

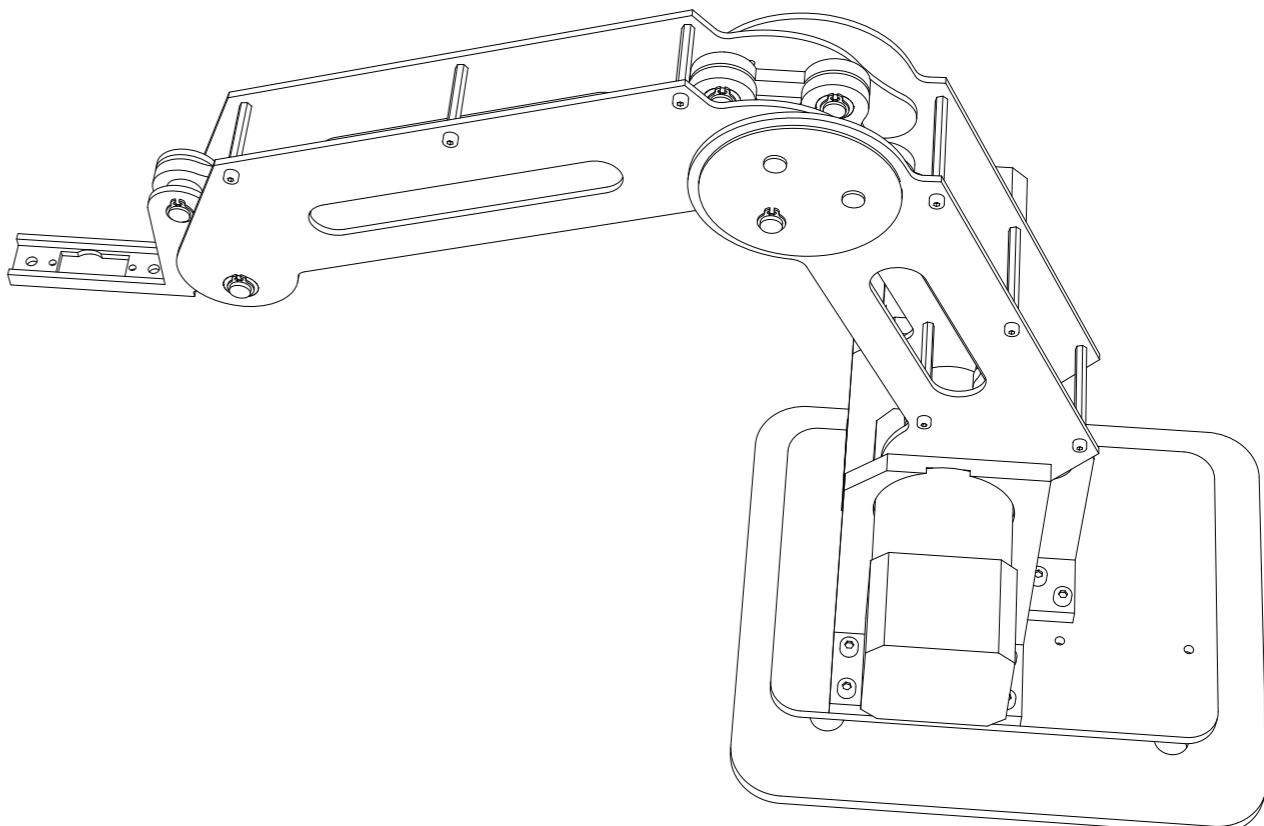


Dobot User Manual

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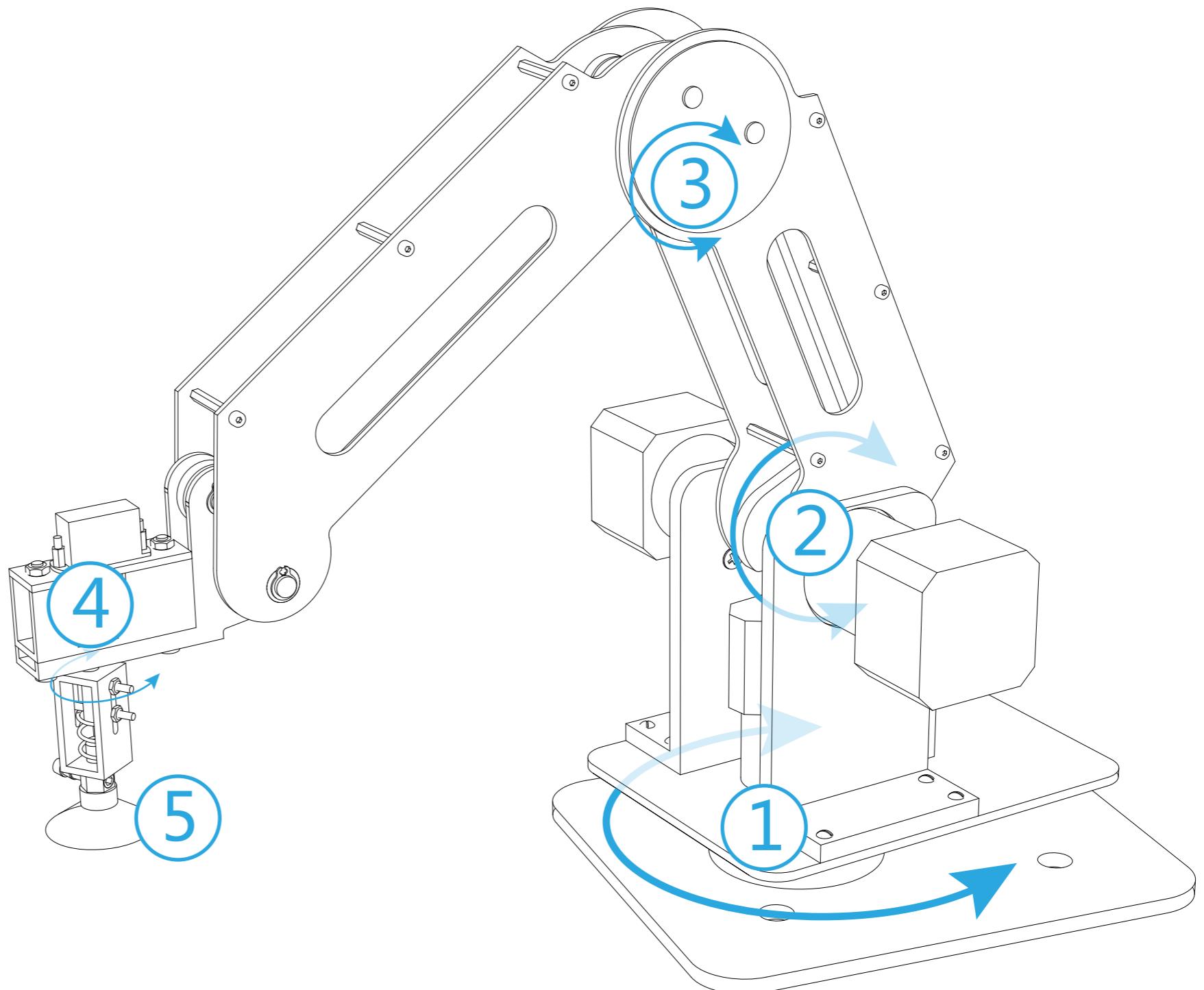
Founded by a group of top industrial robot experts and engineers, the Dobot team is devoted to instilling its ingenuity, creativity, vision and quality into robot design.

