FYS3120 Home Exam

Kandidatnr: 15129

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1 Question 1)

a)

We are looking at a free particle. The easiest coordinate system to use is Cartesian coordinates. The general Lagrangian is given as

$$L = K - V \tag{1}$$

Where K is the kinetic energy and V is the potential energy. The free particle is moving without any potential, so $V = 0$. The kinetic energy in Cartesian coordinates is given as $K = \frac{1}{2}mv^2$. So the Lagrangian of the free particle is thus

$$L = K = \frac{1}{2}mv^2 = \frac{1}{2}m(\dot{x}^2 + \dot{y}^2 + \dot{z}^2) \tag{2}$$

b)

The canonical momentum is defined as

$$p_{c,i} = \frac{\partial L}{\partial \dot{q}_i} = \frac{\partial L}{\partial v_i} \tag{3}$$

If we use out Lagrangian (2) we get that the canonical momentum is

$$\mathbf{p} = m\mathbf{v} \tag{4}$$

Normal, mechanical is given as $\mathbf{p} = m\mathbf{v}$, and as we see from (4):

$$\mathbf{p} = \mathbf{p}_c$$

c)

If we look at the Lagrangian (2) we see that is has no explicit dependence on x, y or z (position)

$$\frac{\partial L}{\partial x} = \frac{\partial L}{\partial y} = \frac{\partial L}{\partial z} = 0$$

This means that these are cyclic coordinates.

d)

We know that there exist constants of motion due to the cyclic coordinates. We can quickly find the first three constants of motions by inserting our Lagrangian in to Lagrange's equation:

$$\frac{d}{dt}\frac{\partial L}{\partial v_i} - \frac{\partial L}{\partial r_i} = \frac{d}{dt}\frac{\partial L}{\partial v_i} = \frac{d}{dt}mv_i = 0 \tag{5}$$

We can see that we have a total time derivative that is zero. This means that the quantity we are differentiating is constant:

$$\frac{d}{dt}mv_i = 0 \Rightarrow mv_i = \text{constant} = c \tag{6}$$

This is the momentum, thus all the components of the momentum is conserved. This gives us the three first constants of motion.

We can find the three other conserved quantities by rewriting the Lagrangian (2) in spherical coordinates:

$$L = \frac{1}{2}m(\dot{r}^2 + r^2\dot{\theta}^2 + r^2\sin^2\theta\dot{\phi}^2) \tag{7}$$

We immediately see that ϕ is a cyclic coordinate. The corresponding constant of motion l is the z-component of the angular momentum. But we are interested in getting showing that all the components of the angular momentum are constants of motion. We are going to do this by doing a infinitesimal rotation around some axis α:

$$\mathbf{r} \to \mathbf{r}' = \mathbf{r} + \delta\mathbf{r} = \mathbf{r} + \delta\alpha \times \mathbf{r}$$

Such an infinitesimal rotation leaves the the Lagrangian invariant (shown in the appendix 4.1). We can now find the conserved quantity

$$\delta K = \sum_i \frac{\partial L}{\partial \dot{r}_i}\delta r_i = \sum_i mv_i\delta r_i = m\mathbf{v}\cdot\delta\mathbf{r}$$

$$= m\mathbf{v}\cdot(\delta\alpha \times \mathbf{r}) = m(\mathbf{r}\times\mathbf{v})\cdot\delta\alpha = (\mathbf{r}\times\mathbf{p})\cdot\delta\alpha = \mathbf{L}\cdot\delta\alpha$$

Since α is arbitrary this means that $\mathbf{L}$, the angular momentum, is the conserved.

This gives us the six constants of motion: the three components of the momentum, and the three components of the angular momentum.

There is a seventh constant of motion, which comes from the Lagrangian's independence of time. This means that

$$\frac{\partial L}{\partial t} = -\frac{dH}{dt} = 0$$

Where $H = K + V$ is the Hamiltonian, and is in our system the same as the energy. This means that energy is a constant of motion.

e)

We can now start to look at a relativistic free particle. We are going to choose the Lagrangian

$$L = \frac{1}{2}mU^\mu U_\mu \tag{8}$$

Where U^μ is the components of the four-velocity.

