

τετραφάρμακος : Vegetation, atmosphere and flight parameters monitoring

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Abstract

The τετραφάρμακος¹ is a Cansat project of the *Proton-thérapeutes* team for the second participation of the Institut d'Optique Graduate School to the C'Space competition co-organised by Planète-Sciences and the CNES.

This space probe will bring a homemade module to detect chlorophyll. It will also make an atmospheric sounding and position tracking during its fall.

We hope these complementary studies could help to determine the chance of life on an Earth-like exoplanet.

1 Introduction

First of all, we need to precise that a Cansat is not really a satellite contained in a can. Indeed it will only fall instead of enter in any orbit. Then it is actually a space probe.

We are making the τετραφάρμακος in order to participate to the competition a Cansat competition co-organised by Planète-Sciences and the CNES : the C'Space 2012. It has to fulfill 2 missions, one of which is free. For the imposed mission, we decided to do an atmospheric sounding. And our Fourier Optics professor Jean Taboury suggested us to make an NDVI measurement for the free mission.

In addition to these 2 missions, another aspect of our work is to build something consistent. That means a probe that can be contained in 33 cL, enough fast to acquire a lot of informations, electrically autonomous, entirely automatic during the flight and finally resistant to a 200m height fall — using a parachute, of course.

2 Context of development

2.1 Club

The *Proton-thérapeutes* team is composed of 3 first-year MSc students at the Institut d'Optique Graduate School. The first time our school participated to the Cansat competition was in 2011. This project has been initiated by Jean-Marie Feybesse, IT professor at Paris XI. But unfortunately, this team² didn't reach the last step of competition because of logistic issues.

As the previous team, we are 3. This number is too little not to be aware of the work of the whole team. Each member has not a specific work. Nevertheless some leadings have emerged, then we can describe the team as the following list:

- Clément: mechanic and electronic chips designer
- Denis: electronics and cameras implementation
- Zubair: sensors implementation and parachute design

2.2 Work plan

3 Definition of the missions

3.1 Proposed mission : Atmospheric sounding

We chose to measure the temperature, the humidity and the pressure during the fall of our cansat thanks to two electronic captors : the BMP085 that measures the temperature and the pressure, and the DHT22 that measures the temperature and the humidity. Measurements are made every two seconds, which is the refreshment rate of the used captors, and the requirement of the mission.

3.2 Free mission : chlorophyll detection

In this mission, we detect active chlorophyll by multispectral imagery.

Chlorophyll spectrum Chlorophyll absorbs much red, and emits in near infrared.

So we use this by taking two pictures of the same scene, one in a red spectral band, the other in a near infrared spectral band. We then calculate the Normalized Difference Vegetation Index (NDVI) with this formula :

$$NDVI = \frac{RED - NIR}{RED + NIR}$$

Detection system The images in red and in NIR bands are taken by two CCD. In order to detect red on one CCD, and NIR on the other, we use a cold mirror and filters. The hot mirror transmits most of visible light, and reflects most of infrared. Just like the chlorophyll its reflection and transmission spectrum cuts around 700nm. Just before the CCD, we put filters more selective filters.

¹prononcez tetrapharmakos

²Archimede, leaded by Sébastien Guidicelli

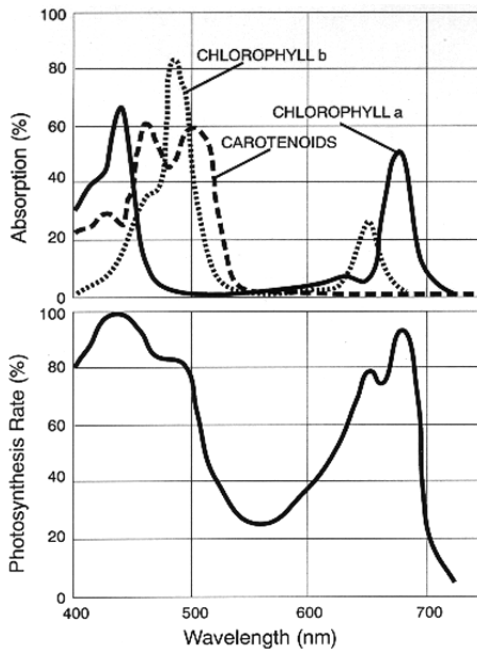


Figure 1: Absorption and fluorescence specrums of chlorophyll

The use of the hot mirror allows to keep a better part of the flux for both bands than a simple beam splitter, and allows to cut infrared for the red detector. Before the hot mirror, we use a camera lens to form the image on both CCD, for instance we used a simple lens.

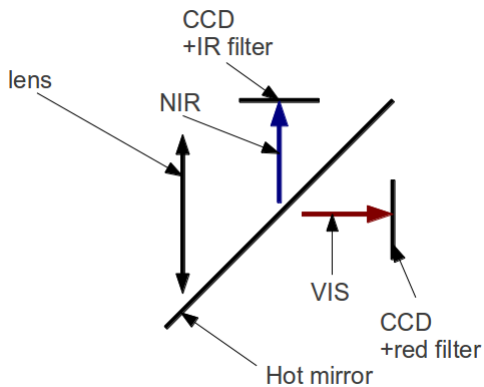


Figure 2: Schematic of the imagery system

3.3 Additionnal measurements

We also track the position and the speed of the cansat thank to an accelerometer and a GPS. It will be useful to fit pressure measurments with a model.



Figure 3: Photograph of the assembled imagery system

4 Cansat architecture

4.1 Electrical architecture

4.2 Mecanical parts

4.3 Telemetry

4.4 Flight algorithm

5 Conclusion

Acknowledment

References