Mining Graph Data

# LINK PREDICTION

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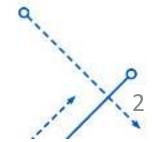
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### Content

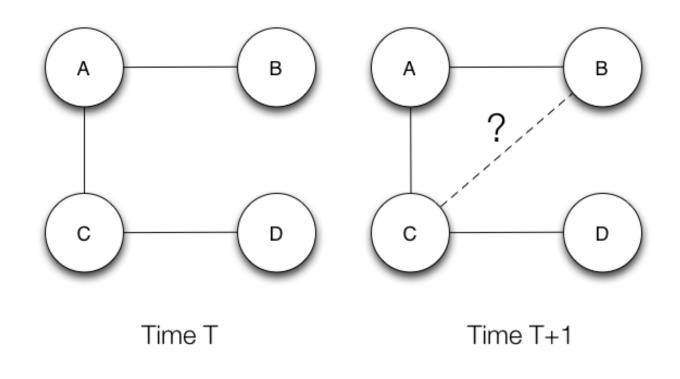
- Link prediction
- Learn in link prediction
  - Unsupervised learning
  - Supervised learning

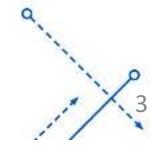


# Link prediction

#### Link prediction problem:

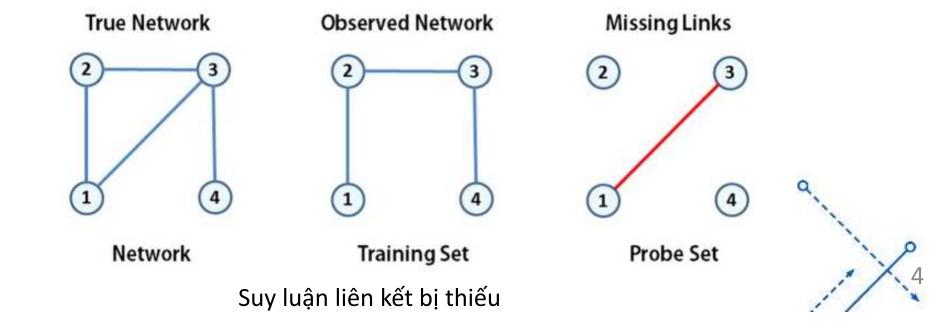
 Given the links in the graph at time, predict the edges that will be added to the graph between and time ' in the future.



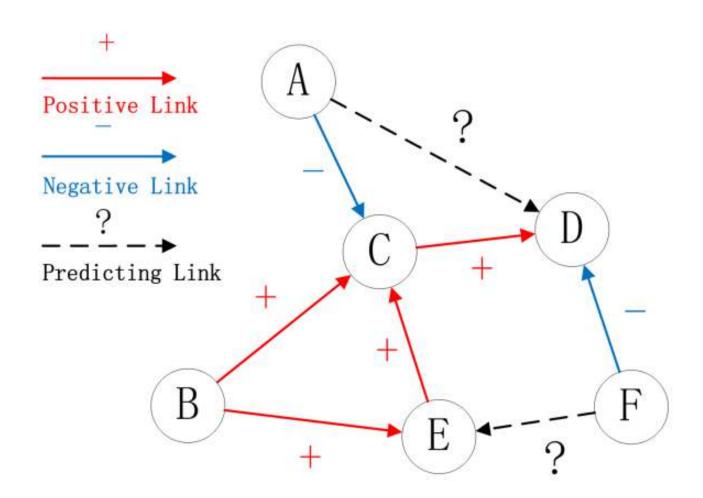


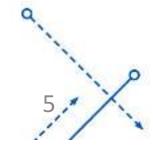
### Link inference is missing

- Association prediction differs from missing (hidden) association inference in that:
  - Link prediction to find links that appear over time
  - Missing association inference to find extra links in static graph.



# Link prediction





# **Application**

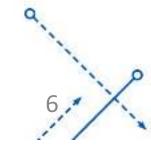
- Suggestions for making friends in social networks
- Predicting connections between members of a terrorist organization
  - facebook
- Proposal for cooperation among researchers
- Suggest the article should be referenced to



Predicting interactions of proteins

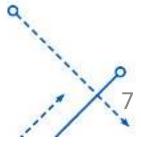






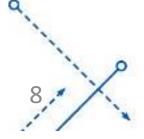
# Link prediction

- The link prediction process is to calculate the score score(u,v) for each pair of  $\langle u,v \rangle$ , then rank it to choose the v with the highest measure to connect with u.
- Usually divided into three groups:
  - Estimation method based on neighbor vertex: number of common neighbors, Jaccard coefficient, Adamic-Adar, path, ...
  - Methods based on all paths: PageRank, SimRank
  - From another method: bigram, clustering