We can show that this is Lorentz invariant. First, mass, m is a Lorentz invariant quantity. Secondly, $U^\mu U_\mu$ is a inner product, and inner products are always invariant. This means that the whole expression only consists of invariant quantities, meaning that the expression itself, the Lagrangian, is invariant.

f)

To find the constants of motion we again look at Lagrange's equations:

$$L = \frac{d}{d\tau}\frac{\partial L}{\partial U^\mu} - \frac{\partial L}{\partial x^\mu} = 0$$

Since out Lagrangian isn't dependent of x^μ, and we have a total time derivative, we get that

$$\frac{\partial L}{\partial U^\mu} = \text{constant} \tag{9}$$

So we have to find $\frac{\partial L}{\partial U^\mu} = \frac{1}{2} m \frac{\partial}{\partial U^\mu} U^\mu U_\mu$:

$$\frac{\partial}{\partial U^\mu} U^\mu U_\mu = \frac{\partial}{\partial U^\mu} U^\mu g_{\mu\nu} U\nu = g_{\mu\nu} \frac{\partial}{\partial U^\mu} U^\mu U\nu$$

We then use the product rule:

$$= g_{\mu\nu} \left(1 \cdot U^\nu + U^\mu \delta_\mu{}^\nu\right) = g_{\mu\nu} \left(U^\nu + U^\nu\right) = 2 g_{\mu\nu} U^\nu$$

And lastly we apply the metric tensor and get that

$$\frac{\partial}{\partial U^\mu} U^\mu U_\mu = 2 U_\mu$$

And we find that

$$\frac{\partial L}{\partial U^\mu} = m U_\mu = \text{constant} \tag{10}$$

This means that $P_\mu = m U_\mu$ is a constant of motion. This means that the three components of the relativistic momentum and the energy are constants of motion.

g)

We are looking at the small Lorentz transformation

$$L^\mu{}_\nu = \delta^\mu{}_\nu + \omega^\mu{}_\nu \tag{11}$$

We are going to use this on something we now are invariant, namely the inner product $x^\mu x_\mu$. To do this we'll have to use that

$$L_\mu{}^\nu = \delta_\mu{}^\nu + \omega_\mu{}^\nu$$

We then find:

$$x^\mu x_\mu = x'^\mu x'_\mu = (L^\mu{}_\nu x^\nu)(L_\mu{}^\rho x_\rho) = (\delta^\mu{}_\nu x^\nu + \omega^\mu{}_\nu x^\nu)(\delta_\mu{}^\rho x_\rho + \omega_\mu{}^\rho x_\rho)$$

Now we distribute the parenthesis, and use that

$$\delta^\mu{}_\nu x^\nu = x^\mu, \qquad \delta_\mu{}^\rho x_\rho = x_\mu$$

And get

$$= x^\mu x_\mu + \omega^\mu{}_\nu x^\nu x_\mu + x^\mu \omega_\mu{}^\rho x_\rho + \omega^\mu{}_\nu x^\nu \omega_\mu{}^\rho x_\rho$$

In the last term $\omega^\mu{}_\nu x^\nu \omega_\mu{}^\rho x_\rho$ we get a higher order of ω, meaning that this term disappears. Leaving us with

$$x^\mu x_\mu = x^\mu x_\mu + \omega^\mu{}_\nu x^\nu x_\mu + x^\mu \omega_\mu{}^\rho x_\rho$$

$$\Rightarrow \omega^\mu{}_\nu x^\nu x_\mu + x^\mu \omega_\mu{}^\rho x_\rho = 0$$

If we rename the index $\rho \to \nu$ we see

$$\Rightarrow \omega^\mu{}_\nu x^\nu x_\mu = -x^\mu \omega_\mu{}^\nu x_\nu$$

$$\Rightarrow \omega^\mu{}_\nu x^\nu x_\mu = -\omega_\mu{}^\nu x^\mu x_\nu$$

If we on the LHS let $\mu \to \nu$ and $\nu \to \mu$ we get

$$\Rightarrow \omega^{\mu}{}_{\nu}x^{\nu}x_{\mu} = -\omega_{\nu}{}^{\mu}x^{\nu}x_{\mu}$$

