# 1 Kompleks analyse:

# 1.1 Komplekse tall:

$$z = x + iy,$$
  $\bar{z} = x - iy,$   $z = r(\cos\theta + i\sin\theta) = re^{i\theta}$  (1)

r = |z| er modulus,  $\theta$  er argumentet.

$$z + \bar{z} = 2Re(z)$$
  $z - \bar{z} = 2Im(z)$ ,  $z\bar{z} = |z|^2 = r^2 = x^2 + y^2$  (2)

$$x = \frac{1}{2}(z + \bar{z}), \qquad y = \frac{1}{2i}(z - \bar{z})$$
 (3)

 $|z-z_0| < R$  er alle z innenfor en radius R

# 1.2 Komplekse røtter:

$$z^{1/n} = \sqrt[n]{r}e^{i\theta/n} = \sqrt[n]{r}(\cos\theta/n + i\sin\theta/n) = \omega_0 \tag{4}$$

Dette gir bare 'the principal root', resten er gitt ved

$$\omega_k = \sqrt[n]{r}e^{i\frac{\theta + 2\pi k}{n}} \tag{5}$$

# 1.3 Analytic functions:

Def: A function is analytic in a region of the complex plane if it has a (unique) derivative at every point in that region.

All analytic functions can be written in terms of z = x + iy alone.

## 1.3.1 Cauchy-Riemann equation:

$$f(z) = u(x,y) + iv(x,y) \tag{6}$$

$$\frac{\partial u}{\partial x} = -\frac{\partial v}{\partial y}, \qquad \frac{\partial v}{\partial x} = \frac{\partial v}{\partial y} \tag{7}$$

If this holds in a region, that f is analytic in this region, and vice versa.

- Regular points: f(z) is analytic
- Singular point/singularities: A point where f(z) is not analytic.
- ullet Isolated singularity: a point where f is not analytic, but is a limit of points where f is analytic.

If f is analytic in some region, it has first order derivatives, then it also has derivatives of all orders in that region.

## 1.3.2 Harmonic Functions:

If f = u + iv is analytic in a region, then u and v are harmonic:

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = 0 \qquad \frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} = 0 \tag{8}$$

If u is harmonic, one can find a v such that f = u + iv is analytic. v is the harmonic conjugate of u.

# 1.4 Contour integrals:

$$\int_{\Gamma} f(z)dz = \lim_{z \to \infty} \sum_{k=1}^{\infty} f(c_k) \Delta z_k$$
(9)

For a generalized curve with parametrization z(t):

$$\int_{\gamma} f(t)dz = \int_{a}^{b} f(z(t))z'(t)dt \tag{10}$$

## 1.4.1 An important integral:

 $C - r = |z - z_0| = r$ :

$$I = \int_{C_r} (z - z_0)^n dz = \begin{cases} 0 & n \neq -1\\ 2\pi i & n = -1 \end{cases}$$
 (11)

## 1.4.2 Upper bound estimate:

Generalized triangle inequality:

$$\left| \sum_{k} z_{k} \right| \le \sum_{k} |z_{k}| \tag{12}$$

Applied to Riemann sum we get the upper bound estimate:

$$\left| \int_{\gamma} f(z)dz \right| \le ML \tag{13}$$

Where  $M = \max |f(z)|$  and L is the length of the curve.

# 1.4.3 Path:

If f is continuous everwhere in D, then contour integrals are independent of paths, and any loop integral is zero. One can also deform a contour without crossing any singularities and get that:

$$\int_{\Gamma_1} f(z)dz = \int_{\Gamma_2} f(z)dz \tag{14}$$

## 1.4.4 Cauchy Theorem:

If f is analytic in a simply connected domain D with no singularities, and  $\Gamma$  is any closed contour in D, then

$$\int_{\Gamma} f(z)dz = 0 \tag{15}$$

# 1.4.5 Cauchy's integral formula:

Let  $\Gamma$  be a simple, closed, positively oriented contour. Assume f is analytic in some simply connected domain D containing  $\Gamma$ , and some  $z_0$  is inside  $\Gamma$ . Then:

$$f(z_0) = \frac{1}{2\pi i} \int_{\Gamma} \frac{f(z)}{z - z_0} dz \tag{16}$$

## 1.4.6 Generalized Cauchy integral formula:

$$f^{(n)}(z) = \frac{n!}{2\pi i} \oint_{\Gamma} \frac{f(w)}{(z-w)^{n+1}} dw$$
 (17)

