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Hw3

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```
close all; clear; clc;
```

Problem 1

Constants

```
ks = 10000;           % N/m
kw = 500000;          % N/m
b = 9800;              % Ns/m
m2 = 350;              % kg
m1 = 10;               % kg

% Linear Time Invariant System
A = [-b/m1, b/m1, -1/m1, 1/m1;
      b/m2, -b/m2, 0, -1/m2;
      kw, 0, 0, 0;
      -ks, ks, 0, 0];

B = [0; 0; -kw; 0];

C = [0, 1, 0, 0];

D = 0;

% Calculate the eigenvalues
[vecs, vals] = eig(A);

% Simulate system
sys = ss(A, B, C, D);

% Step and impulse responses
[y_step, t_step] = step(sys);
[y_imp, t_imp] = impulse(sys);

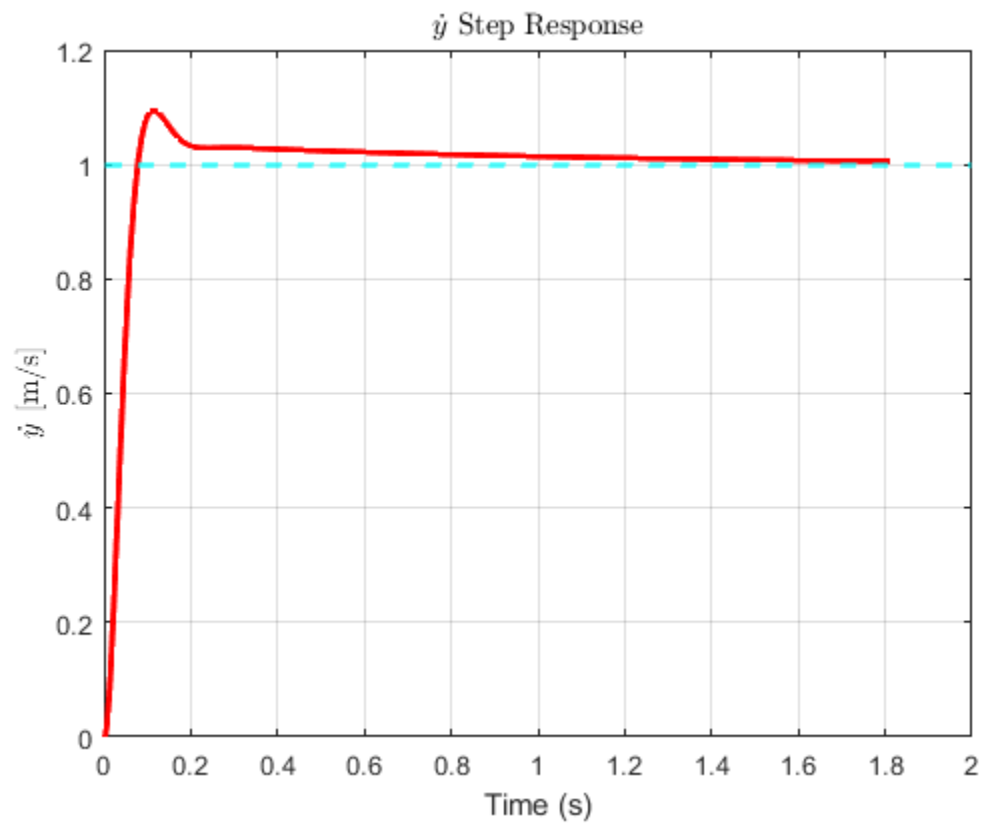
% Step response
figure();
plot(t_step, y_step, 'r', 'LineWidth', 2);
grid on;
hold on;
yline(1, 'color', 'c', 'LineWidth', 2, 'LineStyle', '--')
```

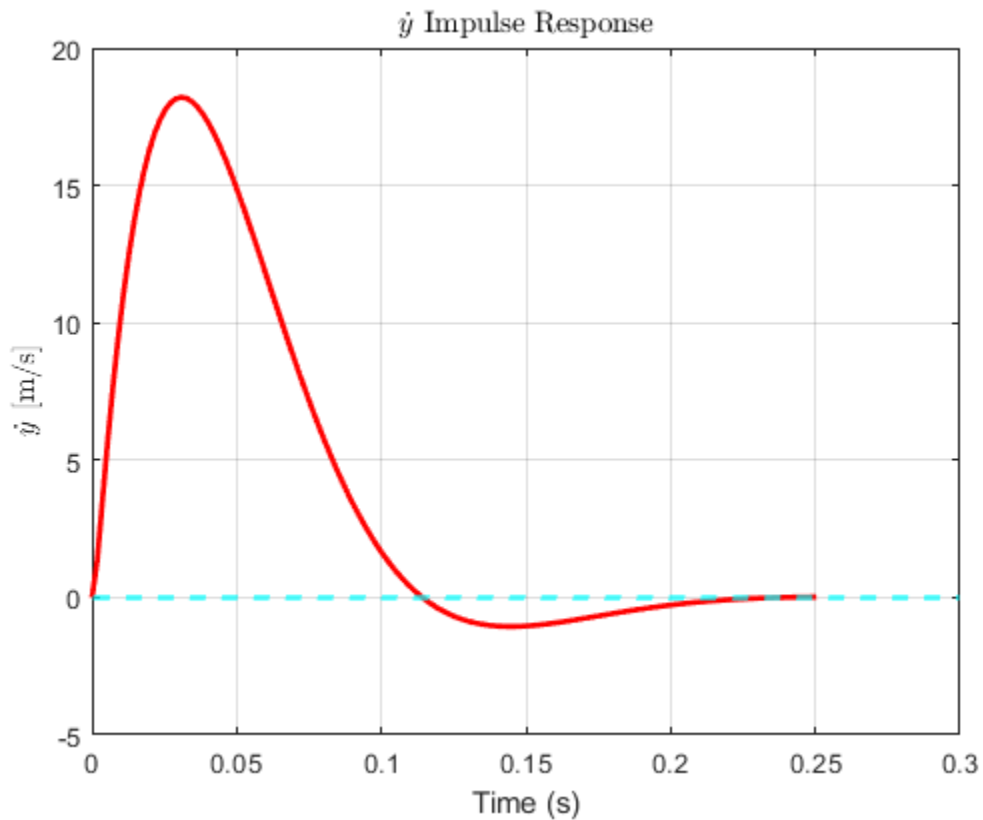
```