With gives us that

$$\omega^{\mu}{}_{\nu} = -\omega_{\nu}{}^{\mu} \tag{12}$$

And we have thus showed that $\omega^{\mu}{}_{\nu}$ is anti-symmetric.

h)

We have the small Lorentz transformation given as

$$\delta x^{\mu}(\tau) = \omega^{\mu}{}_{\nu}x^{\nu}(\tau) \tag{13}$$

We are going to look at the corresponding change in the Lagrangian δL. We are going to start with the definition

$$\delta L = \frac{\partial L}{\partial x^{\mu}}\delta x^{\mu} + \frac{\partial L}{\partial U^{\mu}}\delta U^{\mu}$$

We know how to express δx^{μ}, but we have to find δU^{μ}. We can do this by making the small Lorentz transformation:

$$\delta U^{\mu} = U'^{\mu} - U^{\mu} = L^{\mu}{}_{\nu}U^{\nu} - U^{\mu}$$

$$= (\delta^{\mu}{}_{\nu} + \omega^{\mu}{}_{\nu})U^{\nu} - U^{\mu} = \delta^{\mu}{}_{\nu}U^{\nu} + \omega^{\mu}{}_{\nu}U^{\nu} - U^{\mu}$$

$$= U^{\mu} + \omega^{\mu}{}_{\nu}U^{\nu} - U^{\mu} = \omega^{\mu}{}_{\nu}U^{\nu}$$

We then get that:

$$\delta L = \frac{\partial L}{\partial x^{\mu}}\delta x^{\mu} + \frac{\partial L}{\partial U^{\mu}}\delta U^{\mu} = \frac{\partial L}{\partial x^{\mu}}\omega^{\mu}{}_{\nu}x^{\nu} + \frac{\partial L}{\partial U^{\mu}}\omega^{\mu}{}_{\nu}U^{\nu}$$

$$\delta L = \left(\frac{\partial L}{\partial x^{\mu}}x^{\nu} + \frac{\partial L}{\partial U^{\mu}}U^{\nu}\right)\omega^{\mu}{}_{\nu} \tag{14}$$

i)

We are going to look closer at the small change in the Lagrangian. We note that $\omega^{\mu}{}_{\nu}$ is antisymmetric and can be written as

$$\omega^{\mu}{}_{\nu} = \frac{1}{2}(\omega^{\mu}{}_{\nu} - \omega_{\nu}{}^{\mu})$$

We can use this in (14) to get

$$\delta L = \frac{1}{2}(\omega^{\mu}{}_{\nu} - \omega_{\nu}{}^{\mu})\left(\frac{\partial L}{\partial x^{\mu}}x^{\nu} + \frac{\partial L}{\partial U^{\mu}}U^{\nu}\right)$$

We are then going to use Lagrange's equation:

$$\frac{\partial L}{\partial x^{\mu}} = \frac{d}{d\tau}\frac{\partial L}{\partial U^{\mu}}$$

which gives us

$$\delta L = \frac{1}{2}(\omega^{\mu}{}_{\nu} - \omega_{\nu}{}^{\mu})\left(x^{\nu}\frac{d}{d\tau}\frac{\partial L}{\partial U^{\mu}} + \frac{\partial L}{\partial U^{\mu}}U^{\nu}\right)$$

If we look at $x^{\nu}\frac{d}{d\tau}\frac{\partial L}{\partial U^{\mu}}$ we see that we can use the product rule backwards and get:

$$x^\nu \frac{d}{d\tau}\frac{\partial L}{\partial U^\mu} = \frac{d}{d\tau}\left(\frac{\partial L}{\partial U^\mu}x^\nu\right) - \frac{\partial L}{\partial U^\mu}\frac{d}{d\tau}x^\nu$$

$$= \frac{d}{d\tau}\left(\frac{\partial L}{\partial U^\mu}x^\nu\right) - \frac{\partial L}{\partial U^\mu}U^\nu$$