## 1.4.7 Cauchy inequality:

Let f be analytic on and inside a circle  $(C_r)$  of radius R, centered at  $z_0$ . If  $|f(z)| \leq M$  for some z on  $C_r$ , then the derivatives satisfy:

$$|f^{(n)}(z_0)| \le \frac{n!M}{R^n} \tag{18}$$

This gives Liuvilles theorem: A function which is analytic and bounded in the entire complex plane, is constant.

# 1.5 Taylor and Laurent Series:

## 1.5.1 Taylor:

$$f(z) = f(z_0) + f'(z_0)(z - z_0) + \frac{1}{2!}f''(z_0)(z - z_0)^2 + \dots = \sum_{n} \frac{f^{(n)}(z_0)}{n!}(z - z_0)^n$$
 (19)

If f is analytic in the disk  $|z - z_0| < R$  then the above Taylor series converges in that disk.[i.e. the disk touching the nearest singularity]

If f is analytic at  $z_0$ , then the Taylor series for df/dz can be obtained by termwise differentiation.

## 1.5.2 Laurent:

Let f be analytic in the annulus  $r < |z - z_0| < R$ . Then f can be expanded there as the sum of two series:

$$f(z) = \sum_{k=0}^{\infty} a_k (z - z_0)^k + \sum_{k=1}^{\infty} b_k (z - z_0)^{-k}$$
(20)

With

$$a_n = \frac{1}{2\pi i} \oint_{\Gamma} \frac{f(z)}{(z - z_0)^{n+1}} dz \qquad b_n = \frac{1}{2\pi i} \oint_{\Gamma} \frac{f(z)}{(z - z_0)^{-n+1}} dz$$
 (21)

Def: The coefficient  $b_1$  of the  $1/(z-z_0)$  term is the residue of f(z) at  $z=z_0$ .

Laurent series are unique. So to find them we can use

$$\frac{1}{1-\omega} = \sum_{n=0}^{\infty} \omega^2 \text{ , when } |\omega| < 1$$
 (22)

## 1.6 Zeros:

- A zeros of a function is a point where f is analytic and  $f(z_0) = 0$
- A zeros of order m:  $f(z_0) = f'(z_0) = \dots = f^{m-1}(z_0) = 0$ ,  $f^m(z_0) \neq 0$
- Can be factorized as:  $f(z) = (z z_0)^m \cdot g(z)$ , where g(z) is analytic and  $g(z_0) \neq 0$

## 1.7 Isolated singularities:

Let f have a Laurent series, then we can have:

## 1.7.1 Removable Singularity/Regular point:

If all  $b_n = 0$  at  $z_0$ , f(z) has a limit  $z \to z_0$  and we can be redefined such that f is analytic at  $z_0$ .

## 1.7.2 Essential Singularity:

Infinitely many b-terms at  $z_0$ 

## 1.7.3 Pole of order m

Order m is the highest exponent of the  $1/(z-z_0)$  terms.

$$f(z) = \frac{b_m}{(z - z_0)^m} + \dots + \frac{b_1}{z - z_0} + a_0 + a_1(z - z_0) + \dots$$
 (23)

f(z) can be written as  $\frac{g(z)}{(z-z_0)^m}$ . A pole of order 1 (m=1) is a Simple pole.

# 1.8 Residue Theory:

#### 1.8.1 Residue Theorem:

If  $\Gamma$  is a simple, closed, positively oriented contour, and f is analytic on and inside  $\Gamma$  except at the points  $z_0, z_1, ..., z_n$  inside  $\Gamma$ , then

$$\oint_{\Gamma} f(z)dz = 2\pi i \sum_{k=0}^{n} Res(f, z_k)$$
(24)

## 1.8.2 Determining the residues:

1: Read off  $b_1$  from the Laurent series.

