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	Document Change History		
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	Document Change History			
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2010-09-30	3.1.5	AUTOSAR Administration	<ul> <li>Services         'Icu_DisableEdgeDetection' and         'Icu_EnableEdgeDetection' were         added.</li> <li>Configuration parameters         'IcuEdgeDetectApi'and         'IcuWakeupFunctionalityApi' has         been added.</li> <li>Definition of 'duty cycle' has been         corrected.</li> <li>Corrected values of the parameter         'Icu_SignalMeasurementPropertyTy         pe'</li> </ul>	
2008-08-13	3.1.1	AUTOSAR Administration	Legal disclaimer revised	



	Document Change History		
Date	Release	Changed by	Change Description
2008-02-01	3.0.2	AUTOSAR Administration	<ul> <li>The code file structure of the module was completely reworked.</li> <li>The following requirements were added: SWS_Icu_00088, SWS_Icu_00220, SWS_Icu_00221, SWS_Icu_00228 and SWS_Icu_00229.</li> <li>The flow charts related to the ECU Wake-Up moved to the</li> <li>SWS document of the ECU State Manager.</li> <li>Document meta information extended</li> <li>Small layout adaptations made</li> </ul>
2007-12-21	3.0.1	AUTOSAR Administration	<ul> <li>Default start edge is now used for edge configuration</li> <li>Enable and Disable Notification can now be used for Timestamp functionality.</li> <li>Edge detection functionality is now pre compile time configurable On/Off</li> <li>Legal disclaimer revised</li> <li>Release Notes added</li> <li>"Advice for users" revised</li> <li>"Revision Information" added</li> </ul>
2006-05-16	2.0	AUTOSAR Administration	Added the following services         Icu_SetActivationCondition         Icu_StartTimeStamp         Icu_StopTimeStamp         Icu_GetTimestampIndex         Icu_ResetEdgeCount         Icu_EnableEdgeCount         Icu_DisableEdgeCount         Icu_GetEdgeNumbers         Icu_GetTimeElapsed         Icu_GetDutyCycleValues         Icu_GetVersionInfo
2005-05-31	1.0	AUTOSAR Administration	Initial Release



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### 1 Introduction and functional overview

This specification specifies the functionality, API and configuration of the AUTOSAR Basic Software module ICU driver.

The ICU driver is a module using the input capture unit (ICU) for demodulation of a PWM signal, counting pulses, measuring of frequency and duty cycle, generating simple interrupts and also wakeup interrupts.

The ICU driver provides services for

- Signal edge notification
- Controlling wakeup interrupts
- Periodic signal time measurement
- Edge time stamping, usable for the acquisition of non-periodic signals
- Edge counting



# 2 Acronyms and abbreviations

Abbreviation / Acronym:	Description:
Active Time	This depends on the starting edge of the signal to be captured.
	■ Start edge = falling edge => Active Time = Low Time
	Start edge = rising edge => Active Time = High Time
	Start edge = both edges => Active Time = High Time (if rising edge occurs initially)
	Start edge = both edges => Active Time = Low Time (if falling edge occurs initially)
DEM	Diagnostic Event Manager
DET	Default Error Tracer
EcuM	ECU State Manager
Enumeration	This can be in "C" programming language an enum or a #define.
ICU	Input Capture Unit (not Intensive Care Unit)
ICU Channel	Represents a logical ICU entity bound to one input signal and the hardware resources for the configured measurement mode.
ICU State Logical input state of an ICU Channel.	
	It can be ICU_ACTIVE or ICU_IDLE.
ICU_ACTIVE	Input state of an ICU Channel, an activation edge has been detected.
ICU_IDLE	Input state of an ICU Channel, no activation edge has been detected since the last call of Icu_GetInputState() or Icu_Init().
Symbolic name for a channel	A symbolic name is a substitution of a handle with a name. With this handle each channel and its related properties can be found within the configuration structure.
	In "C" programming language this can be realized e.g. by #defines and enums.
Wakeup event	A wakeup event is understood as a pattern of edges, which will lead to the wake up of this driver. Nevertheless the decision whether a pattern is valid or <u>not</u> isn't done by this driver. This shall be done by an upper layer.



### 3 Related documentation

### 3.1 Input documents

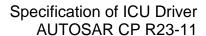
- [1] General Requirements on Basic Software Modules, AUTOSAR\_CP\_SRS\_BSWGeneral.pdf
- [2] General Requirements on SPAL, AUTOSAR\_CP\_SRS\_SPALGeneral.pdf
- [3] Specification of Standard Types, AUTOSAR\_CP\_SWS\_StandardTypes.pdf
- [4] List of Basic Software Modules, AUTOSAR\_CP\_TR\_BSWModuleList.pdf
- [5] Specification of Diagnostics Event Manager (DEM), AUTOSAR\_CP\_SWS\_DiagnosticEventManager.pdf
- [6] Specification of Default Error Tracer, AUTOSAR\_CP\_SWS\_DefaultErrorTracer.pdf
- [7] Requirements on ICU Driver, AUTOSAR\_CP\_SRS\_ICUDriver.pdf
- [8] Specification of ECU Configuration, AUTOSAR\_CP\_TPS\_ECUConfiguration.pdf
- [9] Layered Software Architecture, AUTOSAR\_CP\_EXP\_LayeredSoftwareArchitecture.pdf
- [10] Specification of ECU State Manager, AUTOSAR\_CP\_SWS\_ECUStateManager.pdf
- [11] Basic Software Module Description Template, AUTOSAR\_CP\_TPS\_BSWModuleDescriptionTemplate.pdf
- [12] General Specification of Basic Software Modules AUTOSAR CP SWS BSWGeneral.pdf

#### 3.2 Related standards and norms

[13] IEC 7498-1 The Basic Model, IEC Norm, 1994

### 3.3 Related specification

AUTOSAR provides a General Specification on Basic Software modules [12] (SWS BSW General), which is also valid for ICU Driver.





Thus, the specification SWS BSW General shall be considered as additional and required specification for ICU Driver.



# 4 Constraints and assumptions

# 4.1 Limitations

No limitations.

# 4.2 Applicability to car domains

No restrictions.



# 5 Dependencies to other modules

### **5.1 Module DET (Default Error Tracer)**

The detailed description of the detected errors can be found in chapter 7.2 and chapter 8. ()

#### 5.2 Module MCU

The ICU driver depends on the system clock, prescaler(s) and PLL. Hence the length of an ICU timer tick depends on the clock settings made in the module MCU.

The ICU driver will not take care of setting the registers which configure the <u>global</u> clock, global prescaler(s) and PLL in its Init function. This has to be done by the MCU module. The ICU driver only configures local (ICU peripheral specific) clocks, prescalers and so on.

# 5.3 OS (Operating System)

The ICU driver uses interrupts and therefore there is a dependency on the OS which configures the interrupt sources. It will provide the call-back functions only.

The ICU driver will not take care of setting the registers for interrupt association in its Init function. The overall assignment and activation of the interrupt system is done by the Operating System.

#### 5.4 Module PORT

The configuration of port pins used for the ICU as inputs is done by the PORT driver. Hence the PORT driver has to be initialized prior to the use of ICU functions. Otherwise ICU functions will exhibit undefined behaviour.

#### 5.5 Module EcuM

[SWS\_Icu\_00244] The ICU driver will do the reporting of wakeup interrupts to the EcuM. ()



# 6 Requirements traceability

Requirement	Description	Satisfied by
SRS_BSW_00101	The Basic Software Module shall be able to initialize variables and hardware in a separate initialization function	SWS_lcu_00006
SRS_BSW_00171	Optional functionality of a Basic-SW component that is not required in the ECU shall be configurable at precompile-time	SWS_lcu_00092, SWS_lcu_00095, SWS_lcu_00096, SWS_lcu_00097, SWS_lcu_00098, SWS_lcu_00099, SWS_lcu_00100, SWS_lcu_00101, SWS_lcu_00102, SWS_lcu_00103, SWS_lcu_00104, SWS_lcu_00105, SWS_lcu_00106, SWS_lcu_00122
SRS_BSW_00323	All AUTOSAR Basic Software Modules shall check passed API parameters for validity	SWS_Icu_00024, SWS_Icu_00043, SWS_Icu_00125, SWS_Icu_00385, SWS_Icu_00386, SWS_Icu_00387, SWS_Icu_00388, SWS_Icu_00389, SWS_Icu_00390, SWS_Icu_00391, SWS_Icu_00392, SWS_Icu_00393, SWS_Icu_00394, SWS_Icu_00395, SWS_Icu_00396, SWS_Icu_00397, SWS_Icu_00398, SWS_Icu_00399, SWS_Icu_00400, SWS_Icu_00401, SWS_Icu_00402, SWS_Icu_00403, SWS_Icu_00404
SRS_BSW_00336	Basic SW module shall be able to shutdown	SWS_lcu_00037
SRS_BSW_00344	BSW Modules shall support link-time configuration	SWS_lcu_00006
SRS_BSW_00359	All AUTOSAR Basic Software Modules callback functions shall avoid return types other than void if possible	SWS_lcu_00187
SRS_BSW_00369	All AUTOSAR Basic Software Modules shall not return specific development error codes via the API	SWS_lcu_00049
SRS_BSW_00384	The Basic Software Module specifications shall specify at least in the description which other modules they require	SWS_lcu_00131
SRS_BSW_00404	BSW Modules shall support post-build configuration	SWS_lcu_00006
SRS_BSW_00405	BSW Modules shall support multiple configuration sets	SWS_lcu_00006
SRS_BSW_00406	A static status variable denoting if a BSW module is initialized shall be initialized with value 0 before any APIs	SWS_lcu_00385, SWS_lcu_00386, SWS_lcu_00387, SWS_lcu_00388, SWS_lcu_00389, SWS_lcu_00390, SWS_lcu_00391, SWS_lcu_00392,



	1	
	of the BSW module is called	SWS_lcu_00393, SWS_lcu_00394, SWS_lcu_00395, SWS_lcu_00396, SWS_lcu_00397, SWS_lcu_00398, SWS_lcu_00399, SWS_lcu_00400, SWS_lcu_00401, SWS_lcu_00402, SWS_lcu_00403, SWS_lcu_00404
SRS_BSW_00410	Compiler switches shall have defined values	SWS_lcu_00055, SWS_lcu_00063, SWS_lcu_00090, SWS_lcu_00092, SWS_lcu_00095, SWS_lcu_00096, SWS_lcu_00097, SWS_lcu_00099, SWS_lcu_00100, SWS_lcu_00101, SWS_lcu_00102, SWS_lcu_00103, SWS_lcu_00104, SWS_lcu_00105, SWS_lcu_00106, SWS_lcu_00122
SRS_lcu_12305	The ICU driver shall allow to enable/disable the notification for an ICU channel at runtime	SWS_lcu_00009, SWS_lcu_00010, SWS_lcu_00042, SWS_lcu_00044
SRS_lcu_12369	The ICU driver shall provide notification for an ICU Channel at the configured signal edge	SWS_lcu_00021
SRS_lcu_12370	The ICU driver shall provide a service for selecting the sleep mode	SWS_lcu_00008
SRS_lcu_12371	The ICU driver shall provide a synchronous service that returns the status of the ICU input	SWS_lcu_00030, SWS_lcu_00031, SWS_lcu_00032
SRS_lcu_12407	After initialization of the ICU driver all notifications shall be disabled	SWS_lcu_00040, SWS_lcu_00061
SRS_lcu_12408	The ICU driver shall provide a service for enabling / disabling the wake-up capability of single ICU channels	SWS_lcu_00013, SWS_lcu_00014
SRS_lcu_12425	For each ICU Channel the 'property' that could be measured shall be configurable	SWS_lcu_00088
SRS_lcu_12429	The ICU Driver shall provide the functionality to deinitialize ICU channels to their power on reset state	SWS_lcu_00036
SRS_lcu_12430	The ICU driver shall provide an asynchronous service for starting the timestamp measurement on an ICU channel	SWS_lcu_00063, SWS_lcu_00066
SRS_lcu_12431	The ICU driver shall provide a synchronous service for canceling the timestamp measurement on an ICU	SWS_lcu_00067



	channel	
SRS_lcu_12432	Edge counting service shall be available on an ICU channel	SWS_lcu_00078
SRS_lcu_12433	Edge counting service on a ICU channel shall be disabled	SWS_lcu_00079
SRS_lcu_12434	Edge counting read service shall be available	SWS_lcu_00080
SRS_lcu_12435	The elapsed Signal High Time for each ICU Channel shall be provided	SWS_lcu_00082
SRS_lcu_12436	The High time and Period Time of an ICU Channel shall be provided	SWS_lcu_00084
SRS_lcu_12438	The ICU driver shall provide the functionality to capture timer values on configurable edges to an external buffer	SWS_lcu_00063
SRS_lcu_12439	Edges of a signal shall be counted by the ICU	SWS_lcu_00072, SWS_lcu_00073, SWS_lcu_00074
SRS_lcu_12442	The elapsed Signal Low Time for each ICU Channel shall be provided	SWS_lcu_00081
SRS_lcu_12443	The elapsed Period Time for an ICU Channel shall be provided	SWS_lcu_00083
SRS_lcu_12444	The ICU driver shall provide a notification if the number of requested timestamps are acquired	SWS_lcu_00215
SRS_lcu_12453	The Timestamp index service shall be provided by ICU	SWS_lcu_00071
SRS_lcu_12456	If linear buffer handling is configured, the driver shall stop capturing timer values, when the end of the buffer is reached	SWS_lcu_00065
SRS_lcu_13100	Reseting the value of counted edges of an ICU channel shall be available	SWS_lcu_00072
SRS_SPAL_00157	All drivers and handlers of the AUTOSAR Basic Software shall implement notification mechanisms of drivers and handlers	SWS_lcu_00021, SWS_lcu_00030
SRS_SPAL_12056	All driver modules shall allow the static configuration of notification mechanism	SWS_lcu_00018
SRS_SPAL_12057	All driver modules shall	SWS_lcu_00006, SWS_lcu_00040,



	implement an interface for initialization	SWS_lcu_00060, SWS_lcu_00061		
SRS_SPAL_12063	All driver modules shall only support raw value mode	SWS_lcu_00063, SWS_lcu_00081, SWS_lcu_00082, SWS_lcu_00083		
SRS_SPAL_12064	All driver modules shall raise an error if the change of the operation mode leads to degradation of running operations	SWS_lcu_00133		
SRS_SPAL_12067	All driver modules shall set their wake-up conditions depending on the selected operation mode	SWS_lcu_00008, SWS_lcu_00011, SWS_lcu_00012		
SRS_SPAL_12069	All drivers of the SPAL that wake up from a wake-up interrupt shall report the wake-up reason	SWS_lcu_00055, SWS_lcu_00056, SWS_lcu_00057		
SRS_SPAL_12075	All drivers with random streaming capabilities shall use application buffers	SWS_lcu_00063		
SRS_SPAL_12125	All driver modules shall only initialize the configured resources	SWS_lcu_00054		
SRS_SPAL_12129	The ISRs shall be responsible for resetting the interrupt flags and calling the according notification function	SWS_lcu_00119		
SRS_SPAL_12163	All driver modules shall implement an interface for de-initialization	SWS_lcu_00036, SWS_lcu_00037		
SRS_SPAL_12169	All driver modules that provide different operation modes shall provide a service for mode selection	SWS_lcu_00008		
SRS_SPAL_12448	All driver modules shall have a specific behavior after a development error detection	SWS_lcu_00049, SWS_lcu_00107, SWS_lcu_00108		
SRS_SPAL_12461	Specific rules regarding initialization of controller registers shall apply to all driver implementations	SWS_lcu_00006, SWS_lcu_00051, SWS_lcu_00052, SWS_lcu_00053, SWS_lcu_00128, SWS_lcu_00129		



# 7 Functional specification

#### 7.1 General behavior

### 7.1.1 Background & Rationale

To ensure data consistency re-entrant code shall be provided.

#### 7.1.2 Requirements

**[SWS\_lcu\_00050]** The lcu module functions for different channel numbers shall be re-entrant, except for:

- Icu Init()
- Icu DeInit()
- Icu SetMode()
- Icu GetVersionInfo() ) ()

[SWS\_Icu\_00149] [The Icu module's environment shall check the integrity if several calls for the same ICU channel are used during runtime in different tasks or ISRs.] ()

**[SWS\_Icu\_00150]** [The Icu module shall not check the integrity if several calls for the same ICU channel are used during runtime in different tasks or ISRs. ] ()

[SWS\_lcu\_00258] [The Icu module has 2 modes:

- ICU MODE NORMAL
- ICU MODE SLEEP

] ()

In ICU MODE NORMAL mode all notifications are available as

• [SWS\_lcu\_00011] [configured by service

```
Icu_SetActivationCondition() or IcuDefaultStartEdge. |
(SRS_SPAL_12067)
```

• [SWS\_lcu\_00259] [selected by the <code>Icu\_DisableNotification()</code> and <code>Icu\_EnableNotification()</code> services before or after the call of <code>Icu\_SetMode().]()</code>

In ICU MODE SLEEP mode

• [SWS\_lcu\_00012] [only those wakeup events are available which are configured as wakeup capable, enabled via Icu\_EnableWakeup() after Icu\_Init() and which are not disabled via service



- [SWS\_lcu\_00260] [all other interrupts handled by this module are disabled and must not lead to an exit from the reduced power mode state (e.g. idle, halt) of the MCU if the event occurs. ] ()
- [SWS\_lcu\_00261] [All channels are stopped except those channels
  - o which have been configured as wakeup capable and
  - o which were explicitly enabled by the call of Icu EnableWakeup.] ()

[SWS\_Icu\_00088] [The module Icu shall allow the configuration per channel of the definition on which edge the period starts.] (SRS\_Icu\_12425)

#### 7.1.3 Time Unit Ticks

#### 7.1.3.1 Background & Rationale

To get times out of register values it is necessary to know the oscillator frequency, prescalers and so on. Since these settings are made in the MCU module and/or in other modules it is not possible to calculate such times.

Hence the conversions between time and ticks shall be part of an upper layer.

#### 7.1.3.2 Requirements

All time units used within the API services of the ICU driver are unit ticks.

#### 7.2 Error classification

Section 7.x "Error Handling" of the document "General Specification of Basic Software Modules" describes the error handling of the Basic Software in detail. Above all, it constitutes a classification scheme consisting of five error types which may occur in BSW modules.

Based on this foundation, the following section specifies particular errors arranged in the respective subsections below.:

### 7.2.1 Development Errors

[SWS Icu 00382][

Type of error	Related error code	Error value
API IS called with invalid pointer.	ICU_E_PARAM_ POINTER	0x0A
API service used with an invalid channel identifier or channel was not configured for the functionality of the calling API.	ICU_E_PARAM_ CHANNEL	0x0B
API service used with an invalid or not feasible activation.	ICU_E_PARAM_ ACTIVATION	0x0C



Init function failed.	ICU_E_INIT_FAILED	0x0D
API service used with an invalid buffer size.	ICU_E_PARAM_ BUFFER_SIZE	0x0E
API service Icu_SetMode used with an invalid mode.	ICU_E_PARAM_MODE	0x0F
API service used without module initialization.	ICU_E_UNINIT	0x14
API service Icu_SetMode is called while a running operation.	ICU_E_BUSY_ OPERATION	0x16
API Icu_Init service is called and when the ICU driver and the Hardware are already initialized.	ICU_E_ALREADY_ INITIALIZED	0x17
API Icu_StartTimeStamp is called and the parameter Notify Interval is invalid (e.g. "0", NotifyInterval < 1)	ICU_E_PARAM_ NOTIFY_INTERVAL	0x18
API Icu_GetVersionInfo is called and the parameter versioninfo is is invalid ( e.g. NULL )	ICU_E_PARAM_VINFO	0x19

#### 7.2.2 Runtime Errors

[SWS\_lcu\_91004][

Type of error	Related error code	Error value
API service Icu_StopTimestamp called on a channel which was not started or already stopped	ICU_E_NOT_ STARTED	0x15

]()

#### 7.2.3 Transient Faults

There are no transient faults.