Using this we get:

$$\delta L = \frac{1}{2}(\omega^\mu{}_\nu - \omega_\nu{}^\mu)\left(\frac{d}{d\tau}\left(\frac{\partial L}{\partial U^\mu}x^\nu\right) - \frac{\partial L}{\partial U^\mu}U^\nu + \frac{\partial L}{\partial U^\mu}U^\nu\right)$$

$$= \frac{1}{2}(\omega^\mu{}_\nu - \omega_\nu{}^\mu)\left(\frac{d}{d\tau}\left(\frac{\partial L}{\partial U^\mu}x^\nu\right)\right)$$

Now we want to lower the indices of ω with the metric tensor:

$$\delta L = \frac{1}{2}(g^{\mu\rho}\omega_{\rho\nu} - \omega_{\nu\sigma}g^{\sigma\mu})\left(\frac{d}{d\tau}\left(\frac{\partial L}{\partial U^\mu}x^\nu\right)\right)$$

$$= \frac{1}{2}\left(g^{\mu\rho}\omega_{\rho\nu}\frac{d}{d\tau}\left(\frac{\partial L}{\partial U^\mu}x^\nu\right) - \omega_{\nu\sigma}g^{\sigma\mu}\frac{d}{d\tau}\left(\frac{\partial L}{\partial U^\mu}x^\nu\right)\right)$$

We can now apply the metric tensor to the differentiation

$$= \frac{1}{2}\left(\omega_{\rho\nu}\frac{d}{d\tau}\left(\frac{\partial L}{\partial U_\rho}x^\nu\right) - \omega_{\nu\sigma}\frac{d}{d\tau}\left(\frac{\partial L}{\partial U_\sigma}x^\nu\right)\right)$$

Each term is it's own sum, meaning that we can change the summation indices. On the left term we are going to let $\nu \to \mu$ and $\rho \to \nu$, and on the right term we are going to let $\sigma \to \mu$:

$$= \frac{1}{2}\left(\omega_{\nu\mu}\frac{d}{d\tau}\left(\frac{\partial L}{\partial U_\nu}x^\mu\right) - \omega_{\nu\mu}\frac{d}{d\tau}\left(\frac{\partial L}{\partial U_\mu}x^\nu\right)\right)$$

We can now pull out the ω and the $\frac{d}{d\tau}$ we get the final expression:

$$\delta L = \frac{1}{2}\omega_{\nu\mu}\frac{d}{d\tau}\left(x^\mu\frac{\partial L}{\partial U_\nu} - x^\nu\frac{\partial L}{\partial U_\mu}\right) \tag{15}$$

j)

We want that the changes small in the Lorentz transformation leaves the Lagrangian unchanged. This means that we want

$$\delta L = 0$$

This gives us that

$$\frac{1}{2}\omega_{\nu\mu}\frac{d}{d\tau}\left(x^\mu\frac{\partial L}{\partial U_\nu} - x^\nu\frac{\partial L}{\partial U_\mu}\right) = 0$$

We want this to be true for all small changes $\omega^\mu{}_\nu$ which means that the $d/d\tau$-term has to be zero:

$$\frac{d}{d\tau}\left(x^\mu\frac{\partial L}{\partial U_\nu} - x^\nu\frac{\partial L}{\partial U_\mu}\right) = 0$$

Which implies

$$x^\mu\frac{\partial L}{\partial U_\nu} - x^\nu\frac{\partial L}{\partial U_\mu} = \text{constant}^{\mu\nu} \tag{16}$$

So this is the constant of motion. But what is this quantity? From definition of the relativistic Lagrangian (8) we see that

$$\frac{\partial L}{\partial U_\nu} = mU^\nu, \qquad \frac{\partial L}{\partial U_\mu} = mU^\mu$$