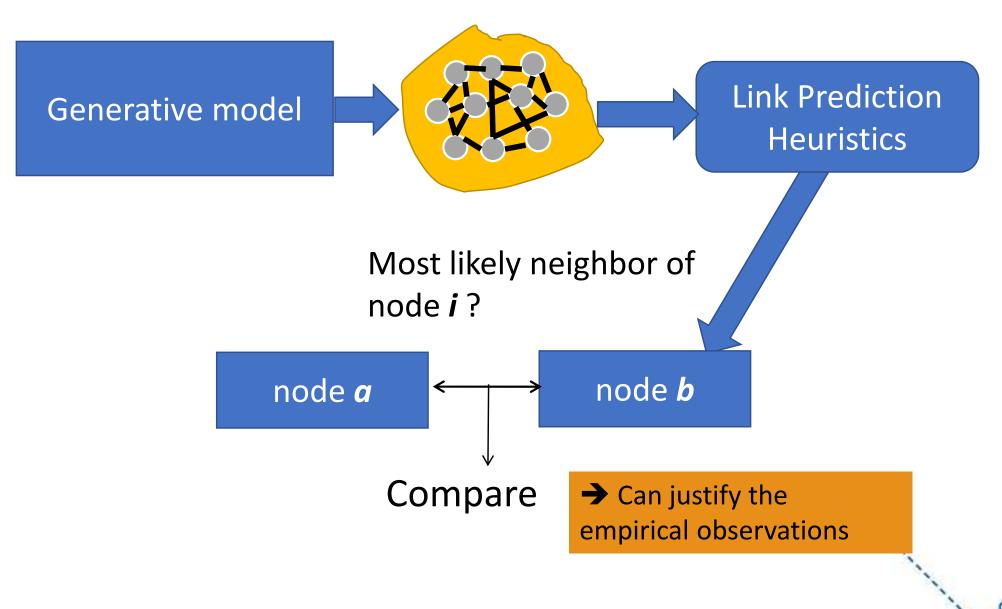


### General pattern

- Step 1: calculate the vertex distance based on some measurement methods such as Jaccard, shortest path, ...
- Step 2: choose a number of pairs of vertices with the closest distance
- Step 3: predict new edge from selected pairs
- Step 4: evaluate the predicted graph with the original graph