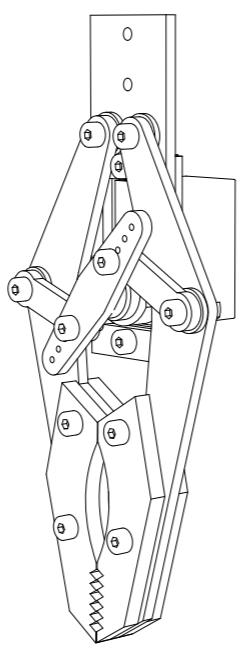
As the first of its category, Dobot is dedicated to bringing its industrial precision robot arm to every desktop, making robot not only highly functional and expandable for makers, but also interactive and fully accessible to non-makers. Interested in engineering, programming and robotics.



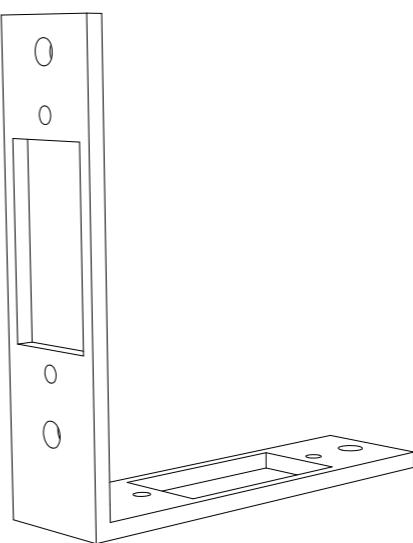
Introduction

1. Joint 1
2. Joint 2
3. Joint 3
4. Joint 4
5. Pump

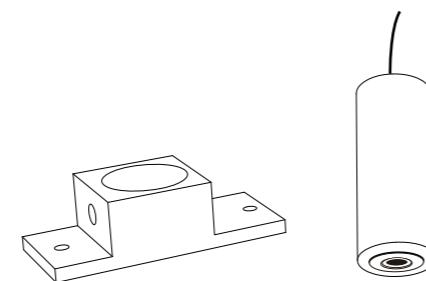




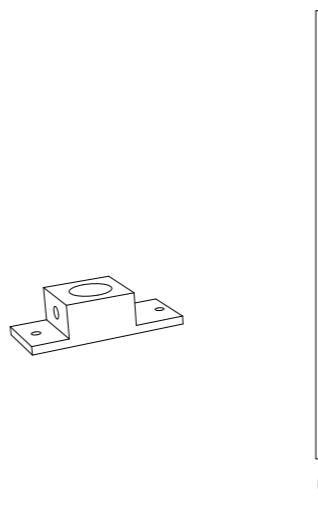
Gripper



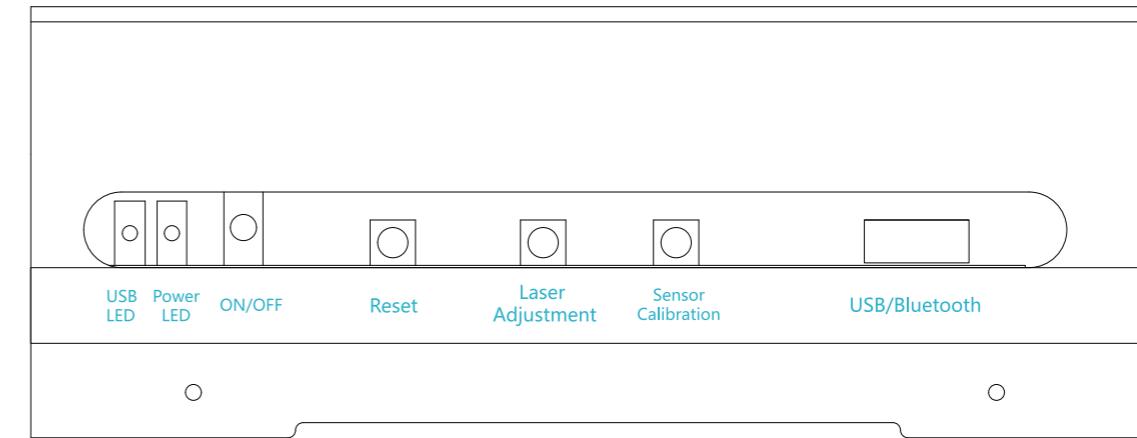
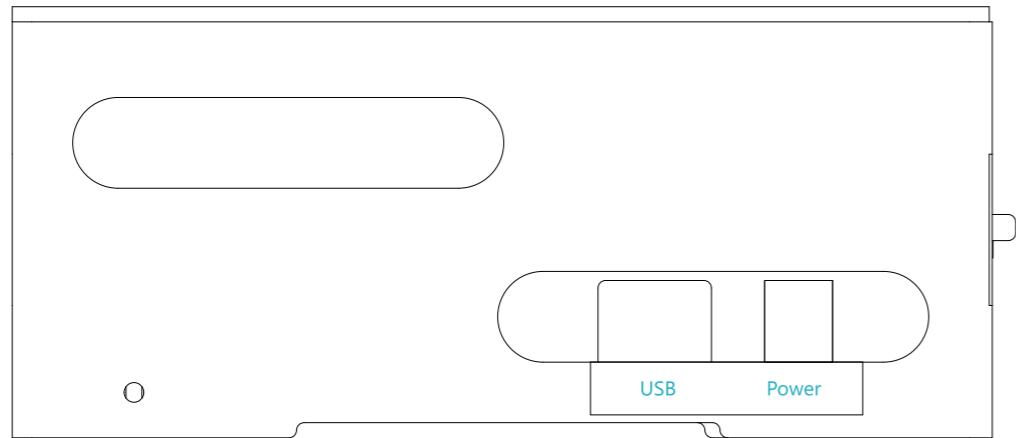
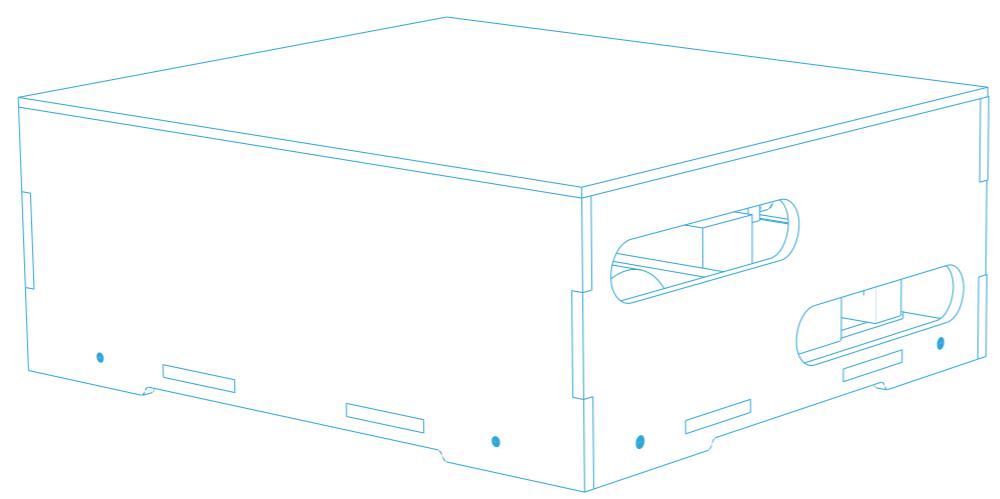
90°Transformer