So the constant of motion is

$$x^\mu mU^\nu - x^\nu mU^\nu = l^{\mu\nu} \tag{17}$$

We recognize this as the four-angular momentum as the constant of motion.
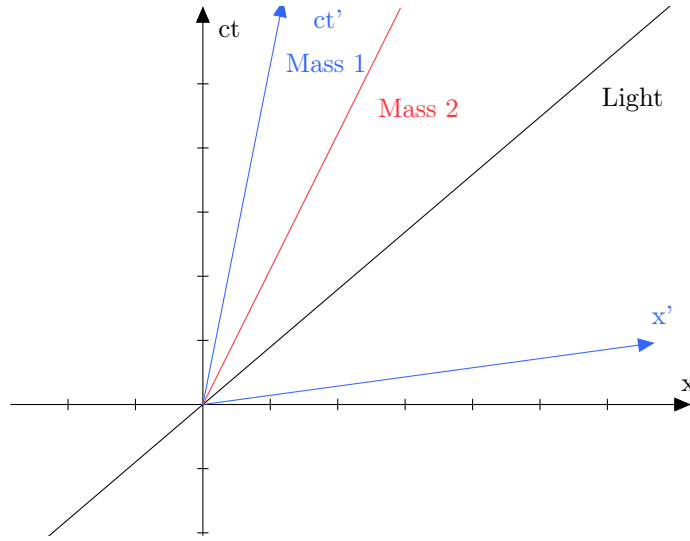
2 Question 2)

Figur 1: Figure showing the Minkowski-diagram for the two massive particles and the light. The world line of the light is at $45°$ to both axes. The axes of the system S' is marked as ct' and x, and is the rest fram of the slower particle with 'Mass 1'.

The rapidity χ is defines as

$$\beta = \tanh\chi \tag{18}$$

We are going to show that the difference in rapidity of the two particles are the same in the two reference systems. In S the difference is simply

$$\chi_2 - \chi_1$$

In S' we have that $\chi_1' = 0$ since we are in the rest frame of particle 1, so the difference is simply χ_2'. So we have to show that

$$\chi_2 - \chi_1 = \chi_2' \tag{19}$$

We get χ_1 and χ_2 straight from (18)

$$\chi_1 = \text{artanh}\left(\frac{v_1}{c}\right), \qquad \chi_2 = \text{artanh}\left(\frac{v_2}{c}\right) \tag{20}$$

χ_2' is a bit more difficult, since we have to find velocity of particle 2 in S'. We have to use the velocity-addition formula:

$$v_2' = \frac{v_2 - v_1}{1 - \frac{v_1 v_2}{c^2}} \tag{21}$$

And we find that

$$\chi_2' = \operatorname{artanh}\left(\frac{v_2/c - v_1/c}{1 - \frac{v_1 v_2}{c^2}}\right) \tag{22}$$

We can now start to unravel (19). We have to use one important identity, namely that

$$\operatorname{artanh} z = \frac{1}{2}\ln\frac{1+z}{1-z} \tag{23}$$

You will find a proof of this identity in the appendix 4.2.

We are now going to start with the RHS.

$$\chi_2 - \chi_1 = \operatorname{artanh}\left(\frac{v_2}{c}\right) - \operatorname{artanh}\left(\frac{v_1}{c}\right)$$

$$= \frac{1}{2}\ln\frac{1+\frac{v_2}{c}}{1-\frac{v_2}{c}} - \frac{1}{2}\ln\frac{1+\frac{v_1}{c}}{1-\frac{v_1}{c}} = \frac{1}{2}\ln\frac{(1+\frac{v_2}{c})(1-\frac{v_1}{c})}{(1-\frac{v_2}{c})(1+\frac{v_1}{c})}$$

$$\chi_2 - \chi_1 = \frac{1}{2}\ln\frac{1+\frac{v_2}{c}-\frac{v_1}{c}-\frac{v_1 v_2}{c^2}}{1-\frac{v_2}{c}+\frac{v_1}{c}-\frac{v_1 v_2}{v^2}} \tag{24}$$

We can now look at χ_2:

$$\chi_2' = \operatorname{artanh}\left(\frac{v_2/c - v_1/c}{1 - \frac{v_1 v_2}{c^2}}\right)$$

$$= \frac{1}{2}\ln\frac{1+\frac{v_2/c-v_1/c}{1-\frac{v_1 v_2}{c^2}}}{1-\frac{v_2/c-v_1/c}{1-\frac{v_1 v_2}{c^2}}}$$

We then pull out $\frac{1}{1-\frac{v_1 v_2}{c^2}}$ from the numerator and denominator, and get that

$$\chi_2' = \frac{1}{2}\ln\frac{1-\frac{v_1 v_2}{c^2}+\frac{v_2}{c}-\frac{v_1}{c}}{1-\frac{v_1 v_2}{c^2}-\frac{v_2}{c}+\frac{v_1}{c}} \tag{25}$$

We see that (24) and (25) are equivalent, and we have thus showed that

$$\chi_2 - \chi_1 = \chi_2'$$

Meaning that the difference in rapidity is the same in both reference systems.