#### 7.2.4 Production Errors

There are no production errors.

#### 7.2.5 Extended Production Errors

There are no extended production errors.



# 8 API specification

# 8.1 Imported types

In this chapter all types included from the following modules are listed:

[SWS\_lcu\_00276][

Module	Header File	Imported Type
EcuM	EcuM.h	EcuM_WakeupSourceType
Std	Std_Types.h	Std_ReturnType
	Std_Types.h	Std_VersionInfoType

]()

# 8.2 Type definitions

#### 8.2.1 lcu\_ModeType

**ISWS Icu 002771**[

[3443_icu_c	00211]				
Name	Icu_ModeType				
Kind	Enumeration	Enumeration			
	ICU_MODE_ NORMAL	0x00	Normal operation, all used interrupts are enabled according to the notification requests.		
Range	ICU_MODE_ SLEEP	0x01	Reduced power operation. In sleep mode only those notifications are available which are configured as wakeup capable.		
Description	Allow enabling / disabling of all interrupts which are not required for the ECU wakeup.				
Available via	lcu.h				

]()

#### 8.2.2 Icu\_ChannelType

[SWS Icu 00278][

Name	Icu_ChannelType
Kind	Туре
Derived	uint



from					
Range	1		This is implementation specific but not all values may be valid within the type. This type shall be chosen in order to have the most efficient implementation on a specific microcontroller platform.		
Description	Νı	Numeric identifier of an ICU channel			
Available via	lcu.h				

# 8.2.3 lcu\_InputStateType

[SWS\_lcu\_00279][

[3442_icu_c	)219]				
Name	lcu_InputSta	Icu_InputStateType			
Kind	Enumeration	l			
Pango	ICU_ ACTIVE	0x00	An activation edge has been detected		
Range	ICU_IDLE	0x01	No activation edge has been detected since the last call of Icu_GetInputState() or Icu_Init().		
Description	Input state of an ICU channel				
Available via	lcu.h				

]()

# 8.2.4 Icu\_ConfigType

[SWS Icu 00280][

[SWS_ICU_C	JU20U]	0200]			
Name	Icu_Config <sup>1</sup>	Icu_ConfigType			
Kind	Structure				
Elements	Type				
	Comment	Hardware and implementation dependent structure. The contents of the initialization data structure are microcontroller specific.			
Description	This type contains initialization data.				
Available via	lcu.h				



[SWS\_lcu\_00287] [If in the definition for each Channel within the  $lcu_ConfigType$  the channel is configured as wakeup capable then the function called for validation of wakeup reason shall be  $lcuM_CheckWakeup.$ ] ()

# 8.2.5 Icu\_ActivationType

[SWS\_lcu\_00289][

10110_104_0	_104_00203]				
Name	Icu_ActivationType				
Kind	Enumeration				
	ICU_RISING_ EDGE	0x00	An appropriate action shall be executed when a rising edge occurs on the ICU input signal.		
Range	ICU_FALLING_ EDGE	0x01	An appropriate action shall be executed when a falling edge occurs on the ICU input signal.		
	ICU_BOTH_ EDGES	0x02	An appropriate action shall be executed when either a rising or falling edge occur on the ICU input signal.		
Description	Definition of the type of activation of an ICU channel.				
Available via	lcu.h				

]()

#### 8.2.6 lcu\_ValueType

[SWS\_lcu\_00290][

[O110_10u_0	70230]			
Name	lcu_ValueType			
Kind	Туре			
Derived from	uint			
Range	0 <width of="" register="" the="" timer="">  Implementation specific. This type shall be chosen in order to have the most efficient implementation on a specific microcontroller platform.</width>			
Description	Width of the buffer for timestamp ticks and measured elapsed timeticks.			
Available via	lcu.h			

**(**()



# 8.2.7 Icu\_DutyCycleType

[SWS\_lcu\_00291][

[3W3_ICU_UU					
Name	Icu_DutyCycleType				
Kind	Structure				
	ActiveTime				
	Туре	Icu_ValueType			
Elemente	Comment This shall be the coherent active-time measured on a channel				
Elements	PeriodTime				
	Туре	Icu_ValueType			
	Comment This shall be the coherent period-time measured on a channel				
Description	Type which shall contain the values, needed for calculating duty cycles.				
Available via	Icu.h				

]()

# 8.2.8 Icu\_IndexType

**ISWS Icu 002921**[

[0440_icu_	,0232J				
Name	Icu_IndexType				
Kind	Тур	е			
Derived from	uint				
Range		Implementation specific. This type shall be chosen in order to have the most efficient implementation on a specific microcontroller platform.			
Description	Type, to abstract the return value of the service lcu_GetTimestampIndex().Since circular buffer handling is supported and lcu_GetTimestampIndex can return '0' as a legally true value ( not as an error according to ICU107 and ICU135), lcu_IndexType may be implemented to have values 1xyz.				
Available via	lcu.h				

]()

# 8.2.9 Icu\_EdgeNumberType

[SWS\_lcu\_00293][

Name	Icu_EdgeNumberType
Kind	Туре



Derived from	uint			
Range	Implementation specific. This type shall be chosen in order to have the most efficient implementation on a specific microcontroller platform.			
Description	Type, to abstract the return value of the service Icu_GetEdgeNumbers().			
Available via	lcu.h			

# 8.2.10 lcu\_MeasurementModeType

[SWS\_lcu\_00294][

[OVVO_ICU_C	0204]						
Name	Icu_MeasurementModeType						
Kind	Enumeration						
	ICU_MODE_SIGNAL_EDGE_ DETECT	0x00	Mode for detecting edges				
Range	ICU_MODE_SIGNAL_ MEASUREMENT	0x01	Mode for measuring different times between various configurable edges				
	ICU_MODE_TIMESTAMP	0x02	Mode for capturing timer values on configurable edges				
	ICU_MODE_EDGE_ COUNTER	0x03	Mode for counting edges on configurable edges				
Description	Definition of the measurement mode type						
Available via	lcu.h						

]()

# 8.2.11 Icu\_SignalMeasurementPropertyType

[SWS Icu 00295][

10110_100_1	10_10d_0200]					
Name	Icu_SignalMeasurementPropertyType					
Kind	Enumeration					
	ICU_LOW_ TIME	0x00	The channel is configured for reading the elapsed Signal Low Time			
Range	ICU_HIGH_ TIME	0x01	The channel is configured for reading the elapsed Signal High Time			
	ICU_ PERIOD_	0x02	The channel is configured for reading the elapsed Signal Period Time			



	TIME		
	ICU_DUTY_ CYCLE	0x03	The channel is configured to read values which are needed for calculating the duty cycle (coherent Active and Period Time).
Description	Definition of the measurement property type		
Available via	lcu.h		

# 8.2.12 lcu\_TimestampBufferType

[SWS\_lcu\_00296][

<u>[0110_icu_c</u>	(0250]				
Name	Icu_TimestampBufferType				
Kind	Enumeration				
Pango	ICU_LINEAR_ BUFFER	0x00	The buffer will just be filled once		
Range	ICU_CIRCULAR_ BUFFER	0x01	After reaching the end of the buffer, the driver restarts at the beginning of the buffer		
Description	Definition of the timestamp measurement property type				
Available via	lcu.h				

]()

# 8.3 Function definitions

This is a list of functions provided for upper layer modules.

# 8.3.1 **Icu\_Init**

[SWS\_lcu\_00191][

Service Name	lcu_Init		
Syntax void Icu_Init (			
Service ID [hex]	0x00		
Sync/Async	Synchronous		
Reentrancy	Non Reentrant		
Parameters (in)	ConfigPtr Pointer to a selected configuration structure		



Parameters (inout)	None
Parameters (out)	None
Return value	None
Description	This function initializes the driver.
Available via	lcu.h

**I()** 

[SWS\_lcu\_00297] [The function Icu Init shall be non re-entrant.] ()

[SWS\_Icu\_00298] [The function Icu Init initializes the driver. | ()

[SWS\_lcu\_00006] [The function Icu\_Init shall initialize all relevant registers of the configured hardware with the values of the structure referenced by the parameter ConfigPtr. ] (SRS\_BSW\_00344, SRS\_BSW\_00404, SRS\_BSW\_00405, SRS\_BSW\_00101, SRS\_SPAL\_12057, SRS\_SPAL\_12461)

The following rules regarding initialization of controller registers shall apply to this driver implementation:

- [SWS\_lcu\_00051] [If the hardware allows for only one usage of the register, the driver module implementing that functionality is responsible for initializing the register.] (SRS\_SPAL\_12461)
- [SWS\_lcu\_00052] [If the register can affect several hardware modules and if it is an I/O register it shall be initialized by the PORT driver.] (SRS\_SPAL\_12461)
- [SWS\_lcu\_00053] [If the register can affect several hardware modules and if it is not an I/O register it shall be initialized by the MCU driver.] (SRS\_SPAL\_12461)
- [SWS\_lcu\_00128] [One-time writable registers that require initialization directly
  after reset shall be initialized by the start-up code.] (SRS\_SPAL\_12461)
- [SWS\_lcu\_00129] [All other registers shall be initialized by the startup code.]
   (SRS\_SPAL\_12461)

[SWS\_lcu\_00061] [The function Icu\_Init shall disable all notifications.] (SRS\_SPAL\_12057, SRS\_lcu\_12407)

[SWS\_lcu\_00121] [The function Icu\_Init shall disable the wakeup-capability of all channels.] ()



[SWS\_lcu\_00040] [The function Icu\_Init shall set all used ICU channels to status ICU IDLE.] (SRS\_SPAL\_12057, SRS\_lcu\_12407)

[SWS\_lcu\_00060] [The function Icu\_Init shall set the module mode to ICU MODE NORMAL.] (SRS\_SPAL\_12057)

[SWS\_lcu\_00054] [The function Icu\_Init shall only set the resources that are configured in the configuration file (including clearing of pending interrupt flags).

The lcu module's environment shall not call Icu\_Init during a running operation (e. g. timestamp measurement or edge counting). | (SRS\_SPAL\_12125)

[SWS\_lcu\_00220] [If development error detection for the ICU module is enabled and the function Icu\_Init is called when the ICU driver and hardware are already initialized, the function Icu\_Init shall raise development error ICU\_E\_ALREADY\_INITIALIZED and return without any action.] ()

**[SWS\_Icu\_00138]** [The initialization function of this module shall always have a pointer as a parameter, even though for Variant PC no configuration set shall be given. Instead a NULL pointer shall be passed to the initialization function.] ()

Note: Parameter checking for the initialization function is specified within BSW General.

#### 8.3.2 Icu\_Delnit

[SWS Icu 00193][

Service Name	Icu_Delnit
Syntax	<pre>void Icu_DeInit (   void )</pre>
Service ID [hex]	0x01
Sync/Async	Synchronous
Reentrancy	Non Reentrant
Parameters (in)	None
Parameters (inout)	None
Parameters (out)	None
Return value	None
Description	This function de-initializes the ICU module.



Available via	lcu.h
---------------	-------

I()

[SWS\_lcu\_00036] [The function Icu\_DeInit shall set the state of the peripherals used by configuration as the same after power on reset.] (SRS\_SPAL\_12163, SRS\_lcu\_12429)

[SWS\_lcu\_00300] [Values of registers which are not writeable are excluded from setting the state by the function Icu DeInit.] ()

[SWS\_lcu\_00091] [The function <code>lcu\_DeInit</code> shall influence only the peripherals which are allocated by static configuration and/or the runtime configuration set passed by the previous call of <code>lcu\_Init().]()</code>

[SWS\_lcu\_00037] [The function Icu\_DeInit shall disable all used interrupts and notifications.] (SRS\_BSW\_00336, SRS\_SPAL\_12163)

[SWS\_lcu\_00152] [The lcu module's environment shall not call Icu\_DeInit during a running operation (e. g. timestamp measurement or edge counting)] ()

[SWS\_lcu\_00092] [The function Icu\_DeInit shall be pre compile time configurable by configuration parameter lcuDeInitApi.] (SRS\_BSW\_00410, SRS\_BSW\_00171)

[SWS\_lcu\_00301] [The function Icu\_DeInit shall be configurable ON/OFF by configuration parameter IcuDeInitApi. | ()

**[SWS\_Icu\_00221]**  $\Gamma$ A re-initialization of the ICU module by executing the  $Icu_Init()$  function requires a de-initialization before by executing the  $Icu_DeInit()$  function.] ()

[SWS\_lcu\_00299] [Icu\_DeInit operation is Non re-entrant.] ()

[SWS\_lcu\_00385] [If development error detection for the lcu module is enabled: This function shall raise development error ICU\_E\_UNINIT when the function Icu Init has not been called.] (SRS\_BSW\_00323, SRS\_BSW\_00406)



#### 8.3.3 Icu\_SetMode

[SWS\_lcu\_00194][

Service Name	Icu_SetMode		
Syntax	<pre>void Icu_SetMode (    Icu_ModeType Mode )</pre>		
Service ID [hex]	0x02		
Sync/Async	Synchronous		
Reentrancy	Non Reentrant		
Parameters (in)	Mode	ICU_MODE_NORMAL: Normal operation, all used interrupts are enabled according to the notification requests. ICU_MODE_SLEEP: Reduced power mode. In sleep mode only those notifications are available which are configured as wakeup capable.	
Parameters (inout)	None		
Parameters (out)	None		
Return value	None		
Description	This function sets the ICU mode.		
Available via	lcu.h		

]()

[SWS\_Icu\_00008] [The function Icu\_SetMode shall set the operation mode to the given mode parameter. The function Icu\_SetMode shall set the operation mode to the given mode parameter. This function influences the functionality of the ICU channels. Therefore the mode switching of the module shall be compatible to the overall state of the ECU. | (SRS SPAL 12067, SRS SPAL 12169, SRS Icu 12370)

[SWS\_Icu\_00302] [The function Icu SetMode shall be non re-entrant.

This function influences the functionality of the ICU channels. Therefore the mode switching of the module shall be compatible to the overall state of the ECU. ()

[SWS\_lcu\_00095] [The function Icu\_SetMode shall be pre-compile time configurable by the configuration parameter IcuSetModeApi.] (SRS\_BSW\_00410, SRS\_BSW\_00171)



[SWS\_lcu\_00303] [The function Icu\_SetMode shall be configurable ON/OFF by the configuration parameter IcuSetModeApi.] ()

[SWS\_lcu\_00125] [If development error detection is enabled for the module lcu the function Icu\_SetMode shall check the parameter Mode and shall raise the error ICU E PARAM MODE if the parameter Mode is not within the allowed range set in the configuration.] (SRS BSW 00323)

**[SWS\_Icu\_00133]** [This service can be called during running operations. If so, an ongoing operation that generates interrupts on a wakeup capable channel like e.g. time stamping or edge counting might lead to the ICU module not being able to properly enter sleep mode. This is then a system or ECU configuration issue not a problem of this specification.] (SRS\_SPAL\_12064)

[SWS\_lcu\_00386] [If development error detection for the lcu module is enabled: This function shall raise development error ICU\_E\_UNINIT when the function Icu Init has not been called.] (SRS\_BSW\_00323, SRS\_BSW\_00406)

#### 8.3.4 lcu\_DisableWakeup

[SWS\_lcu\_00195][

Service Name	Icu_DisableWakeup	
Syntax	<pre>void Icu_DisableWakeup (    Icu_ChannelType Channel )</pre>	
Service ID [hex]	0x03	
Sync/Async	Synchronous	
Reentrancy	Reentrant (limited according to ICU050)	
Parameters (in)	Channel	Numeric identifier of the ICU channel
Parameters (inout)	None	
Parameters (out)	None	
Return value	None	
Description	This function disables the wakeup capability of a single ICU channel.	
Available via	lcu.h	

]()

[SWS\_lcu\_00013] [The function Icu\_DisableWakeup shall disable the wakeup capability of a single ICU channel.] (SRS\_lcu\_12408)



[SWS\_Icu\_00305] [The function Icu\_DisableWakeup shall disable the wakeup capability of a single ICU channel only for ICU channels configured statically as wakeup capable true.] ()

[SWS\_Icu\_00304] [The function Icu DisableWakeup shall be re-entrant.] ()

[SWS\_Icu\_00096] [The function Icu\_DisableWakeup shall be pre compile time configurable by the configuration parameter IcuDisableWakeupApi.] (SRS BSW 00410, SRS BSW 00171)

[SWS\_lcu\_00306] [The function Icu\_DisableWakeup shall be configurable ON/OFF by the configuration parameter IcuDisableWakeupApi.

The settings done by this function are only relevant after the <code>ICU\_MODE\_SLEEP</code> is set. | ()

[SWS\_Icu\_00024] [If development error detection is enabled: The function Icu\_DisableWakeup shall check the parameter Channel and shall raise development error ICU E PARAM CHANNEL if Channel is not within the allowed range set in the configuration.] (SRS\_BSW\_00323)

[SWS\_Icu\_00059] [If development error detection is enabled: The function Icu\_DisableWakeup shall check the parameter Channel. The function Icu\_DisableWakeup shall raise development error ICU E PARAM CHANNEL if Channel is indexing an ICU channel statically not configured as wakeup capable. | ()

[SWS\_lcu\_00387] [If development error detection for the lcu module is enabled: This function shall raise development error ICU\_E\_UNINIT when the function Icu Init has not been called.] (SRS\_BSW\_00323, SRS\_BSW\_00406)

#### 8.3.5 Icu\_EnableWakeup

#### [SWS\_lcu\_00196][

Service Name	lcu_EnableWakeup	
Syntax	<pre>void Icu_EnableWakeup (    Icu_ChannelType Channel )</pre>	
Service ID [hex]	0x04	
Sync/Async	Synchronous	
Reentrancy	Reentrant (limited according to ICU050)	



Parameters (in)	Channel	Numeric identifier of the ICU channel
Parameters (inout)	None	
Parameters (out)	None	
Return value	None	
Description	This function (re-)enables the wakeup capability of the given ICU channel.	
Available via	lcu.h	

[SWS\_Icu\_00307] [The function Icu EnableWakeup shall be re-entrant.] ()

[SWS\_lcu\_00014] [The function Icu\_EnableWakeup shall re-enable the wakeup capability of a single ICU channel for the following ICU mode selection(s). This service is only feasible for ICU channels configured as wakeup capable true.