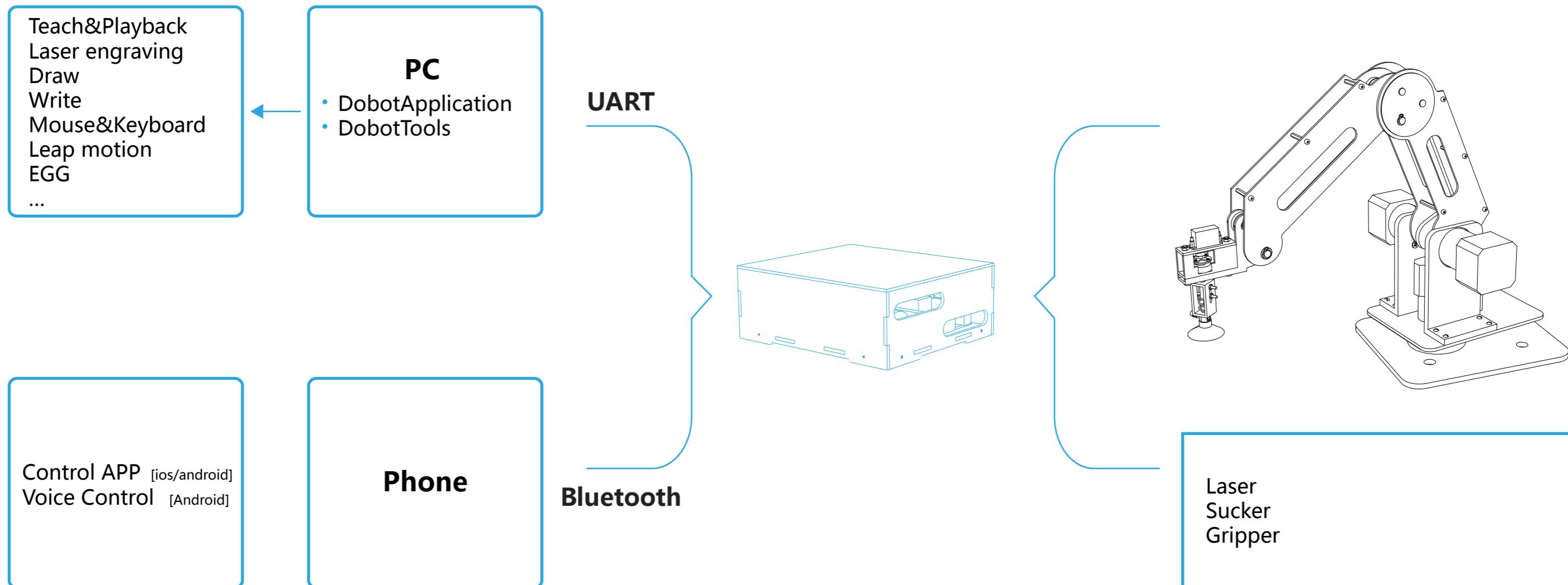
Laser & laser Holder



