

# Tutorial 10

- Paper
- Pen
- Calculator

## Tutorial No. 10 for Digital Signal Processing Flow Graphs; Filter Realizations and Frequency Response

Prepared by Prof. Dr. Thuong Le-Tien  
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### Question 1.

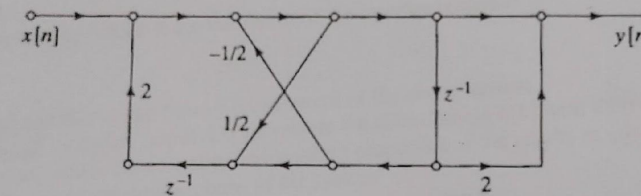
Suppose a digital filter has the transfer function as follows,

$$H(z) = \frac{1 + \frac{7}{8}z^{-1}}{1 - \frac{1}{2}z^{-1}}, \quad |z| > 1/2$$

- Find the poles and zeros then sketch the pole/zero pattern
- Find the  $h(n)$  and conclude about the causality and stability of the function?
- Sketch the frequency response of the filter
- Realize the filter in the direct form and canonical form.

### Question 2:

The flow graph shown in the figure is an implementation of a causal, LTI system



- Draw the transpose of the signal flow graph
- Determine the difference equation relating to the input signal  $x(n)$  to the  $y(n)$
- Find and sketch the pole/zero pattern of the system. Is the system stable?
- Realize the system in the direct and canonical form.
- Determine  $y(2)$  if  $x(n) = (1/2)^n u(n)$ .

### Question 3:

Consider a causal LTI system whose system function is

$$H(z) = \frac{1 - \frac{1}{5}z^{-1}}{\left(1 - \frac{1}{2}z^{-1} + \frac{1}{3}z^{-2}\right)\left(1 + \frac{1}{4}z^{-1}\right)}$$

- Draw the signal flow graphs for implementations of the system in each of following forms: Direct form I; Direct form II; Cascade form; Parallel form; Transpose direct form II.
- Write the difference equations
- Sketch Pole and zero pattern
- Conclusion about the stability of the system?

**Question 1.**

Suppose a digital filter has the transfer function as follows,

$$H(z) = \frac{1 + \frac{7}{8}z^{-1}}{1 - \frac{1}{2}z^{-1}}, \quad |z| > 1/2$$

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# Q1 (answer)

pole =  $\frac{1}{2}$

zero =  $-\frac{7}{8}$

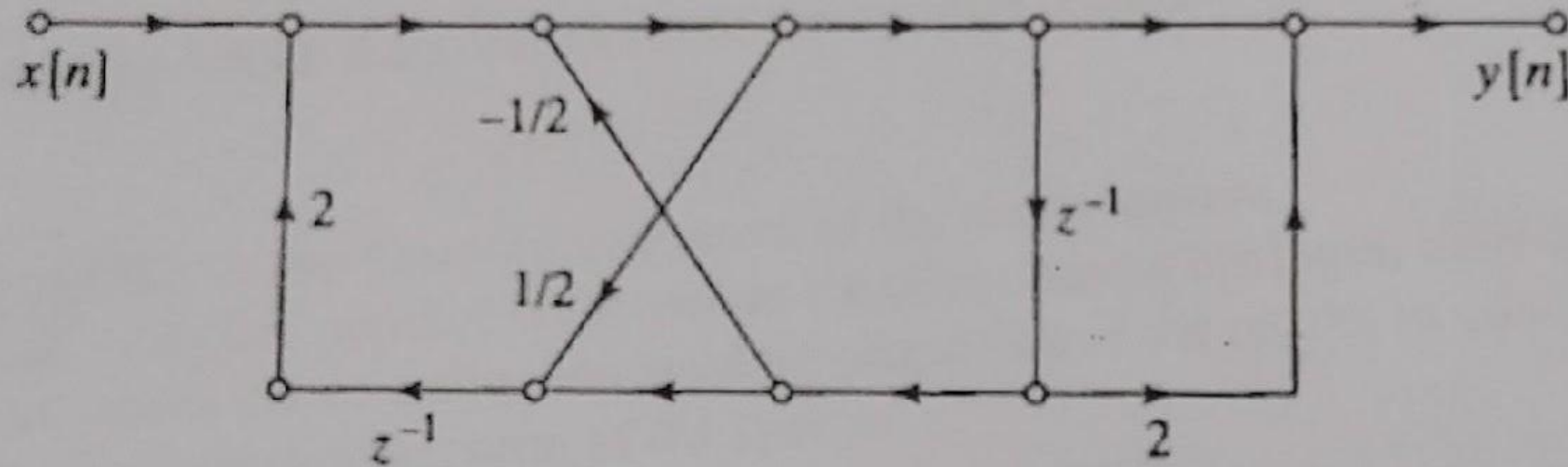
$$H(z) = A + B/(1 - 0.5z^{-1}) \rightarrow h(n) = A\delta(n) + B \times 0.5^n u(n)$$