To make the selection effective a call of the function <code>Icu\_SetMode</code>, requesting the mode <code>ICU\_MODE\_SLEEP</code> is required.] (SRS\_lcu\_12408)

[SWS\_lcu\_00097] [The function Icu\_EnableWakeup shall be pre compile time configurable by configuration parameter IcuEnableWakeupApi.] (SRS\_BSW\_00410, SRS\_BSW\_00171)

[SWS\_lcu\_00308] [The function Icu\_EnableWakeup shall be configurable ON/OFF by configuration parameter IcuEnableWakeupApi.] ()

[SWS\_Icu\_00155] [If development error detection is enabled: The function Icu\_EnableWakeup shall check the parameter Channel and shall raise the error ICU E PARAM CHANNEL if Channel is invalid. | ()

[SWS\_Icu\_00156] [If development error detection is enabled: The function Icu\_EnableWakeup shall check the parameter Channel. The function Icu\_EnableWakeup shall raise the error ICU E PARAM CHANNEL if Channel is indexing an ICU channel statically not configured as wakeup capable.

[SWS\_Icu\_00388] [If development error detection for the Icu module is enabled: This function shall raise development error ICU\_E\_UNINIT when the function Icu Init has not been called.] (SRS\_BSW\_00323, SRS\_BSW\_00406)

#### 8.3.6 Icu\_CheckWakeup



[SWS\_lcu\_00358][

Service Name	Icu_CheckWakeup		
Syntax	<pre>void Icu_CheckWakeup (    EcuM_WakeupSourceType WakeupSource )</pre>		
Service ID [hex]	0x15		
Sync/Async	Synchronous		
Reentrancy	Reentrant (limited according to ICU050)		
Parameters (in)	Wakeup Source	Informatin on wakeup source to be checked. The associated ICU channel can be determined from configuration data.	
Parameters (inout)	None		
Parameters (out)	None		
Return value	None		
Description	Checks if a wakeup capable ICU channel is the source for a wakeup event and calls the ECU state manager service EcuM_SetWakeupEvent in case of a valid ICU channel wakeup event.		
Available via	lcu.h		

|()

[SWS\_lcu\_00359] [The function Icu\_CheckWakeup shall check if a wakeup capable ICU channel is the source for a wakeup event and call EcuM\_SetWakeupEvent to indicate a valid timer wakeup event to the ECU State Manager.] ()

[SWS\_lcu\_00360] [The function Icu\_CheckWakeup is only feasible, if IcuReportWakeupSource is statically configured available.] ()

[SWS\_Icu\_00361] [The ICU module's environment shall only use the re-entrant capability of the function Icu\_CheckWakeup if the ICU module's environment takes care that there is no simultaneous usage of the same channel.] ()

[SWS\_lcu\_00362] [The function Icu\_CheckWakeup shall be pre compile time configurable On/Off by the configuration parameter: IcuWakeupFunctionalityApi]()

[SWS\_lcu\_00363] [If development error detection for the ICU module is enabled: if the function Icu\_CheckWakeup is called before the ICU module was initialized, the function Icu CheckWakeup shall raise the development error ICU E UNINIT] ()



## 8.3.7 Icu\_SetActivationCondition

[SWS\_lcu\_00197][

[3W3_ICU_00197]	1	
Service Name	Icu_SetActivationCondition	
Syntax	<pre>void Icu_SetActivationCondition (    Icu_ChannelType Channel,    Icu_ActivationType Activation )</pre>	
Service ID [hex]	0x05	
Sync/Async	Synchronous	
Reentrancy	Reentrant (limited according to ICU050)	
	Channel	Numeric identifier of the ICU channel
Parameters (in)	Activation	Type of activation (if supported by hardware)  • ICU_RISING_EDGE  • ICU_FALLING_EDGE  • ICU_BOTH_EDGES
Parameters (inout)	None	
Parameters (out)	None	
Return value	None	
Description	This function sets the activation-edge for the given channel.	
Available via	lcu.h	

**(**)

[SWS\_lcu\_00090] [The function Icu\_SetActivationCondition shall set the activation-edge according to Activation parameter for the given channel. This service shall support channels which are configured for the following

IcuMeasurementMode (for details refer to 8.2.10)

- ICU MODE SIGNAL EDGE DETECT
- ICU MODE TIMESTAMP
- ICU MODE EDGE COUNTER (SRS\_BSW\_00410)

[SWS\_lcu\_00139] [The function Icu\_SetActivationCondition shall reset the state for the given channel to ICU IDLE. | ()



[SWS\_lcu\_00309] [The function  $Icu_SetActivationCondition$  shall be reentrant.] ()

[SWS\_Icu\_00159] [If development error detection is enabled the function Icu\_SetActivationCondition shall check the parameter Channel and shall raise the error ICU E PARAM CHANNEL if Channel is not within the range set in the configuration.] ()

[SWS\_Icu\_00043] [If development error detection is enabled the function Icu\_SetActivationCondition shall check the parameter Activation. The function Icu\_SetActivationCondition shall raise the error ICU E PARAM ACTIVATION if Activation is invalid but only for the requested ICU channel.] (SRS\_BSW\_00323)

#### 8.3.8 Icu\_DisableNotification

[SWS\_lcu\_00198][

Service Name	Icu_DisableNotification	
Syntax	<pre>void Icu_DisableNotification (    Icu_ChannelType Channel )</pre>	
Service ID [hex]	0x06	
Sync/Async	Synchronous	
Reentrancy	Reentrant (limited according to ICU050)	
Parameters (in)	Channel Numeric identifier of the ICU channel	
Parameters (inout)	None	
Parameters (out)	None	
Return value	None	
Description	This function disables the notification of a channel.	
Available via	lcu.h	

**(**)

[SWS\_lcu\_00009] [The function  $lcu_DisableNotification$  shall disable the notification on the given channel.] (SRS\_lcu\_12305)



[SWS\_lcu\_00310] [The function  $Icu_DisableNotification shall be reentrant.] ()$ 

[SWS\_Icu\_00160] [If development error detection is enabled the function Icu\_DisableNotification shall check the parameter Channel and shall raise the error ICU E PARAM CHANNEL if Channel is invalid (invalid identifier).] ()

[SWS\_lcu\_00389] [If development error detection for the lcu module is enabled: This function shall raise development error ICU\_E\_UNINIT when the function Icu Init has not been called.] (SRS\_BSW\_00323, SRS\_BSW\_00406)

### 8.3.9 Icu\_EnableNotification

[SWS\_lcu\_00199][

Service Name	Icu_EnableNotification		
Syntax	<pre>void Icu_EnableNotification (    Icu_ChannelType Channel )</pre>		
Service ID [hex]	0x07		
Sync/Async	Synchronous	Synchronous	
Reentrancy	Reentrant (limited according to ICU050)		
Parameters (in)	Channel	Numeric identifier of the ICU channel	
Parameters (inout)	None		
Parameters (out)	None		
Return value	None		
Description	This function enables the notification on the given channel.		
Available via	lcu.h		

]()

[SWS\_lcu\_00010] [The function Icu\_EnableNotification shall enable the notification on the given channel. | (SRS\_lcu\_12305)

[SWS\_Icu\_00311] [The function Icu\_EnableNotification shall be re-entrant.] ()



[SWS\_Icu\_00161] [If development error detection is enabled the function Icu\_EnableNotification shall check the parameter Channel and shall raise the error ICU E PARAM CHANNEL if Channel is invalid (invalid identifier).]()

[SWS\_Icu\_00390] [If development error detection for the Icu module is enabled: This function shall raise development error ICU\_E\_UNINIT when the function Icu Init has not been called.] (SRS\_BSW\_00323, SRS\_BSW\_00406)

#### 8.3.10 Icu\_GetInputState

[SWS\_lcu\_00200][

Service Name	l	Icu_GetInputState		
Syntax	<pre>Icu_InputStateType Icu_GetInputState (    Icu_ChannelType Channel )</pre>			
Service ID [hex]	0x08	0x08		
Sync/Async	Synchronous	Synchronous		
Reentrancy	Reentrant (limited according to ICU050)			
Parameters (in)	Channel	Numeric identifier of the ICU channel		
Parameters (inout)	None			
Parameters (out)	None			
Return value	Icu_Input- StateType	ICU_ACTIVE: An activation edge has been detected ICU_IDLE: No activation edge has been detected since the last call of Icu_GetInputState() or Icu_Init().		
Description	This function returns the status of the ICU input.			
Available via	lcu.h			

|()|

[SWS\_lcu\_00313] [Icu\_GetInputState shall return Icu\_InputStateType which will have value ICU\_IDLE when no activation edge has been detected since the last call of Icu GetInputState() or Icu Init().]()

[SWS\_Icu\_00030] [The function Icu\_GetInputState shall return the status of the ICU input. Only channels which are configured for the following IcuMeasurementMode shall be supported:

ICU MODE SIGNAL EDGE DETECT



■ ICU MODE SIGNAL MEASUREMENT | (SRS\_SPAL\_00157, SRS\_Icu\_12371)

[SWS\_lcu\_00312] [The function Icu\_GetInputState shall be re-entrant.] ()

[SWS\_lcu\_00031] [If an activation edge has been detected the function Icu\_GetInputState shall return ICU\_ACTIVE for Edge Detection channels.] (SRS lcu 12371)

[SWS\_Icu\_00314] [For Signal Measurement a channel should be set to ICU\_ACTIVE not until this measurement has completed and the driver is able to provide useful information on the input signal.] ()

[SWS\_lcu\_00032] [Once the function <code>Icu\_GetInputState</code> has returned the status <code>ICU\_ACTIVE</code>, the function <code>Icu\_GetInputState</code> shall set the stored status to <code>ICU\_IDLE</code> until the next edge is detected. | (SRS\_lcu\_12371)

[SWS\_lcu\_00122] [The function Icu\_GetInputState shall be pre compile time configurable by the configuration parameter IcuGetInputStateApi.] (SRS\_BSW\_00410, SRS\_BSW\_00171)

[SWS\_lcu\_00315] [The function Icu\_GetInputState shall be configurable ON/OFF by the configuration parameter IcuGetInputStateApi.] ()

[SWS\_lcu\_00162] [If development error detection is enabled the function Icu\_GetInputState shall check the parameter Channel and shall raise the error ICU\_E\_PARAM\_CHANNEL if Channel is invalid (invalid identifier or channel not configured for modes ICU\_MODE\_SIGNAL\_EDGE\_DETECT\_or ICU\_MODE\_SIGNAL\_MEASUREMENT)] ()

[SWS\_Icu\_00049] [If development error detection is enabled the function Icu\_GetInputState shall return ICU\_IDLE if an error is detected.

] (SRS\_SPAL\_12448, SRS\_BSW\_00369)

[SWS\_lcu\_00391] [If development error detection for the lcu module is enabled: This function shall raise development error ICU\_E\_UNINIT when the function Icu Init has not been called.] (SRS\_BSW\_00323, SRS\_BSW\_00406)

#### 8.3.11 Icu StartTimestamp

#### **ISWS Icu 002011**

	[		
Service Name	Icu_StartTimestamp		



Syntax	<pre>void Icu_StartTimestamp (    Icu_ChannelType Channel,    Icu_ValueType* BufferPtr,    uint16 BufferSize,    uint16 NotifyInterval )</pre>		
Service ID [hex]	0x09		
Sync/Async	Asynchronou	ıs	
Reentrancy	Reentrant (limited according to ICU050)		
	Channel	Numeric identifier of the ICU channel	
Parameters (in)	BufferSize	Size of the external buffer (number of entries)	
	Notify Interval	Notification interval (number of events). This parameter can not be checked in a reasonable way.	
Parameters (inout)	None		
Parameters (out)	BufferPtr	Pointer to the buffer-array where the timestamp values shall be placed.	
Return value	None		
Description	This function starts the capturing of timer values on the edges.		
Available via	lcu.h		

]()

[SWS\_lcu\_00317] [The function  $lcu_StartTimestamp$  shall start the capturing of timer values on the edges to an external buffer, at the beginning of the buffer. ] ()



[SWS\_Icu\_00063] [The function Icu\_StartTimestamp shall start the capturing of timer values on the edges

activated by the service Icu\_SetActivationCondition()
 (rising / falling / both edges) | (SRS\_BSW\_00410, SRS\_SPAL\_12063, SRS\_SPAL\_12075, SRS\_Icu\_12430, SRS\_Icu\_12438)

[SWS\_lcu\_00316] [The function Icu StartTimestamp shall be re-entrant.] ()

**[SWS\_Icu\_00064]** [If circular buffer handling is configured (for the given channel), when the capture functionality reaches the end of the buffer, the Icu module shall start at the beginning of the buffer.] ()

**[SWS\_lcu\_00065]** [If linear buffer handling is configured, when the capture functionality reaches the end of the buffer, the lcu module shall stop capturing timer values.] (SRS\_lcu\_12456)

**[SWS\_Icu\_00134]** [The Icu module shall only call a notification function if a notification function is configured.] ()

[SWS\_lcu\_00318] [The lcu module shall only call a notification function if the notification has been enabled by the call of Icu EnableNotification().] ()

**[SWS\_lcu\_00319]** [The lcu module shall only call a notification function if NotifyInterval is greater than "0".] ()

[SWS\_lcu\_00320] [The lcu module shall only call a notification function if the number of events specified by NotifyInterval has been captured. ] ()

[SWS\_lcu\_00066] [The function Icu\_StartTimeStamp shall only be available in Measurement Mode "ICU\_MODE\_TIMESTAMP".] (SRS\_lcu\_12430)

[SWS\_lcu\_00098] [The function <code>Icu\_StartTimestamp</code> shall be pre-compile time configurable by the configuration parameter: <code>ICU\_TIMESTAMP\_API.</code>] (SRS\_BSW\_00171)

[SWS\_lcu\_00321] [The function Icu\_StartTimestamp shall be configurable ON/OFF by the configuration parameter: ICU TIMESTAMP API.] ()

[SWS\_lcu\_00163] [If development error detection is enabled the function Icu\_StartTimestamp shall check the parameter Channel and shall raise the error ICU\_E\_PARAM\_CHANNEL if Channel is invalid (invalid identifier or channel not configured for mode ICU\_MODE\_TIMESTAMP).] ()



[SWS\_Icu\_00354] [If development error detection is enabled and a notification function has been configured for the addressed channel, the function Icu\_StartTimestamp shall check the parameter NotifyInterval for validity and raise the error ICU\_E\_PARAM\_NOTIFY\_INTERVAL if the parameter NotifyInterval is "0".] ()

[SWS\_Icu\_00108] [If development error detection is enabled the function Icu\_StartTimestamp shall check the parameter BufferSize (check that size > 0). The function Icu\_StartTimestamp shall raise the error ICU E PARAM BUFFER SIZE if BufferSize is invalid (e.g. "0").

| (SRS SPAL 12448)

[SWS\_lcu\_00392] [If development error detection for the lcu module is enabled: This function shall raise development error ICU\_E\_UNINIT when the function Icu Init has not been called. | (SRS\_BSW\_00323, SRS\_BSW\_00406)

#### 8.3.12 Icu\_StopTimestamp

[SWS Icu 00202][

Service Name	Icu_StopTimestamp	
Syntax	<pre>void Icu_StopTimestamp (    Icu_ChannelType Channel )</pre>	
Service ID [hex]	0x0a	
Sync/Async	Synchronous	
Reentrancy	Reentrant (limited according to ICU050)	
Parameters (in)	Channel Numeric identifier of the ICU channel	
Parameters (inout)	None	
Parameters (out)	None	
Return value	None	
Description	This function stops the timestamp measurement of the given channel.	
Available via	lcu.h	

1()

[SWS\_lcu\_00067] [The function Icu\_StopTimestamp shall stop the timestamp measurement of the given channel.] (SRS lcu 12431)

[SWS\_lcu\_00322] [Icu StopTimestamp operation is Re-entrant.



In production mode the function Icu\_StopTimestamp shall not return an error when the Channel is not active (has not started or has already stopped). ] ()

[SWS\_Icu\_00165] [The function Icu\_StopTimestamp shall only be available in Measurement Mode: ICU\_MODE\_TIMESTAMP.] ()

[SWS\_Icu\_00099] [The function Icu\_StopTimestamp shall be pre-compile time configurable by the configuration parameter: IcuTimestampApi (see also chapter 10.2.4. Configuration of optional API services)] (SRS BSW 00410, SRS BSW 00171)

[SWS\_lcu\_00164] [If development error detection is enabled the function Icu\_StopTimestamp shall check the parameter Channel and shall raise development error ICU\_E\_PARAM\_CHANNEL if Channel is invalid (invalid identifier or channel not configured for mode ICU MODE TIMESTAMP)] ()

[SWS\_lcu\_00323] [The function Icu\_StopTimestamp shall be configurable ON/OFF by the configuration parameter: IcuTimestampApi.| ()

[SWS\_Icu\_00166] [The function Icu\_StopTimestamp shall raise runtime error ICU E NOT STARTED if Channel is not active (has not started or is already stopped).]()

[SWS\_Icu\_00393] [If development error detection for the Icu module is enabled: This function shall raise development error ICU\_E\_UNINIT when the function Icu Init has not been called. | (SRS\_BSW\_00323, SRS\_BSW\_00406)

## 8.3.13 lcu\_GetTimestampIndex

#### [SWS Icu 00203][

[0110_10000_00]		
Service Name	Icu_GetTimestampIndex	
Syntax	<pre>Icu_IndexType Icu_GetTimestampIndex (    Icu_ChannelType Channel )</pre>	
Service ID [hex]	0x0b	
Sync/Async	Synchronous	
Reentrancy	Reentrant (limited according to ICU050)	
Parameters (in)	Channel	Numeric identifier of the ICU channel
Parameters (inout)	None	



Parameters (out)	None	
Return value	lcu_IndexType	Abstract return type to cover different microcontrollers.
Description	This function reads the timestamp index of the given channel.	
Available via	lcu.h	

1()

[SWS\_lcu\_00071] [The function Icu\_GetTimestampIndex shall read the timestamp index of the given channel, which is the next to be written.] (SRS\_lcu\_12453)

[SWS\_lcu\_00324] [The function Icu\_GetTimestampIndex shall be re-entrant.] ()

[SWS\_Icu\_00135] [The function Icu\_GetTimestampIndex shall return "0" in case the service is called before Icu\_StartTimestamp() (no buffer is defined in this case). ] ()

[SWS\_lcu\_00170] [The function Icu\_GetTimestampIndex shall only be available in Measurement Mode ICU MODE TIMESTAMP.] ()

[SWS\_Icu\_00100] [The function Icu\_GetTimestampIndex shall be pre compile time configurable by the configuration parameter: IcuTimestampApi] (SRS\_BSW\_00410, SRS\_BSW\_00171)

[SWS\_lcu\_00325] [The function Icu\_GetTimestampIndex shall be configurable ON/OFF by the configuration parameter: IcuTimestampApi.] ()

[SWS\_lcu\_00169] [If development error detection is enabled the function Icu\_GetTimestampIndex shall check the parameter Channel. If Channel is invalid (invalid identifier or channel not configured for mode ICU\_MODE\_TIMESTAMP), the function Icu\_GetTimestampIndex shall raise development error ICU E PARAM CHANNEL.] ()

[SWS\_lcu\_00107] [If development error detection is enabled the function Icu\_GetTimestampIndex shall return "0" if an error is detected.

| (SRS\_SPAL\_12448)

[SWS\_lcu\_00394] [If development error detection for the lcu module is enabled: This function shall raise development error ICU\_E\_UNINIT when the function Icu\_Init has not been called.] (SRS\_BSW\_00323, SRS\_BSW\_00406)



#### 8.3.14 Icu\_ResetEdgeCount

[SWS Icu 00204][

Service Name	lcu_ResetEdge	eCount
Syntax	<pre>void Icu_ResetEdgeCount (    Icu_ChannelType Channel )</pre>	
Service ID [hex]	0x0c	
Sync/Async	Synchronous	
Reentrancy	Reentrant (limited according to ICU050)	
Parameters (in)	Channel Numeric identifier of the ICU channel	
Parameters (inout)	None	
Parameters (out)	None	
Return value	None	
Description	This function resets the value of the counted edges to zero.	
Available via	lcu.h	

[SWS\_lcu\_00072] [The function Icu\_ResetEdgeCount shall reset the value of the counted edges to zero.] (SRS\_lcu\_12439, SRS\_lcu\_13100)

[SWS\_lcu\_00326] [The function Icu ResetEdgeCount shall be re-entrant.] ()

[SWS\_Icu\_00101] [The function Icu\_ResetEdgeCount shall be pre-compile time configurable by the configuration parameter ICU\_EDGE\_COUNT\_API.] (SRS\_BSW\_00410, SRS\_BSW\_00171)

[SWS\_lcu\_00327] [The function Icu\_ResetEdgeCount shall be configurable ON/OFF by the configuration parameter: ICU\_EDGE\_COUNT\_API.] ()

[SWS\_Icu\_00171] [If development error detection is enabled the function Icu\_ResetEdgeCount shall check the parameter Channel. If Channel is invalid (invalid identifier or channel not configured for mode ICU\_MODE\_EDGE\_COUNTER), then Icu\_ResetEdgeCount shall raise development error ICU\_E\_PARAM\_CHANNEL.] ()

[SWS\_lcu\_00395] [If development error detection for the lcu module is enabled: This function shall raise development error ICU\_E\_UNINIT when the function Icu Init has not been called.] (SRS\_BSW\_00323, SRS\_BSW\_00406)



### 8.3.15 Icu\_EnableEdgeCount

[SWS\_lcu\_00205][

Service Name	lcu_EnableEdgeCount		
Syntax	<pre>void Icu_EnableEdgeCount (    Icu_ChannelType Channel )</pre>		
Service ID [hex]	0x0d	0x0d	
Sync/Async	Synchronous		
Reentrancy	Reentrant (limited according to ICU050)		
Parameters (in)	Channel Numeric identifier of the ICU channel		
Parameters (inout)	None		
Parameters (out)	None		
Return value	None		
Description	This function enables the counting of edges of the given channel.		
Available via	lcu.h		

|()|

[SWS\_lcu\_00078] [The function Icu\_EnableEdgeCount shall enable the counting of edges of the given channel.] (SRS\_lcu\_12432)

Note: This service does not do the real counting itself.

