

Contrôle post hoc des faux positifs pour des hypothèses structurées

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Multiple testing setting

- ▶ Data $X \in (\mathcal{X}, \mathfrak{X})$ with $X \sim P$ unknown \mathcal{P} a family of distributions
- ▶ m null hypotheses $H_{0,i} \subset \mathcal{P}$ on P
- ▶ $\mathcal{H}_0 = \{i : P \in H_{0,i}\}$: $i \in \mathcal{H}_0 \Leftrightarrow H_{0,i}$ is true
- ▶ m p -values $p_i = p_i(X)$ such that $p_i \succeq \mathcal{U}([0, 1])$ if $i \in \mathcal{H}_0$
- ▶ Definition: for every subset of hypothesis S : $V(S) = |S \cap \mathcal{H}_0|$

Classic MT theory: form a rejection set R with a guarantee on $V(R)$

- ▶ $\text{FWER}(R) = \mathbb{P}(V(R) > 0)$
- ▶ $\text{FDR}(R) = \mathbb{E} \left[\frac{V(R)}{|R| \vee 1} \right]$

Example: Gaussian one-sided case $(X_1, \dots, X_m) \sim \mathcal{N}(\mu, \Sigma)$, $H_{0,i} : \mu_i = 0$
versus $H_{1,i} : \mu_i > 0$, $p_i(X) = p_i(X_i) = 1 - \Phi(X_i)$

Exploratory analysis in multiple testing

Exploratory analysis: searching interesting hypotheses that will be cautiously investigated after.

Desired properties [Goeman and Solari (2011)]:

- ▶ Mildness: allows some false positives
- ▶ Flexibility: the procedure does not prescribe, but advise
- ▶ Post hoc: take decisions on the procedure after seeing the data

[Goeman and Solari (2011)]

This **reverses the traditional roles** of the user and procedure in multiple testing. Rather than [...] to let the user choose the quality criterion, and to let the procedure return the collection of rejected hypotheses, the **user chooses the collection of rejected hypotheses freely**, and the multiple testing procedure returns the **associated quality criterion**.

Post hoc and replication crisis

Post hoc done wrong: p -hacking

- ▶ Pre-selecting variables that seem significant, exclude others
- ▶ Theoretical results no longer hold because the selection step is random
- ▶ Example: selecting the 1000 smallest p -values in a genetic study with 10^6 variants

- ▶ p -hacking may be one of the causes of the replication crisis
- ▶ Replication crisis: many published results non reproducible

⇒ need for exploratory analysis MT procedures with the above properties

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Our goal: post hoc inference

Or simultaneous inference

Confidence bounds on any set of selected variables

A confidence bound is a (random) function \hat{V} such that

$$\mathbb{P} \left(\forall S \subset \mathbb{N}_m, V(S) \leq \hat{V}(S) \right) \geq 1 - \alpha$$

- ▶ Hence for any selected \hat{S} , $\mathbb{P} \left(V(\hat{S}) \leq \hat{V}(\hat{S}) \right) \geq 1 - \alpha$ holds
- ▶ Originates from [Genovese and Wasserman (2006) and Meinshausen (2006)]
- ▶ A guarantee over any selected set instead of a rejected set, advise some \hat{S} instead of prescribe one R : the MT paradigm is reversed

BNR technology

[Blanchard et al. (2020)]

Key concept: reference family

- ▶ $\mathfrak{R} = (R_k, \zeta_k)$ (random) such that Joint Error Rate (JER) control:

$$\text{JER}(\mathfrak{R}) = \mathbb{P}(\exists k, |R_k \cap \mathcal{H}_0| > \zeta_k) \leq \alpha$$

- ▶ Conversely, $\mathbb{P}(\forall k, |R_k \cap \mathcal{H}_0| \leq \zeta_k) \geq 1 - \alpha$
- ▶ Confidence bound only on the members of \mathfrak{R}
- ▶ \implies Derivation of a global confidence bound by interpolation

BNR technology

[Blanchard et al. (2020)]

Idea: we get the following info on \mathcal{H}_0 : $\mathcal{H}_0 \in \{A, \forall k, |R_k \cap A| \leq \zeta_k\}$.

