : 2,
       "R" : 3,
        "Q" : 4.
       "K" : 5,
        "p" : 6,
        "n" : 7,
       "b" : 8,
       "r" : 9,
        "q" : 10,
        "k" : 11,
        "0": 12
   }
   L = FENtoL(fen)
   one_hot_array = np.zeros((g_grid_num, g_num_labels), dtype = np.int32) # 64__
 →by 13
   for i, c in enumerate(L):
       one_hot_array[i, rules[c]] = 1
```

```
return one_hot_array
# get 8*8 char matrix
def LtoCharMat(1):
    if type(1) == list:
       return np.array(1).reshape((8,8))
   if type(1) == str:
       return np.array([1]).reshape((8,8))
def GetBoardCell(board_image, row = 0, col = 0, size = 50):
   return np.array(board_image)[row*size:(row+1)*size,col*size:(col+1)*size]
# get grids of image
def ImageToGrids(image, grid_size_x, grid_size_y):
   return skimage.util.shape.view_as_blocks(image, block_shape = (grid_size_y,_
⇒grid_size_x, 3)).squeeze(axis = 2)
# get grids of image
def ImageToGrids_grey(image, grid_size_x, grid_size_y):
   return skimage.util.shape.view_as_blocks(image, block_shape = (grid_size_y,__

→grid_size_x, 1)).squeeze(axis = 2)
```

1.4 Section 2. Data pre-processing

1.4.1 Pre-processing - generic

```
[8]: # split into 64 small square from 1 board
    # image resized to 400x 400 to 200x 200. 64 square at 25x 25 each
    def PreprocessImage(image):
        image = transform.resize(image, (g_down_sampled_size, g_down_sampled_size),__
     →mode='constant')
        # 1st and 2nd dim is 8
        grids = ImageToGrids(image, g_down_sampled_grid_size,_
     return grids.reshape(g_grid_row * g_grid_col, g_down_sampled_grid_size,_u
     →g_down_sampled_grid_size, 3)
    # split into 64 small square from 1 board -
    # output of x: number of image x 64 x 25 x 25 x 3 , y: number of image x 64 x 13
    def func_generator(train_file_names):
        x = []
        y = []
        for image_file_name in train_file_names:
```

```
img = ReadImage(image_file_name)
    x.append(PreprocessImage(img))
    y.append(np.array(FENtoOneHot(GetCleanNameByPath(image_file_name))))
return np.array(x), np.array(y)
```

1.5 Section 3. Implement algorithms

Base class for all classifiers

```
[9]: import abc
     # interface of the classifiers
     class IClassifier:
         # this method should accept a list of file names of the training data
         @abc.abstractmethod
         def Train(self, train_file_names):
             raise NotImplementedError()
         # this should accept a 400 * 400 * 3 numpy array as query data, and returns_{\sqcup}
      \rightarrow the fen notation of the board.
         @abc.abstractmethod
         def Predict(self, query_data):
             raise NotImplementedError()
         # this should accept a list of file names, and returns the predicted labels_
      \rightarrow as 1d numpy array.
         @abc.abstractmethod
         def Predict(self, query_data):
             raise NotImplementedError()
```

10-fold related functions

```
[10]: # filters accepts a list of file names, and return the data matrix and labels
import random
from sklearn.metrics import confusion_matrix

# get balanced accuracy from confusion matrix
def BalancedAccuracyFromConfusionMatrix(cm):
    ret = np.empty((cm.shape[0]))

    for idx, row in enumerate(cm):
        ret[idx] = row[idx] / row.sum()

    return ret.mean()