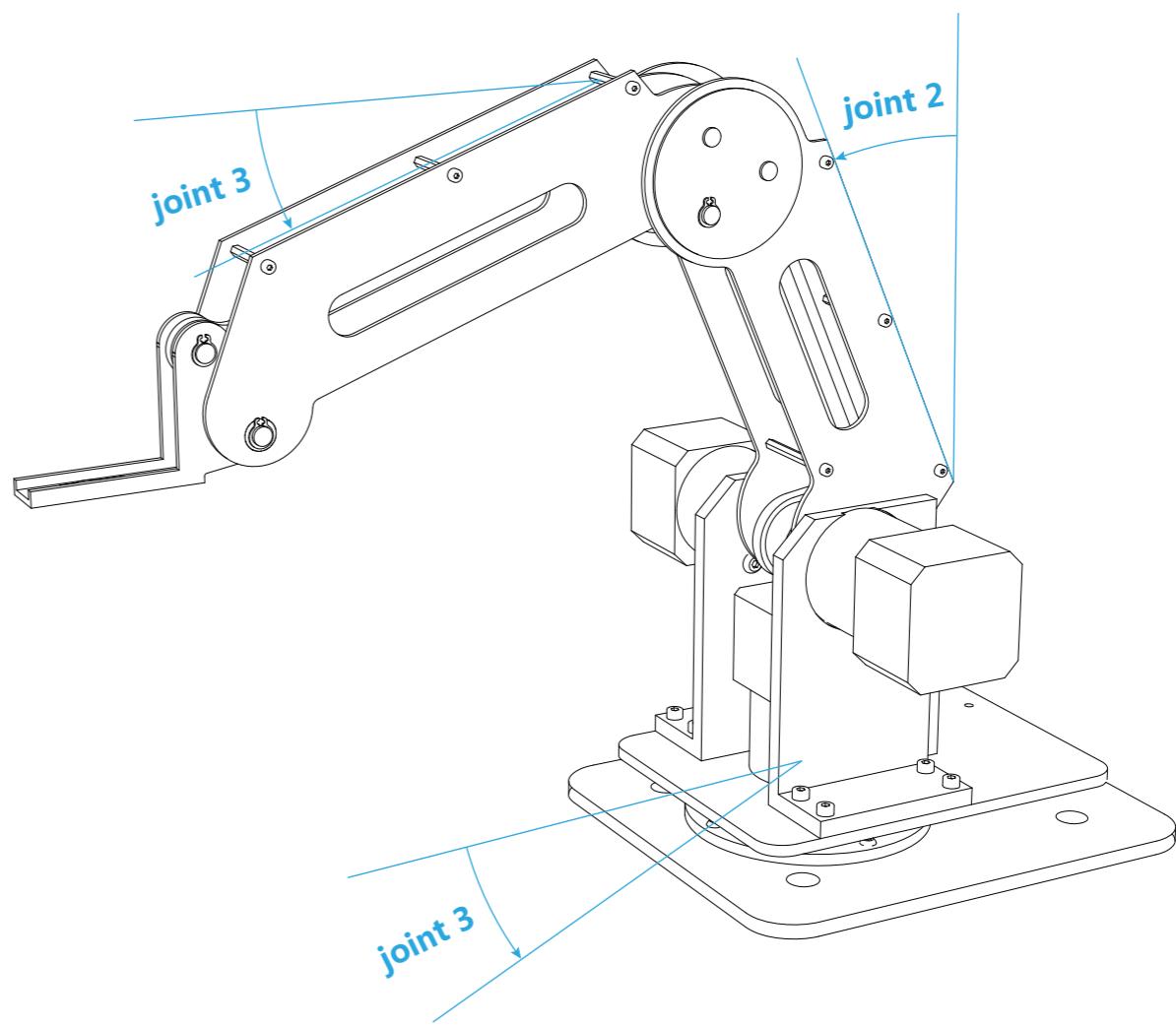
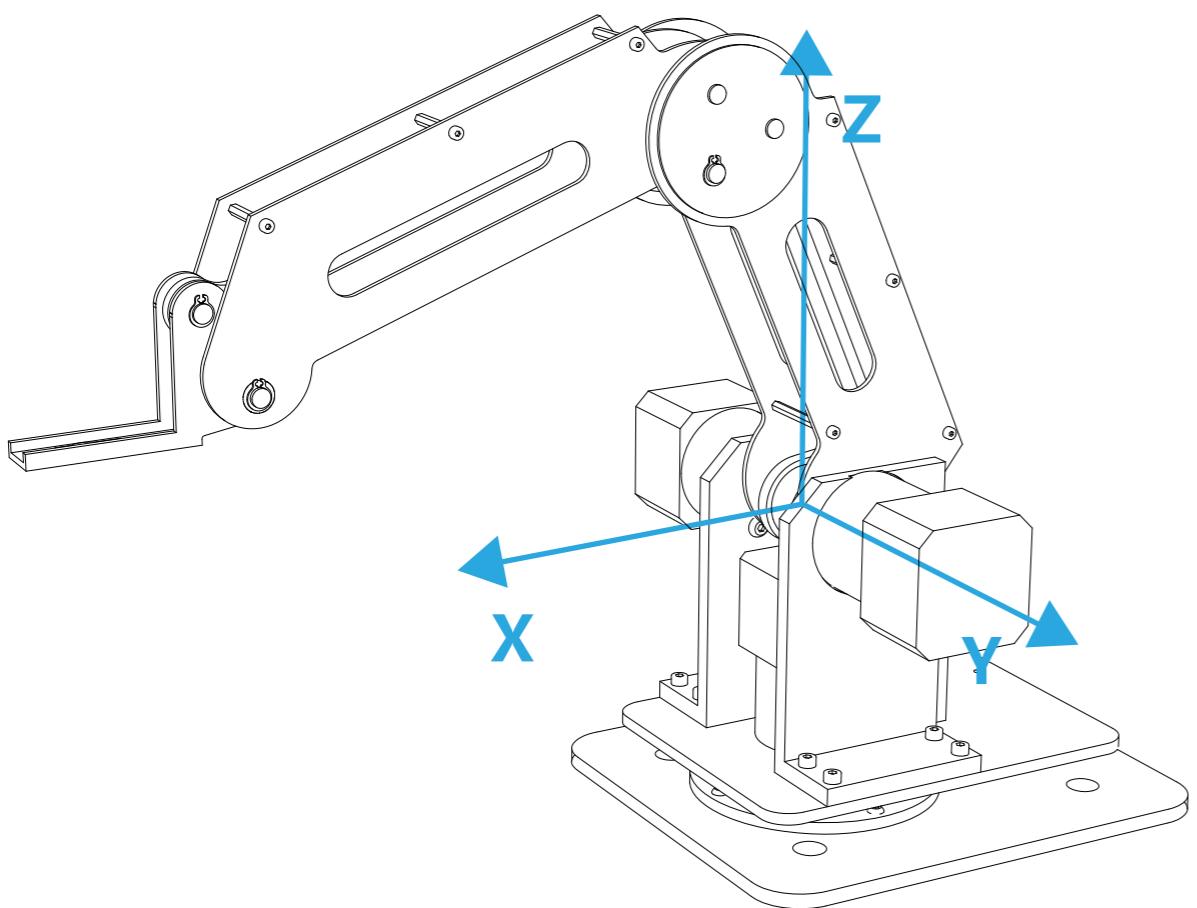
Pen & Pen Holder