Two different bounds

- ▶ $V_{\mathfrak{N}}^*(S) = \max \{|S \cap A|, \forall k, |R_k \cap A| \leq \zeta_k\}$ optimal but hard to compute
- ▶ $\overline{V}_{\mathfrak{N}}(S) = \min_k (\zeta_k + |S \setminus R_k|) \wedge |S|$ easy to compute

BNR technology

A versatile approach

- ▶ Compatible with previous works, like the closed testing approach of [Goeman and Solari (2011)]
- ▶ BNR approach: $\zeta_k = k - 1$ and find $R_k = \{i : p_i < t_k\}$ such that JER control. Example: $t_k = \alpha k/m$ (Simes inequality).
 - ▶ JER control becomes “simultaneous k -FWER control”

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Spatial structure

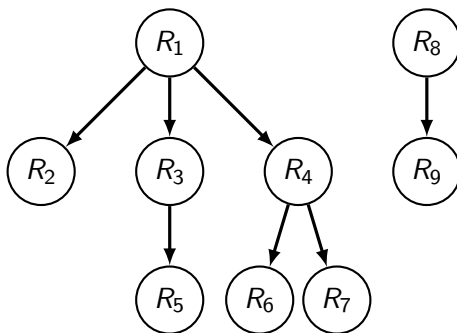
Informal assumption

The signal is localized in some spatially structured regions, with, possibly, different levels (e.g. active SNPs into genes into chromosomes)

- ▶ Accordingly, find adapted new reference families
- ▶ We want $V_{\mathfrak{A}}^*$ to be easy to compute
- ▶ Our approach: deterministic R_k 's capturing spatial hierarchy, estimate the true nulls inside them (i.e. ζ_k random)
 - ▶ the opposite of [Blanchard et al. (2020)]

Forest structure

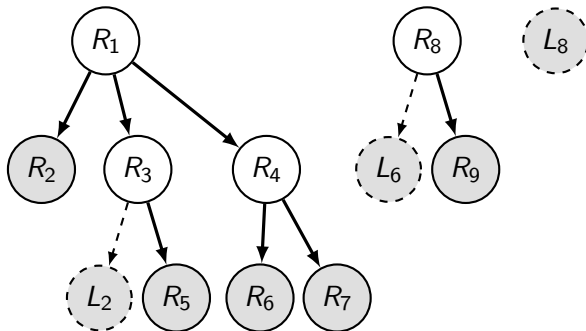
- ▶ $\forall k, k' \in \mathcal{K}, R_k \cap R_{k'} \in \{R_k, R_{k'}, \emptyset\}$
- ▶ Accommodates to different levels of signal localization through the different depths of the nodes
- ▶ Includes nested families or totally disjoint families



Forest structure

Property

- ▶ Each forest structure can be completed to includes all leaves
- ▶ For an added leaf L_i , just state $\zeta_i = |L_i|$



New interpolation bounds

Goal: compute $V_{\mathfrak{R}}^*$ easily with forest structure

Definition

For any $q \leq K = |\mathcal{K}|$,

$$\tilde{V}_{\mathfrak{R}}^q(S) = \min_{Q \subset \mathcal{K}, |Q| \leq q} \left(\sum_{k \in Q} \zeta_k \wedge |S \cap R_k| + \left| S \setminus \bigcup_{k \in Q} R_k \right| \right),$$

and

$$\tilde{V}_{\mathfrak{R}}(S) = \tilde{V}_{\mathfrak{R}}^K(S).$$

Property

$$V_{\mathfrak{R}}^*(S) \leq \tilde{V}_{\mathfrak{R}}(S) \leq \tilde{V}_{\mathfrak{R}}^{K-1}(S) \leq \dots \leq \tilde{V}_{\mathfrak{R}}^2(S) \leq \tilde{V}_{\mathfrak{R}}^1(S) = \overline{V}_{\mathfrak{R}}(S)$$

Main results

Compute $V_{\mathfrak{N}}^*$ easily with forest structure

Theorem

$$V_{\mathfrak{N}}^*(S) = \tilde{V}_{\mathfrak{N}}(S)$$

More precisely,

$$V_{\mathfrak{N}}^*(S) = \tilde{V}_{\mathfrak{N}}^{\ell}(S),$$

with ℓ = number of leaves (without completion).