[SWS\_lcu\_00073] [The function Icu\_EnableEdgeCount shall only count the configured¹ edges (rising edge / falling edge / both edges).] (SRS\_lcu\_12439)

[SWS\_lcu\_00074] [The function Icu\_EnableEdgeCount shall be available for each ICU channel in Measurement Mode "Edge Counter". | (SRS Icu 12439)

[SWS\_lcu\_00328] [The function Icu\_EnableEdgeCount shall be re-entrant.] ()

[SWS\_lcu\_00102] [The function Icu\_EnableEdgeCount shall be pre-compile time configurable by the configuration parameter ICU\_EDGE\_COUNT\_API] (SRS\_BSW\_00410, SRS\_BSW\_00171)

[SWS\_lcu\_00329] [The function Icu\_EnableEdgeCount shall be configurable On/Off by the configuration parameter: ICU EDGE COUNT API.] ()

<sup>&</sup>lt;sup>1</sup> Configured edge after the call of Icu\_Init() (default-edge) or Icu\_SetActivationCondition().

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[SWS\_lcu\_00172] [If development error detection is enabled, the function Icu\_EnableEdgeCount shall check the parameter Channel. If Channel is invalid (invalid identifier or channel not configured for mode ICU\_MODE\_EDGE\_COUNTER), then the function Icu\_EnableEdgeCount shall raise development error ICU E PARAM CHANNEL.] ()

[SWS\_lcu\_00396] [If development error detection for the lcu module is enabled: This function shall raise development error ICU\_E\_UNINIT when the function Icu Init has not been called.] (SRS\_BSW\_00323, SRS\_BSW\_00406)

#### 8.3.16 lcu\_EnableEdgeDetection

[SWS\_lcu\_00364][

[3442_icu_00304]	50304]		
Service Name	Icu_EnableEdgeDetection		
Syntax	<pre>void Icu_EnableEdgeDetection (    Icu_ChannelType Channel )</pre>		
Service ID [hex]	0x16		
Sync/Async	Synchronous		
Reentrancy	Reentrant (limited according to ICU050)		
Parameters (in)	Channel Numeric identifier of the ICU channel		
Parameters (inout)	None		
Parameters (out)	None		
Return value	None		
Description	This function enables / re-enables the detection of edges of the given channel.		
Available via	lcu.h		

I()

[SWS\_lcu\_00365] [The function Icu\_EnableEdgeDetection shall enable the detection of edges for the given channel. | ()

[SWS\_lcu\_00366] [The function Icu\_EnableEdgeDetection shall only detect the configured edges (rising edge / falling edge / both edges). | ()

[SWS\_lcu\_00367] [The function Icu\_EnableEdgeDetection shall be available for each ICU Channel in Measurement Mode "Edge Detection".] ()



[SWS\_lcu\_00368] [The function  $lcu_EnableEdgeDetection$  shall be reentrant.] ()

[SWS\_lcu\_00369] [The function Icu\_EnableEdgeDetection shall be precompile time configurable by the configuration parameter IcuEdgeDetectApi. | ()

[SWS\_lcu\_00370] [The function Icu\_EnableEdgeDetection shall be configurable ON/OFF by the configuration parameter: IcuEdgeDetectApi.] ()

[SWS\_lcu\_00371] [If development error detection is enabled; the function Icu\_EnableEdgeDetection shall check the parameter Channel. If Channel is invalid (invalid identifier or channel not configured for mode ICU\_MODE\_SIGNAL\_EDGE\_DETECT), then the function Icu\_EnableEdgeDetection shall raise development error ICU\_E\_PARAM\_CHANNEL.]()

[SWS\_Icu\_00397] [If development error detection for the Icu module is enabled: This function shall raise development error ICU\_E\_UNINIT when the function Icu Init has not been called.] (SRS\_BSW\_00323, SRS\_BSW\_00406)

## 8.3.17 lcu\_DisableEdgeDetection

#### [SWS\_lcu\_00377][

Service Name	Icu_DisableEdgeDetection		
Syntax	<pre>void Icu_DisableEdgeDetection (    Icu_ChannelType Channel )</pre>		
Service ID [hex]	0x17		
Sync/Async	Synchronous		
Reentrancy	Reentrant (limited according to ICU050)		
Parameters (in)	Channel Numeric identifier of the ICU channel		
Parameters (inout)	None		
Parameters (out)	None		
Return value	None		
Description	This function disables the detection of edges of the given channel.		
Available via	lcu.h	lcu.h	



**(**()

[SWS\_lcu\_00372] [The function <code>lcu\_DisableEdgeDetection</code> shall disable the detection of edges of the given channel] ()

[SWS\_lcu\_00373] [The function Icu\_DisableEdgeDetection shall be reentrant.] ()

[SWS\_lcu\_00374] [The function Icu\_DisableEdgeDetection shall be precompile time configurable by the configuration parameter IcuEdgeDetectApi | ()

[SWS\_lcu\_00375] [The function Icu\_DisableEdgeDetection shall be configurable ON/OFF by the configuration parameter IcuEdgeDetectApi] ()

[SWS\_lcu\_00376] [If development error detection is enabled the function Icu\_DisableEdgeDetection shall check the parameter Channel. If Channel is invalid (invalid identifier or channel not configured for mode ICU\_MODE\_SIGNAL\_EDGE\_DETECT), the function Icu\_DisableEdgeDetection shall raise development error ICU\_E\_PARAM\_CHANNEL.] ()

[SWS\_lcu\_00398] [If development error detection for the lcu module is enabled: This function shall raise development error ICU\_E\_UNINIT when the function Icu Init has not been called. | (SRS\_BSW\_00323, SRS\_BSW\_00406)

#### 8.3.18 Icu\_DisableEdgeCount

**ISWS Icu 002061**[

Service Name	Icu_DisableEdgeCount	
Syntax	<pre>void Icu_DisableEdgeCount (    Icu_ChannelType Channel )</pre>	
Service ID [hex]	0x0e	
Sync/Async	Synchronous	
Reentrancy	Reentrant (limited according to ICU050)	
Parameters (in)	Channel Numeric identifier of the ICU channel	
Parameters (inout)	None	
Parameters (out)	None	
Return value	None	



Description	This function disables the counting of edges of the given channel.
Available via	lcu.h

[SWS\_Icu\_00079] [The function Icu\_DisableEdgeCount shall disable the counting of edges of the given channel. | (SRS Icu 12433)

[SWS\_lcu\_00330] [The function Icu\_DisableEdgeCount shall be re-entrant. To reset the edge counter, the service Icu\_ResetEdgeCount() is available.] ()

[SWS\_Icu\_00103] [The function Icu\_DisableEdgeCount shall be pre-compile time configurable by the configuration parameter IcuEdgeCountApi.] (SRS\_BSW\_00410, SRS\_BSW\_00171)

[SWS\_lcu\_00331] [The function Icu\_DisableEdgeCount shall be configurable ON/OFF by the configuration parameter IcuEdgeCountApi.] ()

[SWS\_lcu\_00173] [If development error detection is enabled the function Icu\_DisableEdgeCount shall check the parameter Channel. If Channel is invalid (invalid identifier or channel not configured for mode ICU\_MODE\_EDGE\_COUNTER), the function Icu\_DisableEdgeCount shall raise development error ICU E PARAM CHANNEL.] ()

[SWS\_lcu\_00399] [If development error detection for the lcu module is enabled: This function shall raise development error ICU\_E\_UNINIT when the function Icu Init has not been called.] (SRS\_BSW\_00323, SRS\_BSW\_00406)

### 8.3.19 Icu\_GetEdgeNumbers

[SWS Icu 00207][

Service Name	Icu_GetEdgeNumbers		
Syntax	<pre>Icu_EdgeNumberType Icu_GetEdgeNumbers (    Icu_ChannelType Channel )</pre>		
Service ID [hex]	0x0f		
Sync/Async	Synchronous		
Reentrancy	Reentrant (limited according to ICU050)		
Parameters (in)	Channel Numeric identifier of the ICU channel		
Parameters (inout)	None		



Parameters (out)	None		
Return value	Icu_EdgeNumber- Type	Abstract return type to cover different microcontrollers.	
Description	This function reads the number of counted edges.		
Available via	lcu.h		

]()

[SWS\_lcu\_00080] [The function Icu\_GetEdgeNumbers shall read the number of counted edges after the last call of Icu ResetEdgeCount().] (SRS\_lcu\_12434)

[SWS\_lcu\_00332] [The function Icu GetEdgeNumbers shall be re-entrant.] ()

[SWS\_Icu\_00104] [The function Icu\_GetEdgeNumbers shall be pre compile time configurable by the configuration parameter: ICU\_EDGE\_COUNT\_API] (SRS BSW 00410, SRS BSW 00171)

[SWS\_Icu\_00333] [The function Icu\_GetEdgeNumbers shall be configurable ON/OFF by the configuration parameter: ICU EDGE COUNT API.] ()

[SWS\_lcu\_00174] [If development error detection is enabled, the function Icu\_GetEdgeNumbers shall check the parameter Channel. If Channel is invalid (invalid identifier or channel not configured for mode ICU\_MODE\_EDGE\_COUNTER), the function Icu\_GetEdgeNumbers shall raise development error ICU\_E\_PARAM\_CHANNEL.] ()

[SWS\_lcu\_00175] [If development error detection is enabled the function Icu\_GetEdgeNumbers shall return "0" if an error is detected.]()

[SWS\_lcu\_00400] [If development error detection for the lcu module is enabled: This function shall raise development error ICU\_E\_UNINIT when the function Icu Init has not been called.] (SRS\_BSW\_00323, SRS\_BSW\_00406)

## 8.3.20 lcu\_StartSignalMeasurement

[SWS\_lcu\_00208][

Service Name	Icu_StartSignalMeasurement
Syntax	<pre>void Icu_StartSignalMeasurement (    Icu_ChannelType Channel )</pre>



Service ID [hex]	0x13	
Sync/Async	Asynchronous	
Reentrancy	Reentrant (lim	ited according to ICU050)
Parameters (in)	Channel	Numeric identifier of the ICU channel
Parameters (inout)	None	
Parameters (out)	None	
Return value	None	
Description	This function starts the measurement of signals.	
Available via	lcu.h	

|()|

[SWS\_lcu\_00334] [The function Icu\_StartSignalMeasurement shall be reentrant.] ()

[SWS\_Icu\_00140] [The function Icu\_StartSignalMeasurement shall start the measurement of signals beginning with the configured default start edge which occurs first after the call of this service. | ()

[SWS\_lcu\_00141] [The function Icu\_StartSignalMeasurement shall only be available in Measurement Mode "ICU MODE SIGNAL MEASUREMENT".] ()

[SWS\_lcu\_00146] [The function <code>Icu\_StartSignalMeasurement</code> shall reset the state for the given channel to <code>ICU\_IDLE.</code>] ()

[SWS\_lcu\_00142] [The function Icu\_StartSignalMeasurement shall be precompile time configurable by the configuration parameter

IcuSignalMeasurementApi | ()

[SWS\_Icu\_00335] [The function Icu\_StartSignalMeasurement shall be configurable ON/OFF by the configuration parameter IcuSignalMeasurementApi.] ()

[SWS\_Icu\_00176] [If development error detection is enabled, the function Icu\_StartSignalMeasurement shall check the parameter Channel. If Channel is invalid (invalid identifier or channel not configured for mode ICU\_MODE\_SIGNAL\_MEASUREMENT), the function Icu\_StartSignalMeasurement shall raise development error ICU\_E\_PARAM\_CHANNEL.] ()



[SWS\_lcu\_00401] [If development error detection for the lcu module is enabled: This function shall raise development error ICU\_E\_UNINIT when the function Icu Init has not been called.] (SRS\_BSW\_00323, SRS\_BSW\_00406)

#### 8.3.21 Icu\_StopSignalMeasurement

[SWS\_lcu\_00209][

Service Name	Icu_StopSignalMeasurement		
Syntax	<pre>void Icu_StopSignalMeasurement (    Icu_ChannelType Channel )</pre>		
Service ID [hex]	0x14		
Sync/Async	Synchronous		
Reentrancy	Reentrant (limited according to ICU050)		
Parameters (in)	Channel Numeric identifier of the ICU channel		
Parameters (inout)	None		
Parameters (out)	None		
Return value	None		
Description	This function stops the measurement of signals of the given channel.		
Available via	lcu.h	lcu.h	

()

[SWS\_lcu\_00336] [The function  $lcu_StopSignalMeasurement$  shall be Reentrant.] ()

[SWS\_lcu\_00143] [The function Icu\_StopSignalMeasurement shall stop the measurement of signals of the given channel.] ()

[SWS\_lcu\_00144] [The function Icu\_StopSignalMeasurement shall only be available in Measurement Mode"ICU MODE SIGNAL MEASUREMENT"] ()

[SWS\_lcu\_00145] [The function Icu\_StopSignalMeasurement shall be pre compile time configurable by the configuration parameter IcuSignalMeasurementApi] ()



[SWS\_lcu\_00337] [The function <code>Icu\_StopSignalMeasurement</code> shall be configurable <code>ON/OFF</code> by the configuration parameter

IcuSignalMeasurementApi.]()

[SWS\_lcu\_00177] [If development error detection is enabled the function Icu\_StopSignalMeasurement shall check the parameter Channel. If Channel is invalid (invalid identifier or channel not configured for mode ICU\_MODE\_SIGNAL\_MEASUREMENT), the function Icu\_StopSignalMeasurement shall raise development error ICU E PARAM CHANNEL.] ()

[SWS\_Icu\_00402] [If development error detection for the Icu module is enabled: This function shall raise development error ICU\_E\_UNINIT when the function Icu Init has not been called.] (SRS\_BSW\_00323, SRS\_BSW\_00406)

### 8.3.22 lcu\_GetTimeElapsed

[SWS Icu 00210][

[3773_ICU_00210]		
Service Name	Icu_GetTimeElapsed	
Syntax	<pre>Icu_ValueType Icu_GetTimeElapsed (    Icu_ChannelType Channel )</pre>	
Service ID [hex]	0x10	
Sync/Async	Synchronous	
Reentrancy	Reentrant (limited according to ICU050)	
Parameters (in)	Channel Numeric identifier of the ICU channel	
Parameters (inout)	None	
Parameters (out)	None	
Return value	Icu_ValueType see Description	
Description	This function reads the elapsed Signal Low Time for the given channel.	
Available via	lcu.h	



**(**()

[SWS\_lcu\_00338] [The function Icu\_GetTimeElapsed shall be re-entrant.] ()

[SWS\_lcu\_00081] [The function Icu\_GetTimeElapsed shall read the elapsed Signal Low Time for the given channel that is configured in Measurement Mode "Signal Measurement, Signal Low Time". The elapsed time is measured between a falling edge and the consecutive rising edge of the channel.] (SRS\_SPAL\_12063, SRS\_lcu\_12442)

[SWS\_lcu\_00082] [The function Icu\_GetTimeElapsed shall read the elapsed Signal High Time for the given channel that is configured in Measurement Mode "Signal Measurement, Signal High Time". The elapsed time is measured between a rising edge and the consecutive falling edge of the channel.] (SRS\_SPAL\_12063, SRS\_lcu\_12435)

[SWS\_lcu\_00083] [The function Icu\_GetTimeElapsed shall read the elapsed Signal Period Time for the given channel that is configured in Measurement Mode "Signal Measurement, Signal Period Time". The elapsed time is measured between consecutive rising (or falling) edges of the channel. The period start edge is configurable. | (SRS\_SPAL\_12063, SRS\_lcu\_12443)

[SWS\_lcu\_00136] [The function Icu\_GetTimeElapsed shall return "0" in case no requested time has been captured (see Figure 9.19, letter "A"). | ()

[SWS\_lcu\_00339] [The function <code>Icu\_GetTimeElapsed</code> shall return "0" in case the capturing of a requested time is ongoing and not finished (see Figure 9.19, letter "B")] () [SWS\_lcu\_00340] [The function <code>Icu\_GetTimeElapsed</code> shall return "0" in case a captured time was already returned once by this service and this service is called again (see Figure 9.19, letter "D") | ()

[SWS\_Icu\_00105] [The function Icu\_GetTimeElapsed shall be pre compile time configurable by the configuration parameter IcuGetTimeElapsedApi.] (SRS\_BSW\_00410, SRS\_BSW\_00171)

[SWS\_lcu\_00341] [The function Icu\_GetTimeElapsed shall be configurable ON/OFF by the configuration parameter IcuGetTimeElapsedApi.] ()

[SWS\_Icu\_00178] [If development error detection is enabled, the parameter Channel shall be checked by this service. If Channel is invalid (invalid identifier or channel not configured for mode ICU\_MODE\_SIGNAL\_MEASUREMENT), then the error ICU E PARAM CHANNEL shall be reported to the Default Error Tracer.] ()



[SWS\_lcu\_00179] [If development error detection is enabled and an error is detected this service shall return "0".] ()

[SWS\_lcu\_00403] [If development error detection for the lcu module is enabled: This function shall raise development error ICU\_E\_UNINIT when the function Icu Init has not been called.] (SRS\_BSW\_00323, SRS\_BSW\_00406)

### 8.3.23 Icu\_GetDutyCycleValues

[SWS\_lcu\_00211][

[0110_100_001	5_1CU_00211]		
Service Name	Icu_GetDutyCycleValues		
Syntax	<pre>void Icu_GetDutyCycleValues (    Icu_ChannelType Channel,    Icu_DutyCycleType* DutyCycleValues )</pre>		
Service ID [hex]	0x11		
Sync/Async	Synchronous	Synchronous	
Reentrancy	Reentrant (limited according to ICU050)		
Parameters (in)	Channel Numeric identifier of the ICU channel		
Parameters (inout)	None		
Parameters (out)	DutyCycle Values Pointer to a buffer where the results (high time and period time) shall be placed.		
Return value	None		
Description	This function reads the coherent active time and period time for the given ICU Channel.		
Available via	lcu.h		

[SWS\_lcu\_00342] [The function Icu\_GetDutyCycleValues shall be re-entrant.]