# General pattern

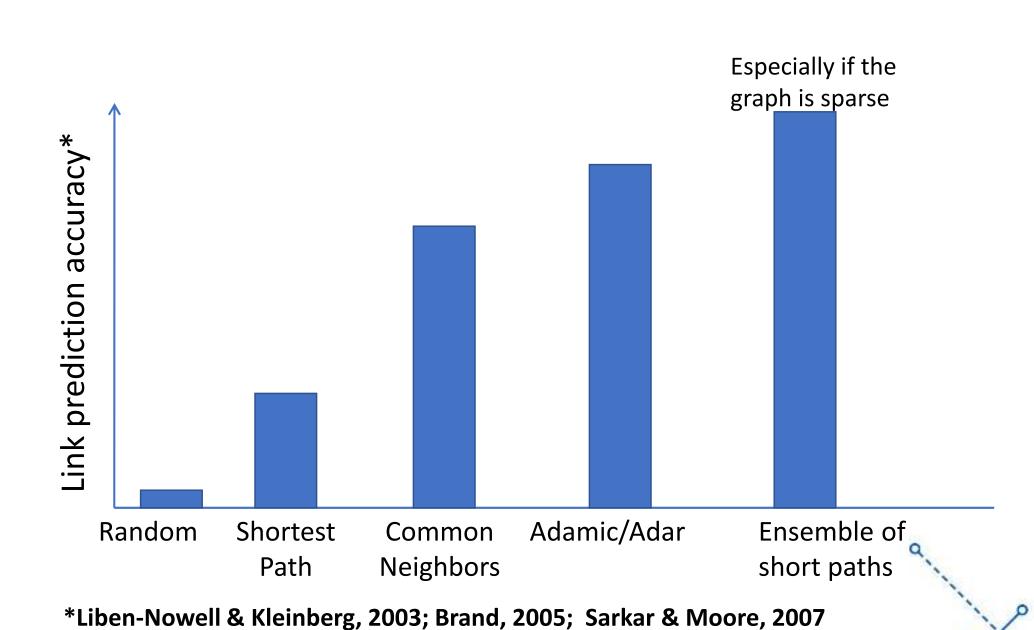


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# Link prediction

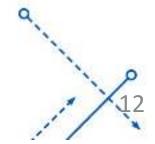
graph distance	(negated) length of shortest path between $x$ and $y$
common neighbors	$ \Gamma(x) \cap \Gamma(y) $
Jaccard's coefficient	$\Gamma(x)\cap\Gamma(y)$ $\Gamma(x)\cup\Gamma(y)$
Adamic/Adar	$\sum_{z \in \Gamma(x) \cap \Gamma(y)} \frac{1}{\log  \Gamma(z) }$
preferential attachment	$ \Gamma(x)  \cdot  \Gamma(y) $
$\mathrm{Katz}_{eta}$	$\sum_{\ell=1}^{\infty} eta^{\ell} \cdot  paths_{x,y}^{\langle\ell angle} $
	where $paths_{x,y}^{\langle\ell\rangle} := \{ paths \text{ of length exactly } \ell \text{ from } x \text{ to } y \}$ weighted: $paths_{x,y}^{\langle1\rangle} := number of collaborations between  x, y.$ unweighted: $paths_{x,y}^{\langle1\rangle} := 1 \text{ iff } x \text{ and } y \text{ collaborate.}$
hitting time stationary-normed commute time stationary-normed	$-H_{x,y}$ $-H_{x,y} \cdot \pi_y$ $-(H_{x,y} + H_{y,x})$ $-(H_{x,y} \cdot \pi_y + H_{y,x} \cdot \pi_x)$
	where $H_{x,y}$ := expected time for random walk from $x$ to reach $y$ $\pi_y$ := stationary distribution weight of $y$ (proportion of time the random walk is at node $y$ )
rooted PageRank $_{\alpha}$	stationary distribution weight of $y$ under the following random walk: with probability $\alpha$ , jump to $x$ . with probability $1 - \alpha$ , go to random neighbor of current node.
$\operatorname{SimRank}_{\gamma}$	$\begin{cases} 1 & \text{if } x = y \\ \gamma \cdot \frac{\sum_{a \in \Gamma(x)} \sum_{b \in \Gamma(y)} score(a, b)}{ \Gamma(x)  \cdot  \Gamma(y) } & \text{otherwise} \end{cases}$

# Comparison of methods



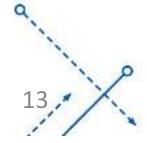
### Content

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  - Supervised learning



# Learn in link prediction

- Learning in link prediction is divided into two types:
  - Unsupervised: No train test
    - Similarity-based: similar vertices are connected
    - Cluster-based: vertices from the same group demonstrate similar connectivity patterns.
  - Supervised: provide a set of associated vertices to train the model



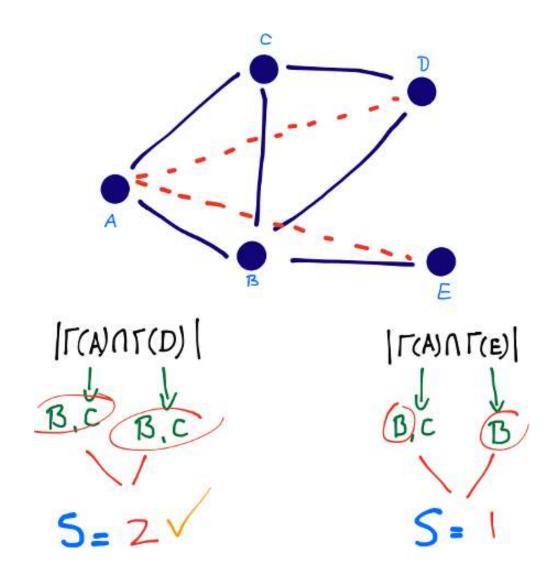
# Link prediction based on similarity

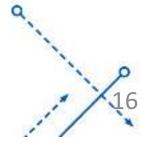
- Similarity (unsupervised learning) measures the distance between vertices in a graph.
- Classify:
  - 1-step: neighboring vertices are connected
  - Laplacian: dissimilar vertices are connected (L = D-A)
  - Degree: vertices of similar degree
  - A<sup>2</sup>: vertices shared with neighbors(2-hop)
  - Closeness: vertices have nearly the same center
  - Betweeness: vertices have the same intermediate center,

# Based on neighboring vertices

- Common neighbors proposed by Ahmad Sadrei as the simplest measure.
  - Considered the effect of triangular closure (closing a triangle)
- The first is to find the intersection between two neighbors of two vertices, the measure of similarity between the two vertices is the number of elements in this set.
- $score(u, v) = |N(u) \cap N(v)|$
- If this measurement is greater than the given threshold, a link is created

# Based on neighboring vertices

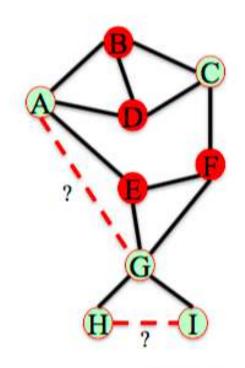




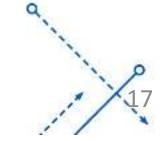
#### Jaccard coefficient

 The Jaccard coefficient normalizes the number of common neighbors by the total number of neighbors.