$$H(w) = H(z=e^{jw})$$

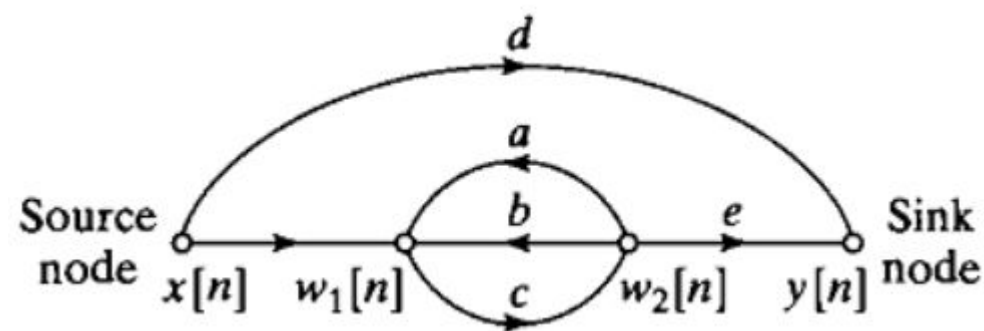
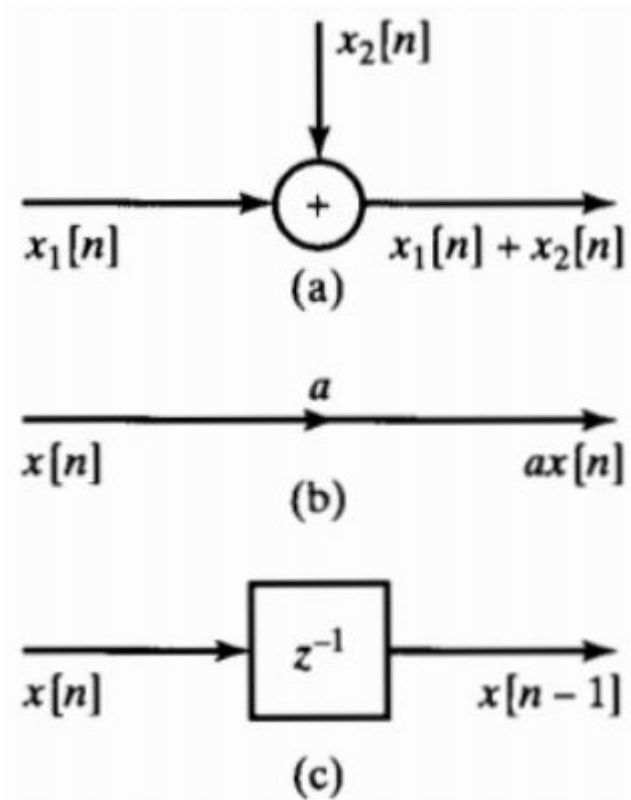
- $H(z) = \dots = (b_0 + b_1 \cdot z^{-1} + b_2 \cdot z^{-2} + \dots) / (1 + a_1 \cdot z^{-1} + a_2 \cdot z^{-2} + \dots)$