DobotFramework

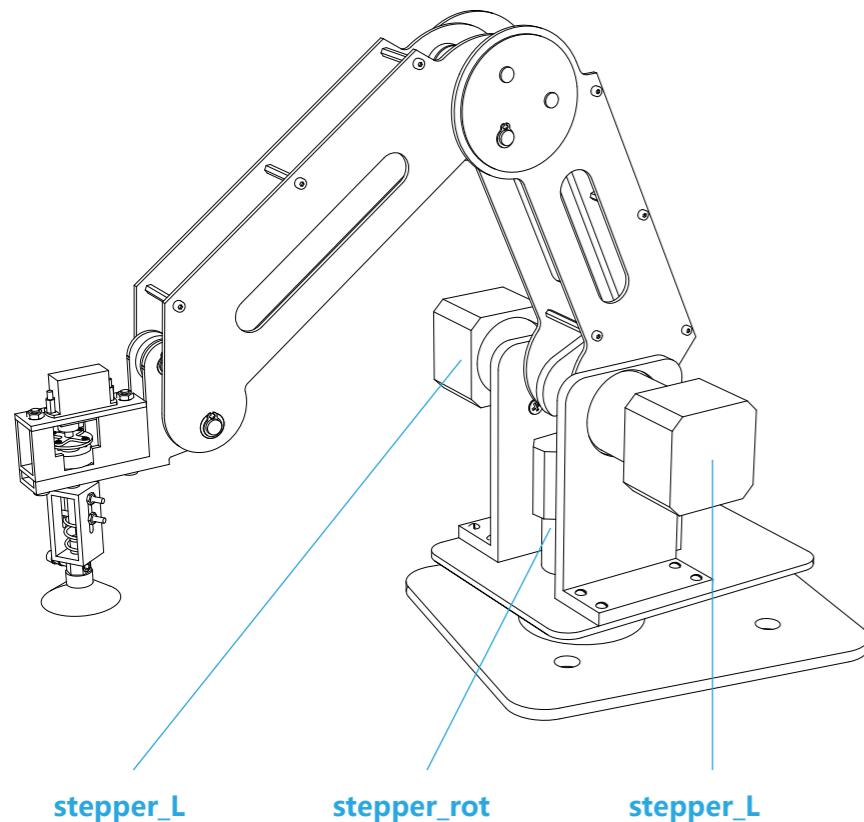


Reference Frame

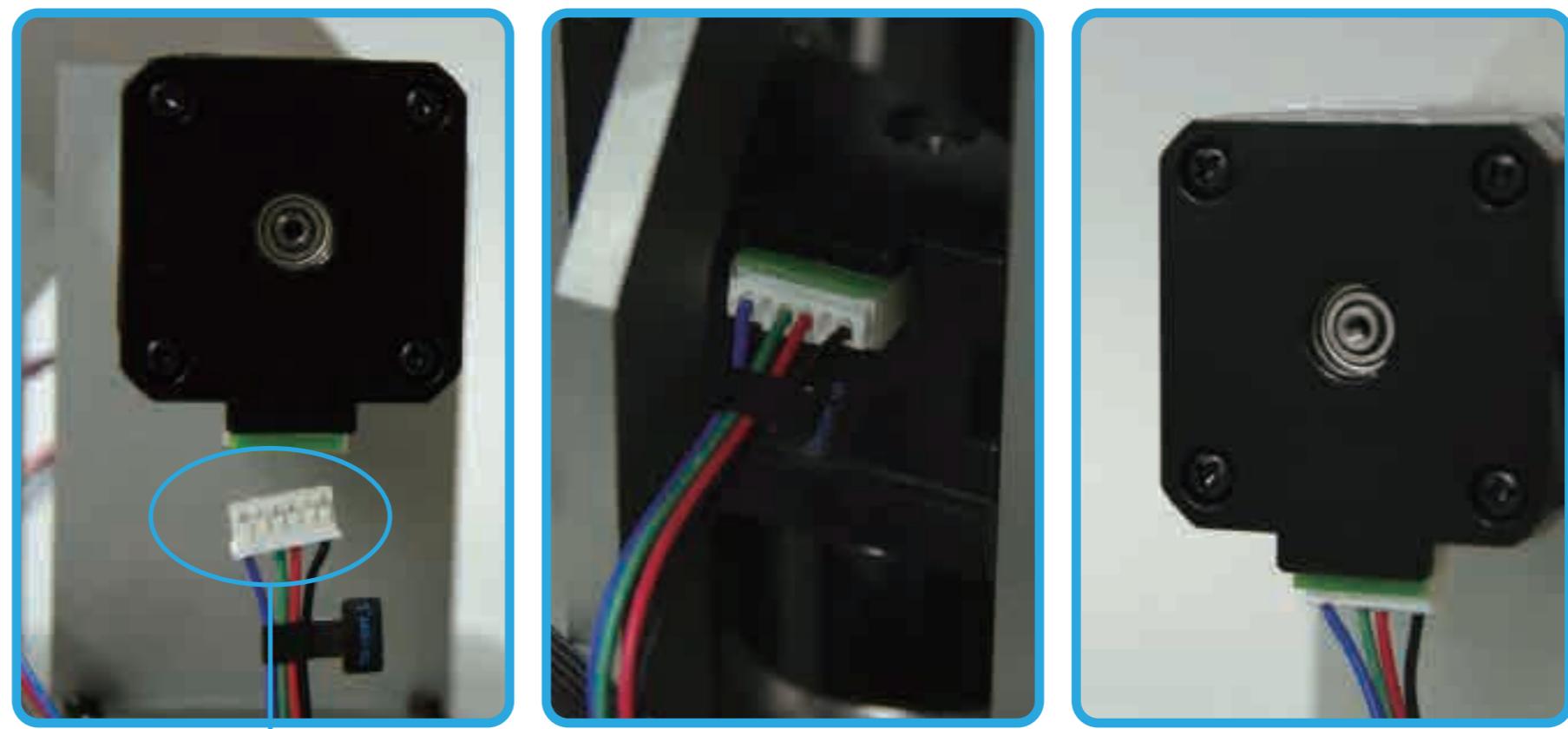


Get started