• 
$$score(u, v) = \frac{|N(u) \cap N(v)|}{|N(u) \cup N(v)|}$$



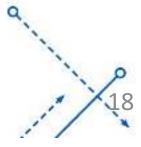
$$\text{jacc\_coeff}(A, C) = \frac{|\{B, D\}|}{|\{B, D, E, F\}|} = \frac{2}{4} = \frac{1}{2}$$



#### Adamic Adar measure

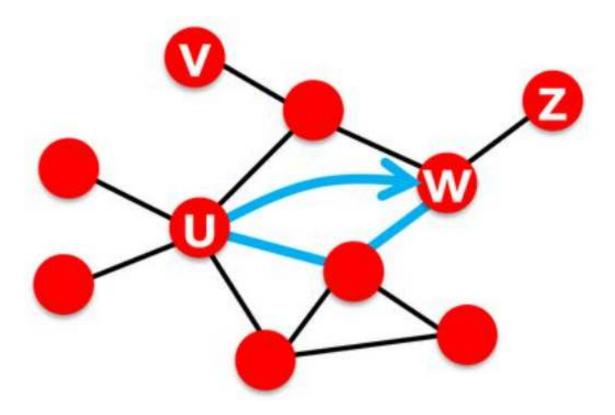
- Measure proposed by Lada Adamic and Eytan Adar (2003)
- In addition to counting the number of common neighbors, the Adamic Adar measure also sums the log inverses of the neighbors' degrees.
  - Counts common neighbors but lowers vertices that have too many neighbors
  - The triangle closure effect is heavily influenced by low-order vertices.

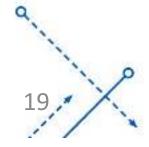
$$score(u, v) = \sum_{z \in N(u) \cap N(v)} \frac{1}{\log(N(z))}$$



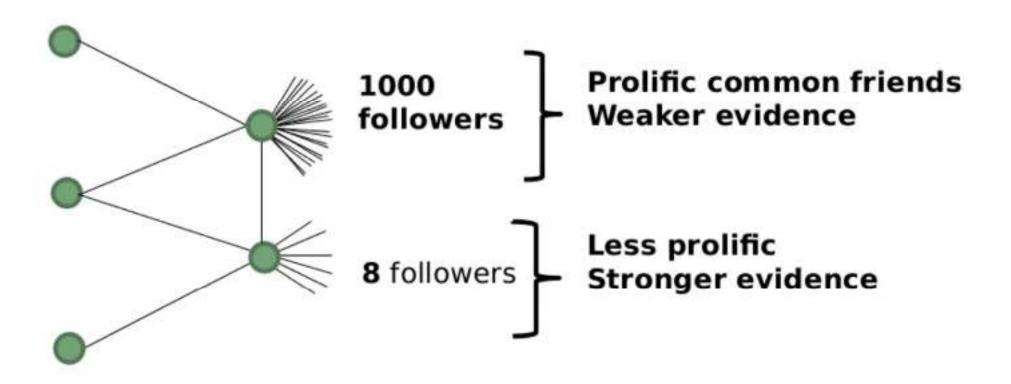
### Triangle closing effect

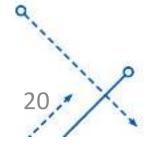
 92% of new Facebook friend connections are in friend-of-a-friend



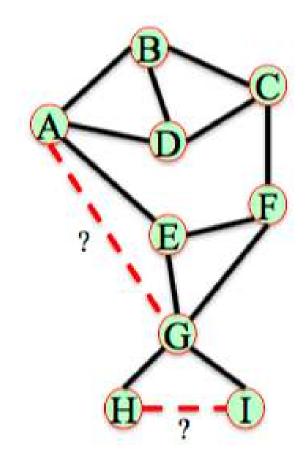


#### Adamic Adar measure

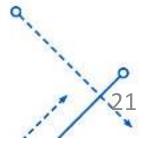




#### Adamic Adar measure



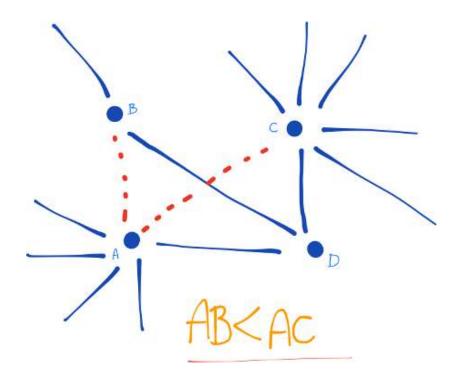
adamic\_adar(A, C) = 
$$\frac{1}{\log(3)} + \frac{1}{\log(3)} = 1.82$$