### Question 2:

The flow graph shown in the figure is an implementation of a causal, LTI system



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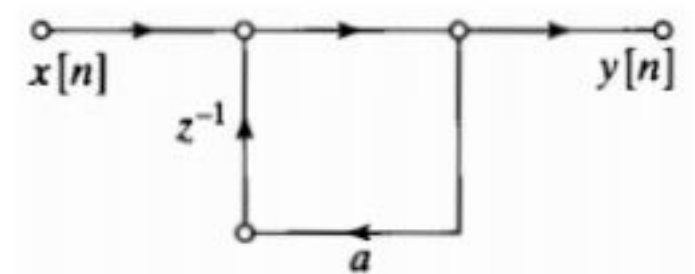
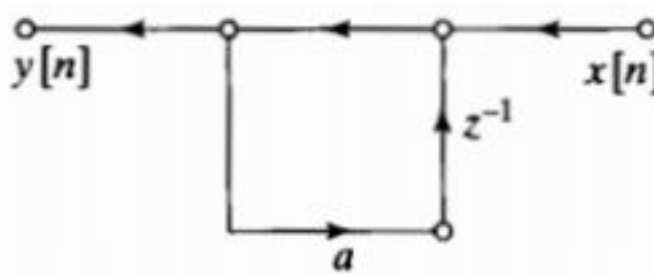
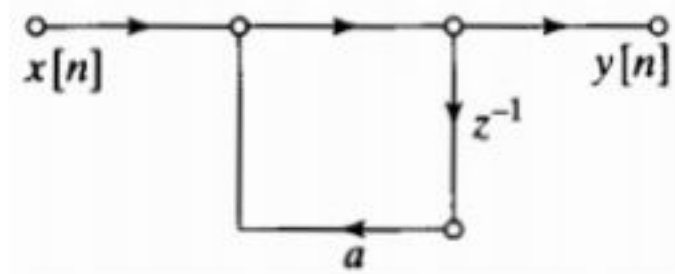


$$w_1[n] = x[n] + aw_2[n] + bw_2[n],$$

$$w_2[n] = cw_1[n],$$

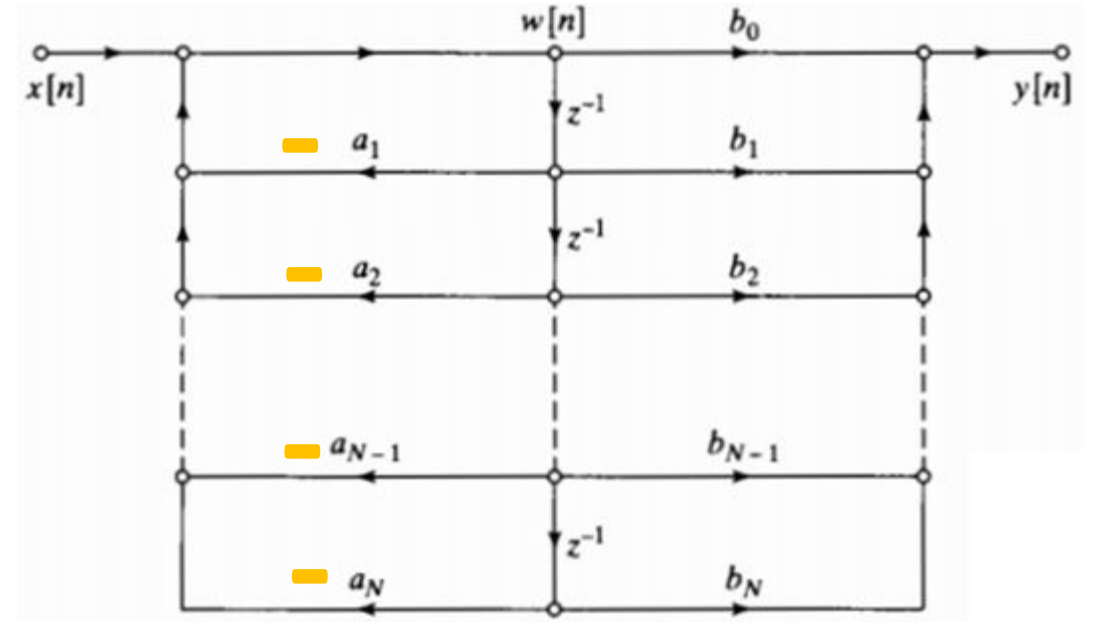
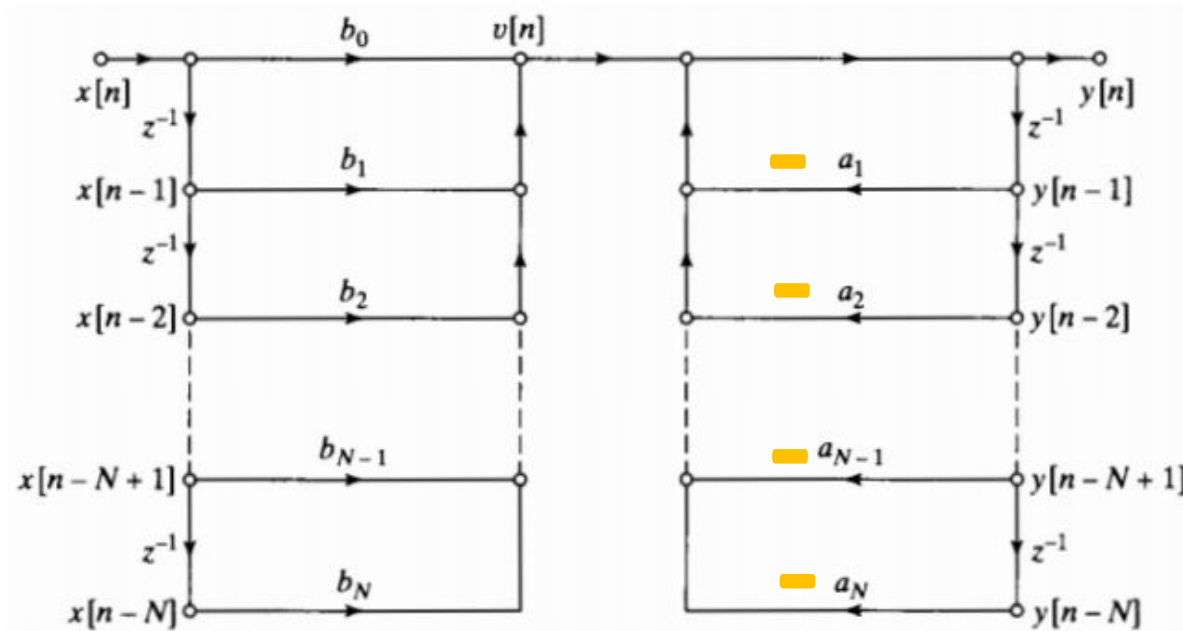
$$y[n] = dx[n] + ew_2[n].$$