Step 1: Connect the cables

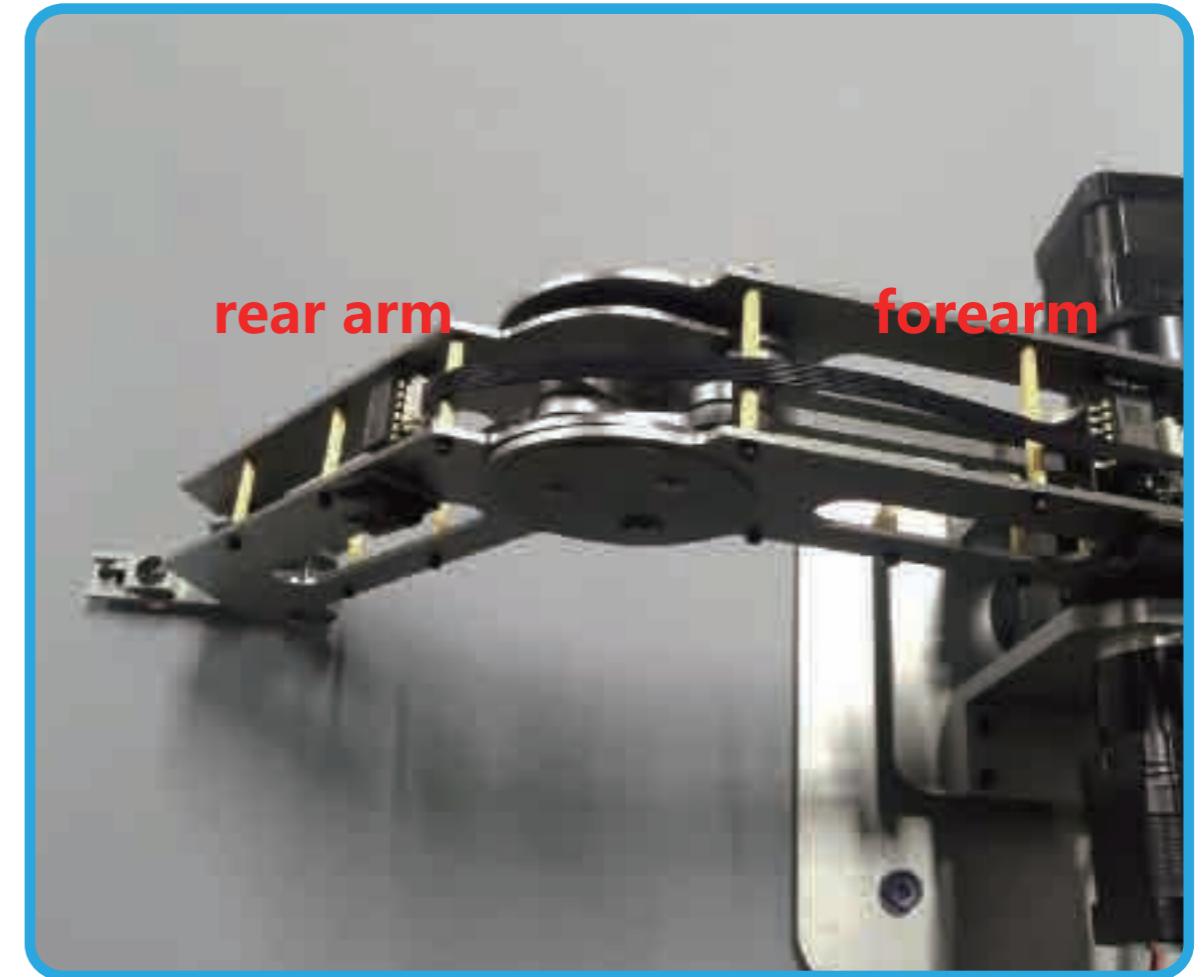
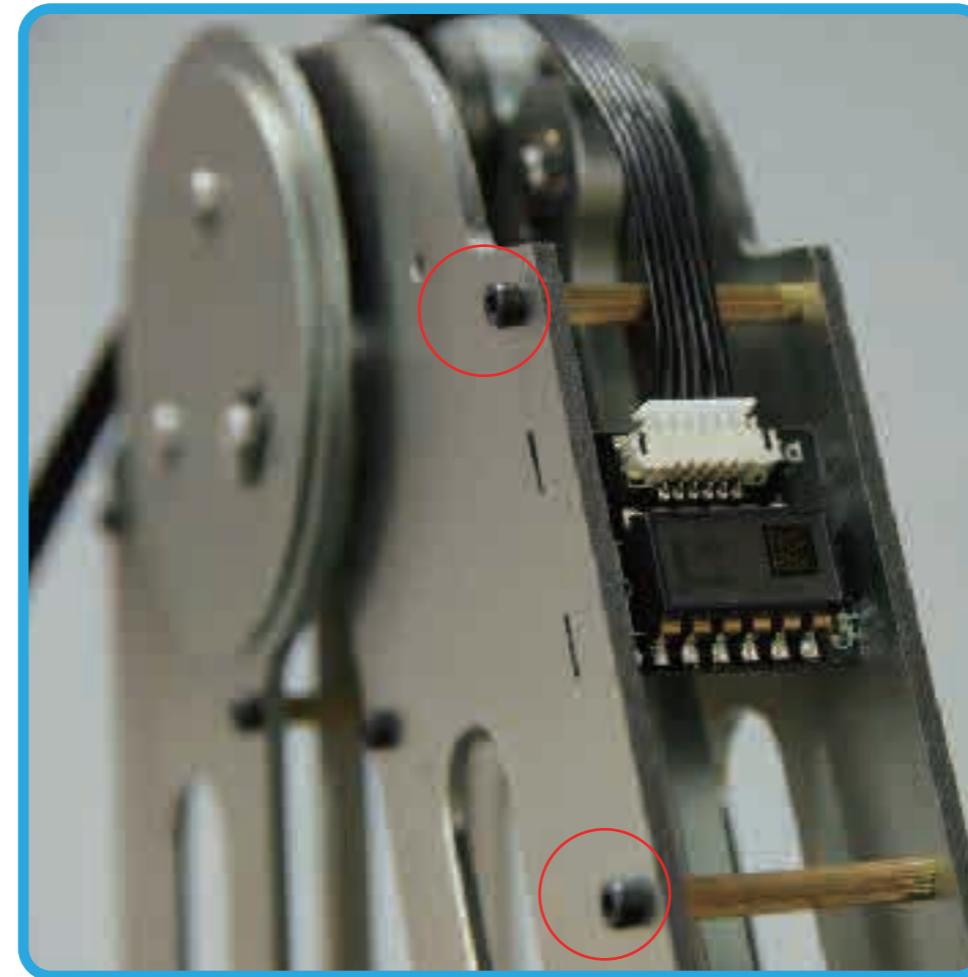
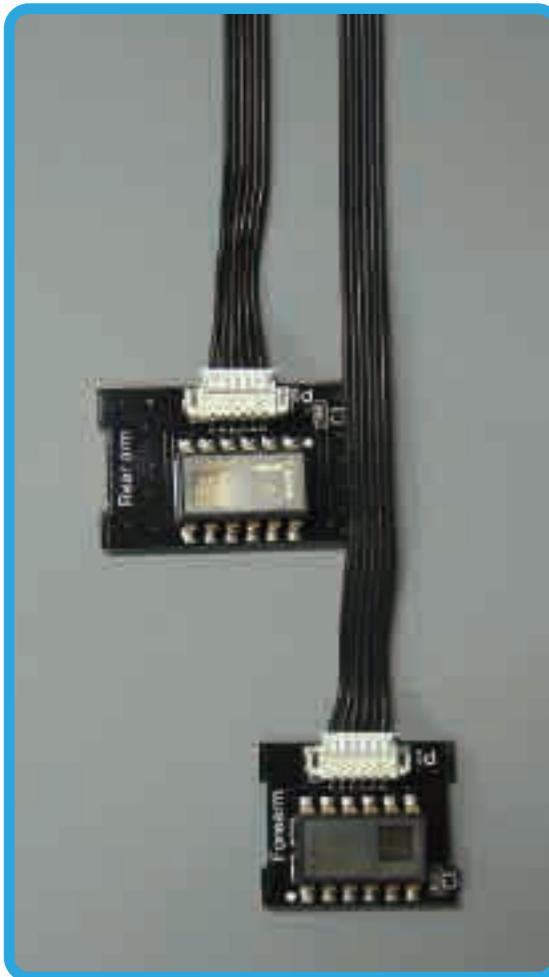