2: Simple poles:

$$Res(z_0) = b_1 = \lim_{z \to z_0} (z - z_0) f(z)$$
 (25)

Finite answer only if the pole is of first order.

$$f(z) = \frac{P(z)}{Q(z)} \Rightarrow Res(z_0) = \frac{P(z_0)}{Q'(z_0)}$$

$$\tag{26}$$

3: Multiple poles: If f has a pole of order m at  $z_0$ , then

$$Res(z_0) = \lim_{z \to z_0} \left[ \frac{1}{(m-1)!} \frac{d^{m-1}}{dz^{m-1}} \left( (z - z_0)^m f(z) \right) \right]$$
 (27)

Ok to overshoot with value if m.

# 1.9 Applications to Real Integrals:

# 1.9.1 Type 1:

Rational and finite functions of  $\sin \theta$  and  $\cos \theta$  over the interval  $[0, 2\pi]$ . Use:

- $z = e^{i\theta}$ ,  $d\theta = dz/iz$
- $\cos \theta = \frac{1}{2}(e^{i\theta} + e^{-i\theta}) = \frac{1}{2}(z + 1/z), \quad \sin \theta = \frac{1}{2i}(e^{i\theta} e^{-i\theta}) = \frac{1}{2i}(z 1/z)$
- then use residue theorem.

# 1.9.2 Type 2a

Integrals of rational functions from  $-\infty$  to  $\infty$ 

$$I = \int_{-\infty}^{\infty} \frac{P(x)}{Q(x)} dx \tag{28}$$

- Make a contour  $\gamma_{\rho}$  from  $-\rho$  to  $\rho$
- Add a second contour from  $\rho$  via a the complex plane(half circle in the upper part of the complex plane) back to  $-\rho$ ,  $C_{\rho}$ .
- use the residue theorem. Remember that the singularities have to be in the upper part
- Show that the contribution form  $C_{\rho}$  vanishes as  $\rho \to \infty$

## 1.9.3 Type 2b:

$$I = \int_{-\infty}^{\infty} \frac{P(x)}{Q(x)} \cos(mx) dx, \qquad I = \int_{-\infty}^{\infty} \frac{P(x)}{Q(x)} \sin(mx) dx \tag{29}$$

Alt 1(Always safe):

use  $\cos(mx) = \frac{1}{2}(e^{imx} + e^{-imx})$ 

$$I = \frac{1}{2} \int_{-\infty}^{\infty} \frac{P(x)}{Q(x)} e^{imx} dx + \int_{-\infty}^{\infty} \frac{P(x)}{Q(x)} e^{-imx} dx$$

$$(30)$$

FOr the first term, use a closed contour in the upper part of the complex plane, for the second term use one in the lower half.

Alt 2: safe as long as P/Q is real. Note that  $\cos(mx) = Re(e^{mx})(\text{and }\sin(mx) = Im(e^{mx}))$ . We can therfor use  $\cos(mx) \to e^{imx}$  and then take the real part at the end(or the imaginary if we have  $\sin(mx)$ 

## 1.9.4 Jordan's lemma:

If m > 0 (real) and P/Q is the quotient of two polynomial such that  $deg(Q) \ge deg(P) + 1$ , then

$$\lim_{\rho \to \infty} \int_{C_{\rho}^{+}} \frac{P}{Q} e^{imz} dz = 0 \tag{31}$$

Where  $C_{\rho}^{+}$  is the contour in the upper plane. Same holds for m < 0 but with  $C_{\rho}^{-}$  in the lower plane.

## 1.9.5 Type 3:

Singularities on the real plane. We get Principal Values.

$$PV \int_{a}^{b} f(x)dx = \lim_{r \to 0} \int_{a}^{c-r} f(x)dx + \int_{c+r}^{b} f(x)dx$$
 (32)

Where c is a singularity. If the singularities are simple poles the integral can be calculated with the residue theorem.

$$PV \int_{-\infty}^{\infty} f(x)dx = 2\pi i \sum_{k} Res(z_k) + \pi i \sum_{j} Res(z_j)$$
 (33)

Where  $z_k$  are singularities on the upper half plane, and  $z_i$  are singularities on the real line.