#### Preferential attachement

- Preferential attachement proposed by Albert-László Barabási and Réka Albert to describe the phenomenon of vertices with many relationships tending to be interconnected.
- "Rich-get-Richer"

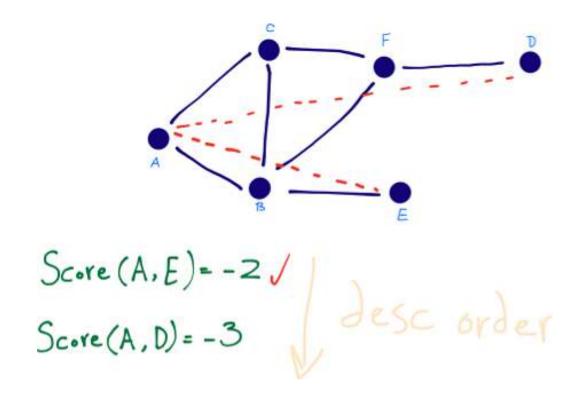
$$score(u, v) = degree(u) \times degree(v)$$

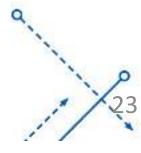




### Shortest path

- The pair of vertices with the shortest path will tend to connect
- score(u, v) = -shortestPath(u, v)



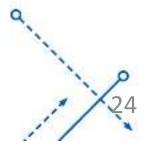


#### Katz measure

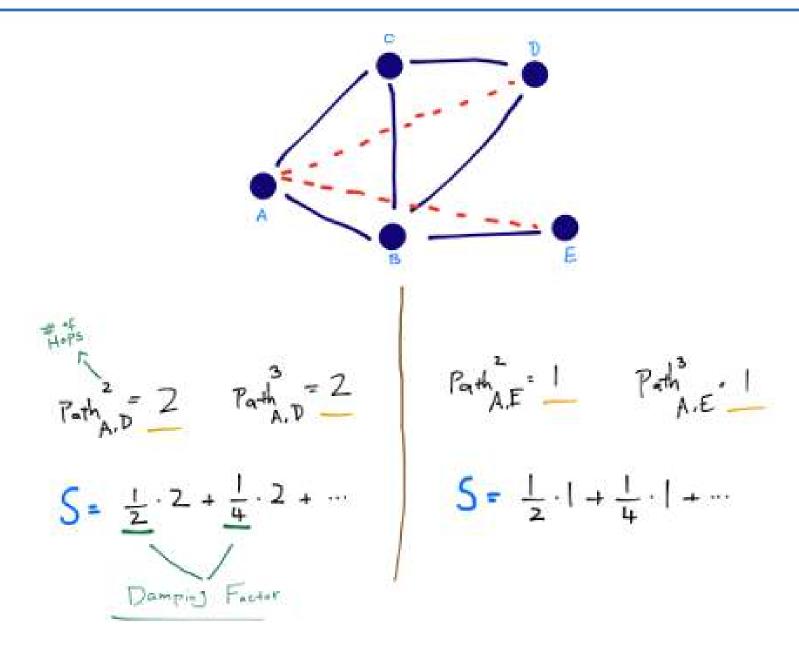
- The Katz measure considers not only the shortest path between vertices, but also all paths between them.
- The shorter the path, the more weighted

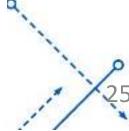
$$score(u, v) = \sum_{l=1}^{\infty} \beta^l |paths_{u,v}^{\langle l \rangle}|$$

with  $paths_{u,v}^{< l>}$  is the set of length paths I between you and v,  $\beta$  is a very small constant to make the path as long as possible with little contribution to the sum.



#### Katz measure



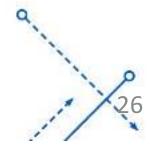


#### SimRank

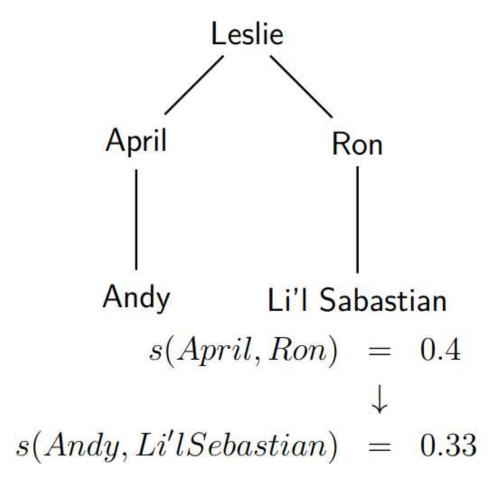
 SimRank Calculated based on the measure of neighbors, meaning that the more similar the neighbors, the more connected those two vertices tend to be.