[SWS\_lcu\_00084] [The function Icu\_GetDutyCycleValues shall read the coherent active time and period time for the given ICU Channel, if it is configured in Measurement Mode "Signal Measurement, Duty Cycle Values". | (SRS\_lcu\_12436)

[SWS\_lcu\_00137] [The function Icu\_GetDutyCycleValues shall return "0" in case no coherent active- and period time has been captured (similar to Figure 9.19, letter "A").] ()



[SWS\_lcu\_00343] [The function Icu\_GetDutyCycleValues shall return "0" in case the capturing of a requested high- and period time is ongoing and not finished (meant: the function shall return "0" until the first valid value has been captured and the captured value shall be stored until a new value is captured) (similar to Figure 9.19, letter "B").] ()

[SWS\_lcu\_00344] [The function Icu\_GetDutyCycleValues shall return "0" in case captured duty cycle values were already returned once by this service and this service is called again (similar to Figure 9.19, letter "D")] ()

[SWS\_lcu\_00106] [The function Icu\_GetDutyCycleValues shall be pre compile time configurable by the configuration parameter IcuGetDutyCycleValuesApi.] (SRS\_BSW\_00410, SRS\_BSW\_00171)

[SWS\_lcu\_00345] [The function Icu\_GetDutyCycleValues shall be configurable ON/OFF by the configuration parameter IcuGetDutyCycleValuesApi.] ()

[SWS\_lcu\_00180] [If development error detection is enabled: the function Icu\_GetDutyCycleValues shall check the parameter Channel. If Channel is invalid (invalid identifier or channel not configured for mode ICU\_MODE\_SIGNAL\_MEASUREMENT, Duty Cycle Values), the function Icu\_GetDutyCycleValues shall raise development error ICU\_E\_PARAM\_CHANNEL.] ()

[SWS\_lcu\_00181] [If development error detection is enabled, the function Icu\_GetDutyCycleValues shall check the parameter DutyCycleValues. If DutyCycleValues is invalid, the function Icu\_GetDutyCycleValues shall raise development error ICU E PARAM POINTER.] ()

[SWS\_lcu\_00404] [If development error detection for the lcu module is enabled: This function shall raise development error ICU\_E\_UNINIT when the function Icu Init has not been called.] (SRS\_BSW\_00323, SRS\_BSW\_00406)

#### 8.3.24 Icu GetVersionInfo

#### **ISWS Icu 002121**

Service Name	Icu_GetVersionInfo		
Syntax	<pre>void Icu_GetVersionInfo (    Std_VersionInfoType* versioninfo )</pre>		
Service ID [hex]	0x12		
Sync/Async	Synchronous		



Reentrancy	Reentrant		
Parameters (in)	None	None	
Parameters (inout)	None	None	
Parameters (out)	versioninfo	versioninfo Pointer to where to store the version information of this module.	
Return value	None		
Description	This function returns the version information of this module.		
Available via	lcu.h		

]()

[SWS\_lcu\_00356] [If development error detection for the lcu module is enabled: The function <code>lcu\_GetVersionInfo</code> shall check the parameter <code>versioninfo</code> for not being <code>NULL</code> and shall raise the development error code <code>lcu\_E\_PARAM\_VINFO</code> if the check fails.] ()

## 8.3.25 Icu\_DisableNotificationAsync

[SWS\_lcu\_91002][

Service Name	Icu_DisableNotificationAsync	
Syntax	<pre>void Icu_DisableNotificationAsync (    Icu_ChannelType Channel )</pre>	
Service ID [hex]	0x18	
Sync/Async	Asynchronous	
Reentrancy	Reentrant (limited according to ICU050)	
Parameters (in)	Channel	Numeric identifier of the ICU channel.
Parameters (inout)	None	
Parameters (out)	None	
Return value	None	
Description	This function disables the notification of a channel.	
Available via	lcu.h	

**(**()



## 8.3.26 Icu\_EnableNotificationAsync

[SWS\_lcu\_91003][

Service Name	Icu_EnableNotificationAsync	
Syntax	<pre>void Icu_EnableNotificationAsync (    Icu_ChannelType Channel )</pre>	
Service ID [hex]	0x19	
Sync/Async	Asynchronous	
Reentrancy	Non Reentrant Reentrant (limited according to ICU050)	
Parameters (in)	Channel	Numeric identifier of the ICU channel.
Parameters (inout)	None	
Parameters (out)	None	
Return value	None	
Description	This function enables the notification on the given channel.	
Available via	lcu.h	

]()

#### 8.4 Callback notifications

Since the ICU is a driver module, it doesn't provide any callback functions for lower layer modules.

#### 8.5 Scheduled functions

None.

## 8.6 Expected Interfaces

In this chapter, all interfaces required from other modules are listed.

## 8.6.1 Mandatory Interfaces

This chapter defines all interfaces, which are required, in order to fulfill the core functionality of the module.

**ISWS Icu 910011** 

<u>•                                      </u>	4.	
API Function	Header	Description



	File	
Det_Report- RuntimeError	Det.h	Service to report runtime errors. If a callout has been configured then this callout shall be called.

**I()** 

## 8.6.2 Optional Interfaces

This chapter defines all interfaces which are required to fulfil an optional functionality of the module.

[SWS Icu 00213][

[6116_164_66216]		
API Function	Header File	Description
Det_Report- Error	Det.h	Service to report development errors.
EcuM Check- Wakeup	EcuM.h	This function can be called to check the given wakeup sources. It will pass the argument to the integrator function EcuM_CheckWakeupHook. It can also be called by the ISR of a wakeup source to set up the PLL and check other wakeup sources that may be connected to the same interrupt.
EcuM_Set- Wakeup- Event	EcuM.h	Sets the wakeup event.

**I()** 

The service EcuM CheckWakeup will be called if all of the following are true:

- [SWS\_Icu\_00055] [The static configuration parameter IcuReportWakeupSource is set to "ON" ] (SRS\_SPAL\_12069, SRS\_BSW\_00410)
- [SWS\_lcu\_00056] [The module is in mode ICU\_MODE\_SLEEP] (SRS\_SPAL\_12069)
- [SWS\_lcu\_00057] [A wakeup event occurs on a wakeup capable ICU channel.]
   (SRS\_SPAL\_12069)

[SWS\_Icu\_00228] [EcuM\_CheckWakeup shall be called within the Interrupt Service Routine servicing the ICU channel wakeup event on wakeup-capable channel.] ()

**[SWS\_lcu\_00229]** The ISR's, providing the wakeup events, shall be responsible for resetting the interrupt flags if required by hardware. ()



#### 8.6.3 Configurable interfaces

In this chapter all interfaces are listed where the target function could be configured. The target function is usually a call-back function. The names of these kinds of interfaces are not fixed because they are configurable.

[SWS\_lcu\_00119] [The ISRs shall reset the interrupt flags (if needed by hardware) and call the corresponding notification functions.] (SRS\_SPAL\_12129)

[SWS\_Icu\_00018] [The Icu notification functions shall be configurable as function pointers within the initialization data structure (Icu\_ConfigType).] (SRS\_SPAL\_12056)

**[SWS\_lcu\_00187]** [The lcu module's notification functions shall have no parameters and no return value.] (SRS\_BSW\_00359)

[SWS\_lcu\_00214][

[5W5_ICU_00Z14]	
Service Name	Icu_SignalNotification_ <channel></channel>
Syntax	<pre>void Icu_SignalNotification_<channel> (   void )</channel></pre>
Sync/Async	Synchronous
Reentrancy	Reentrancy of interface not relevant for this module. (in general it is in this case not reentrant).
Parameters (in)	None
Parameters (inout)	None
Parameters (out)	None
Return value	None
Description	According to the last call of Icu_EnableNotification, this notification function to be called if the requested signal edge (rising / falling / both edges) occurs (once per edge).
Available via	lcu_Externals.h

|()

## [SWS\_Icu\_00348] [Re-entrancy of operation

Icu\_SignalNotification\_<Channel> is not relevant for this module (In general
it is in this case not re-entrant).] ()



[SWS\_lcu\_00021] [According to the last call of Icu\_EnableNotification(), the lcu module shall call the notification function lcu\_SignalNotification\_<Channel> if the requested signal edge (rising / falling / both edges) occurs (once per edge).] (SRS\_SPAL\_00157, SRS\_lcu\_12369)

**[SWS\_lcu\_00044]** [Only those edge notifications shall be provided, which are supported by hardware.] (SRS\_lcu\_12305)

**[SWS\_Icu\_00042]** [After a call of Icu\_DisableNotification, the Icu module shall not call the notification function Icu\_SignalNotification\_<Channel>.] (SRS\_Icu\_12305)

[SWS\_lcu\_00215][

Service Name	Icu_TimestampNotification_ <channel></channel>
Syntax	<pre>void Icu_TimestampNotification_<channel> (   void )</channel></pre>
Sync/Async	Synchronous
Reentrancy	Reentrancy of interface not relevant for this module. (in general it is in this case not reentrant).
Parameters (in)	None
Parameters (inout)	None
Parameters (out)	None
Return value	None
Description	This notification to be called if the number of requested timestamps (Notification interval > 0) are acquired and if the notification has been enabled by the call of Icu_EnableNotification().
Available via	Icu_Externals.h

[(SRS\_lcu\_12444)

#### [SWS\_lcu\_00349] [Re-entrancy of the

 $\label{lower} {\tt Icu\_TimestampNotification\_<Channel> is not relevant for this module (in general it is in this case not re-entrant).} \ \ \, ()$ 

## [SWS\_Icu\_00216] [The Icu module shall call the notification

Icu\_TimestampNotification\_<Channel> if the number of requested
timestamps (Notification interval > 0) are acquired and if the notification has been
enabled by the call of Icu EnableNotification().]()



[SWS\_lcu\_00217] [After a call of lcu\_DisableNotification the lcu module shall NOT call the notification Icu TimestampNotification <Channel>.] ()

## [SWS\_lcu\_00218] [The lcu module's notification

Icu\_TimestampNotification\_<Channel> depends on pre-processor switch
IcuTimestampApi]()



## 9 Sequence diagrams

## 9.1 lcu\_Init

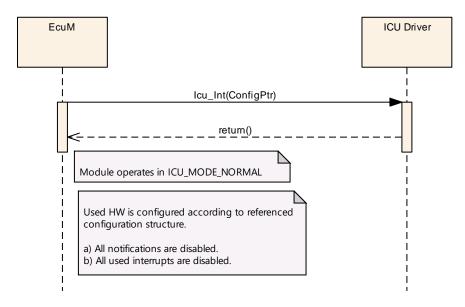


Figure 9.1: Initialization of the ICU driver

## 9.2 Icu\_Delnit

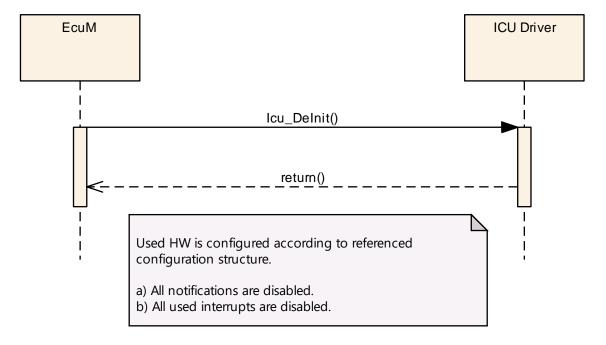
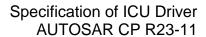


Figure 9.2: De-Initialization of the ICU driver

# 9.3 Check Wakeup Events





Note: The Sequence charts for the ICU can be found in the ECU State Manager specification [10]



