



# UNIVERSAL ROBOTS

CompanyUniversal Robots

Drawing number3.0.0.1

Project nameUniversal Robots UR10

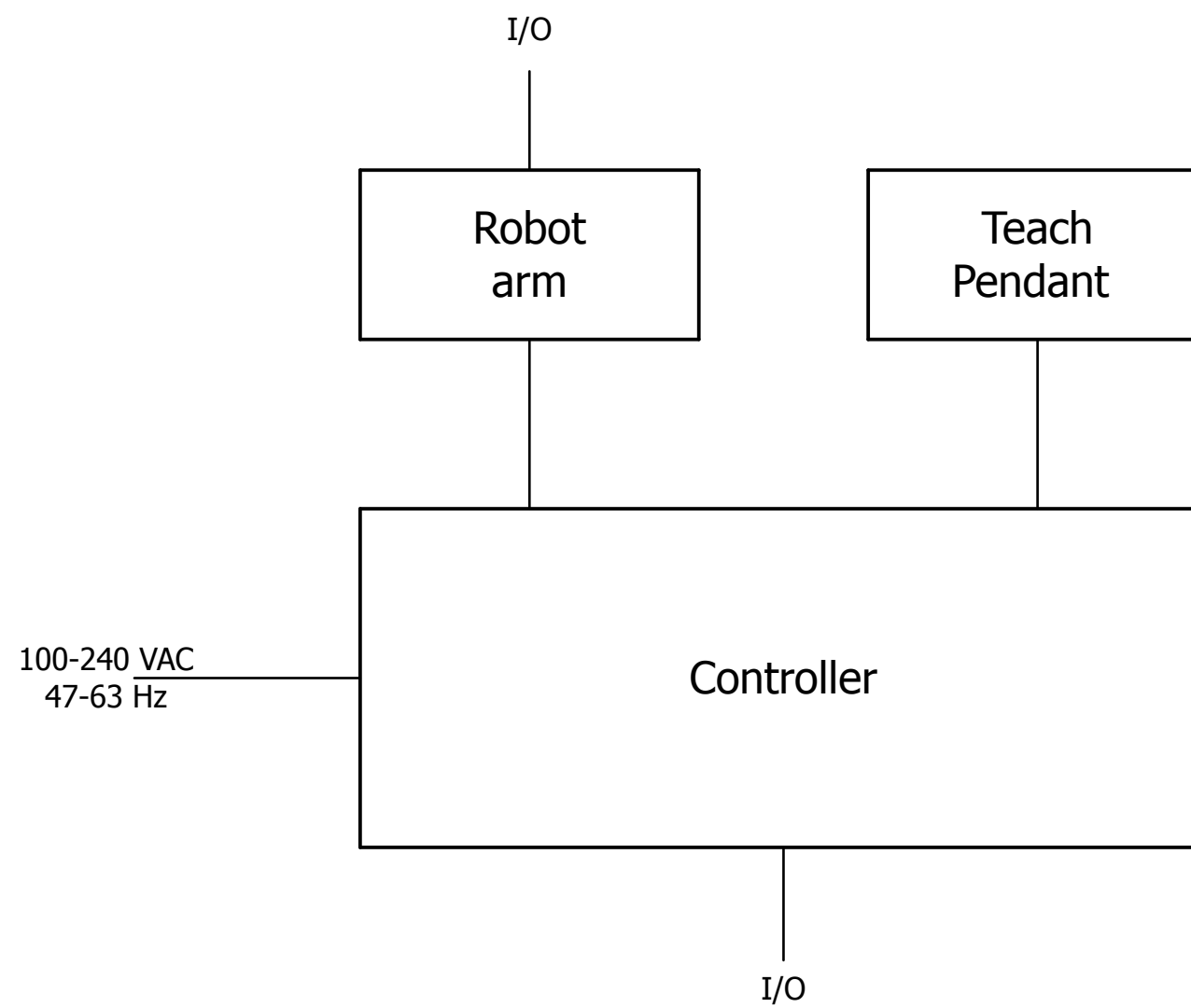
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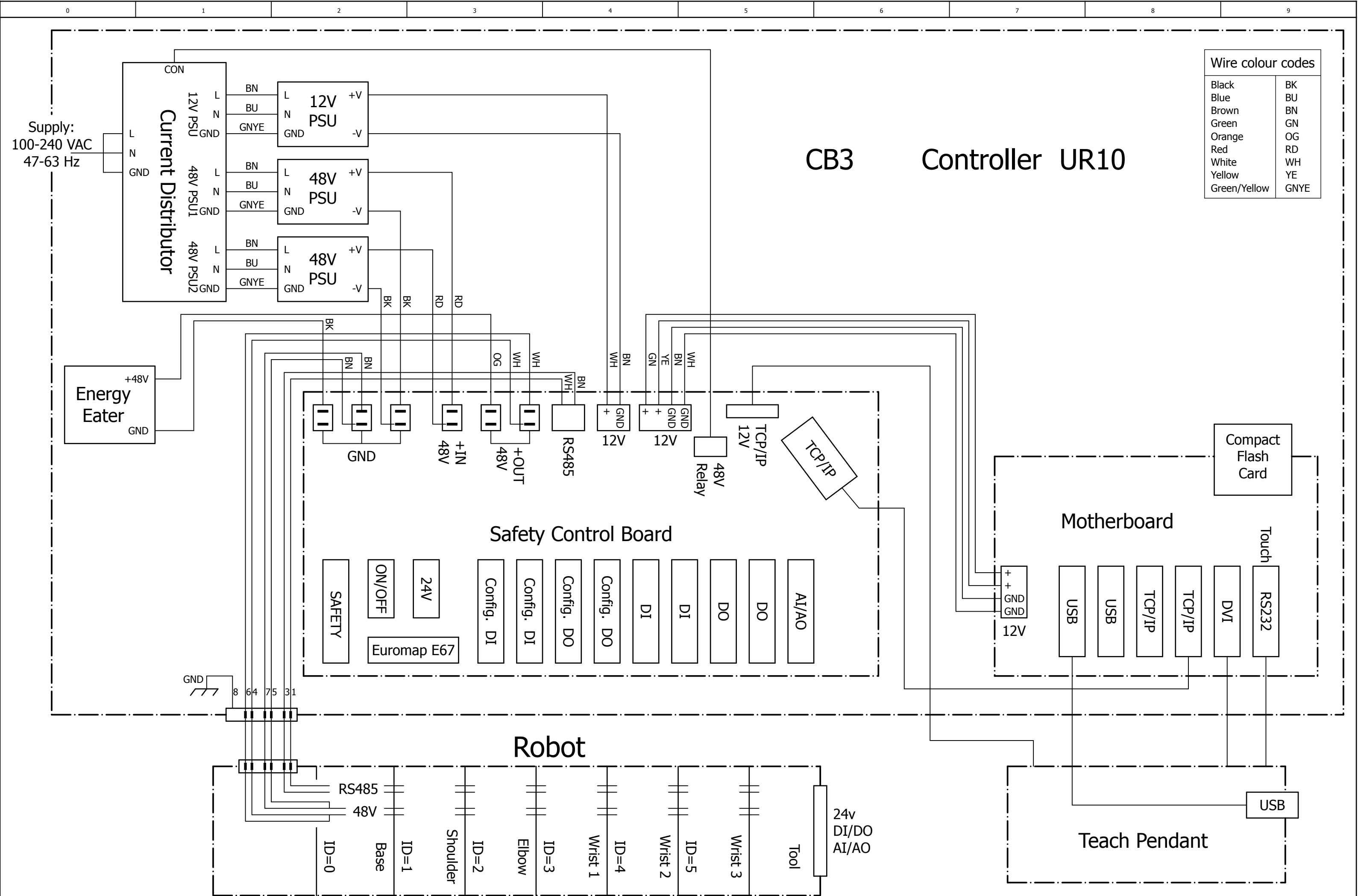