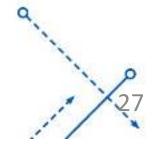
• 
$$score(u, v) = \frac{c}{|N(u)| \cdot |N(v)|} \sum_{z \in N(u)} \sum_{z' \in N(v)} score(z, z')$$

with C is the constant in paragraph [0,1]



### **SimRank**



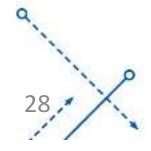


# Hitting Time

- The hitting time from vertex u to v is the random number of steps expected to meet vertex v when starting from u.
- Similar measurement based on hitting time:

$$score(u, v) = -H_{u,v}$$

• However, some vertices with large connections will easily lead to an immediate random walk to it no matter where it comes from. To avoid this phenomenon, we standardize it:  $score(u, v) = -H_{u,v}\pi_v$ 



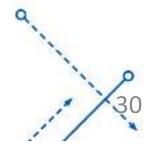
#### Commute time

Because the hitting time is asymmetrical, we can

calculate: 
$$score(u, v) = -(H_{u,v}\pi_v + H_{v,u}\pi_u)$$

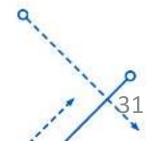
### Closeness centrality

- Closeness centrality: An agent I is close center if it can interact easily with all other agents.
- Or, the distance of i to all other agents is short



# Closeness centrality (tt)

- The shortest distance from agent i to agent j (symbol d(i,j)) is measured by the number of links on the shortest path.
- The closeness centre of agent i is denoted Cc(i) and is normalized with n-1 as the sum of the shortest distances from i to all other agents.



# Closeness centrality (tt)

 For a scalar graph: the center near Cc(i) of agent i is defined as:

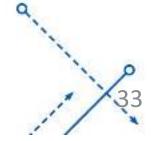
$$C_{\mathcal{C}}(i) = \frac{n-1}{\sum_{j=1}^{n} d(i,j)}$$

Note: this expression is only possible in the case of a connected graph



### Betweenness centrality

- Betweenness centrality: If two nonadjacent agents j
  and k want to interact and agent i is between j and k,
  then i may have some control over their interactions.
- If i is in the path of many of these kinds of interactions, then i is an important agent.



# Betweenness centrality (tt)

For a scalar graph, the intermediate properties of an agent i are defined by the number of shortest paths through i (symbols pjk(i), j ≠ i and k ≠ i) and normalized by the total number of shortest paths of all agent pairs except i:

$$C_B(i) = \sum_{j < k} \frac{p_{jk}(i)}{p_{jk}}$$

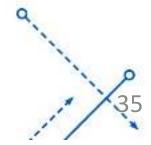


# Betweenness centrality (tt)

• To ensure that the value is between 0 and 1, CB(i) is normalized with (n-1)(n-2)/2, which is the maximum value of CB(i):

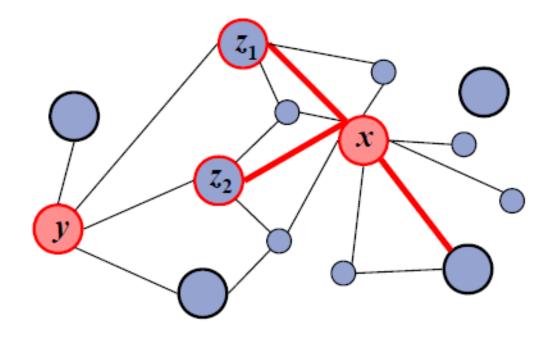
$$C_B(i) = \frac{2\sum_{j < k} \frac{p_{jk}(i)}{p_{jk}}}{(n-1)(n-2)}$$

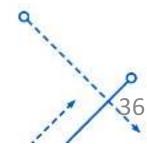
• Unlike proximity, intermediate can be calculated even if the graph is not connected.



# **Unseen Bigram**

- Bigram (N-gram) Expresses two characters/words standing next to each other in a natural language sentence.
- If the bigram does not appear in the training set but appears in the test set, it is called unseen bigram.
- Use a method in the language model to calculate.



