

Tutorial 9

- Paper
- Pen
- Calculator

Question 1:

When the input to a causal LTI system is $x(n) = -\frac{1}{3}\left(\frac{1}{2}\right)^n u(n) - \frac{4}{3}2^n u(-n-1)$ and the z-

transform of the output is $Y(z) = \frac{1+z^{-1}}{(1-z^{-1})(1+0.5z^{-1})(1-2z^{-1})}$

- Discuss about the causality property of the input $x(n)$ then find the z-transform of $x(n)$
- Find and sketch the pole/zero pattern for the $X(z)$; $Y(z)$
- What is the region of convergence of $Y(z)$?
- Find the causal impulse response of the system
- Is the system stable?
- Realize the system in the canonical form.

Question 2:

The given system for which the z-transform of the impulse response is

$$H(z) = \frac{1-z^3}{1-z^4}$$

- Find and sketch the Poles/Zeros Pattern of the above system.
- Find all available impulse responses in the time domain $h[n]$ with their ROCs
- Discuss about the causality and stability properties of the results in question 2(b)
- Draft the frequency response of the system.
- Realize the block diagram of the system in direct form.

Question 3:

A given causal LTI system with the frequency response

$$H(e^{j\omega}) = \left(1 + 0.4e^{-j(\omega+\pi)}\right) \left(\frac{1 + \frac{1}{2}e^{-2j\omega}}{1 + e^{-2j\omega} + \frac{1}{4}e^{-4j\omega}} \right) \quad -\pi < \omega \leq \pi$$

- Find the $H(z)$?
- Is the system is FIR or IIR filter? Explain?
- Find the I/O equation of the system?
- Sketch the pole/zero pattern of the $H(z)$ then specify the ROC and stability?
- Based on the pole/zero pattern, draft the amplitude of the given frequency response of the system?
- Realize the block diagram of the system?

Question 1:

When the input to a causal LTI system is $x(n) = -\frac{1}{3}\left(\frac{1}{2}\right)^n u(n) - \frac{4}{3}2^n u(-n-1)$ and the z-

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Q1 (answer)

- $X(z) = ?$
- $H(z) = Y(z)/X(z) = \dots = A_1/(1-p_1z^{-1}) + A_2/(1-p_2z^{-1}) + \dots + B_0 + B_1z^{-1} + \dots$
- Causal $h(n) = A_1 \cdot p_1^n u(n) + A_2 \cdot p_2^n u(n) + \dots + B_0 \delta(n) + B_1 \delta(n-1) + \dots$

Question 2:

Consider an LTI system that is stable and for which $H(z)$, the z-transform of the impulse response, is given by

$$H(z) = \frac{2 - 4z^{-1} + 2z^{-2}}{1 + 3z^{-1} - 4z^{-2}}$$

Suppose $x(n)$, the input to the system, is a unit step sequence.

- Find the output $y(n)$ by evaluating the discrete convolution of $x(n)$ and $y(n)$
- Find the output $y(n)$ by computing the inverse z-transform of $Y(z)$
- Sketch the Pole/zero pattern of $H(z)$ and the magnitude of the frequency response
- Realize the above filter with the direct form and Canonical form.

$$H(z) = \frac{2 - 4z^{-1} + 2z^{-2}}{1 + 3z^{-1} - 4z^{-2}}$$

- $H(z) = \dots = A_1/(1-p_1z^{-1}) + A_2/(1-p_2z^{-1}) + B_0$
- $H(z) = 2(1-z^{-1})^2/\{(1-z^{-1})(1+4z^{-1})\} = (2-2z^{-1})/(1+4z^{-1}) = A_1/(1+4z^{-1}) + B_0$
- Stable \square ROC contains the unit circle $\square \text{ROC}_H = \{|z| < |-4|\} = \{|z| < 4\}$
- $\square h(n) = B_0 \delta(n) - A_1(-4)^n u(-n-1)$
- $y(n) = x(n) * h(n) = u(n) * h(n)$
- $Y(z) = H(z).X(z) = \{2(1-z^{-1})/(1+4z^{-1})\}.1/(1-z^{-1}) = 2/(1+4z^{-1})$
- $\text{ROC}_Y = \text{ROC}_X \cap \text{ROC}_H = \{|z| < 4\}$
- $\square y(n) = -2(-4)^n u(-n-1)$

Question 3.

