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Clean

```
close all; clear; clc;
```

Problem 1

```
Rm = 19.2; % ohm
Lm = 1.9 / 1000; % H
Kt = 40.1 / 1000; % Nm/A
Jm = 12.5 / (1000 * 100^2); % kgm^2
Kb = 1/238 * 1/(2*pi) * 60; % V/(rad/s)
N = 10 * 120 / 36;

% Load moment of inertia
% Brass
b1 = 1.9;
b2 = 1.5;
b3 = 3.8;
b_rho = 8.73;
b_mass = 2 * b1*b2*b3 * b_rho / 1000; % kg
r_brass = 26.5 / 100; % m
I_brass = b_mass * r_brass^2; % kg m^2

% Aluminium
a1 = 1.1;
a2 = 0.6;
a3 = 27.5;
a_rho = 2.7;
a_mass = a1*a2*a3 * a_rho / 1000; % kg
r_aluminium = a3 / 2 / 100; % m
I_aluminium = a_mass * r_aluminium^2; % kgm^2

% Aluminium square
a_mass_2 = 16 * 0.6 * a_rho / 1000;
I_aluminium_2 = 1/12 * a_mass_2 * ((4/100)^2 + (4/100)^2);

Jl = I_brass + I_aluminium + I_aluminium_2;
Jeq = Jl + N^2 * Jm;

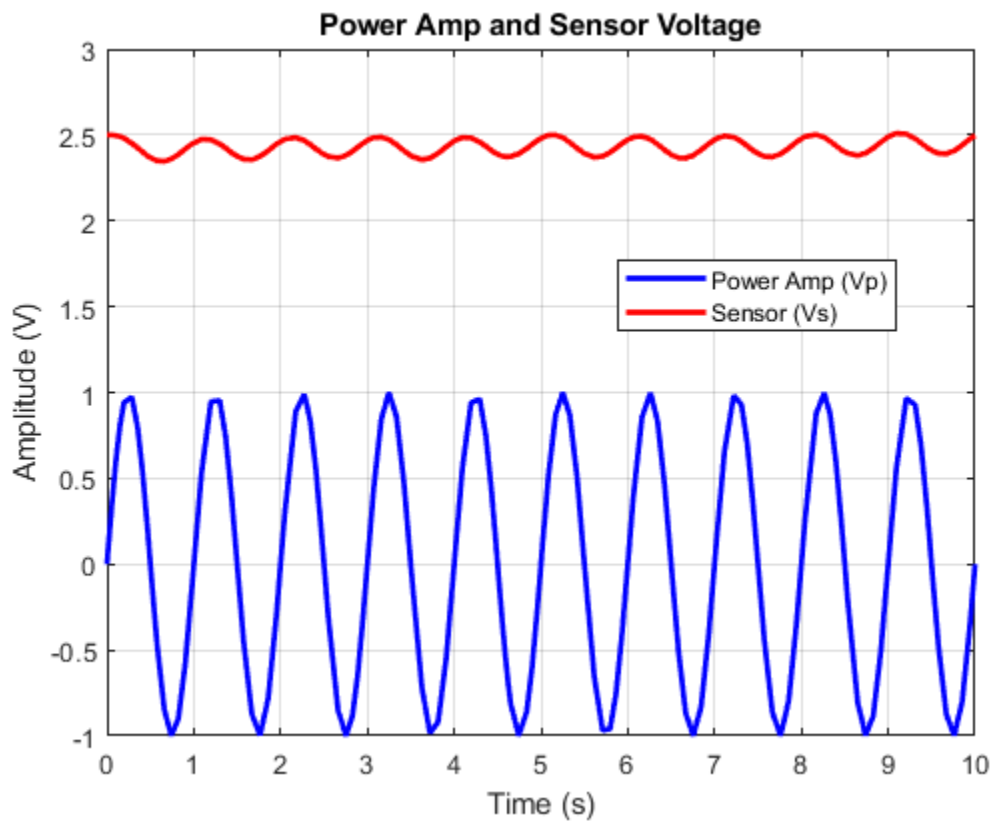
% Potentionmeter scale factor
dataKs = [-pi/2, 1.25; 0, 2.488; pi/2, 3.76];
coeff = polyfit(dataKs(:,1), dataKs(:,2), 1);
xPlot = linspace(-pi, pi, 100);
```

```
yPlot = polyval(coeff, xPlot);  
Ks = coeff(1);
```