# 2 Tensor:

## 2.1 Cartesian Tensor

Transform properly under rotation of Cartesian coordinate system.

$$e_i' \cdot e_j = \cos \theta_{i'j} \equiv A_{ij} \tag{34}$$

# 2.1.1 Transformation of a position vector

$$\vec{r} = x_i e_i = x_i' e_i' \tag{35}$$

$$x_i' = \vec{r} \cdot e_i' = e_i' \cdot e_j x_j = A_{ij} x_j \tag{36}$$

Reverse:

$$x_i = e_i \cdot \vec{r} = e_i \cdot e'_j x'_j = A'_{ji} x_j = A^T_{ij} x'_j \tag{37}$$

$$A^{-1} = A^T \tag{38}$$

## 2.1.2 Cartesian vector/tensor

$$v' = Av, T'_{kl} = A_{ki}A_{lj}T_{ij} (39)$$

$$\vec{j} = \sigma \vec{E} \text{ Ohm's law}$$
 (40)

## 2.1.3 Inertia Tensor

Rigid body rotation around fixed axis:

$$\vec{L} = I\vec{\omega} \tag{41}$$

Rotation around a point. I is a rank 2 tensor

$$L_i = I_{ij}\omega_j \tag{42}$$

Determined from

$$\vec{L} = \sum_{k} m_k r_k \times (\omega \times r_k) \tag{43}$$

Uniform mass density: sum goes to integral I is symmetric: can find coord. system in which I is diagonal. Eigenvetors (axes of new coord. system): Principal axes of inertia.

# 2.2 Levi-Civita and Kronicker Delta

$$\delta_{ij} = \begin{cases} 1 & i = j \\ 0 \end{cases} \tag{44}$$

$$\epsilon_{ijk} = \begin{cases} 1 & \text{even permutation} \\ -1 & \text{odd permutation} \\ 0 \end{cases} \tag{45}$$

$$\epsilon_{ijk}\epsilon_{imn} = \delta_{jm}\delta_{kn} - \delta_{jn}\delta_{km} \tag{46}$$

Inner product:  $\vec{u} \cdot \vec{c} = u_i v_j \delta_{ij} = u_i u_i$ Cross Product:  $\vec{A} \times \vec{B} = \epsilon_{ijk} A_j B_k$ Curl:  $(\nabla \times \vec{V})_i = \epsilon_{ijk} \frac{\partial}{\partial x_j} V_k$ 

# 3 Calculus of Variation:

Minimize:

$$I = \int_{x_1}^{x_2} F(x, y, y') dx \tag{47}$$

$$\frac{\partial F}{\partial y} - \frac{d}{dx} \left( \frac{\partial F}{\partial y'} \right) = 0 \tag{48}$$

Can simplify Euler-Lagrange by change of variables:

$$x' = \frac{1}{y'}, \qquad dx = x'dy \text{ or } dy = y'dx \tag{49}$$

# 3.1 Optics – Fermat's Principle:

$$P = \int nds, \qquad ds = \sqrt{dx^2 + dy^2} \tag{50}$$

# 4 ODE:

# 4.1 Linear First order DE:

$$y' + P(x)y = Q(x)$$
  $dy + [Py - Q]dx = 0$  (51)

## 4.1.1 Exact DE's

$$du = \frac{\partial u}{\partial x}dx + \frac{\partial u}{\partial y}dy, \qquad M(x,y)dx + N(x,y)dy = 0$$
 (52)

The last DE is called exact if the LHS is a total differential,

$$M = \frac{\partial u}{\partial x}; \qquad N = \frac{\partial u}{\partial y} \tag{53}$$

This gives:

$$du = 0 \Leftrightarrow u = \text{const}$$
 (54)

## 4.1.2 Integrating factor:

$$y(x) = \frac{1}{\mu(x)} \left[ \int \mu(x)Q(x)dx + C \right], \qquad \mu(x) = e^{\int P(x)dx}$$
 (55)