# dummy filter to return all files
```

```
def DefaultFilter(file_names, rate = 1):
   return file_names
# filter using random_sampling:
def RandomFilter(file_names, rate = 1):
    # we fix the random part to assure the results are consistent
   random seed = 4242
   random.seed(random_seed)
   return random.sample(file_names, k = int(len(file_names) * rate))
⇒sampling_rate = 0.001):
   confusion_matrices = []
   accuracies = []
   accuracies_balanced = []
   train_time_cost = []
   validation_time_cost = []
   # split name list into 10 equal parts
   division = len(test file names) / float(10)
   complete_name_folds = [ test_file_names[int(round(division * i)):_
→int(round(division * (i + 1)))] for i in range(10) ]
   filtered_name_folds = complete_name_folds.copy()
   for i in range(10):
       filtered_name_folds[i] = filter(complete_name_folds[i], rate = __
 →sampling rate)
   # we use filtered name folds to train, and validation.
   for iv in range(10):
       # merge the 9 folds:
       train_names = []
       validation_names = []
       for i in range(10):
           if i != iv:
               train_names.extend(filtered_name_folds[i])
           else:
               # validation_names = complete_name_folds[i].copy()
               validation_names = filtered_name_folds[i].copy()
       # train the classifier:
       print("training started:
                                  ", type(classifier).__name__, "for fold #",_
 →iv, "# train files:", len(train_names))
       t = time.time()
       classifier.Train(train_names)
```

```
train_time_cost.append(time.time() - t)
       print("training finished: ", type(classifier).__name__, "for fold #",__
⇒iv,
             "time: {}s".format(time.time() - t))
       print("predicting started: ", type(classifier).__name__, "for fold #",__
نv)
       t = time.time()
       ypreds, y_true = classifier.PredictMultiple(validation_names)
       validation_time_cost.append(time.time() - t)
       ypreds = ypreds.reshape((-1, 1))
       y_true = y_true.reshape((-1, 1))
       conf_mat = confusion_matrix(y_true, ypreds, labels = g_labels)
       confusion_matrices.append(conf_mat)
       accuracy = np.trace(conf_mat) / float(np.sum(conf_mat))
       accuracies.append(accuracy)
       accuracy_balanced = BalancedAccuracyFromConfusionMatrix(conf_mat)
       accuracies_balanced.append(accuracy_balanced)
       print("predicting finished: ", type(classifier).__name__, "for fold #",__
⇒iv,
             "time: {}s".format(time.time() - t), " accuracy: ", accuracy, "__
→balanced_accuracy:", accuracy_balanced)
   return confusion_matrices, accuracies, accuracies_balanced,_
→train_time_cost, validation_time_cost
```

1.5.1 Convolutional Neural Network Classifier (CNN)

Class definition for CNN

```
import tensorflow as tf
from tensorflow.keras import layers

import cv2
from skimage import io, transform
import numpy as np
import os

#import tensorflow as tf
#from tensorflow import keras
#from tensorflow import keras
#from tf.keras.models import Sequential
#from tf.keras.layers.core import Flatten, Dense, Dropout, Activation
```

```
#from tf.keras.layers.convolutional import Convolution2D
class CNNClassifier(IClassifier):
    # the file name format does not accept batch as parameter. link:
    # https://github.com/tensorflow/tensorflow/issues/38668
    s_check_point_file_name = "./CNN_training_checkpoint/cp_{epoch:
\hookrightarrow02d}-{accuracy:.2f}.ckpt"
    s_check_point_path = os.path.dirname(s_check_point_file_name)
    s_save_frequence = 10000 # save a checkpoint every s_save_frequence batches
   def __init__(self):
        #tf.config.threading.set_inter_op_parallelism_threads(3)
        #tf.config.threading.set_intra_op_parallelism_threads(3)
        # define our model
       self.__model__ = keras.Sequential(
                layers.Convolution2D(32, (3, 3), input_shape =
 →(g_down_sampled_grid_size, g_down_sampled_grid_size, 3)),
               layers.Activation('relu'),
                layers.Dropout(0.1),
                layers.Convolution2D(32, (3, 3)),
                layers.Activation('relu'),
                layers.Convolution2D(32, (3, 3)),
                layers.Activation('relu'),
               layers.Flatten(),
               layers.Dense(128),
                layers.Activation('relu'),
                layers.Dropout(0.3),
                layers.Dense(13),
                layers.Activation("softmax")
           ]
        )
       self.__model__.compile(loss = "categorical_crossentropy", optimizer =_u
self.__save_check_point_callback__ = tf.keras.callbacks.ModelCheckpoint(
            filepath = CNNClassifier.s_check_point_file_name,
           monitor='val_accuracy',
            save_weights_only = True,
```