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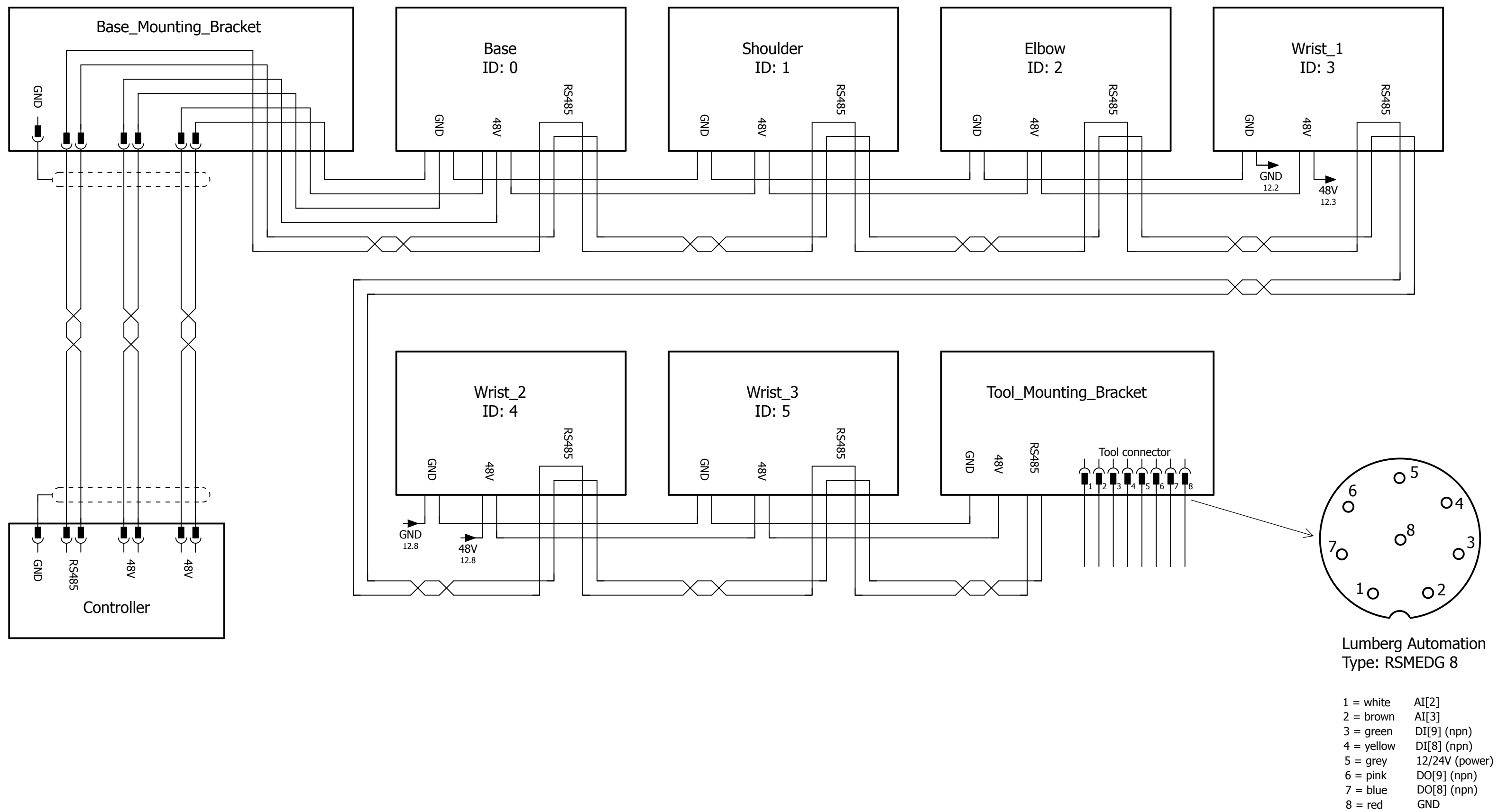