3   Question 3)

We are going to find the shortest path between two points on a sphere. A length of a path is defined as

$$S = \int ds \tag{26}$$

Where ds is the line element. We are going to use the normal 'physicist' definitions of spherical coordinates, where θ is the angle from the z-axis, and ϕ is the angle in the xy-plane. The line element is in these coordinates defined as

$$ds = \sqrt{dr^2 + r^2 d\theta^2 + r^2\sin^2(\theta)d\phi^2}$$

We want find the path on the surface of the sphere, which means that $dr = 0$, so

$$ds = \sqrt{dr^2 + r^2 d\theta^2 + r^2 \sin^2(\theta) d\phi^2} \tag{27}$$

We then get the path

$$S = \int \sqrt{r^2 d\theta^2 + r^2 \sin^2(\theta) d\phi^2}$$

We want a function $\phi(\theta)$ so pull $d\theta$ out of the square root and make in the integration variable. We also pull out r, and get

$$S = r \int_{\theta_1}^{\theta_2} \sqrt{1 + \sin^2(\theta) \left(\frac{d\phi}{d\theta}\right)^2} \, d\theta \tag{28}$$

This is a calculus of variation problem, so to find the shortest path we use Euler-Lagrange's equation:

$$\frac{d}{d\theta} \frac{\partial L}{\partial \phi'} - \frac{\partial L}{\partial \phi} = 0 \tag{29}$$

Where

$$L = \sqrt{1 + \sin^2(\theta)\phi'^2} \tag{30}$$

With $\phi = \frac{d\phi}{d\theta}$. We immediately see that L has no explicit dependence on ϕ meaning that (29) reduces to

$$\frac{d}{d\theta} \frac{\partial L}{\partial \phi'} = 0$$

Meaning that

$$\frac{\partial L}{\partial \phi'} = c = \text{constant} \tag{31}$$

If we differentiate L we find that

$$\frac{\sin^2(\theta)\phi'}{\sqrt{1 + \sin^2(\theta)\phi'^2}} = c \tag{32}$$

We then have to do some algebra to isolate ϕ'. We start squaring the expression and moving the denominator to the other side

$$\Rightarrow \sin^4(\theta)\phi'^2 = c^2(1 + \sin^2(\theta)\phi'^2)$$

And we then see that

$$\phi'^2 = \frac{c^2}{\sin^4(\theta) - c^2 \sin^2(\theta)}$$

And thus we get

$$\phi' = \frac{c}{\sin(\theta)\sqrt{\sin^2(\theta) - c^2}} \tag{33}$$

So to find $\phi(\theta)$ we have to solve this differential equation. We take the integral of both sides:

$$\phi_2 - \phi_1 = \int_{\theta_1}^{\theta_2} \frac{c}{\sin(\theta)\sqrt{\sin^2(\theta) - c^2}} d\theta \tag{34}$$

8

This is a difficult integral to solve, I have done it in the appendix 4.3, but here I am just going to give the answer

$$\phi_2 - \phi_1 = \arccos\left(\frac{c}{\sqrt{1-c^2}}\cot\theta_2\right) - \arccos\left(\frac{c}{\sqrt{1-c^2}}\cot\theta_1\right) \tag{35}$$

We are starting in the point $(r, \theta_1, \phi_1) = (r, \frac{\pi}{2}, 0)$. If we insert this into (35) we get that the parametrization of $\phi(\theta)$

$$\phi_2 = \phi(\theta) = \arccos\left(\frac{c}{\sqrt{1-c^2}}\cot\theta\right) - \frac{\pi}{2} \tag{36}$$

Given a point (r, θ_2, ϕ_2) we can insert these values into (36) and get the value for c. And with c determined (36) gives a parameterization for the curve of the shortest path between the two points.