## 9.4 Icu\_SetMode

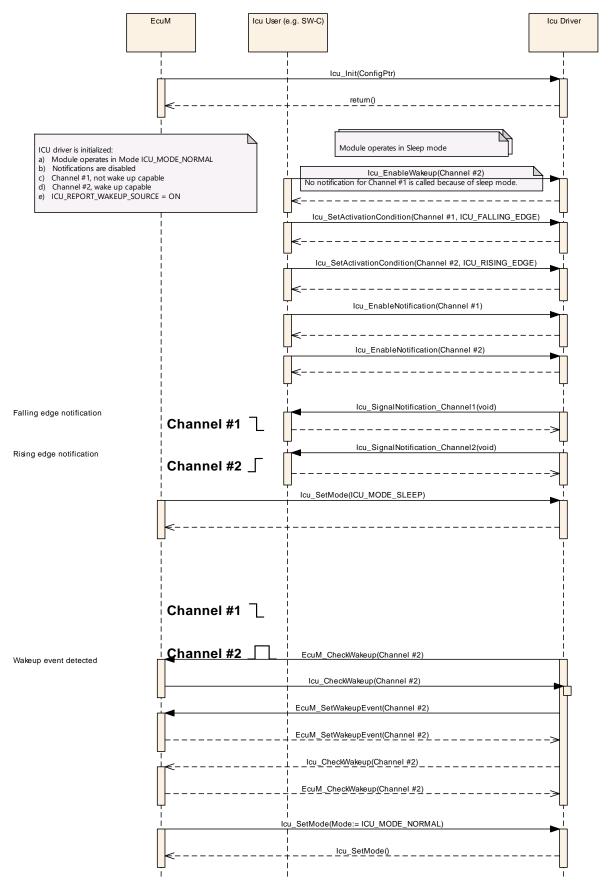


Figure 9.3: Enabled notifications in SLEEP mode



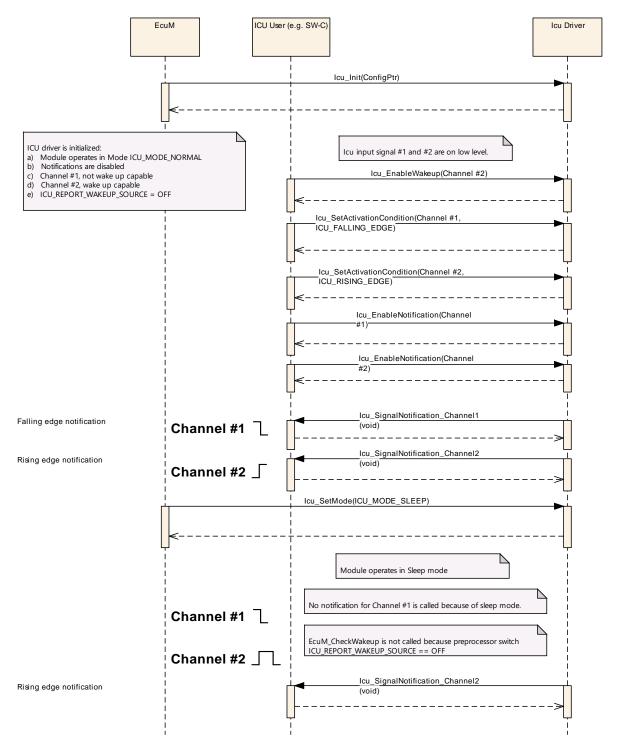


Figure 9.4: Disabled reporting of wakeup sources in SLEEP mode



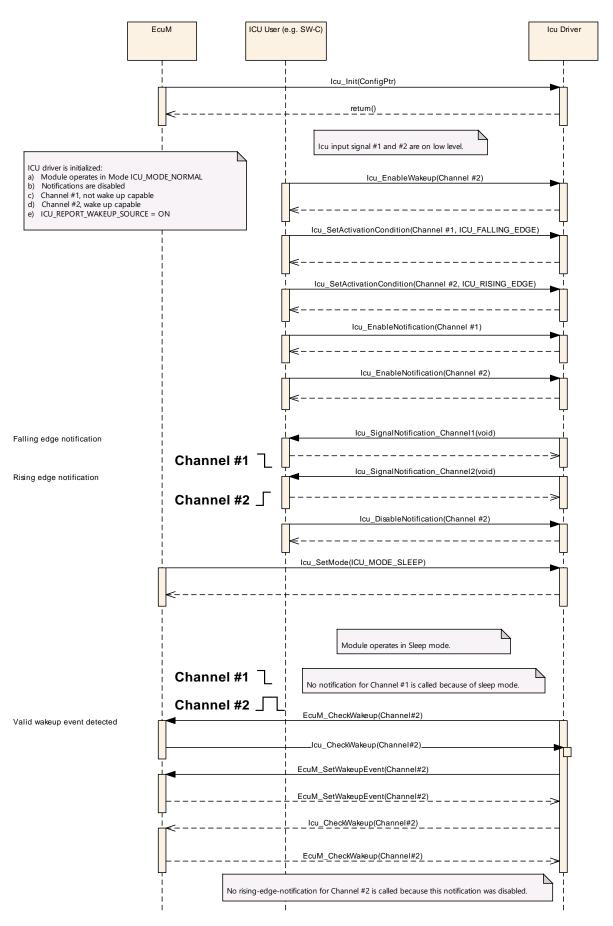


Figure 9.5: Disabled edge notification in SLEEP mode



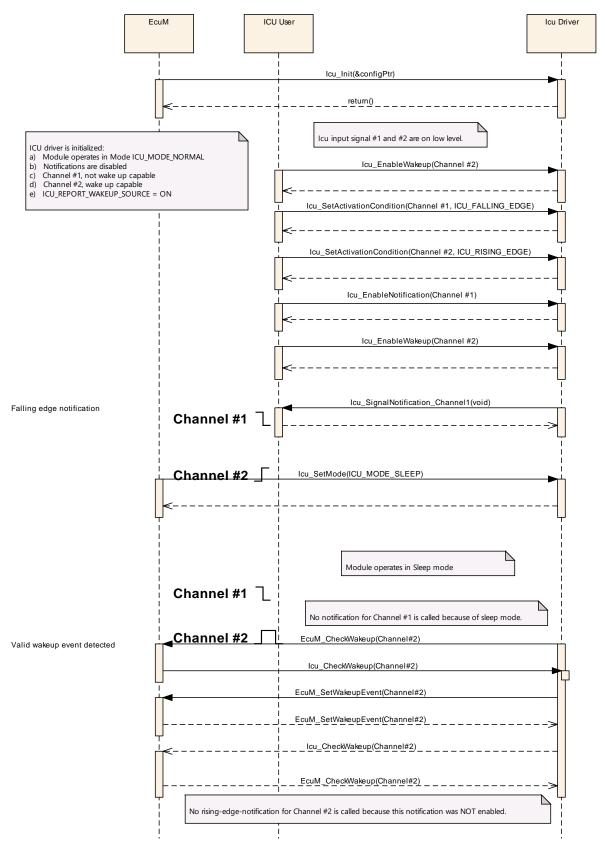


Figure 9.6: Un-Enabled reporting of notifications in SLEEP mode



# 9.5 lcu\_DisableWakeup

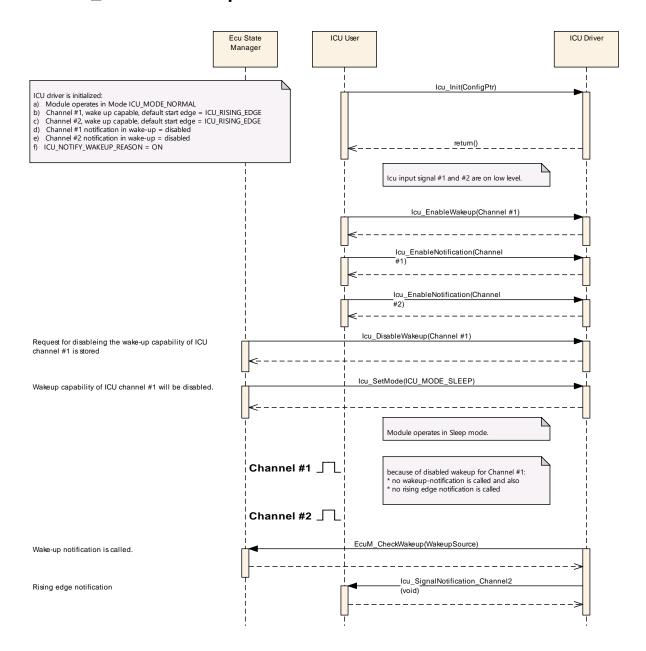


Figure 9.7: Disabling of wakeup-capabilities



#### 9.6 lcu\_EnableWakeup

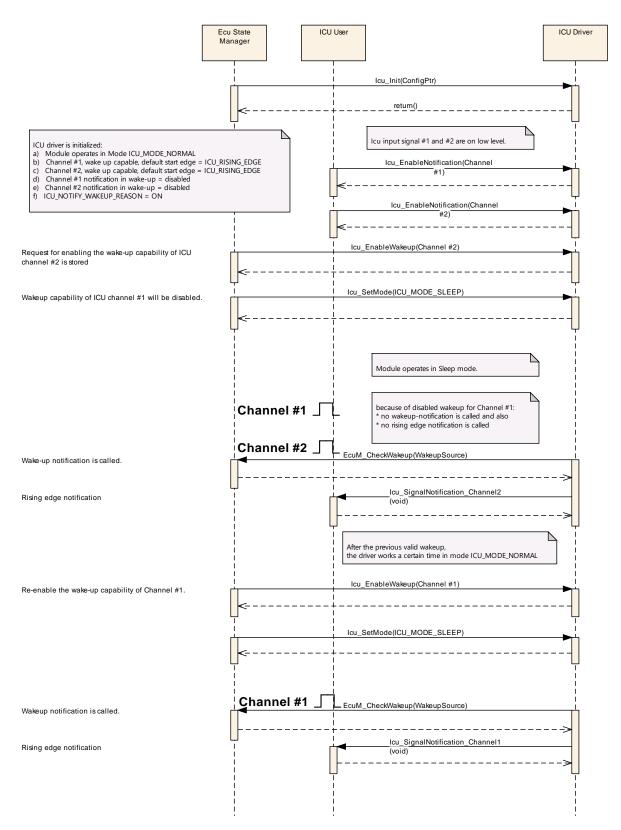


Figure 9.8: Enabling of wakeup-capabilities



### 9.7 Icu\_SetActivationCondition

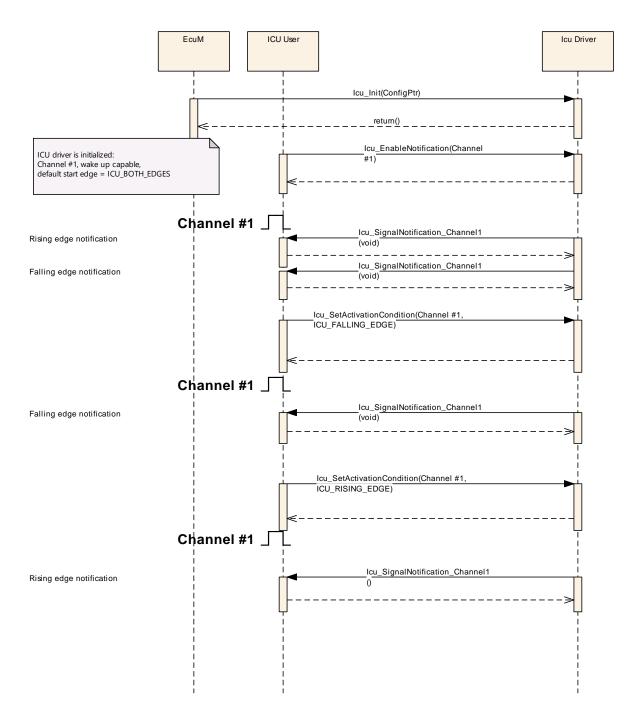


Figure 9.9: Setting up the activation condition for a channel



# 9.8 Icu\_DisableNotification

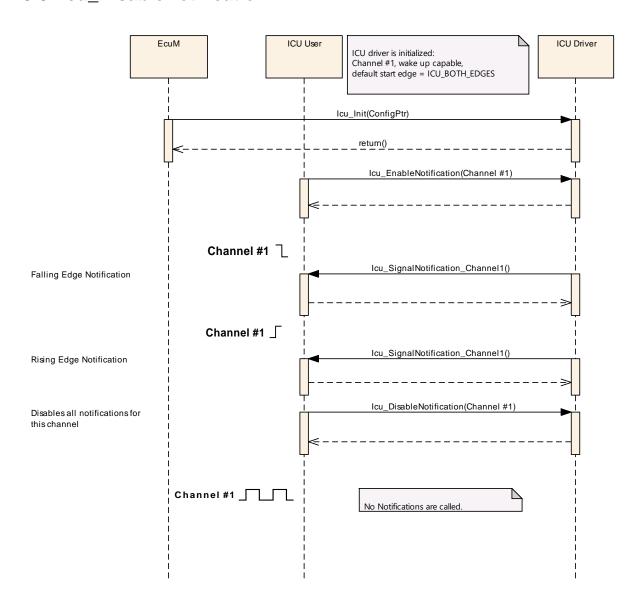


Figure 9.10: Disabling of the notification for a channel



# 9.9 Icu\_EnableNotification

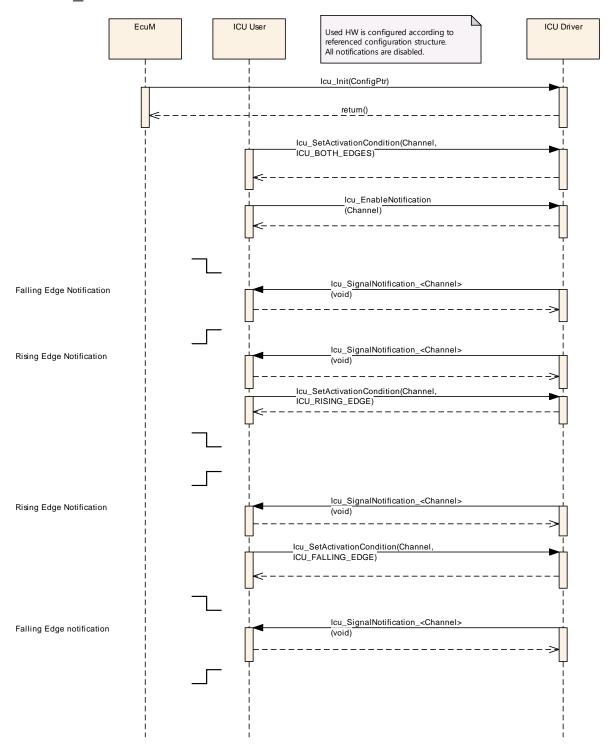


Figure 9.11: Enabling of the edge-notification for a channel



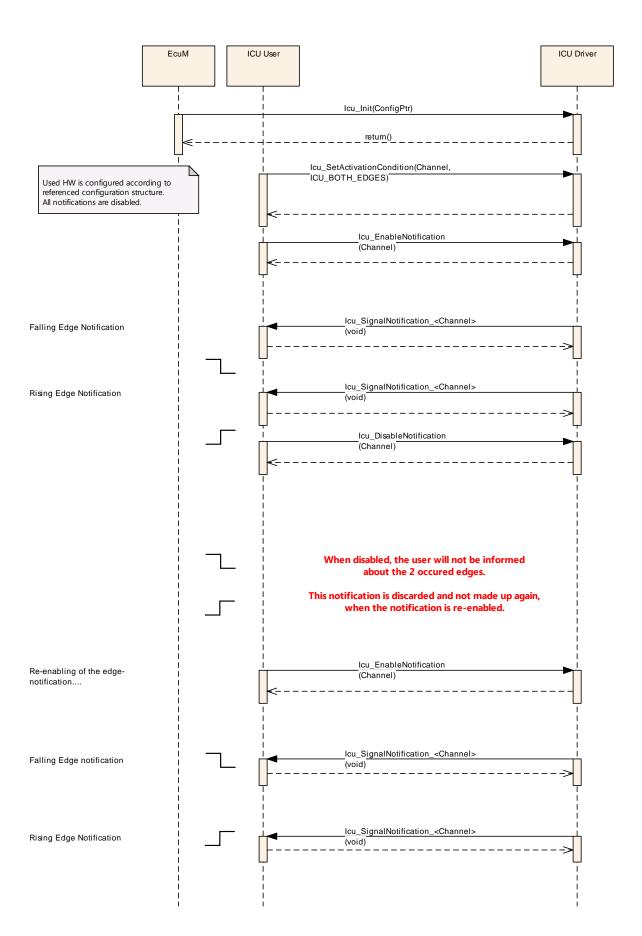




Figure 9.12: Re-enabling of the notification for a channel

#### 9.10 Icu\_GetInputState

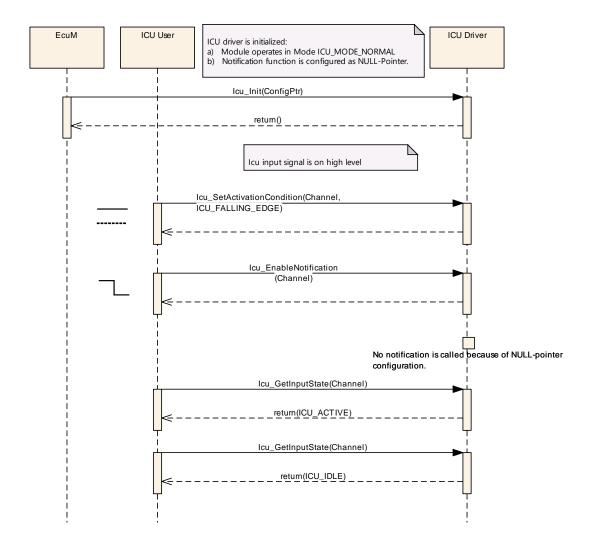


Figure 9.13: Polling of the channel status



### 9.11 Icu Timestamping

The following figure shall show the interactions between the different timestamp API-services.

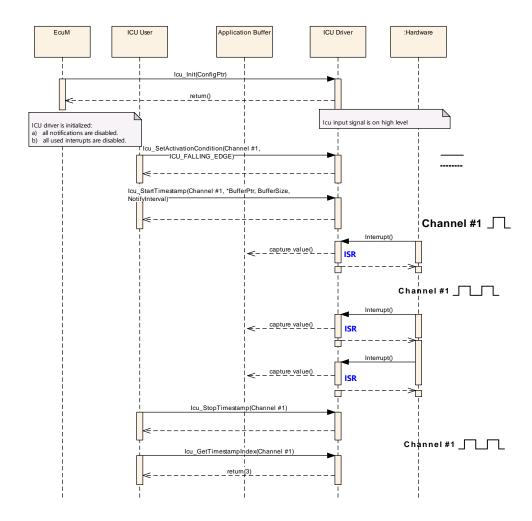


Figure 9.14: Overview of the timestamping functionality of the ICU driver



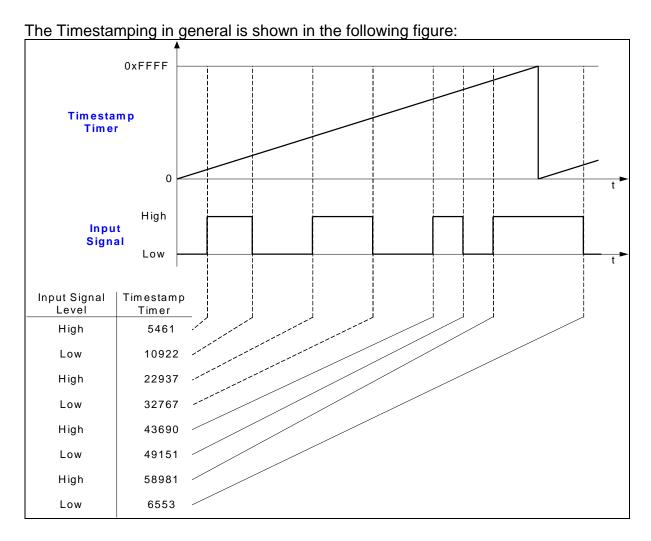


Figure 9.15: Timestamping overview



### 9.12 Icu Edge Counting

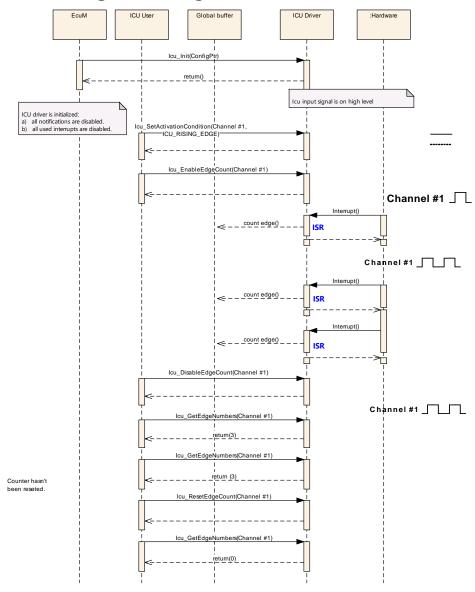


Figure 9.16: Inquire the number of counted edges



# 9.13 lcu\_GetTimeElapsed

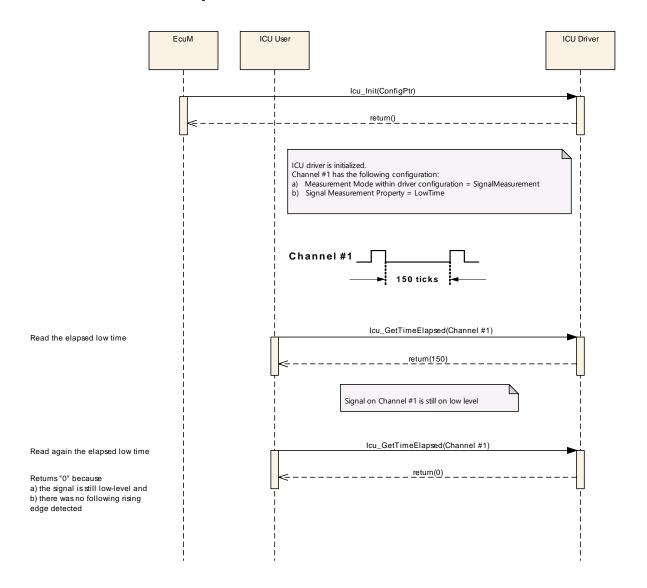


Figure 9.17: Inquire the elapsed level-time of a channel



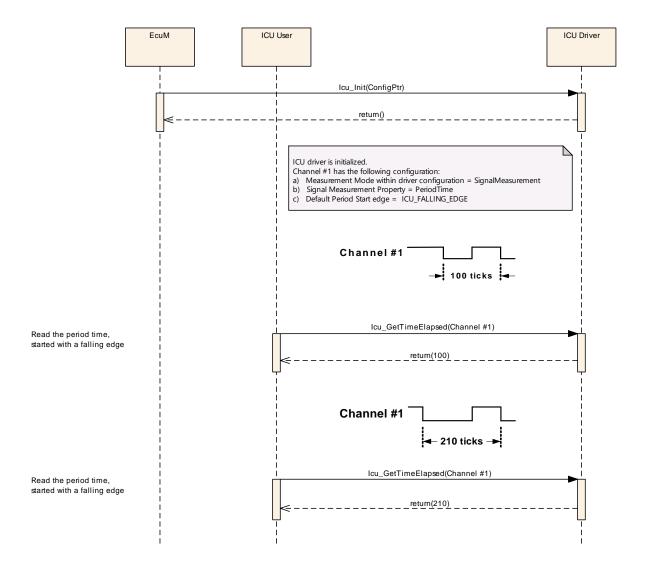


Figure 9.18: Inquire the elapsed period time of a channel



The following example shows the exemplary behaviour before, while and after capturing the "high time" of a signal.

