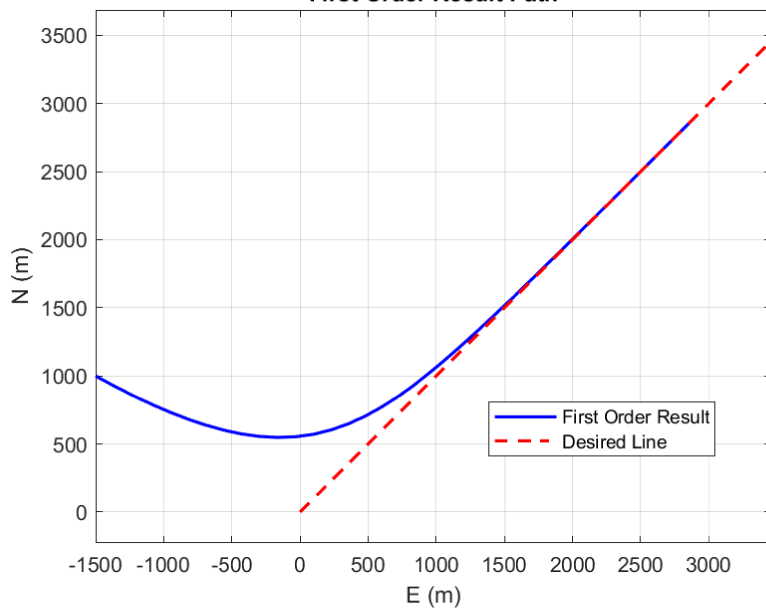
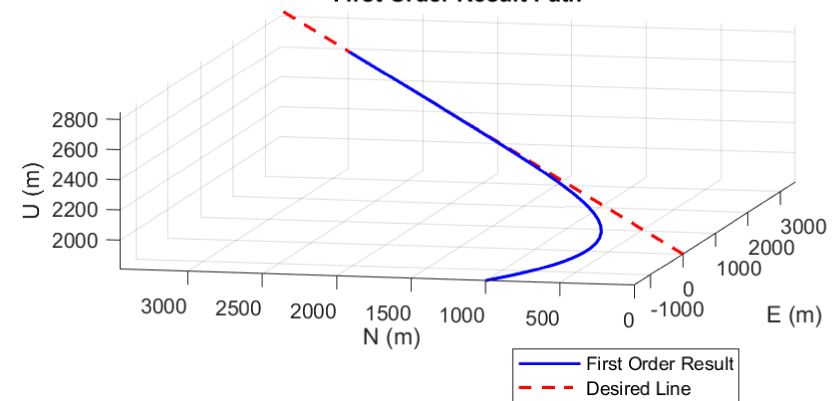


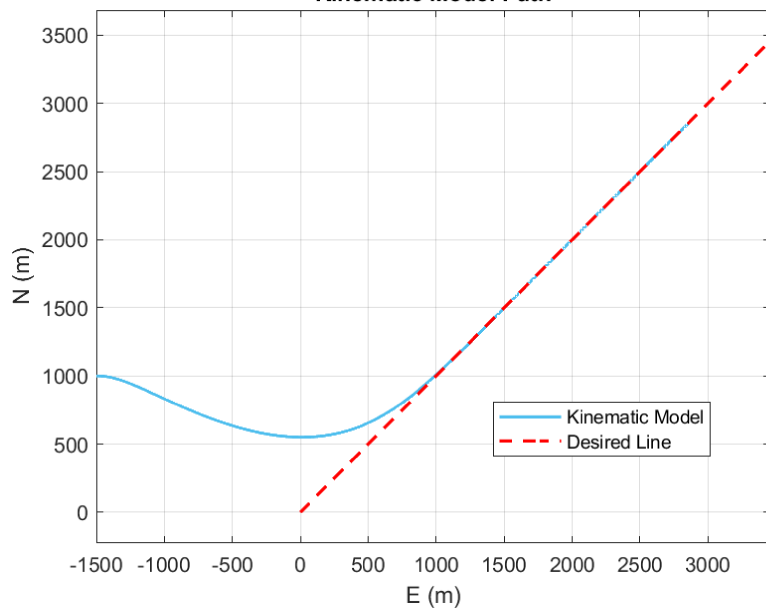
First Order Result Path



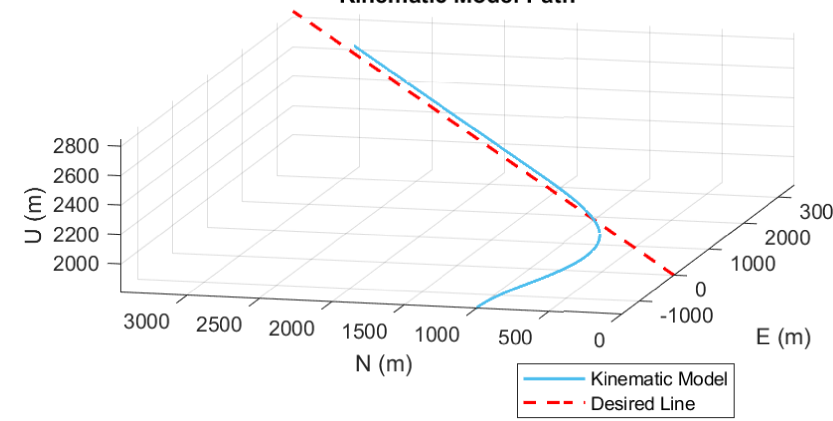
First Order Result Path



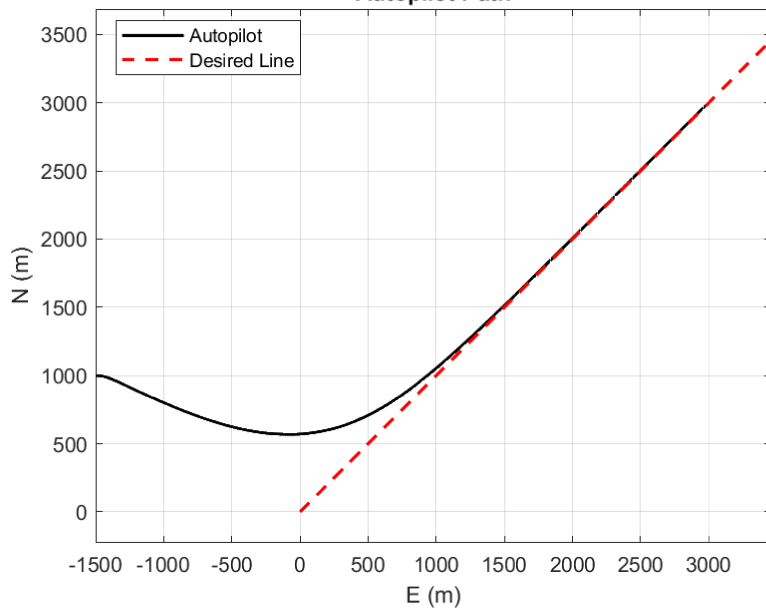
Kinematic Model Path



Kinematic Model Path



Autopilot Path



Autopilot Path