If Q(x) = 0, the homogeneous case:

$$y(x) = \frac{C}{\mu(x)} = Ce^{-\int P(x)dx}$$

$$\tag{56}$$

# 4.2 Ordinary 2nd order DE:

$$y'' + P(x)y' + Q(x)y = R(x), y(x) = y_h + y_p = c_1y_1 + c_2y_2 + y_p (57)$$

If  $y_1$  and  $y_2$  are linearly independent, it must hold that the Wronskian determinant

$$W(x_0) = \begin{vmatrix} y_1(x_0) & y_2(x_0) \\ y'_1(x_0) & y'_2(x_0) \end{vmatrix} \neq 0 \qquad \forall x_0$$
 (58)

# **4.3** Homogeneous equations (R(x) = 0)

# 4.3.1 Variations of Constants:

if  $y_1$  is a solution, an other linearly independent solution can be found as

$$y_2(x) = c(x)y_1(x)$$
 (59)

Where c(x) can be found from the DE.

# 4.3.2 Homogeneous DE's with constant coefficients

$$y'' + ay' + by = 0,$$
  $\lambda^2 + a\lambda + b = 0$   $\lambda_{\pm} = \frac{1}{2}[-a \pm \sqrt{a^2 - 4b}]$  (60)

Case 1:  $\lambda_{-} \neq \lambda_{+}$ , both real  $(a^{2} - 4b > 0)$ , gives two linearly independent solutions:

$$y(x) = C_1 e^{\lambda_+ x} + C_2 e^{\lambda_- x} \tag{61}$$

Case 2: Double root  $\lambda_+ = \lambda_- \equiv \lambda = \frac{-a}{2}$ 

$$y(x) = (Ax + B)e^{\lambda x} \tag{62}$$

Case 3: Complex root  $(a^2 - 4b < 0)$ 

$$\lambda_{\pm} = -\frac{a}{2} \pm i\sqrt{4b - a^2} = -\frac{a}{2} \pm i\omega$$
 (63)

$$y(x) = Ae^{-a/2 + i\omega} + Be^{-a/2 - i\omega} = e^{-ax/2} \left( A\cos(\omega x) + B\sin(\omega x) \right)$$

$$\tag{64}$$

$$= e^{-ax/2} \left( \tilde{A}e^{i\omega x} + \tilde{B}e^{-i\omega x} \right) = ke^{-ax/2} \sin(\omega x + \phi)$$
 (65)

#### 4.3.3 **Euler-Cauchy:**

$$x^{2}y'' + a_{1}xy' + a_{0}y = 0$$
, or  $y'' + \frac{a_{1}}{x}y' + \frac{a_{0}}{x^{2}}y = 0$  (66)

Use:

$$x = e^z, \qquad z = \ln x, \qquad dx = e^z dz = x dz$$
 (67)

For x > 0

$$x = -|x| = -e^z, z = \ln|x|, dx = -e^z dz = xdz$$
 (68)

For x < 0. We then get

$$\frac{d^2y(z)}{dz^2} + (a_1 - 1)\frac{dy(z)}{dz} + a_0y(z) = 0$$
(69)

Solve then transform back to y(x). No solution at x=0, and different coefficients for cases x<0and x > 0!

# Inhomogeneous DE

$$y(x) = y_h(x) + y_p(x) \tag{70}$$

#### Methods of Undetermined Coefficients: 4.4.1

$$y'' + ay' + by = R(x) \tag{71}$$

Where R(x) is simple. If R(x) is a sum of simple functions, then  $y_p$  is also a sum.

Case 1:  $R(x) = Ae^{kx}$ . Assume  $\alpha$ ,  $\beta$  are the roots of the characteristic equation of the homogeneous solution.

a) If  $k \neq \alpha, \beta$ . Try  $y_p = Be^{kx}$  (Find B from the DE) b)  $k = \alpha$  or  $k = \beta$ . Try  $y_p = Cxe^{kx}$ c)  $k = \alpha = \beta$ , so  $y_h = (Ax + B)e^{kx}$ , try:  $y_p = Dx^2e^{kx}$ Case 2:  $R(x) = A\sin kx$  or  $\cos kx$ . Has the form  $y_p = B\cos kx + C\sin kx$ . Efficient: Solve or  $\tilde{R}(x) = e^{ikx}$  and take Re or Im at the end.