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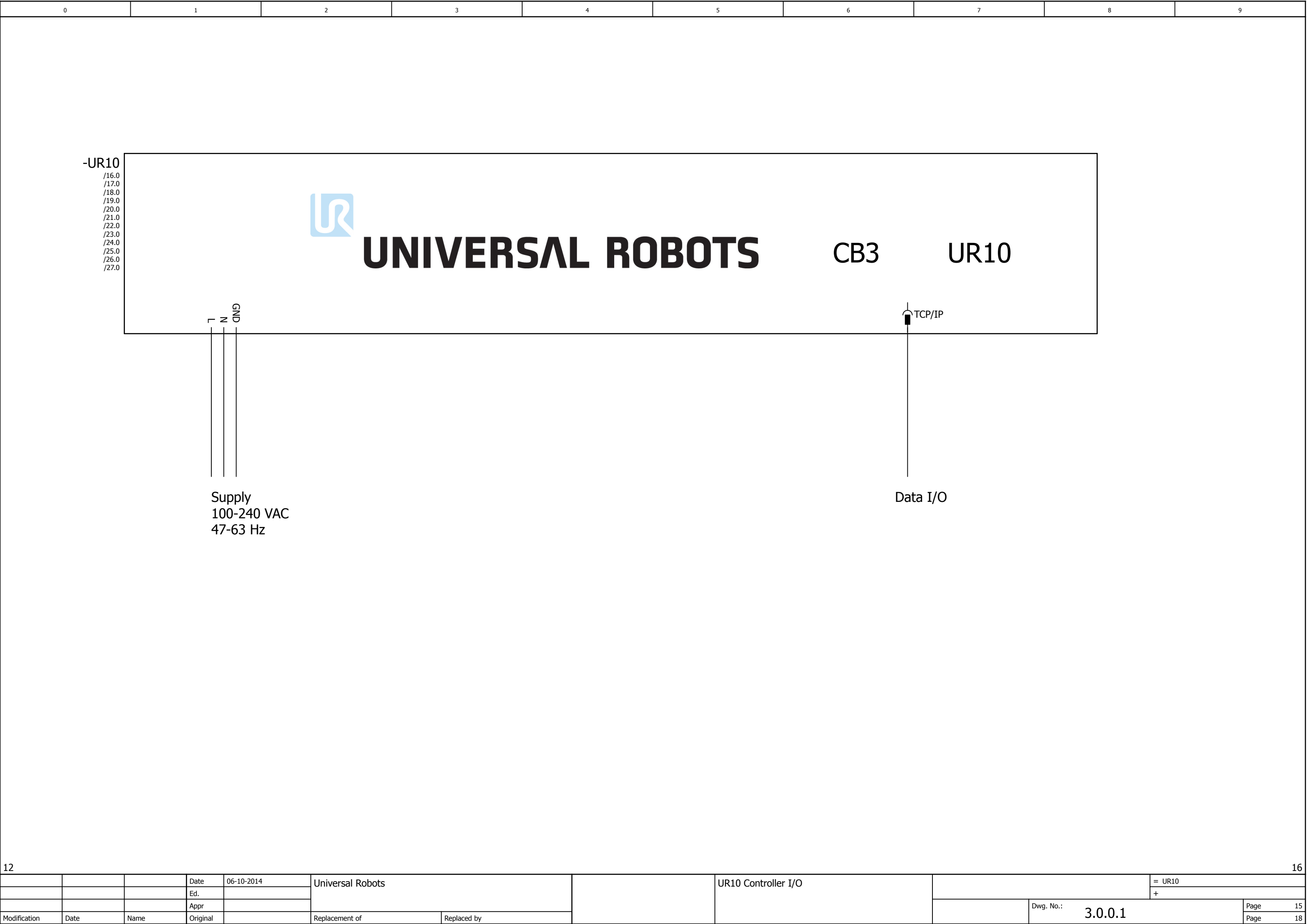
CB3 Overview UR10