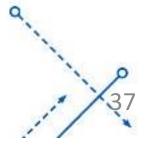


# **Unseen Bigram**

• Put  $S_u^{<\delta>}$  is a vertex  $\delta$  set that is highly similar to you through some measure:

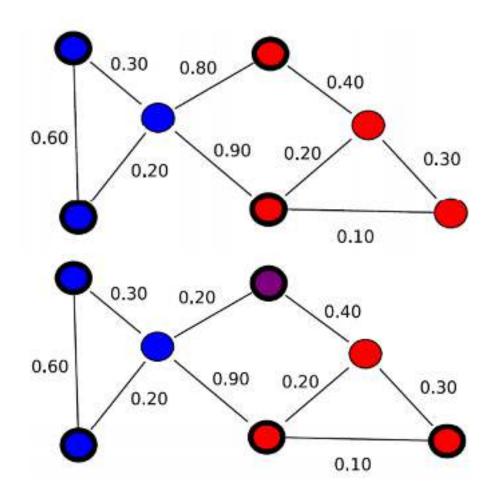
• 
$$score_{unweighted}(u, v) = |\{z: z \in N(v) \cap S_u^{<\delta>}\}|$$

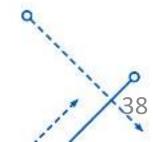
$$score_{weighted}(u, v) = \sum_{z \in N(v) \cap S_u^{<\delta>}} score(u, z)$$



### Based on grouping

- Apply several grouping methods (e.g. DB-Scan) to perform graph grouping (community detection).
- Connect vertices in a group based on defined criteria.



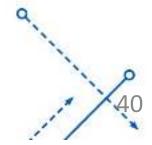


### **Unsupervised Method Review**

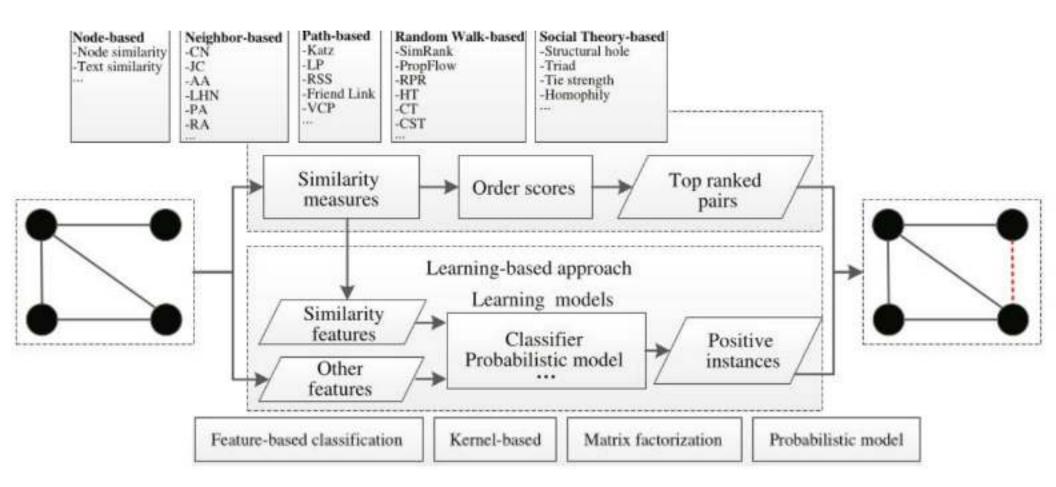
- After an analogue measure is selected, the result is a list of the most similar pairs filtered out.
- Precision, recall, or accuracy can be evaluated using a test graph.
- However, the quality is often very low when used in a realworld network due to multiple edges being created for no logical reason.

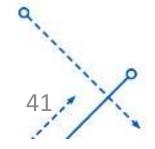
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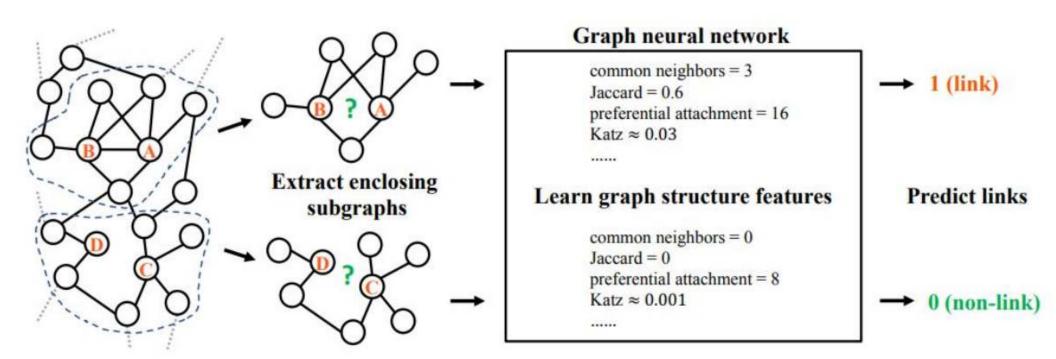
### Learn to predict