Case 3:  $R(x) = e^{kx} P_n(x)$ .  $P_n$  and  $Q_n$  are here polynomials of order n.

- a) If  $k \neq \alpha, \beta$ . Try  $y_p = Q_n(x)e^{kx}$  (Find B from the DE)
- b)  $k = \alpha$  or  $k = \beta$ . Try  $y_p = xQ_n(x)e^{kx}$ c)  $k = \alpha = \beta$ , so  $y_h = (Ax + B)e^{kx}$ , try:  $y_p = x^2Q_n(x)e^{kx}$

# More General: $y_p$ from factorization:

$$y'' + P(x)y' + Q(x)y = R(x)$$
(72)

Assume u(x) is a known solution of the homogeneous DE. Make the ansatz  $y_p = u(x)v(x)$ . v(x) is found from inserting into the DE. If we define v' = w we'll get

$$w' + \left(\frac{2u}{u'} + P\right)w = \frac{R}{u} \tag{73}$$

Solve by integrating factor. And then get

$$v = \int w dx \tag{74}$$

## 4.4.3 Variation of Parameters:

NB! Write DE on the standard form y'' + Py' + Q = R. This works if the homogeneous solutions are fully known!

$$y_p(x) = -y_1 \int \frac{y_2 R}{W} dx + y_2 \int \frac{y_1 R}{W} dx$$
 (75)

Where W is the Wronskian

$$W(x_0) = \begin{vmatrix} y_1(x_0) & y_2(x_0) \\ y'_1(x_0) & y'_2(x_0) \end{vmatrix}$$
(76)

# 4.5 Fröbenius method:

Any DE of the form

$$y'' + \frac{B(x)}{x}y' + \frac{C(x)}{x^2}y = 0 (77)$$

Where B and C are analytic in the singular point x = 0 (if the whole equation is analytic here, we can use power series).

$$y(x) = x^s \sum_n a_n x^n \tag{78}$$

## 4.5.1 Indicial equation:

Write  $x^2y'' + xb(x)y' + c(x)y = 0$ , with  $b(x) = b_0 + b_1x^1 + ...$ ,  $c(x) = c_0 + c_1x^1 + ...$  and  $y(x) = a_0x^s + a_1x^{s+1} + ...$  If we insert these series in to the DE, and equate the coefficients for the lowest possible power  $x^s$  we get

$$s(s-1) + b_0 s_0 + c_0 = 0 (79)$$

a) Two distinct roots  $s_1, s_2$  and  $s_1 - s_2 \neq$  integer: Two linearly independent solutions.

$$y_i = x^{s_i} \sum_n a_n x^n \tag{80}$$

- b) Two distinct roots  $s_1, s_2$  but  $s_1 s_2 =$  integer. Choose  $s_1 > s_2$
- Often  $s_2$  gives a complete solution. Always try the smallest root first.
- Sometimes  $s_2$  does not give a solution,  $s_1$  always does: Find  $y_1$ , then  $y_2 = c(x)y_1$  from variations of constants.
- Double root  $s_1 = s_2 = s$ . Then find  $y_1$  from s, then  $y_2 = c(x)y_1$

# 4.5.2 Hermite Eq:

From harmonic oscillator:  $-\psi'' + x^2\psi = (2n+1)\psi$ . Use factorization  $\psi(x) = e^{-x^2/2}y(x)$ . We then get the Hermite DE:

$$y'' - 2xy' + ny = 0 (81)$$

Solution

$$a_{k+2} = -\frac{2(n-k)}{(k+1)(k+2)}a_k, \qquad H_n(x) = (-1)^n e^{x^2} \frac{d^2}{dx^2} e^{-x^2}$$
(82)