stepper motor



Tip: The flat side of the connectors is parallel to the end of the stpper motor

Angle Sensor

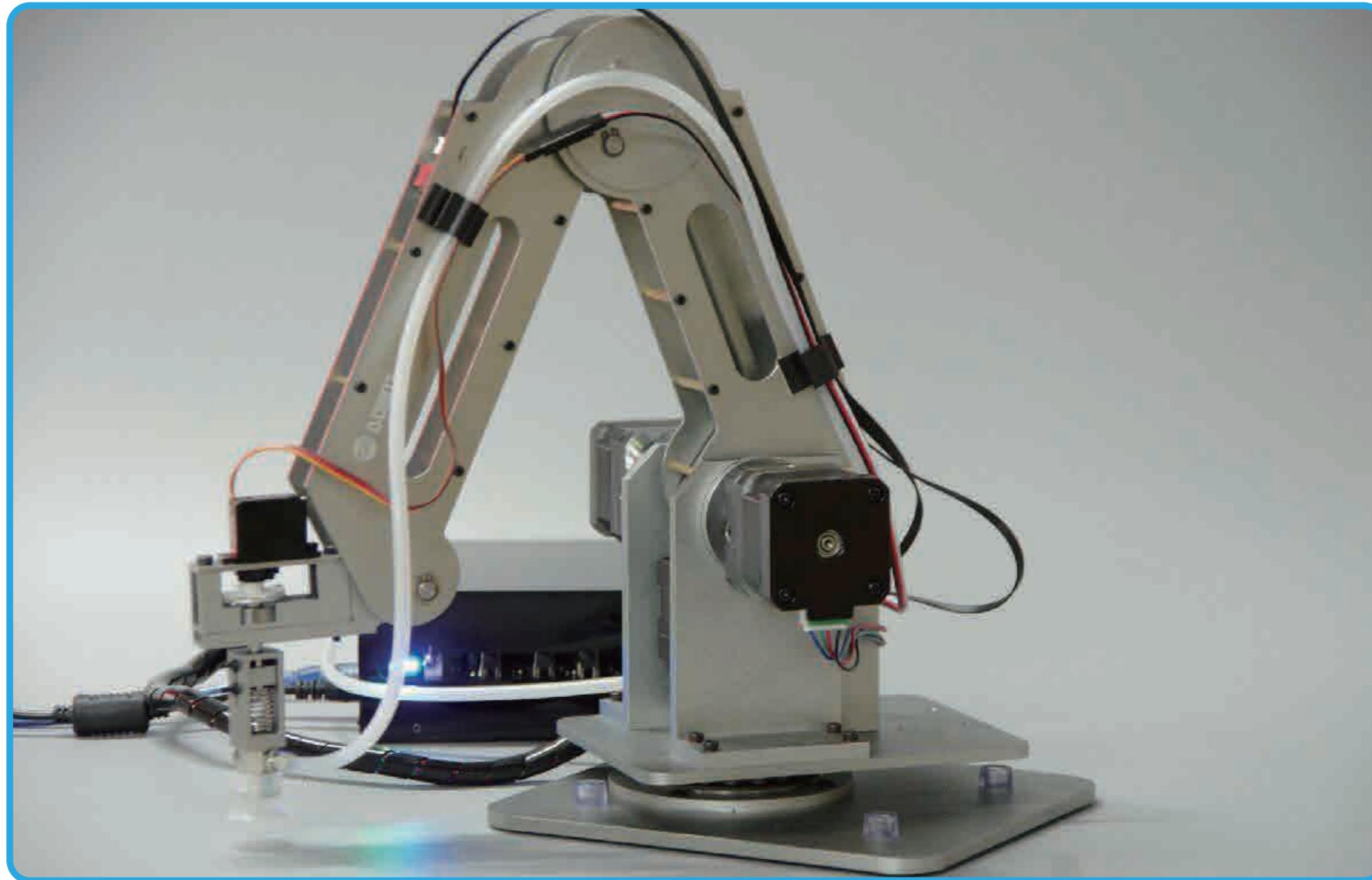


- Loosen the two bolts
- Insert the convex portion at one side of the sensor module into the two strip holes
- Push the other side into the corresponding position
- Tighten the two bolts.