# The shown behaviour is also appropriate for the service Icu\_GetDutyCycleValues().

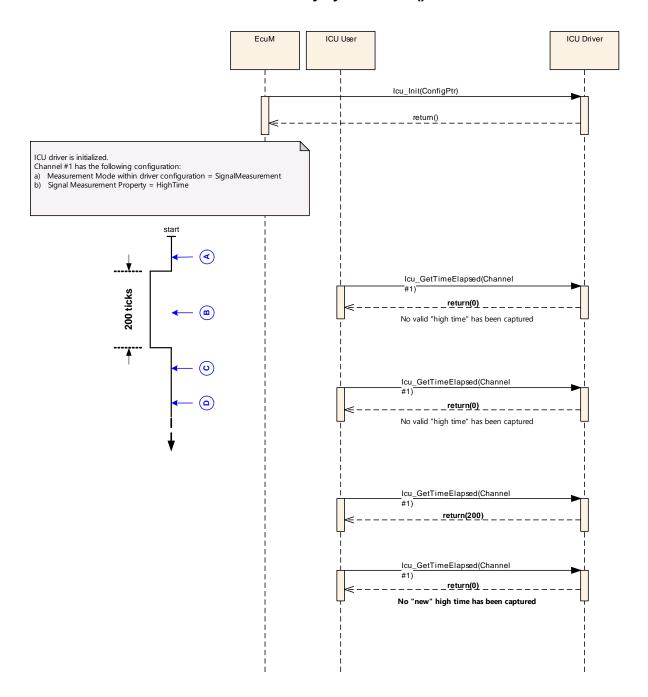


Figure 9.19: Inquire the elapsed high time of a channel



# 9.14 Icu\_GetDutyCycleValues

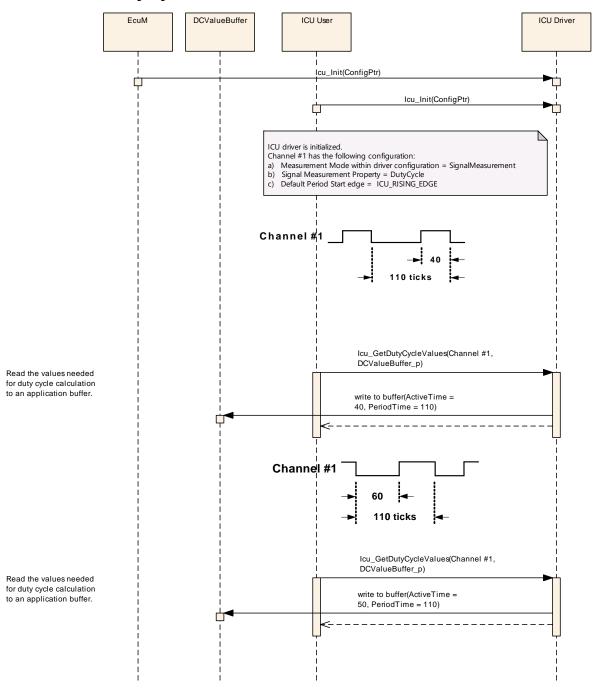


Figure 9.20: Measure the values needed for calculation of duty cycles



### 9.15 Icu\_DisableNotificationAsync

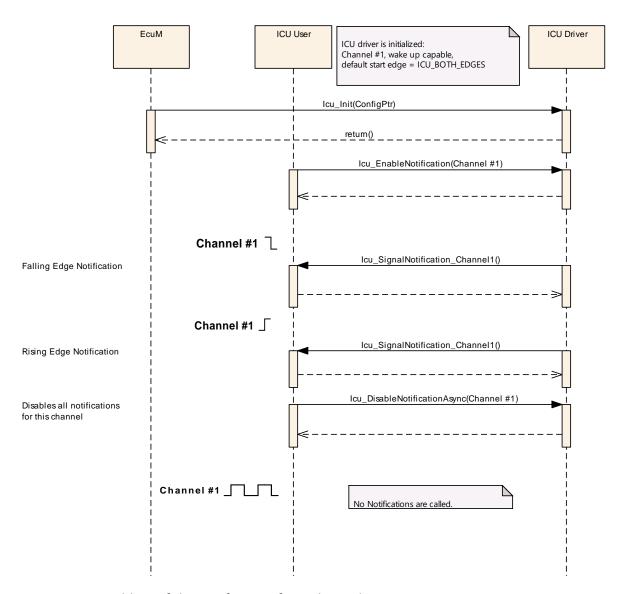


Figure 9.21: Disabling of the notification for a channel

### 9.16 lcu\_SignalNotification and lcu\_GetInputState



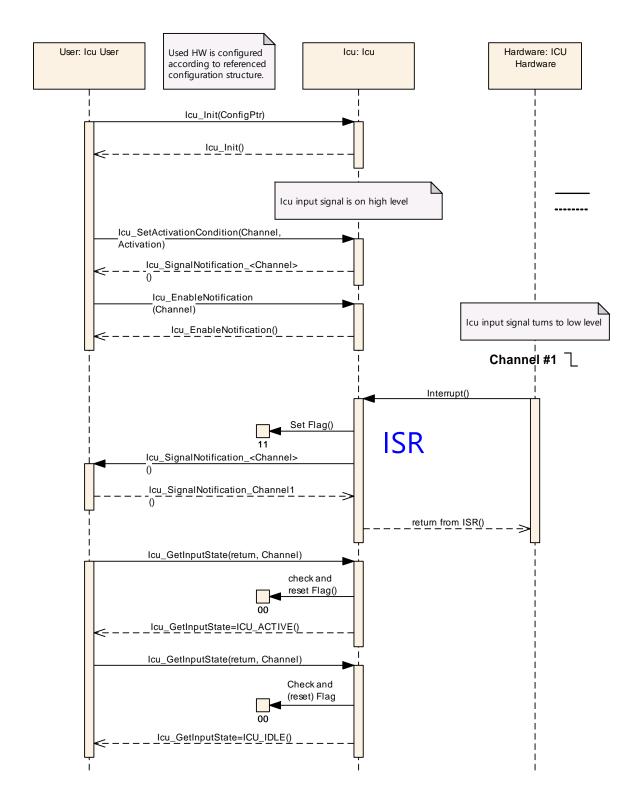


Figure 9.22: Cooperative usage of notification and polling mechanism



# 9.17 Icu\_EnableNotificationAsync

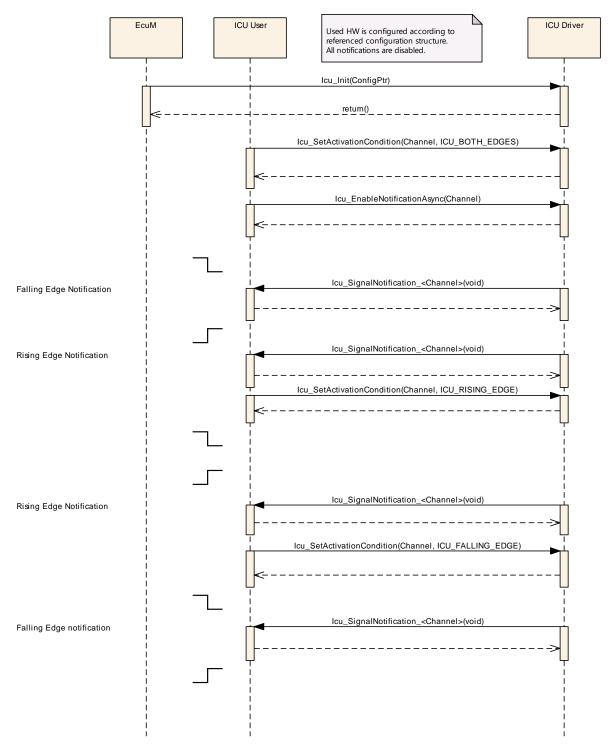


Figure 9.23: Enabling of the edge-notification for a channel via asynchronous API



### 10 Configuration specification

In general, this chapter defines configuration parameters and their clustering into containers. In order to support the specification, Chapter 10.1 describes fundamentals. It also specifies a template (table) you shall use for the parameter specification. We intend to leave Chapter 10.1 in the specification to guarantee comprehension.

Chapter 10.2 specifies the structure (containers) and the parameters of the module ICU.

Chapter 10.3 specifies published information of the module ICU.

#### 10.1 How to read this chapter

For details refer to the chapter 10.1 "Introduction to configuration specification" in SWS\_BSWGeneral.



#### 10.2 Containers and configuration parameters

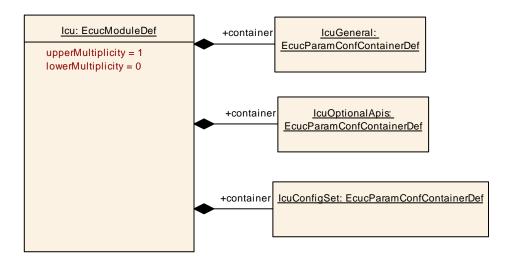
The following chapters summarize all configuration parameters. The detailed meanings of the parameters describe Chapters 7 and Chapter 8.

**[SWS\_lcu\_00384]** \( \text{ The lcu module shall reject configurations with partition mappings which are not supported by the implementation. \( \)()

#### 10.2.1 Icu

SWS Item	[ECUC_lcu_00357]
Module Name	Icu
Description	Configuration of the Icu (Input Capture Unit) module.
Post-Build Variant Support	true
Supported Config Variants	VARIANT-POST-BUILD, VARIANT-PRE-COMPILE

Included Containers			
Container Name	Multiplicity	Scope / Dependency	
IcuConfigSet	1	This container contains the configuration parameters and sub containers of the AUTOSAR Icu module.	
IcuGeneral	1	Configuration of general ICU parameters.	
IcuOptional- Apis	1	This container contains all configuration switches for configuring optional API services of the ICU driver.	





#### 10.2.2 IcuGeneral

SWS Item	[ECUC_lcu_00026]	
Container Name	IcuGeneral	
Parent Container	Icu	
Description	Configuration of general ICU parameters.	
Configuration Parameters		

SWS Item	[ECUC_lcu_00232]		
Parameter Name	IcuDevErrorDetect		
Parent Container	IcuGeneral		
Description	Switches the development error detection and notification on or off.     true: detection and notification is enabled.     false: detection and notification is disabled.		
Multiplicity	1		
Туре	EcucBooleanParamDef		
Default value	false		
Post-Build Variant Value	false		
	Pre-compile time	Х	All Variants
Value Configuration Class	Link time		
	Post-build time		
Scope / Dependency	scope: local		

SWS Item	[ECUC_lcu_00233]
Parameter Name	IcuReportWakeupSource
Parent Container	IcuGeneral
Description	Switch for enabling Wakeup source reporting. true: Report Wakeup source. false: Do not report Wakeup source.
Multiplicity	1
Туре	EcucBooleanParamDef
Default value	
Post-Build Variant Value	false



Value Configuration Class	Pre-compile time	Х	All Variants
	Link time		
	Post-build time		
Scope / Dependency	scope: local		

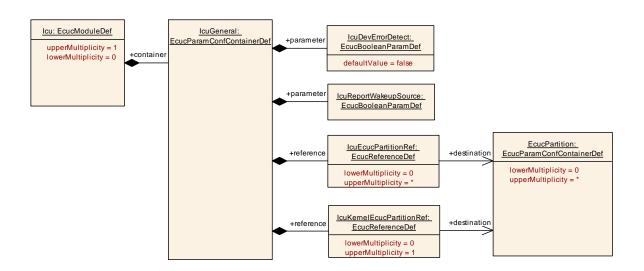
SWS Item	[ECUC_lcu_00358]			
Parameter Name	IcuEcucPartitionRef			
Parent Container	IcuGeneral			
Description	Maps the ICU driver to zero or multiple ECUC partitions to make the driver API available in the according partition.			
Multiplicity	0*	0*		
Туре	Reference to EcucPartition			
Post-Build Variant Multiplicity	true			
Post-Build Variant Value	true			
	Pre-compile time	Х	All Variants	
Multiplicity Configuration Class	Link time			
-	Post-build time			
	Pre-compile time	Х	All Variants	
Value Configuration Class	Link time			
	Post-build time			
Scope / Dependency	scope: ECU	•		

SWS Item	[ECUC_lcu_00359]
Parameter Name	IcuKernelEcucPartitionRef
Parent Container	IcuGeneral
Description	Maps the ICU kernel to zero or one ECUC partitions to assign the driver kernel to a certain core. The ECUC partition referenced is a subset of the ECUC partitions where the ICU driver is mapped to.
Multiplicity	01
Туре	Reference to EcucPartition
Post-Build Variant Multiplicity	true
Post-Build Variant	true



Value			
Marita II - Mar	Pre-compile time	Х	All Variants
Multiplicity Configuration	Link time		
Class	Post-build time		
Value	Pre-compile time	Х	All Variants
Configuration Class	Link time		
	Post-build time		
Scope / Dependency	scope: ECU		

#### **No Included Containers**



[SWS\_Icu\_CONSTR\_00001] \( \text{ The ECUC partitions referenced by IcuKernelEcucPartitionRef shall be a subset of the ECUC partitions referenced by IcuEcucPartitionRef.\( \)()

[SWS\_lcu\_CONSTR\_00003] [ If lcuEcucPartitionRef references one or more ECUC partitions, lcuKernelEcucPartitionRef shall have a multiplicity of one and reference one of these ECUC partitions as well.]()

#### 10.2.3 IcuOptionalApis

SWS Item	[ECUC_lcu_00114]
Container Name	IcuOptionalApis
Parent	Icu



Container			
Description	This container contains all configuration switches for configuring optional API services of the ICU driver.		
Configuration Parameters			

SWS Item	[ECUC_lcu_00234]		
Parameter Name	IcuDeInitApi		
Parent Container	IcuOptionalApis		
Description	Adds / removes the service lcu_Delnit() from the code. true: lcu_Delnit() can be used. false: lcu_Delnit() can not be used.		
Multiplicity	1		
Туре	EcucBooleanParamDef		
Default value			
Post-Build Variant Value	false		
	Pre-compile time	Х	All Variants
Value Configuration Class	Link time		
	Post-build time		
Scope / Dependency	scope: local		

SWS Item	[ECUC_lcu_00235]			
Parameter Name	IcuDisableWakeupApi	IcuDisableWakeupApi		
Parent Container	IcuOptionalApis	IcuOptionalApis		
Description	Adds / removes the service Icu_DisableWakeup() from the code. true: Icu_DisableWakeup() can be used. false: Icu_DisableWakeup() can not be used.			
Multiplicity	1			
Туре	EcucBooleanParamDef			
Default value				
Post-Build Variant Value	false			
Value	Pre-compile time	Х	All Variants	
Configuration Class	Link time			
Ciass	Post-build time			
Scope / Dependency	scope: local			



SWS Item	[ECUC_lcu_00124]		
Parameter Name	IcuEdgeCountApi		
Parent Container	IcuOptionalApis		
Description	Adds / removes all services related to the edge counting functionality as listed below, from the code: Icu_ResetEdgeCount(), Icu_EnableEdgeCount(), Icu_DisableEdgeCount(), Icu_GetEdgeNumbers(). true: The services listed above can be used.		
Multiplicity	1		
Туре	EcucBooleanParamDef		
Default value			
Post-Build Variant Value	false		
Value	Pre-compile time	Х	All Variants
Configuration	Link time		
Class	Post-build time		
Scope / Dependency	scope: local		

SWS Item	[ECUC_lcu_00356]		
Parameter Name	IcuEdgeDetectApi		
Parent Container	IcuOptionalApis		
Description	Adds / removes the services related to the edge detection functionality, from the code: Icu_EnableEdgeDetection() and Icu_DisableEdgeDetection(). true: These services can be used.		
Multiplicity	1		
Туре	EcucBooleanParamDef		
Default value			
Post-Build Variant Value	false		
Value	Pre-compile time	Х	All Variants
Configuration Class	Link time		
Class	Post-build time		
Scope / Dependency	scope: local		



SWS Item	[ECUC_lcu_00236]			
Parameter Name	IcuEnableWakeupApi	IcuEnableWakeupApi		
Parent Container	IcuOptionalApis			
Description	Adds / removes the service lcu_EnableWakeup() from the code. true: lcu_EnableWakeup() can be used.			
Multiplicity	1			
Туре	EcucBooleanParamDef			
Default value				
Post-Build Variant Value	false			
Value	Pre-compile time X All Variants			
Configuration Class	Link time			
Class	Post-build time			
Scope / Dependency	scope: local			

SWS Item	[ECUC_lcu_00237]		
Parameter Name	IcuGetDutyCycleValuesApi		
Parent Container	IcuOptionalApis		
Description	Adds / removes the service lcu_GetDutyCycleValues() from the code. true: lcu_GetDutyCycleValues() can be used. false: lcu_GetDutyCycleValues() can not be used.		
Multiplicity	1		
Туре	EcucBooleanParamDef		
Default value			
Post-Build Variant Value	false		
Value	Pre-compile time	Х	All Variants
Configuration	Link time		
Class	Post-build time		
Scope / Dependency	scope: local dependency: If IcuSignalMeasurementApi==false this switch shall also be set to false.		

SWS Item	[ECUC_lcu_00238]
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Parameter Name	IcuGetInputStateApi			
Parent Container	IcuOptionalApis			
Description	Adds / removes the service lcu_GetInputState() from the code. true: lcu_GetInputState() can be used. false: lcu_GetInputState() can not be used.			
Multiplicity	1	1		
Туре	EcucBooleanParamDef			
Default value				
Post-Build Variant Value	false			
Value	Pre-compile time	Х	All Variants	
Configuration Class	Link time			
Class	Post-build time			
Scope / Dependency	scope: local			

SWS Item	[ECUC_lcu_00239]			
OTTO ILCIII	[[2000_100_00239]			
Parameter Name	IcuGetTimeElapsedApi			
Parent Container	IcuOptionalApis	IcuOptionalApis		
Description	Adds / removes the service Icu_GetTimeElapsed() from the code. true: Icu_GetTimeElapsed() can be used. false: Icu_GetTimeElapsed() can not be used.			
Multiplicity	1	1		
Туре	EcucBooleanParamDef			
Default value				
Post-Build Variant Value	false			
Value	Pre-compile time	Х	All Variants	
Value Configuration	Link time			
Class	Post-build time			
Scope / Dependency	scope: local dependency: If IcuSignalMeasurementApi==false this switch shall also be set to false.			