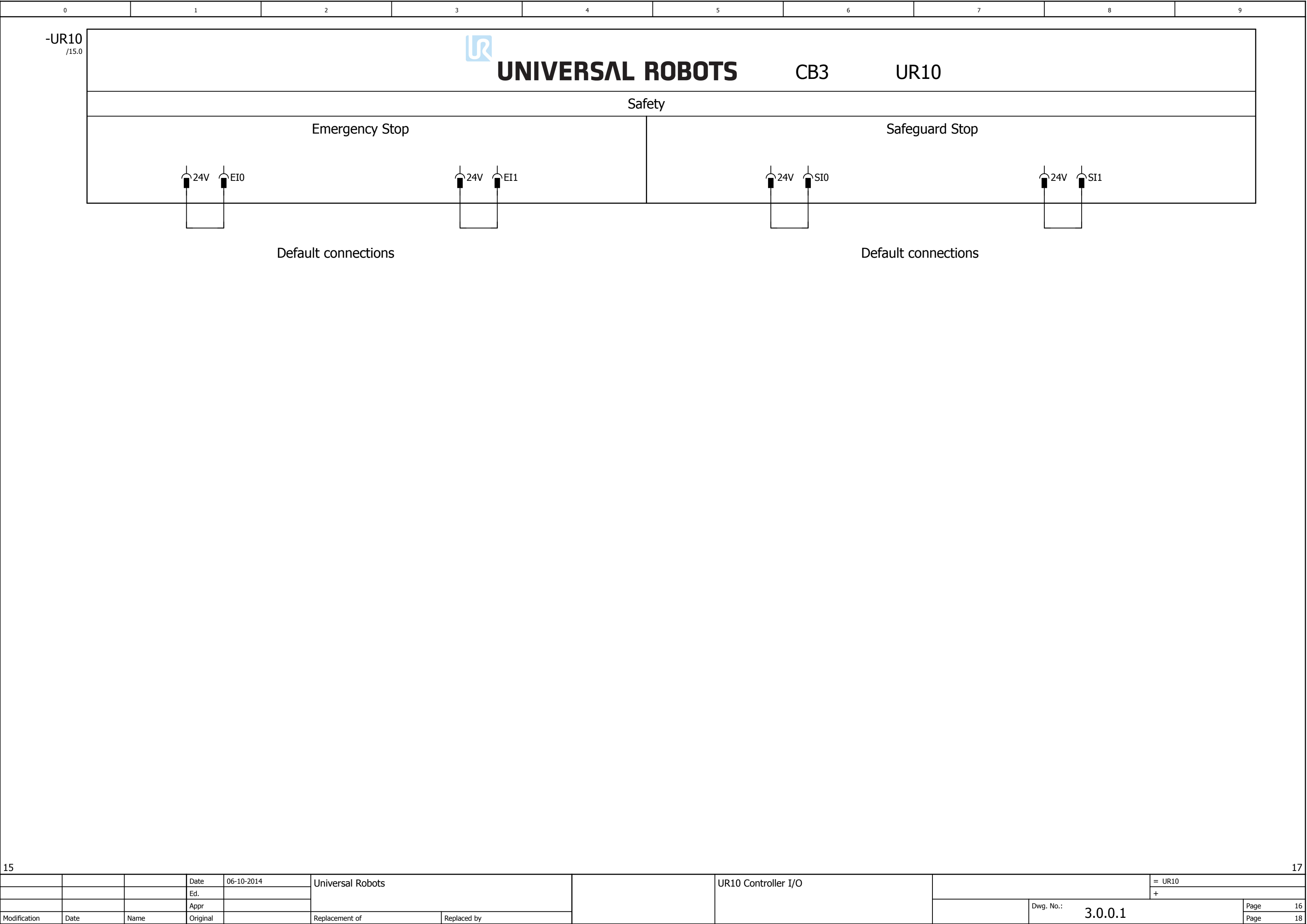




CB3      UR10      Robot arm







UR10

## Power



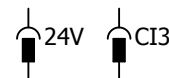
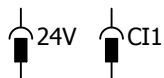
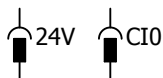
## Default connections





UR10

## Configurable Inputs

[illegible]



UR10

24V CI4

24V CI5

24V CI6

24V CI7

[illegible]



UR10



0V

 COO

CO<sub>2</sub>



0V

 CO3

CO3



UR10



0V

0V



CO4



0V



CO5



0V

0V



CO



0V



CO2

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## Digital Inputs



DIO



DI1



DI2



DI

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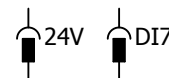
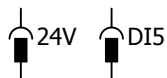
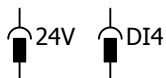


# UNIVERSAL ROBOTS

CB3

UR10

## Digital Inputs



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			Appr									
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## Digital Outputs



0V



DOO



0V



DO1



0V



D02



0V



D03

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		Ed.								+
		Appr								
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## Digital Outputs



0V



D04



0V



D05



0V



D06



0V



D07

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		Appr								
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UR10

AC

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