Servo & Air Tube

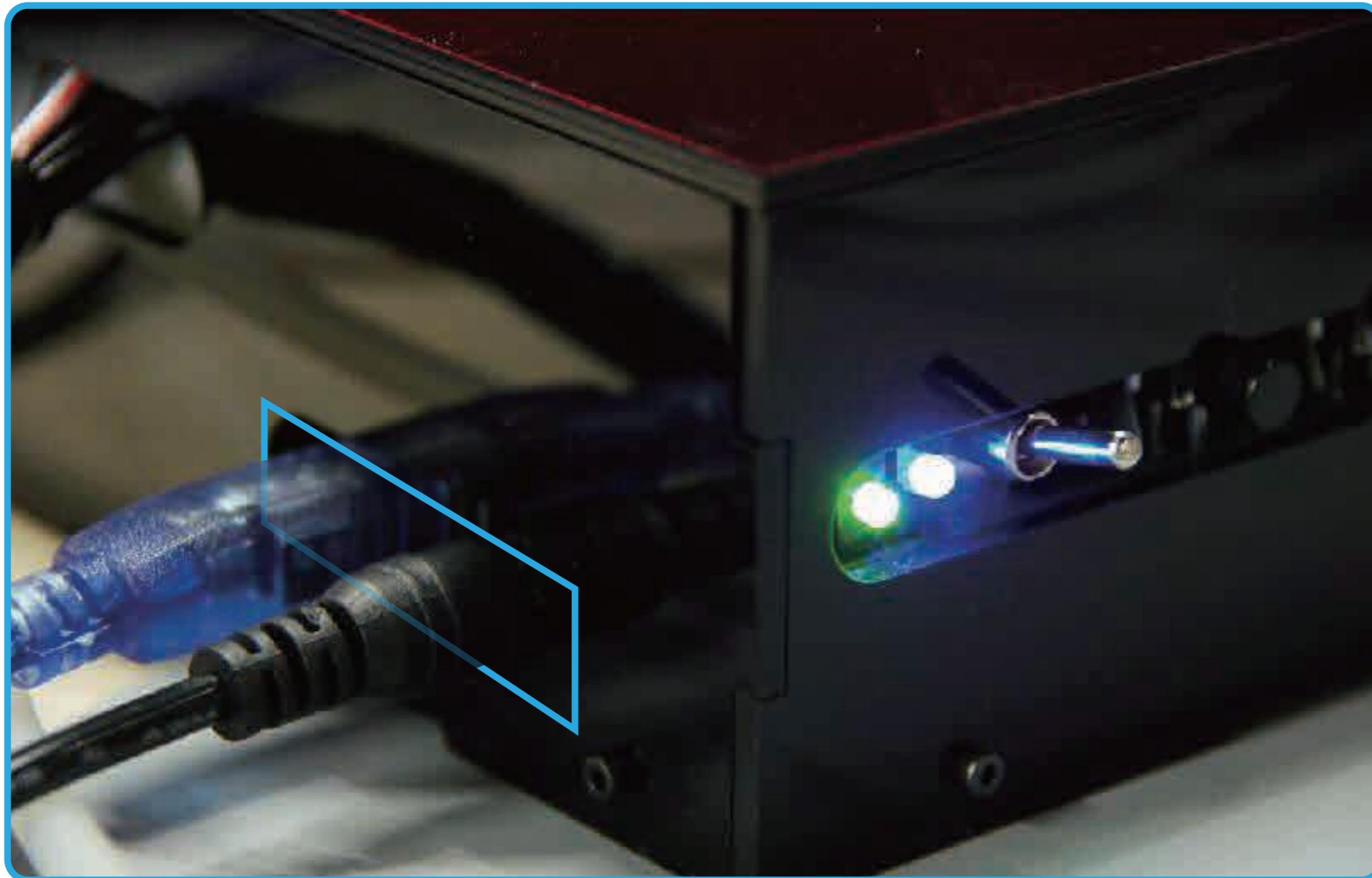


Fix the cable and air tube(selectable)



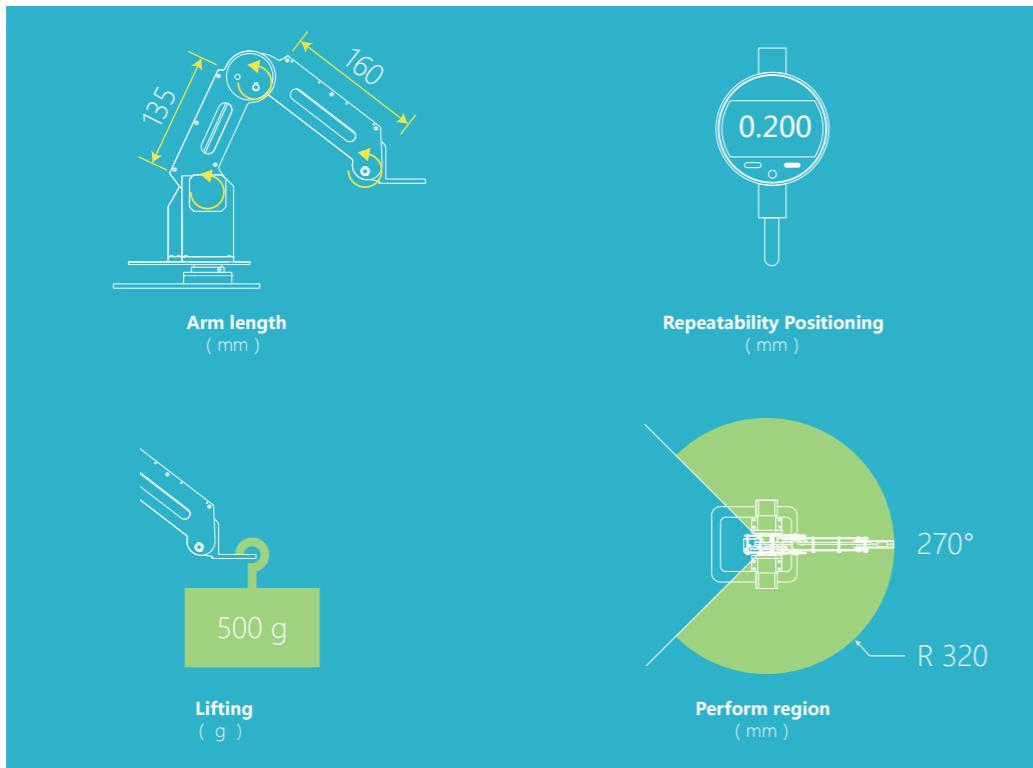
If you like, you can attach the wire holder to the body of the arm and fix the cable and air tube.

Connect USB and Power



**Now your Dobot is ready!
Download softwares and instructions form our website, enjoy!**

Specification



Number of Axes	4
Weight	3kg
Payload	500g
Position repeatability	0.2mm
Material	Aluminium Alloy 6061
Controller	Arduino Mege2560
Communication	UART/Bluetooth
Power Supply	12V 5A DC