# 4.6 Greens functions:

$$Dy(x) = R(x), \qquad D = \frac{d^2}{dx^2} + P(x)\frac{d}{dx} + Q(x)$$
 (83)

$$DG(x,z) = \delta(x-z), \qquad y(a) = y(b) = 0$$
 (84)

$$y(x) = \int_{a}^{b} G(x, z)R(x)dz \tag{85}$$

G is continuous at x=z, but its derivatives has a discontinuity of 1

$$G(z+\epsilon,z) - G(x-\epsilon,z) = 0, \qquad G'(z+\epsilon,z) - G'(x-\epsilon,z) = 1$$
(86)

## 5 Fourier Series:

# 5.1 Some orthogonality Relations:

$$\frac{1}{2\pi} \int_{-\pi}^{\pi} \cos(nx) dx = \frac{1}{2\pi} \int_{-\pi}^{\pi} \sin(nx) dx = 0$$
 (87)

$$\frac{1}{2\pi} \int_{-\pi}^{\pi} \cos(mx) \sin(nx) dx = 0 \tag{88}$$

$$\frac{1}{2\pi} \int_{-\pi}^{\pi} \cos(nx) \cos(mx) dx = \begin{cases} 0 & n \neq m \\ 1/2 & n = m \neq 0 \\ 1 & n = m = 0 \end{cases}$$
 (89)

$$\frac{1}{2\pi} \int_{-\pi}^{\pi} \sin(nx) \sin(mx) dx = \begin{cases} 0 & n \neq m \\ 1/2 & n = m \neq 0 \\ 0 & n = m = 0 \end{cases}$$
 (90)

$$\int_{-\pi}^{\pi} e^{inx} e^{-imx} dx = 2\pi \delta_{nm} \tag{91}$$

## 5.2 Dirichlet Conditions:

Sufficient conditions for the Fourier series to converge:

- A finite number of maxima and minima in the basic interval
- A finite number of finite discontinuities [bonded]
- At point  $y_0$  where f(x) has a discontinuity, the Fourier series converges at the midpoint.
- The Fourier Series my be integrated term by term
- If f'(x) satisfies the Dirichlet conditions, the Fourier series may be differentiated term by term

# 5.3 Interval $[0, 2\pi]$ :

$$f(x) = \frac{1}{2}a_0 + \sum_{n=1}^{\infty} a_n \cos(nx) + \sum_{n=1}^{\infty} b_n \sin(nx)$$
 (92)

$$a_n = \frac{1}{\pi} \int_{-\pi}^{\pi} f(x) \cos(nx) dx, \qquad b_n = \frac{1}{\pi} \int_{-\pi}^{\pi} f(x) \sin(nx) dx$$
 (93)

# 5.4 Complex Series:

$$f(x) = \sum_{n=-\infty}^{\infty} c_n e^{inx}, \qquad c_k = \frac{1}{2\pi} \int_{-\pi}^{\pi} f(x) e^{-ikx} dx$$
 (94)

Can find a sin-cos series from the complex, and vice versa.

## 5.5 Other intervals:

We can simply change the interval to another basic interval of length 2L:

$$x \to \frac{\pi x}{L}, \qquad \frac{1}{\pi} \int_{-\pi}^{\pi} \to \frac{1}{L} \int_{-L}^{L}$$
 (95)

## 5.6 Even and Odd Functions:

Even: f(-x) = f(x), ex:  $(\cos x)$ Odd: f(-x) = -f(x), ex:  $(\sin x)$ 

 $even \cdot even = odd \cdot odd = even, even \cdot odd = odd$ 

$$\int_{-L}^{L} f(x)dx = \begin{cases} 0 & \text{f is odd} \\ 2\int_{0}^{L} f(x)dx & \text{f is even} \end{cases}$$
 (96)

## 5.6.1 Fourier of odd Function, sine-series:

$$f(x) = \sum_{n=1}^{\infty} b_n \sin\left(\frac{n\pi x}{L}\right), \qquad b_n = \frac{2}{L} \int_{-L}^{L} f(x) \sin\left(\frac{n\pi x}{L}\right) dx \tag{97}$$