```
save_freq = CNNClassifier.s_save_frequence,
           verbose = 1
           )
    # generator
   Ostaticmethod
   def func_generator(train_file_names):
       for image file name in train file names:
           img = ReadImage(image_file_name)
           x = CNNClassifier.PreprocessImage(img)
           y = np.array(FENtoOneHot(GetCleanNameByPath(image_file_name)))
           yield x, y
   # this method should accept N * 64 * m * n numpy array as train data, and N_{\sqcup}
\rightarrow lists of 64 chars as label.
   def Train(self, train data names):
       train_size = len(train_data_names)
       ## try load last checkpoint
       #if not self.LoadMostRecentModel():
       # os.makedirs(CNNClassifier.s_check_point_path, exist_ok = True)
       # train
       self.__model__.fit(CNNClassifier.func_generator(train_data_names),
                           use_multiprocessing = False,
                           \#batch\_size = 1000,
                           steps_per_epoch = train_size / 20,
                           epochs = 2,
                           #callbacks = [self. save check point callback ],
                           verbose = 1)
   # this should accept a 64 * m * n numpy array as query data, and returns \Box
\rightarrow the fen notation of the board.
   def Predict(self, query_data):
       grids = CNNClassifier.PreprocessImage(query_data)
       y_pred = self.__model__.predict(grids).argmax(axis=1)
       return y_pred
   # predict by file name:
   def PredictMultiple(self, file_names):
       preds = []
       truth = []
       for f in file_names:
```

```
img = ReadImage(f, gray = False)
           y_pred = LabelArrayToL(self.Predict(img))
           y_true = FENtoL(GetCleanNameByPath(f))
           preds.append(y_pred)
           truth.append(y_true)
       all_pred = np.vstack(preds)
       all_truth = np.vstack(truth)
       return all_pred, all_truth
  def LoadModel(self, name):
       self.__model__.load_weights(name)
  def SaveModel(self, name):
       os.makedirs(os.path.dirname(name), exist_ok = True)
       self.__model__.save_weights(name)
  def PrintModel(self):
       self.__model__.summary()
  def LoadMostRecentModel(self):
       return \ self. Load Most Recent Model From Directory (CNNClassifier. \\
→s_check_point_path)
  def LoadMostRecentModelFromDirectory(self, path):
           last_cp = tf.train.latest_checkpoint(path)
           self.__model__.load_weights(last_cp)
           print("Loaded checkpoint from " + last_cp)
           return True
       except:
           print("No checkpoint is loaded.")
           return False
  def TestAccuracy(self, test_file_names):
       num_files = len(test_file_names)
       predict_result = self.__model__.predict(CNNClassifier.

¬func_generator(test_file_names)).argmax(axis=1)
       predict_result = predict_result.reshape(num_files, -1)
       predicted_fen_arr = np.array([LtoFEN(LabelArrayToL(labels)) for labels_
→in predict_result])
       test_fens = np.array([GetCleanNameByPath(file_name) for file_name in_
→test_file_names])
```

```
final_accuracy = (predicted_fen_arr == test_fens).astype(np.float).

>mean()
    return final_accuracy

@staticmethod
    def PreprocessImage(image):
        image = transform.resize(image, (g_down_sampled_size,_u)

>g_down_sampled_size), mode='constant')

# 1st and 2nd dim is 8
        grids = ImageToGrids(image, g_down_sampled_grid_size,_u)

>g_down_sampled_grid_size)

# debug
    #plt.imshow(grids[0][3])
    #plt.show()

return grids.reshape(g_grid_row * g_grid_col, g_down_sampled_grid_size,_u)