Proof by construction \implies computation algorithm

Corollary

$\ell = 1$ for nested families and a property in BNR is recovered

Main results

Compute $V_{\mathfrak{R}}^*$ easily with forest structure

Corollary (derived from the proof)

There is a simple and efficient algorithm to compute $\tilde{V}_{\mathfrak{R}}$ if \mathfrak{R} is complete ($O(Hm)$ complexity).

Lemma

Completing the family does not change $V_{\mathfrak{R}}^*$ and $\tilde{V}_{\mathfrak{R}}$.

Corollary

There is a simple algorithm to compute $V_{\mathfrak{R}}^*(S)$ in any case by completing the family first.

Note: all of the above does not depend on the choice of the ζ_k and works for random R_k .

True nulls estimation inside regions

That is, ζ_k computation

- ▶ K deterministic regions, let $C = \sqrt{\frac{1}{2} \log \left(\frac{K}{\alpha} \right)}$
- ▶ $\zeta_k = |R_k| \wedge \min_{t \in [0,1)} \left[\frac{C}{2(1-t)} + \left(\frac{C^2}{4(1-t)^2} + \frac{\sum_{i \in R_k} \mathbf{1}\{p_i > t\}}{1-t} \right)^{1/2} \right]^2$
- ▶ Comes from carefully handling the DKWM inequality [Dvoretzky et al. (1956) and Massart (1990)]
 - ▶ Requires independence!
- ▶ Replace $\min_{t \in [0,1)}$ and t above by $\min_{0 \leq \ell \leq s}$ and $p_{(\ell)}$ for practical usage \implies computation of $(\zeta_k)_k$ is also $O(Hm)$ complex
- ▶ α/K instead of α in C : union bound for JER control
- ▶ Dependence on α (and to K !) only through a log
- ▶ $\zeta_k > 0$ (entry cost)

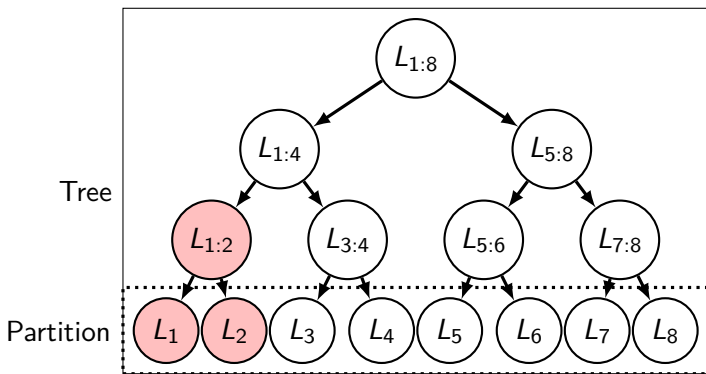
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Comparison of 3 bounds

Simes bound of BNR, and 2 new

- ▶ V_{tree} and V_{part} , from a complete binary tree or only the partition of leaves
- ▶ Signal in adjacent leaves, good performance of V_{tree} expected despite worst K
- ▶ Parameters: signal $\bar{\mu}$ and signal proportion in active leaves r



Comparison of 3 bounds

- ▶ $S(x)$ = the x -th smallest p -values
- ▶ But for large r , new bounds better
- ▶ V_{tree} better than V_{part} as expected, despite a worst union bound correction

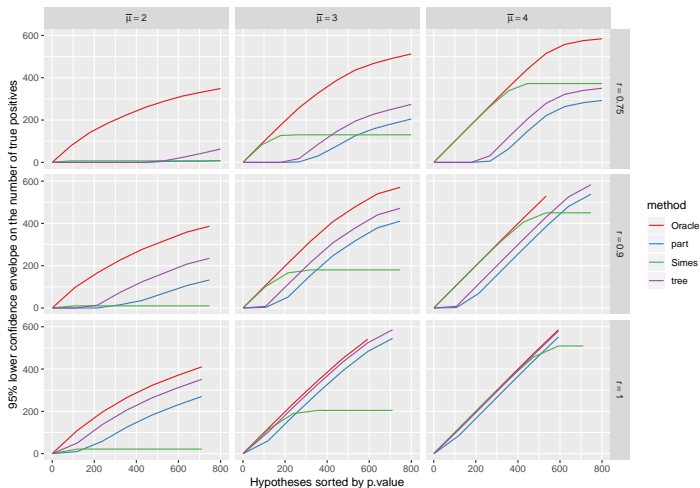


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Conclusion

New confidence bounds that exploit the signal localization to improve on existing bounds, with an acceptable computation time

