

COS10004: Computer Systems

Lab 9

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4. Provide a brief description of the following:

4.1. what is the code in each file doing ?

- kernel7.asm : Flashing the LED light of GPIO18 with the number of times equals the factorial of a number
- TIMER.asm: Delay time between processes
- factorialj.asm: Calculating the factorial of a number

4.2. what register holds the input to the program (and what is the input) ?

Register r0 holds the input to the program (#4)

5. You are going to modify the code in kernel7.ASM by breaking up logical components into functions. Open up HOWTO_Lab9.pdf from the task resources and follow the instructions on how to do this (or, if you want to do it your own way, go for it!).

kernel7.asm:

;Calculate

mov r1,#4 ;input

mov sp,\$1000 ;make room on the stack

mov r0,r1

bl FACTORIAL

mov r7,r0 ;store answer

BASE = \$3F000000 ;RP2 and RP3 ;GPIO_SETUP

mov r0,BASE

bl SETUP_LED

mov r0,BASE

mov r1,r7

bl FLASH

wait:

b wait

include "TIMER.asm"

include "factorialj.asm"

include "GPIO.asm"

TIMER.asm:

;TIMER - dumb timer

;r2=number of loops

TIMER:

wait1\$:

sub r2,#1

```
cmp r2,#0
```

```
bne wait1$
```

```
bx lr
```

factorialj.asm:

```
FACTORIAL:
```

```
sub r1,r1,#1
```

```
cmp r1,#1
```

```
beq EXIT
```

```
mul r0,r0,r1
```

```
push {r1,lr}
```

```
;push onto the stack without changing the stack pointer
```

```
bl FACTORIAL ;call FACTORIAL
```

```
EXIT:
```

```
pop {r1,lr} ;pop off the stack
```

```
bx lr ;RETURN
```

GPIO.asm:

```
SETUP_LED:
```

```
GPIO_OFFSET = $200000
```

```
orr r0,GPIO_OFFSET
```

```
mov r1,#1
```

```
lsl r1,#24
```

```
str r1,[r0,#4]
```

```
bx lr
```

```
FLASH:
```

```
mov r2,r0
```

```
orr r0,GPIO_OFFSET
```

```
mov r7,r1
```

```
loop$:
```

```
mov r1,#1
```

```
lsl r1,#18
```

```
str r1,[r0,#28]
```

```
mov r1,#1
```

```
lsl r1,#18
```

```
str r1,[r0,#40]
```

```
push {r0,r1,r7,lr}
```

```
mov r0,BASE
```

```
mov r1,$0F0000
```

```
bl TIMER
```

```
pop {r0,r1,r7,lr}
```

```
sub r7,#1
```

```
cmp r7,#0
```

bne loop\$

bx lr

TIMER2.asm:

Delay: ;this function has 2 parameters

TIMER_OFFSET=\$3000

mov r3,r0 ;BASE - depends on Pi model

orr r3,TIMER_OFFSET

mov r4,r1 ;\$80000 passed as a parameter

ldrd r6,r7,[r3,#4]

mov r5,r6

loopt1: ;label still has to be different from one

in _start

ldrd r6,r7,[r3,#4]

sub r8,r6,r5

cmp r8,r4

bls loopt1

bx lr ;return