-g_down_sampled_grid_size, 3)
```

test code for CNN

```
[12]: if not load_saved_model:
          cnn = CNNClassifier()
          train_names = GetFileNamesInDir(g_train_dir)
          cnn.Train(train_names)
          cnn.SaveModel(cnn_model_file)
      else:
          cnn = CNNClassifier()
          cnn.PrintModel()
          print("cnn: loading model from " + cnn_model_file)
          cnn.LoadModel(cnn_model_file)
          predicted_label = cnn.Predict(ReadImage(a_random_file))
          L = predicted_label
          FEN = LtoFEN(LabelArrayToL(L))
          print("predicted: " + FEN)
          print("Original: " + GetCleanNameByPath(a_random_file))
          #test_file_names = GetFileNamesInDir(q_test_dir)[:1000]
          #print("CNN: Testing accuracy for {} board images.".
       → format(len(test_file_names)))
          #accuracy = cnn.TestAccuracy(test file names)
          #print("CNN: Final accuracy: {}".format(accuracy))
          y_pred, y_true = cnn.PredictMultiple(GetFileNamesInDir(g_test_dir))
```

```
conf_mat = confusion_matrix(y_true.reshape((-1, 1)), y_pred.reshape((-1, 

→1)), labels = g_labels)

print("confusion matrix:\n", conf_mat)

print("Balanced accuracy: ", BalancedAccuracyFromConfusionMatrix(conf_mat))
```

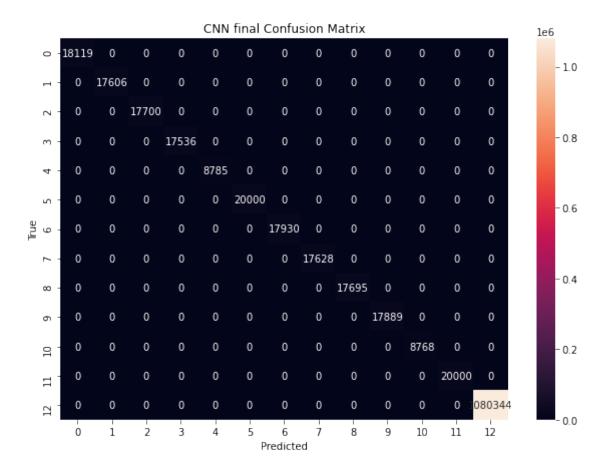
Model: "sequential"

Layer	(type)		Outpu	t Sh	 ape			 Param #	
conv2	2d (Conv2	2D)	(None	, 23	, 23,	32)		896	
activ	vation (A	ctivation)	(None	, 23	, 23,	32)		0	
dropo	out (Drop	oout)	(None	, 23	, 23,	32)		0	
conv2	2d_1 (Cor	 1v2D)	(None	, 21	, 21,	32)		9248	
activ	vation_1	(Activation	n) (None	, 21	, 21,	32)		0	
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Balanced accuracy: 1.0

```
[13]: import seaborn as sns
  def plot_confusion_mat(conf_mat, title = ""):
      plt.figure(figsize=(10,7))
      ax = sns.heatmap(conf_mat, annot=True, fmt="d")
      plt.ylabel('True')
      plt.xlabel('Predicted')
      plt.title(title)
      plt.show()
plot_confusion_mat(conf_mat, title = "CNN final Confusion Matrix")
```



1.6 10-fold cross validation for 3 classifiers

```
[15]: if test_CNN_ten_fold:
    # dump the matrices for report.
```

```
os.makedirs(os.path.dirname(ten_fold_result_path), exist_ok = True)

np.save(ten_fold_result_path + "confusion_matrices_cnn.npy",__

confusion_matrices_cnn)

np.save(ten_fold_result_path + "accuracies_cnn.npy", accuracies_cnn)

np.save(ten_fold_result_path + "accuracies_balanced_cnn.npy",__

caccuracies_balanced_cnn)

np.save(ten_fold_result_path + "train_time_cost_cnn.npy",__

chrain_time_cost_cnn)

np.save(ten_fold_result_path + "validation_time_cost_cnn.npy",__

chrain_time_cost_cnn)

cnn_tf.SaveModel(cnn_model_file)
```

1.6.1 Bonus: GUI: see GUI_with_Classifiers.ipynb

Run Bonus_GUI/GUI_with_classifiers.ipynb