Problem 2

```
num_thetaVp = [-1];  
den_thetaVp = [Jeq*Lm / (Kt*N), Jeq*Rm / (Kt*N), Kb*N, 0];  
output_prob2 = sim('theta_vp.slx');  
t = output_prob2.t;  
u = output_prob2.u;  
y = output_prob2.y;
```

```
figure();  
plot(t, u, 'linewidth', 2, 'color', 'b');  
hold on  
grid on  
plot(t, y, 'linewidth', 2, 'color', 'r');  
  
xlabel('Time (s)')  
ylabel('Amplitude (V)')  
title('Power Amp and Sensor Voltage')  
legend('Power Amp (Vp)', 'Sensor (Vs)', 'location', 'best')
```



Problem 5/6

Transfer function theta R and theta L

```
Gp = -10;
Gd = -0.1;

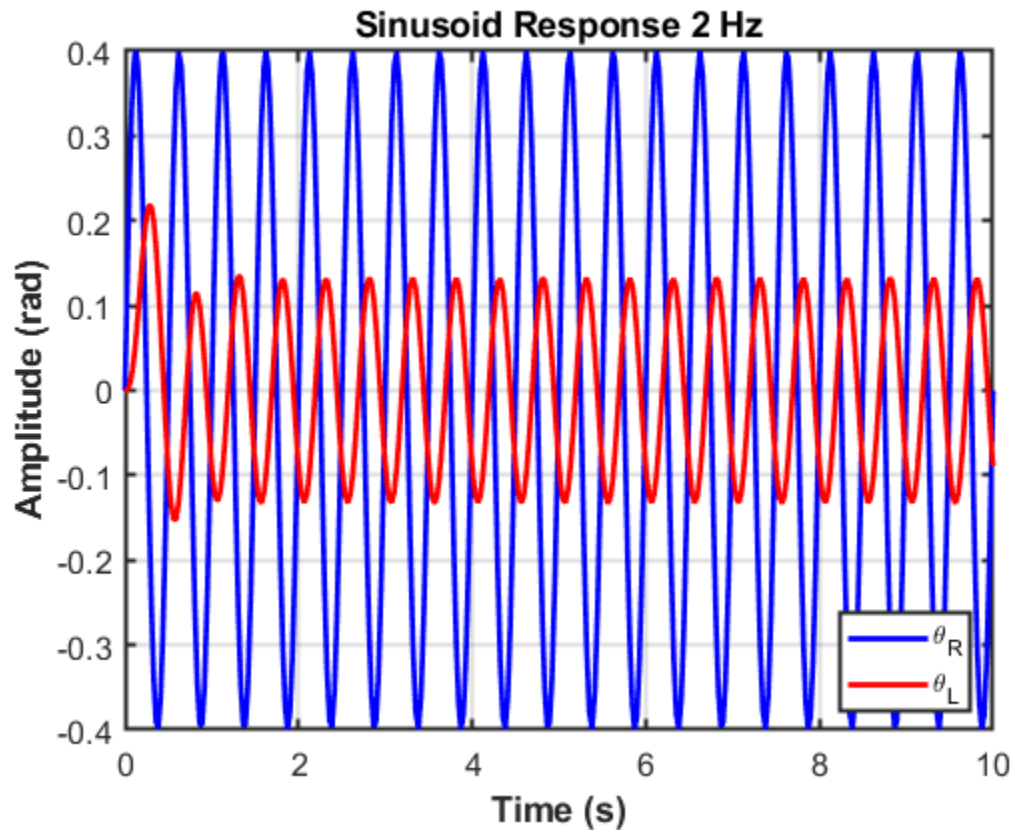
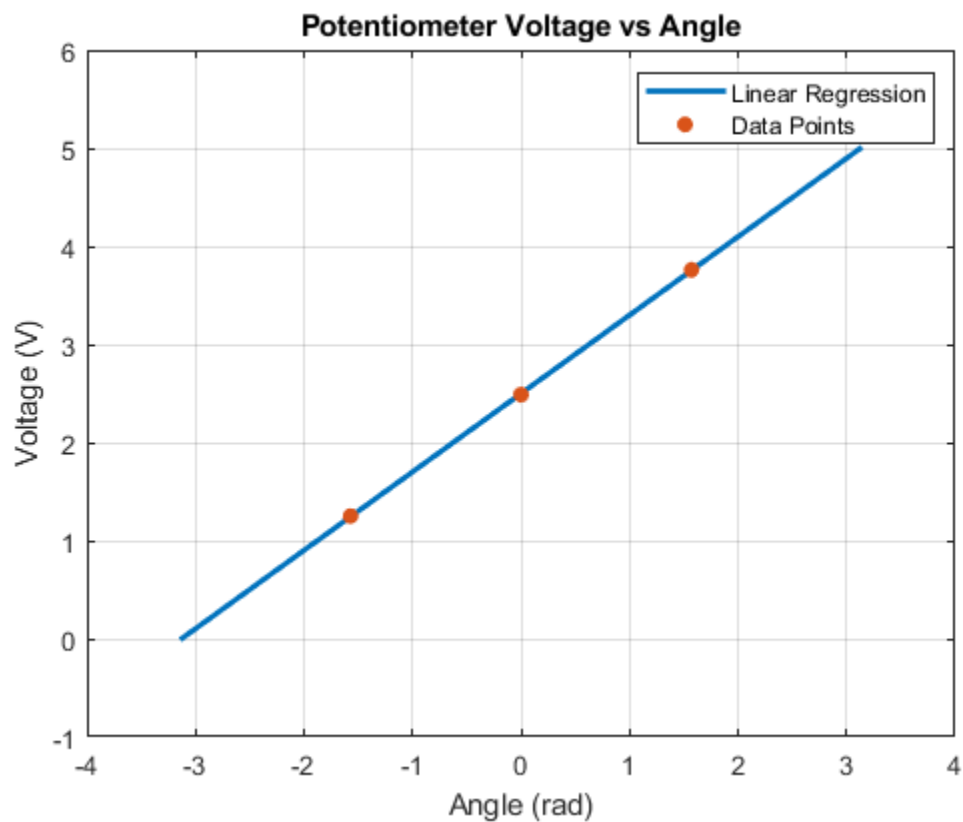
% Call the simulink model
output = sim('thetaRef_thetaL.slx');
t = output.t;
thetaR = output.thetaR;
thetaL = output.thetaL;
Vp = output.Vp;

% Potentiometer voltage
figure();
plot(xPlot, yPlot, 'linewidth', 2);
hold on;
scatter(dataKs(:,1), dataKs(:,2), 'filled')
grid on
xlabel('Angle (rad)')
ylabel('Voltage (V)')
title('Potentiometer Voltage vs Angle')
legend('Linear Regression', 'Data Points')

% System Response
figure();
plot(t, thetaR, 'b-', 'LineWidth', 2); % Blue solid line, thicker
hold on;
plot(t, thetaL, 'r', 'LineWidth', 2); % Red dashed line, thicker

xlabel('Time (s)', 'FontSize', 12, 'FontWeight', 'bold');
ylabel('Amplitude (rad)', 'FontSize', 12, 'FontWeight', 'bold');
title('Sinusoid Response 2 Hz', 'FontSize', 14, 'FontWeight', 'bold');

legend('\theta_R', '\theta_L', 'Location', 'best', 'FontSize', 10);
grid on; % Enable grid for better readability
xlim([min(t), max(t)]); % Adjust x-axis limits based on data
ylim auto; % Auto-scale y-axis
set(gca, 'FontSize', 12, 'LineWidth', 1.5); % Improve axis appearance
```



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