# Transposed form



- $x[n] \leftrightarrow y[n]$
- arrow: inverse
- Result: the same

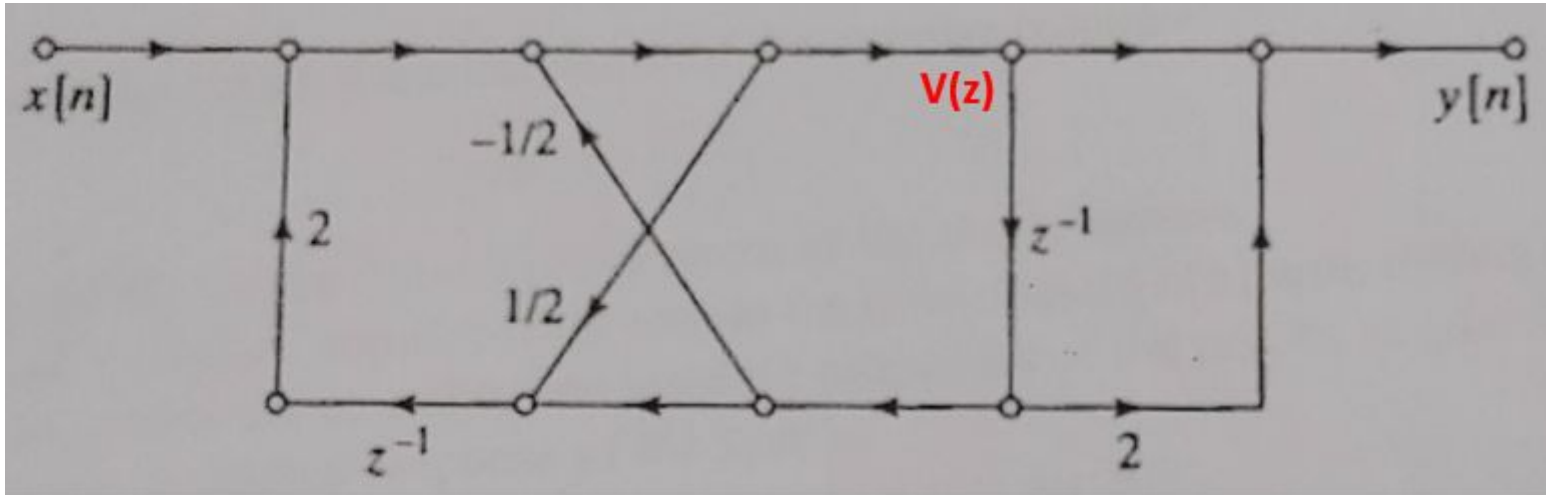
# Direct form (I) and canonical form (direct II)