SWS Item	[ECUC_lcu_00240]
Parameter Name	IcuGetVersionInfoApi
Parent Container	IcuOptionalApis



Description	Adds / removes the service Icu_GetVersionInfo() from the code. true: Icu_Get VersionInfo() can be used. false: Icu_GetVersionInfo() can not be used.		
Multiplicity	1		
Туре	EcucBooleanParamDef		
Default value	false		
Post-Build Variant Value	false		
Value	Pre-compile time X All Variants		All Variants
Configuration	Link time		
Class	Post-build time		
Scope / Dependency	scope: local		

SWS Item	[ECUC_Icu_00241]			
Parameter Name	IcuSetModeApi			
Parent Container	IcuOptionalApis			
Description	Adds / removes the service Icu_SetMode() from the code. true: Icu_Set Mode() can be used. false: Icu_SetMode() can not be used.			
Multiplicity	1	1		
Туре	EcucBooleanParamDef			
Default value				
Post-Build Variant Value	false			
	Pre-compile time	Х	All Variants	
Value Configuration Class	Link time			
	Post-build time			
Scope / Dependency	scope: local			

SWS Item	[ECUC_lcu_00242]
Parameter Name	IcuSignalMeasurementApi
Parent Container	IcuOptionalApis
Description	Adds / removes the services Icu_StartSignalMeasurement() and Icu_StopSignal Measurement() from the code. true: Icu_StartSignalMeasurement() and Icu_Stop



	SignalMeasurement() can be used. false: lcu_StartSignalMeasurement() and lcu_StopSignalMeasurement() can not be used.			
Multiplicity	1			
Туре	EcucBooleanParamDef			
Default value				
Post-Build Variant Value	false			
Value	Pre-compile time X All Variants			
Configuration Class	Link time			
	Post-build time			
Scope / Dependency	scope: local			

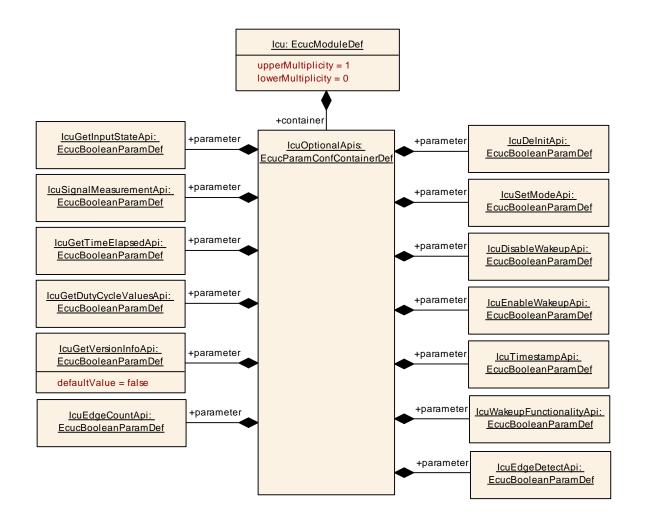
SWS Item	[ECUC_lcu_00123]		
Parameter Name	IcuTimestampApi		
Parent Container	IcuOptionalApis		
Description	Adds / removes all services related to the below from the code: Icu_StartTimestamp TimestampIndex(). true: The services listed services listed above can not be used.	(), Icu_St	opTimestamp(), Icu_Get
Multiplicity	1		
Туре	EcucBooleanParamDef		
Default value			
Post-Build Variant Value	false		
Value	Pre-compile time	Х	All Variants
Configuration Class	Link time		
	Post-build time		
Scope / Dependency	scope: local		

SWS Item	[ECUC_lcu_00355]
Parameter Name	IcuWakeupFunctionalityApi
Parent Container	IcuOptionalApis
Description	Adds / removes the service Icu_CheckWakeup() from the code. true: Icu_



	CheckWakeup() can be used. false: lcu_	CheckW	akeup() cannot be used.
Multiplicity	1		
Туре	EcucBooleanParamDef		
Default value			
Post-Build Variant Value	false		
Value	Pre-compile time	Х	All Variants
Configuration Class	Link time		
	Post-build time		
Scope / Dependency	scope: local		

#### **No Included Containers**





#### 10.2.4 IcuChannel

SWS Item	[ECUC_lcu_00027]		
Container Name	IcuChannel		
Parent Container	IcuConfigSet		
Description	Configuration of an individual ICU channel.		
Configuration Parameters			

SWS Item	[ECUC_lcu_00354]				
Parameter Name	IcuChannelld				
Parent Container	IcuChannel	IcuChannel			
Description	Channel Id of the ICU channel. This value name derived of the IcuChannel contains				
Multiplicity	1				
Туре	EcucIntegerParamDef (Symbolic Name	EcucIntegerParamDef (Symbolic Name generated for this parameter)			
Range	0 65535				
Default value					
Post-Build Variant Value	false				
	Pre-compile time	Х	All Variants		
Value Configuration Class	Link time				
	Post-build time				
Scope / Dependency	scope: ECU				

SWS Item	[ECUC_lcu_00222]
Parameter Name	IcuDefaultStartEdge
Parent Container	IcuChannel
Description	Configures the default-activation-edge which shall be used for this channel if there was no activation-edge configured by the call of service Icu_SetActivation Condition().  In case the Measurement Mode is "IcuSignalMeasurement" and the properties "DutyCycle" or "Period" are set, the edge configured here is used as Default Period Start Edge.  Implementation Type: Icu_ActivationType
Multiplicity	1
Туре	EcucEnumerationParamDef



	ICU_BOTH_EDGES	As default, both edges are used.		
Range	ICU_FALLING_EDGE	As default, falling edge is the used.		
	ICU_RISING_EDGE	As default, rising edge is the used.		
Post-Build Variant Value	true			
Value	Pre-compile time	Х	VARIANT-PRE-COMPILE	
Configuration	Link time			
Class	Post-build time	X VARIANT-POST-BUILD		

Parameter Name   IcuMeasurementMode		Ī		
Description   Configures the measurement mode of this channel. Implementation Type: Icu_MeasurementModeType	SWS Item	[ECUC_lcu_00223]		
Container   Configures the measurement mode of this channel.   Implementation Type: Icu_MeasurementModeType		IcuMeasurementMode		
Implementation Type: Icu_MeasurementModeType		IcuChannel		
Type    EcucEnumerationParamDef	Description			
The channnel is used to count the edges which are configured by the call of the service Icu_SetActivation Condition(). The following API services support this mode:  ICU_MODE_EDGE_COUNTER  Icu_EnableEdgeCount()  Icu_DisableEdgeCount()  Icu_GetEdgeNumbers()  Icu_ResetEdgeCount()  This mode can only be configured if IcuEdgeVountApi is switched on.  The channel is used for detecting the edges which are configured by the call of the service Icu_SetActivation Condition(). The following API services support this	Multiplicity	1		
Range    Configured by the call of the service Icu_SetActivation Condition(). The following API services support this mode:   Icu_EnableEdgeCount()     Icu_DisableEdgeCount()     Icu_GetEdgeNumbers()     Icu_ResetEdgeCount()     This mode can only be configured if IcuEdgeVountApi is switched on.    The channel is used for detecting the edges which are configured by the call of the service Icu_SetActivation Condition(). The following API services support this mode:    Condition()   The following API services support this mode:   Condition()   The follow	Туре	EcucEnumerationPara	mDef	
configured by the call of the service Icu_SetActivation Condition(). The following API services support this	Range		configured by the call of the service Icu_SetActivation Condition(). The following API services support this mode:  • Icu_EnableEdgeCount()  • Icu_DisableEdgeCount()  • Icu_GetEdgeNumbers()  • Icu_ResetEdgeCount()  This mode can only be configured if IcuEdgeVountApi is	
SIGNAL_EDGE_ DETECT  • Icu_EnableNotification()  • Icu_DisableNotification()  • Icu_GetInputState()			configured by the call of the service Icu_SetActivation Condition(). The following API services support this mode:  • Icu_EnableNotification()  • Icu_DisableNotification()	
		ICU_MODE_	The channel is used to measure different times between	



	SIGNAL_ MEASUREMENT	period-st be chang support t  I  I  This mod following	configurable edges. The configuration of the cart edges are done by configuration and cannot ged during runtime. The following API services this mode:  cu_GetTimeElapsed()  cu_GetDutyCycleValues()  cu_GetInputState()  de can only be configured if at least one of the switches are set to "true":  cuGetDutyCycleValuesApi  cuGetTimeElapsedApi
	ICU_MODE_ TIMESTAMP	which are Activation this mode    • I  • I	cu_StartTimestamp() cu_StopTimestamp() cu_GetTimestampIndex() de can only be configured if IcuTimeStampApi is
Post-Build Variant Value	true		
Value	Pre-compile time	Х	VARIANT-PRE-COMPILE
Configuration Class	Link time		
CidSS	Post-build time	Х	VARIANT-POST-BUILD
Scope / Dependency	scope: local dependency: The possible measurement modes are depending on the pre-processor switches, which enable/disable optional API services.		

SWS Item	[ECUC_lcu_00224]
Parameter Name	IcuWakeupCapability
Parent Container	IcuChannel
Description	Information about the wakeup-capability of this channel. true: Channel is wakeup capable. false: Channel is not wakeup capable.
Multiplicity	1
Туре	EcucBooleanParamDef
Default value	
Post-Build Variant Value	true



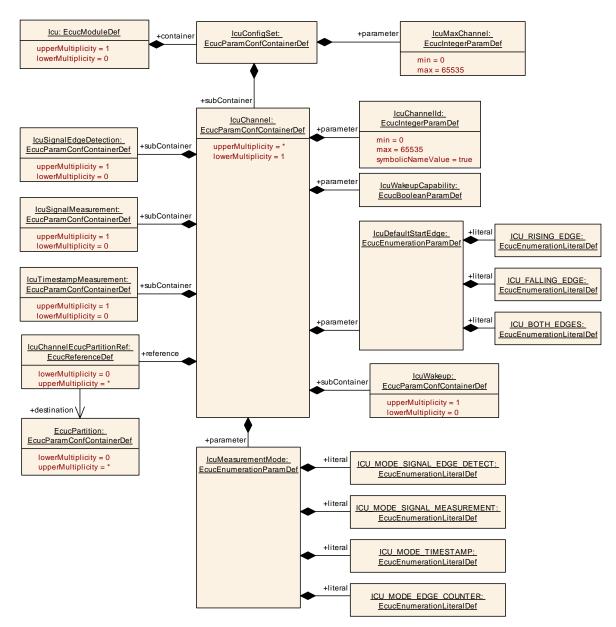
	Pre-compile time	Х	VARIANT-PRE-COMPILE
Value Configuration Class	Link time	-	
	Post-build time	Χ	VARIANT-POST-BUILD
Scope / Dependency	scope: local		

SWS Item	[ECUC_lcu_00360]			
Parameter Name	IcuChannelEcucPartitionRef			
Parent Container	IcuChannel			
Description	Maps an ICU channel to zero or multiple ECUC partitions to limit the access to this channel. The ECUC partitions referenced are a subset of the ECUC partitions where the ICU driver is mapped to.			
Multiplicity	0*	0*		
Туре	Reference to EcucPartition			
Post-Build Variant Multiplicity	true			
Post-Build Variant Value	true			
Multiplicity	Pre-compile time	Х	All Variants	
Multiplicity Configuration Class	Link time			
Class	Post-build time			
Value	Pre-compile time	Х	All Variants	
Configuration Class	Link time			
	Post-build time			
Scope / Dependency	scope: ECU			

Included Containers		
Container Name	Multiplicity	Scope / Dependency
IcuSignalEdge- Detection	01	This container contains the configuration (parameters) in case the measurement mode is "IcuSignalEdgeDetection"
IcuSignal- Measurement	01	This container contains the configuration (parameters) in case the measurement mode is "IcuSignalMeasurement"
IcuTimestamp- Measurement	01	This container contains the configuration (parameters) in case the measurement mode is "IcuTimestamp"
IcuWakeup	01	This container contains the configuration (parameters) needed



to configure a wakeup capable channel



[SWS\_Icu\_CONSTR\_00002] \( \) The ECUC partitions referenced by IcuChannelEcucPartitionRef shall be a subset of the ECUC partitions referenced by IcuEcucPartitionRef. \( \)()

[SWS\_lcu\_CONSTR\_00004] [ If lcuEcucPartitionRef references one or more ECUC partitions, lcuChannelEcucPartitionRef shall have a multiplicity of greater than one and reference one or several of these ECUC partitions as well. |()



#### 10.2.5 IcuSignalEdgeDetection

SWS Item	[ECUC_lcu_00021]	
Container Name	IcuSignalEdgeDetection	
Parent Container	IcuChannel	
Description	This container contains the configuration (parameters) in case the measurement mode is "IcuSignalEdgeDetection"	
Configuration Parameters		

SWS Item	[ECUC_lcu_00225]		
Parameter Name	IcuSignalNotification	IcuSignalNotification	
Parent Container	IcuSignalEdgeDetection	on	
Description	Notification function fo	r sig	nal notification.
Multiplicity	01		
Туре	EcucFunctionNameDe	ef	
Default value			
Regular Expression			
Post-Build Variant Multiplicity	true		
Post-Build Variant Value	true		
	Pre-compile time	Х	VARIANT-PRE-COMPILE
Multiplicity Configuration Class	Link time		
	Post-build time	Х	VARIANT-POST-BUILD
	Pre-compile time	Х	VARIANT-PRE-COMPILE
Value Configuration Class	Link time		
	Post-build time	Х	VARIANT-POST-BUILD
Scope / Dependency	scope: local dependency: IcuMeasurementMode		

#### **No Included Containers**



#### 10.2.6 IcuSignalMeasurement

SWS Item	[ECUC_lcu_00226]	
Container Name	IcuSignalMeasurement	
Parent Container	IcuChannel	
Description This container contains the configuration (parameters) in case the measurement mode is "IcuSignalMeasurement"		
Configuration Parameters		

SWS Item	[ECUC_lcu_00227]			
Parameter Name	IcuSignalMeasurementProperty			
Parent Container	IcuSignalMeasurement			
Description	Configures the property that could be measured in case the mode is "IcuSignal Measurement". This property can not be changed during runtime.  Implementation Type: Icu_SignalMeasurementPropertyType			
Multiplicity	1			
Туре	EcucEnumerationParamDe	ef		
	ICU_DUTY_CYCLE	The channel is configured to read values which are needed for calculating the duty cycle (coherent Active and Period Time).		
Range	ICU_HIGH_TIME	The channel is configured for reading the elapsed Signal High Time		
	ICU_LOW_TIME	The channel is configured for reading the elapsed Signal Low Time		
	ICU_PERIOD_TIME	The channel is configured for reading the elapsed Signal Period Time		
Post-Build Variant Value	true			
Value	Pre-compile time	Х	VARIANT-PRE-COMPILE	
Configuration	Link time			
Class	Post-build time	Х	VARIANT-POST-BUILD	
Scope / Dependency	scope: local dependency: lcuMeasurem ElapsedApi	entMod	e, IcuGetDutyCycleValuesApi, IcuGetTime	

#### **No Included Containers**



#### 10.2.7 IcuTimestampMeasurement

SWS Item	[ECUC_lcu_00228]	
Container Name	IcuTimestampMeasurement	
Parent Container	IcuChannel	
Description	This container contains the configuration (parameters) in case the measurement mode is "IcuTimestamp"	
Configuration Parameters		

SWS Item	[ECUC_lcu_00229]			
Parameter Name	IcuTimestampMeasurem	IcuTimestampMeasurementProperty		
Parent Container	IcuTimestampMeasuren	nent		
Description	Configures the handling of the buffer in case the mode is "Timestamp" Implementation Type: Icu_TimestampBufferType			
Multiplicity	1	1		
Туре	EcucEnumerationParamDef			
Pango	ICU_CIRCULAR_ BUFFER	After reaching the end of the buffer, the driver restarts at the beginning of the buffer		
Range	ICU_LINEAR_ BUFFER	The buffer will just be filled once		
Post-Build Variant Value	true			
	Pre-compile time	Х	VARIANT-PRE-COMPILE	
Value Configuration Class	Link time			
	Post-build time	Х	VARIANT-POST-BUILD	
Scope / Dependency	scope: local dependency: lcuMeasurementMode			

SWS Item	[ECUC_lcu_00230]
Parameter Name	IcuTimestampNotification
Parent Container	IcuTimestampMeasurement
Description	Notification function if the number of requested timestamps (Notification interval > 0) are acquired.
Multiplicity	01
Туре	EcucFunctionNameDef



Default value				
Regular Expression				
Post-Build Variant Multiplicity	true			
Post-Build Variant Value	true			
	Pre-compile time	Х	VARIANT-PRE-COMPILE	
Multiplicity Configuration Class	Link time			
_	Post-build time	Х	VARIANT-POST-BUILD	
	Pre-compile time	Х	VARIANT-PRE-COMPILE	
Value Configuration Class	Link time			
	Post-build time	Х	VARIANT-POST-BUILD	
Scope / Dependency	scope: local dependency: IcuTimestampApi			

#### **No Included Containers**

# 10.2.8 IcuWakeup

SWS Item	[ECUC_lcu_00126]	
Container Name	IcuWakeup	
Parent Container	IcuChannel	
Description	This container contains the configuration (parameters) needed to configure a wakeup capable channel	
Configuration Parameters		

SWS Item	[ECUC_lcu_00231]
Parameter Name	IcuChannelWakeupInfo
Parent Container	IcuWakeup
Description	If the wakeup-capability is true the wakeup source referenced is transmitted to the ECU State Manager (EcuM) . Implementation Type: reference to EcuM_WakeupSourceType
Multiplicity	01
Туре	Symbolic name reference to EcuMWakeupSource



Post-Build Variant Multiplicity	true		
Post-Build Variant Value	true		
Multiplicity Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time		
	Post-build time	Х	VARIANT-POST-BUILD
Value Configuration Class	Pre-compile time	Х	VARIANT-PRE-COMPILE
	Link time		
	Post-build time	Х	VARIANT-POST-BUILD
Scope / Dependency	scope: local dependency: IcuWakeupCapability and IcuReportWakeupSource		

**No Included Containers** 

# 10.2.9 IcuConfigSet

SWS Item	[ECUC_lcu_00219]	
Container Name	IcuConfigSet	
Parent Container	Icu	
Description	This container contains the configuration parameters and sub containers of the AUTOSAR Icu module.	
Configuration Parameters		

SWS Item	[ECUC_lcu_00220]		
Parameter Name	IcuMaxChannel		
Parent Container	IcuConfigSet		
Description	This parameter contains the number of Channels configured. It will be gathered by tools during the configuration stage. calculationFormula = Number of configured Icu Channels Implementation Type: Icu_ChannelType		
Multiplicity	1		
Туре	EcucIntegerParamDef		
Range	0 65535		



Default value			
Post-Build Variant Value	true		
Value Configuration Class	Pre-compile time	Х	VARIANT-PRE-COMPILE
	Link time		
	Post-build time	Х	VARIANT-POST-BUILD
Scope / Dependency	scope: local		

Included Containers				
Container Name Multiplicity Scope / Dependency		Scope / Dependency		
IcuChannel	1*	Configuration of an individual ICU channel.		



#### 10.3 Published Information

**[SWS\_lcu\_00131]** The ICU driver shall describe which other modules (in which versions) are required. This description shall be done by the implementer. (SRS\_BSW\_00384)



### 11 Not applicable requirements

[SWS Icu NA 00380] [These requirements are not applicable to this specification.] (SRS BSW 00300, SRS BSW 00301, SRS BSW 00302, SRS BSW 00304, SRS BSW 00305, SRS BSW 00306, SRS BSW 00307, SRS BSW 00308, SRS BSW 00309, SRS BSW 00310, SRS BSW 00312, SRS BSW 00314, SRS BSW 00318, SRS BSW 00321, SRS BSW 00325, SRS BSW 00327, SRS BSW 00328, SRS BSW 00330, SRS BSW 00331, SRS BSW 00333, SRS BSW 00334, SRS BSW 00335, SRS BSW 00341, SRS BSW 00342, SRS BSW 00347, SRS BSW 00348, SRS BSW 00350, SRS BSW 00353, SRS BSW 00357, SRS BSW 00358, SRS BSW 00360, SRS BSW 00373, SRS BSW 00377, SRS BSW 00378, SRS BSW 00379, SRS BSW 00383, SRS BSW 00395, SRS BSW 00397, SRS BSW 00398, SRS BSW 00399, SRS BSW 00400, SRS BSW 00408, SRS BSW 00409, SRS BSW 00413, SRS BSW 00414, SRS BSW 00005, SRS BSW 00006, SRS BSW 00007, SRS BSW 00009, SRS BSW 00010, SRS\_BSW\_00160, SRS\_BSW\_00161, SRS\_BSW\_00162, SRS\_BSW\_00164, SRS\_BSW\_00167, SRS BSW 00168, SRS BSW 00170, SRS BSW 00171, SRS BSW 00172, SRS BSW 00415, SRS BSW 00416, SRS BSW 00417, SRS BSW 00422, SRS BSW 00423, SRS BSW 00424, SRS BSW 00425, SRS BSW 00426, SRS BSW 00427, SRS BSW 00428, SRS BSW 00429, SRS BSW 00432, SRS BSW 00433, SRS BSW 00437, SRS BSW 00439, SRS BSW 00440, SRS BSW 00441, SRS SPAL 12068, SRS SPAL 12077, SRS SPAL 12092, SRS SPAL 12265, SRS SPAL 12463, SRS BSW 00450)