- a. Determine the unit step response of the causal system for which the z-transform of the impulse response is $H(z) = \frac{1 - z^3}{1 - z^4}$
- b. Realize the above filter with the direct form and Canonical form

$$x(n) = u(n) \rightarrow X(z) = 1/(1 - z^{-1}) = z/(z - 1), \text{ ROC}_X = \{|z| > 1\}$$

$$\text{causal system} \rightarrow \text{ROC}_H = \{|z| > 1\}$$

$$\rightarrow \text{ROC}_Y = \text{ROC}_X \cap \text{ROC}_H = \{|z| > 1\}$$

$$\rightarrow Y(z) = H(z).X(z) = -(1 + z + z^2)z / \{(1 - z).(1 + z).(1 + z^2)\}$$

$$= (z^{-3} + z^{-2} + z^{-1}) / \{(1 - z^{-1}).(1 + z^{-1}).(1 + z^{-2})\} = \dots = A_1/(1 - p_1 z^{-1}) + A_2/(1 - p_2 z^{-1}) + A_3/(1 - p_3 z^{-1}) + A_4/(1 - p_4 z^{-1})$$

$$\square y(n) = A_1 p_1^n u(n) + \dots$$

Question 3.

- a. Determine the unit step response of the causal system for which the z-transform of the impulse response is $H(z) = \frac{1 - z^3}{1 - z^4}$
- b. Realize the above filter with the direct form and Canonical form

- $y(n) = h(n) * x(n)$
- $H(z) = (1+z+z^2)/\{(1+z).(1+z^2)\} = (z^{-3}+z^{-2}+z^{-1})/\{(1+z^{-1}).(1+z^{-2})\} = \dots = B_1/(1-p_1z^{-1}) + B_2/(1-p_2z^{-1}) + B_3/(1-p_3z^{-1}) + B_0$
- Causal $\square h(n) = B_1p_1^n u(n) + \dots + B_0\delta(n)$
- $(1-z^4)H(z) = 1 - z^3 \square h(n) - h(n+4) = \delta(n) - \delta(n+3) \quad (m=n+4 \square n=m-4)$
- $\square h(m-4) - h(m) = \delta(m-4) - \delta(m-1) \quad (n=m)$
- $\square h(n-4) - h(n) = \delta(n-4) - \delta(n-1) \square h(n) = h(n-4) - \delta(n-4) + \delta(n-1) \square$
- $h(n < 0) = 0$ (causal), $h(0) = 0$, $h(1) = 1$, $h(2) = 0$, $h(3) = 0$, $h(4) = -1$, $h(5)=h(1)=1$, ...

Question 2:

The given system for which the z-transform of the impulse response is

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- Find and sketch the Poles/Zeros Pattern of the above system.
- Find all available impulse responses in the time domain $h[n]$ with their ROCs
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Q2 (answer)

- $H(z) = \dots = A_1/(1-p_1z^{-1}) + A_2/(1-p_2z^{-1}) + A_3/(1-p_3z^{-1})$
- $|p_1|=|p_2|=|p_3|=1$
- $\square \text{ ROC}_1 = |z|>1 : h_1(n) = A_1 \cdot p_1^n u(n) + A_2 \cdot p_2^n u(n) + A_2 \cdot p_3^n u(n)$, causal, margin stable
- and $\text{ROC}_2 = |z|<1 : h_2(n) = -A_1 \cdot p_1^n u(-n-1) - A_2 \cdot p_2^n u(-n-1) - A_2 \cdot p_3^n u(-n-1)$, anticausal, margin stable
- Frequency response $H(w) = H(z=e^{jw}) = \dots \quad \square \text{ period } 2\pi$
 - $|H(w)|$
 - $\arg H(w)$
- Block diagram: $H(z) = (b_0 + b_1 \cdot z^{-1} + b_2 \cdot z^{-2} + \dots) / (1 + a_1 \cdot z^{-1} + a_2 \cdot z^{-2} + \dots)$

Question 3:

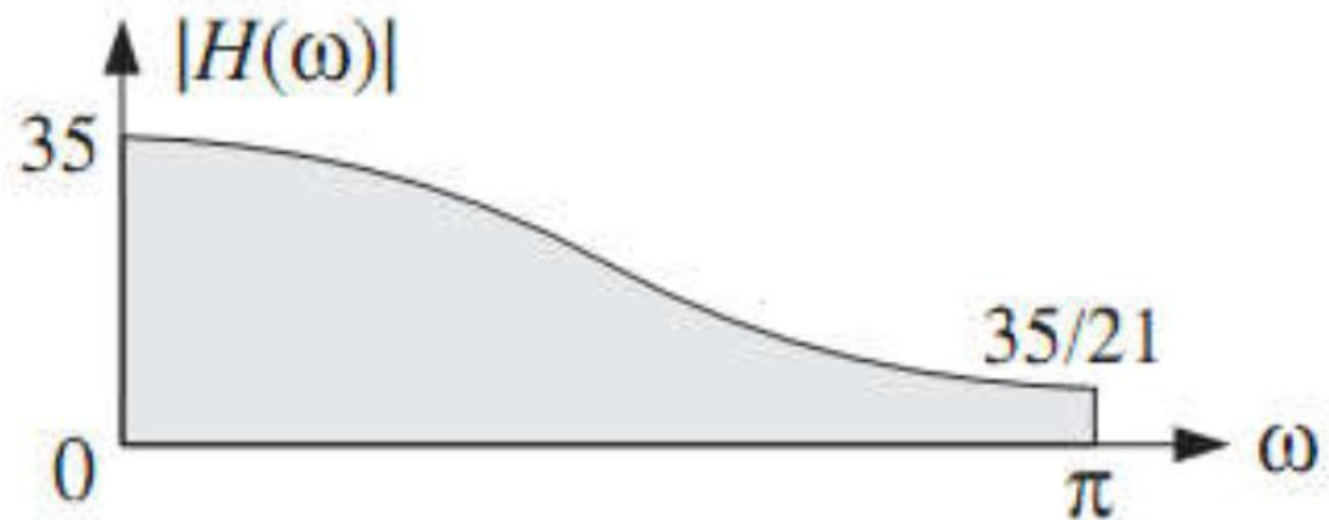
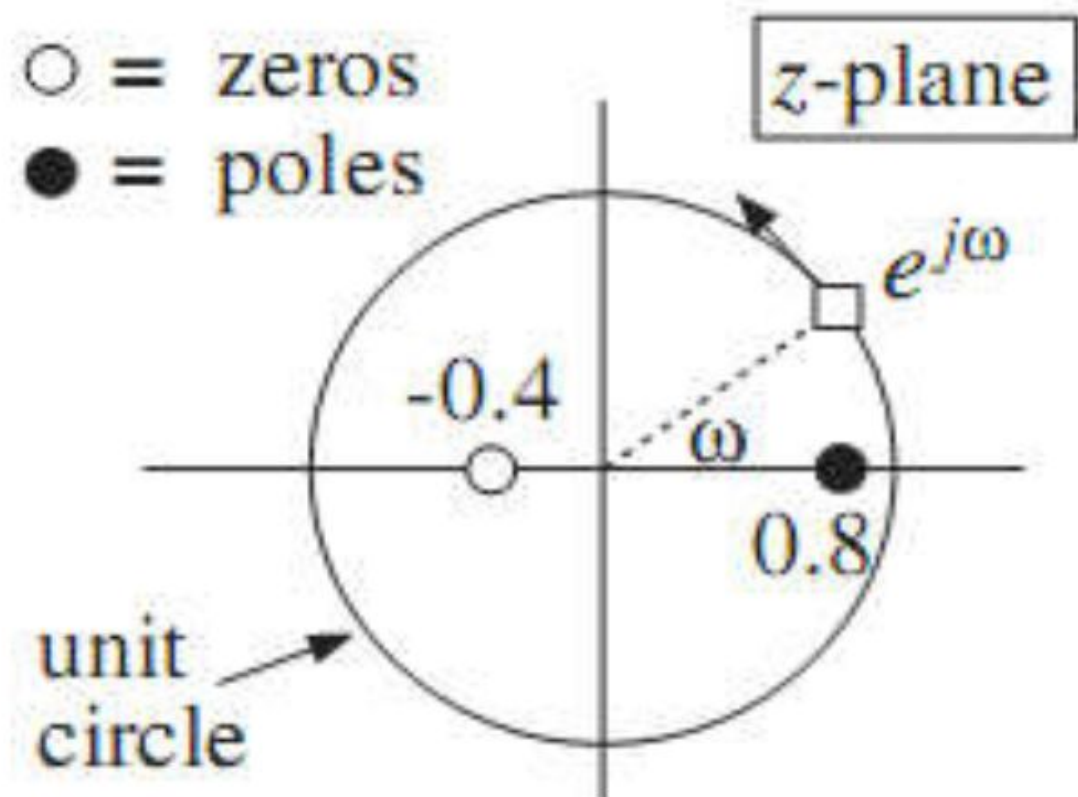
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Q3 (answer)

- $z = e^{j\omega}$
- $e^{-j\omega} = z^{-1}$
- $e^{-2j\omega} = z^{-2}$
- $e^{-j(\omega+\pi)} = e^{-j\omega} \cdot (e^{-j\pi}) = -z^{-1}$
- $H(z) = \dots = Y(z)/X(z) = (b_0 + b_1 \cdot z^{-1} + b_2 \cdot z^{-2} + \dots) / (1 + a_1 \cdot z^{-1} + a_2 \cdot z^{-2} + \dots)$
- I/O equation: $y(n) = b_0 x(n) + b_1 x(n-1) + b_2 x(n-2) + \dots - a_1 y(n-1) - a_2 y(n-2) - \dots$
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Pole/zero pattern and magnitude response