$$H(z) = \frac{N(z)}{D(z)} = \frac{b_0 + b_1 z^{-1} + b_2 z^{-2} + \dots + b_L z^{-L}}{\mathbf{1}_0 + a_1 z^{-1} + a_2 z^{-2} + \dots + a_M z^{-M}}$$

$$\mathbf{y}_n = -a_1 y_{n-1} - a_2 y_{n-2} - \dots - a_M y_{n-M} + b_0 x_n + b_1 x_{n-1} + b_2 x_{n-2} + \dots + b_L x_{n-L}$$

## Q2 (answer)



b)  $H(z) = Y(z)/X(z) = (1 + 2z^{-1})/(1 - 0.5z^{-1} - 2z^{-2})$  □ different equation

e)  $h(n) = 0.5h(n-1) + 2h(n-2) + \delta(n) + 2\delta(n-1)$

•causal □  $h(n < 0) = 0$ ,  $h(0) = 1$ ,  $h(1) = 2.5$ ,  $h(2) = 3.25$

• $y(2) = x(0).h(2) + x(1).h(1) + x(2).h(0) = 3.25 + 1.25 + 0.25 = 4.75$



### Question 3:

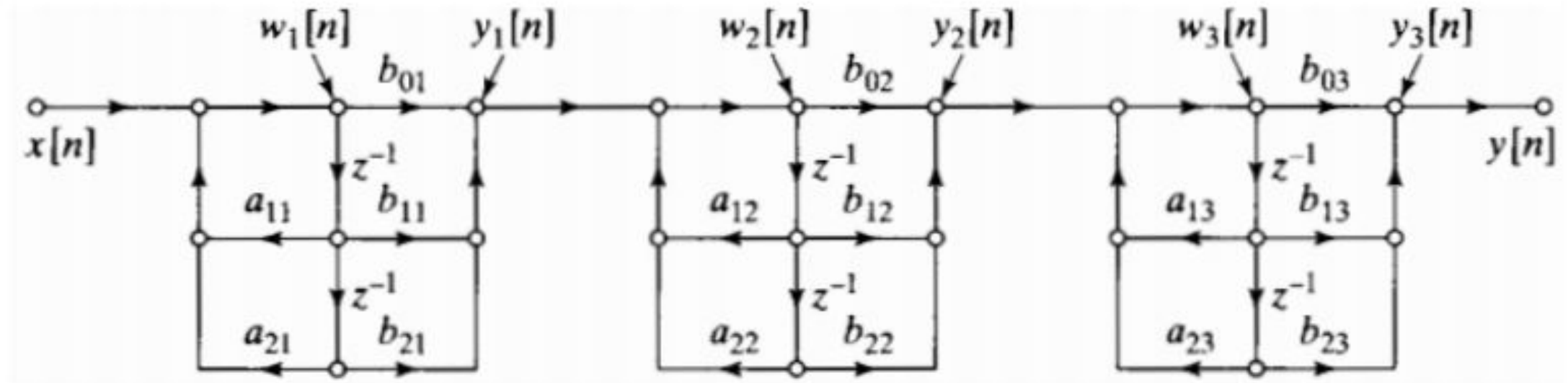
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# Cascade form (Second Order Section)

$$H(z) = \prod_{k=1}^{N_s} \frac{b_{0k} + b_{1k}z^{-1} + b_{2k}z^{-2}}{1 - a_{1k}z^{-1} - a_{2k}z^{-2}},$$



# Parallel form

$$H(z) = \sum_{k=0}^{N_p} C_k z^{-1} + \sum_{k=1}^{N_1} \frac{A_k}{1 - c_k z^{-1}} + \sum_{k=1}^{N_2} \frac{B_k(1 - e_k z^{-1})}{(1 - d_k z^{-1})(1 - d_k^* z^{-1})},$$