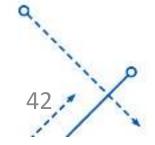




### Learning features

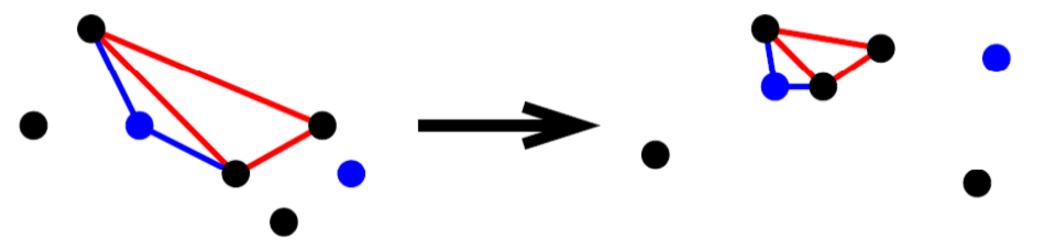
Local cartouche-based learning

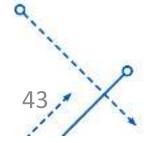




### Learning on global characteristics

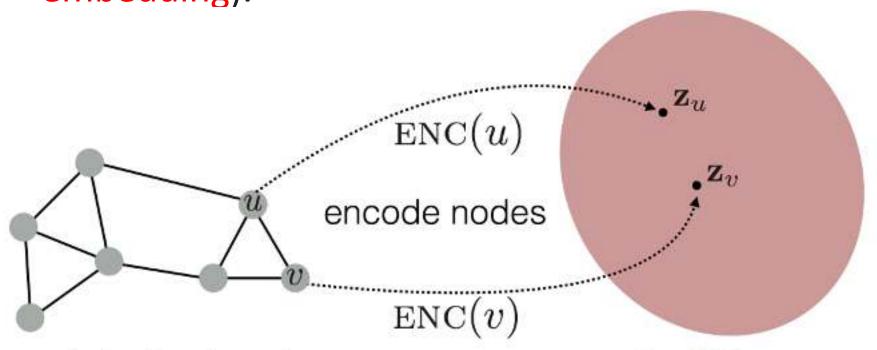
- Learning on global characteristics
  - Use a known subnet to readjust the distance before applying similarity





### **Embedded-based learning**

 It is possible to learn based on conversions to other dimensions to determine similarity (vertex embedding).



original network

embedding space

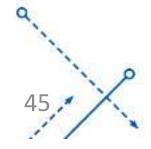
G -> embedded in vector space -> calculate distance

44

### Target function

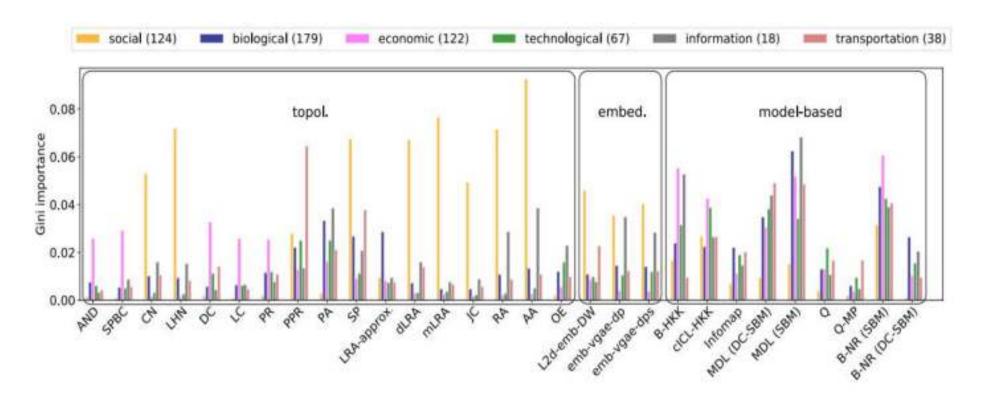
$$F(\mathbf{A}_{source}) \subseteq \mathbf{A}_{target}$$

$$\min ||F(\mathbf{A}_{source}) - \mathbf{A}_{target}||_{\mathrm{F}}$$

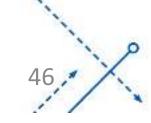


#### Which is best?

550 structurally diverse networks from six scientific domains



no one predictor or family is best, or worst, across all realistic inputs



#### References

 http://redalertproject.eu/wpcontent/uploads/2019/05/D3-2-Link-predictionmodels-FINAL.pdf

