				(1, 2, 3)				
x_1	x_2	x_3	f	(±, = , ⊙)	x_2	x_3	x_1	f
0	0	0	f_0		0	0	0	f_0
0	0	1	f_1		0	1	0	f_2
0	1	0	f_2		1	0	0	f_4
0	1	1	f_3		1	1	0	f_6
1	0	0	f_4		0	0	1	f_1
1	0	1	f_5		0	1	1	f_3
1	1	0	f_6		1	0	1	f_5
1	1	1	f_7		1	1	1	f_7