With constant $\phi = 0$ or $\theta = \frac{\pi}{2}$ this parameterization beaks down. For example if we have constant $\theta = \frac{\pi}{2}$ equation (36) gives us a constant ϕ for every end point (r, θ_2, ϕ_2) we have chosen. This means that for every end point on the equator the parameterization is unable to move from the starting point. But for simplicity we are going to ignore these solutions, and take (36) to be the final solution of the problem.

4   Appendix

4.1   Invariance under infinitesimal rotation

We can show that this rotation leaves the Lagrangian invariant by seeing that

$$\mathbf{r}^2 = r^2 \rightarrow (\mathbf{r} + \delta\alpha \times \mathbf{r})^2 \approx \mathbf{r}^2 + 2\mathbf{r}\cdot(\delta\alpha \times \mathbf{r}) = \mathbf{r}^2$$

and

$$\dot{\mathbf{r}}^2 \rightarrow \dot{\mathbf{r}}'^2 = (\dot{\mathbf{r}} + \delta\alpha \times \dot{\mathbf{r}})^2 \approx \dot{\mathbf{r}}^2 + 2\dot{\mathbf{r}}\cdot(\delta\alpha \times \dot{\mathbf{r}}) = \dot{\mathbf{r}}^2$$

Thus leaving the Lagrangian invariant.

4.2   Proof of artanh-identity

To show that

$$\mathrm{artanh}(z) = \frac{1}{2}\ln\frac{1+z}{1-z}$$

We are going to start with

$$w = \tanh z = \frac{\sinh z}{\cosh z} = \frac{e^z - e^{-z}}{e^z + e^{-z}}$$

We can then multiply the fraction by e^z

$$w = \frac{e^{2z} - 1}{e^{2z} + 1}$$

$$e^{2z}(w - 1) = -1 - w$$

$$e^{2z} = \frac{1+w}{1-w}$$

If we then take the logarithm of both sides and divide by 2, we get

$$z = \frac{1}{2}\ln\frac{1+w}{1-w}$$

Since $\tanh(z) = w$ gives us that $z = \tanh^{-1}(w)$, we can see that

$$\operatorname{artanh}(z) = \frac{1}{2}\ln\frac{1+z}{1-z}$$

4.3   Solving the integral from 3)

This solution was heavily inspired/taken from [1].

We are going to solve

$$\int \frac{c}{\sin(\theta)\sqrt{\sin^2(\theta) - c^2}}d\theta$$

We start by pulling out one more $\sin\theta$

$$\int \frac{c}{\sin^2(\theta)\sqrt{1 - \frac{c^2}{\sin^2(\theta)}}}d\theta$$

We now use that

$$\frac{1}{\sin^2(\theta)} = \csc^2(\theta) = 1 + \cot^2(\theta)$$

We then get

$$\int \frac{c \cdot \csc^2(\theta)}{\sqrt{1 - c^2 - c^2\cot^2(\theta)}}d\theta$$

We are now going to use the

$$u = \frac{c}{\sqrt{1-c^2}}\cot(\theta) \Leftrightarrow c^2\cot^2(\theta) = u^2(1-c^2)$$

and

$$du = -\frac{c}{\sqrt{1-c^2}}\csc^2(\theta)d\theta \Leftrightarrow \csc^2(\theta)d\theta = -\frac{\sqrt{1-c^2}}{c}du$$

This gives us

$$-\int \frac{\sqrt{1-c^2}}{c}\frac{c}{\sqrt{1 - c^2 - u^2(1-c^2)}}du$$

$$= -\int \sqrt{1-c^2}\frac{1}{\sqrt{1-c^2}\sqrt{1-u^2}}du$$

$$= -\int \frac{1}{\sqrt{1-u^2}}du$$

This is an integral we recognize as $\arccos(u)$. So we have finally solved the integral and we got

$$\int \frac{c}{\sin(\theta)\sqrt{\sin^2(\theta) - c^2}}d\theta = \arccos(u) = \arccos\left(\frac{c}{\sqrt{1-c^2}\cot(\theta)}\right) \qquad (37)$$

Referanser

[1] Sphere geodesic problem. http://http://campus.mst.edu/physics/courses/409/Problem-Solutions/HW%235/HW5_prob1_sphere_geodesic.pdf, Read: 28.03.17.