#include”ZumoMotors.h” //Zumo马达驱动库文件

ZumoMotors motors;

setLeftSpeed(int speed)；

setRightSpeed(int speed)；

void setup()

{

motors.setLeftSpeed(100);

motors.setRightSpeed(100);

delay(1875); //自A点出发 前进30CM到达场地中点

motors.setLeftSpeed(0);

motors.setRightSpeed(100);

delay(1500); //左转90° 调转方向驶向B站侧

motors.setLeftSpeed(100);

motors.setRightSpeed(100);

delay(5625); //继续前进90CM 到达场地左侧

motors.setLeftSpeed(100);

motors.setRightSpeed(0);

delay(5000); //右转90° 调转方向驶向B点

motors.setLeftSpeed(100);

motors.setRightSpeed(100);

delay(1875); //前进30CM 到达目的地B点

motors.setLeftSpeed(0);

motors.setRightSpeed(0); //停车

}