## 5.6.2 Fourier of even Function, cos-series:

$$f(x) = \frac{a_0}{2} + \sum_{n=1}^{\infty} a_n \cos\left(\frac{n\pi x}{L}\right), \qquad a_n = \frac{2}{L} \int_{-L}^{L} f(x) \cos\left(\frac{n\pi x}{L}\right) dx \tag{98}$$

A given function may be represented by several different Fourier Series depending on the physics/context. Given a function defined only on half the interval [0, L]. We may either define an **even** extension of f(x) to the period 2L by only using the cosine-series; or we may define an **odd** extension by using the sine-series.

## 5.7 Parseval's Theorem:

$$\frac{1}{2L} \int_{-L}^{L} |f(x)|^2 dx = \sum_{-\infty}^{\infty} |c_n|^2 = \left(\frac{1}{2}a_0\right)^2 + \frac{1}{2} \sum_{n=1}^{\infty} a_n^2 + \frac{1}{2} \sum_{n=1}^{\infty} b_n^2$$
 (99)

$$\int_{-\infty}^{\infty} |f(x)|^2 = \int_{-\infty}^{\infty} |F(k)|^2 \tag{100}$$

# 6 Fourier Transforms:

$$F(k) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} f(x)e^{-ikx}dx = \mathcal{F}[f(x)]$$
 (101)

$$f(x) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} F(k)e^{ikx}dk \tag{102}$$

# 6.1 Fourier Integral Theorem:

$$f(x) = \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{ikx} \underbrace{\int_{-\infty}^{\infty} f(\tilde{x})e^{-ik\tilde{x}}d\tilde{x}}_{\sqrt{2\pi}F(k)} dk$$
 (103)

Is OK if f(x) satisfied the Dirichlet conditions on every finite interval, and  $\int_{-\infty}^{\infty} |f(x)| dx$  is finite.

# 6.2 Fourier Transforms of Derivatives:

$$\mathcal{F}[f^{(n)}(x)] = (ik)^n \mathcal{F}[f(x)] \tag{104}$$

## 6.2.1 With DE:

$$y'' + ay' + b = f(x), Y(k) = \mathcal{F}[y(x)] = \frac{F(k)}{-k^2 + aik + b}$$
 (105)

$$y(x) = \mathcal{F}^{-1}[Y(k)] = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} e^{ikx} Y(k) dk$$
 (106)

## 6.3 Sin and cos-transformations

Even and odd functions are represented by cosine and sine Fourier integrals, respectively. If f(x) is even/odd, so is F(k)

$$F(k) = \frac{2}{\sqrt{2\pi}} \int_0^\infty f(x) \cos(kx) dx, \qquad f(x) = \frac{1}{\sqrt{2\pi}} \int_0^\infty F(k) \cos(kx) dk \tag{107}$$

Same for sine

## 6.4 The $\delta$ -function:

$$\mathcal{F}[\delta(x)] = \frac{1}{\sqrt{2\pi}}, \qquad \delta(x-a) = \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{ik(x-a)} dk \tag{108}$$

$$\delta(-x) = \delta(x), \qquad \delta(ax) = \frac{1}{|a|}\delta(x)$$
 (109)

$$\int_{-\infty}^{\infty} \delta^{(k)}(x-a)f(x)dx = (-1)^k f^{(k)}(a), \qquad H'(x) = \delta(x)$$
(110)

# 6.4.1 $\delta$ -sequence:

$$\lim_{n \to \infty} \int_{-\infty}^{\infty} \phi_n(x - a) f(x) dx = f(a)$$
(111)

Possible:

$$\phi_n(x) = \begin{cases} 0 & |x| \ge 1/n \\ n/2 & |x| < 1/n \end{cases}$$
 (112)

$$\phi_n = \frac{n}{\pi} \frac{1}{1 + n^2 x^2}, \qquad \frac{n}{\sqrt{\pi}} e^{-n^2 x^2}, \qquad \frac{1}{n\pi} \frac{\sin^2 nx}{x^2}$$
 (113)