title('$\dot{y}$ Step Response', 'Interpreter','latex');
xlabel('Time (s)');
ylabel('$\dot{y}$ [m/s]', 'Interpreter','latex');

% Impulse response
figure();
plot(t_imp, y_imp, 'r', 'LineWidth', 2);
grid on;
hold on;
yline(0, 'color', 'c', 'LineWidth', 2, 'LineStyle', '--')
title('$\dot{y}$ Impulse Response', 'Interpreter','latex');
xlabel('Time (s)');
ylabel('$\dot{y}$ [m/s]', 'Interpreter','latex');

```





Problem 3

```
La = 10 / 1000;      % H
Ra = 1;               % ohm
J1 = 0.1;             % kg m^2
J2 = 1;               % kg m^2
k = 10;               % Nm/rad
b = 0.01;             % Nms/rad
kt = 1;               % Nm/A
ke = 1;               % Vs/rad
B = 0.01;             % Nms/rad

% Create state space
A = [-Ra/La, 0, -ke/La, 0, 0;
      0, 0, 1, 0, 0;
      kt/J1, -k/J1, -(B+b)/J1, k/J1, b/J1;
      0, 0, 0, 0, 1;
      0, k/J2, b/J2, -k/J2, -b/J2];

B = [1/La; 0; 0; 0; 0];

C = [0, 1, 0, 0, 0];

D = [0];
```

```
% Eigenvalues  
[vecs, vals] = eig(A);
```

```
% Simulate  
% sys = ss(A, B, C, D);  
% figure()  
% impulse(sys);
```

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