Limitations:

- ▶ DKWM inequality involves independence
- ▶ The chosen ζ_k can't reject a whole subset (including individual hypotheses)
- ▶ The R_k have to be fixed before seeing the data (not post hoc!)
- ▶ The union bound correction chosen may induce conservativeness
- ▶ Real data application?

Published paper in Scandinavian Journal of Statistics (2020) [Durand et al. (2020)]

Also on arXiv: 1807.01470

R package available on github: sansSouci

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Next steps I

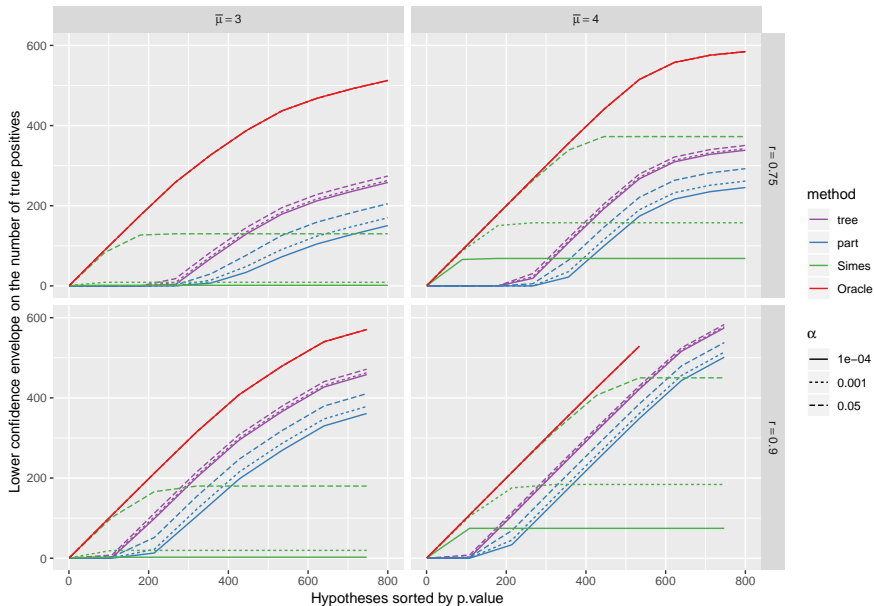
- ▶ Depart from independence with $\zeta_k(X) = L_k(\alpha/K)$ such that $\mathbb{P}_{X \sim P}(|R_k \cap \mathcal{H}_0(P)| \leq L_k(\lambda)) \leq \lambda$
 - ▶ Concentration inequalities for dependent variables?
 - ▶ λ -calibration under known dependence or permutation invariance [Hemerik and Goeman (2018) and Blanchard et al. (2020)]
 - ▶ Use local tests [Goeman and Solari (2011) and Meijer et al. (2015)], App. B. of my thesis
 - ▶ Different L_k at different hierarchical levels [Dobriban (2020)]
- ▶ Reduce union bound penalty with some α -recycling (App. B of my thesis)
- ▶ Other families combining BNR approach and a deterministic partition
 - ▶ $\mathfrak{R} = (R_{k,i_k}, \zeta_{k,i_k})_{\substack{k \in \mathcal{K} \\ 1 \leq i_k \leq |R_k|}}, \zeta_{k,i_k} = i_k - 1$
 - ▶ The results on forest structures allows the regions to be random
 - ▶ A first step toward automatic selection of the forest structure
 - ▶ Otherwise : MC independent random choices of the regions?

Next steps II

- ▶ Reuse some of those ideas to go back to FWER control (App. B of my thesis)
- ▶ Pursue work on closed testing shortcuts for post hoc bounds (App. A.1 of my thesis)
- ▶ Applications, real-life favorable cases like neuroimagery [Vesely et al. (2021)]

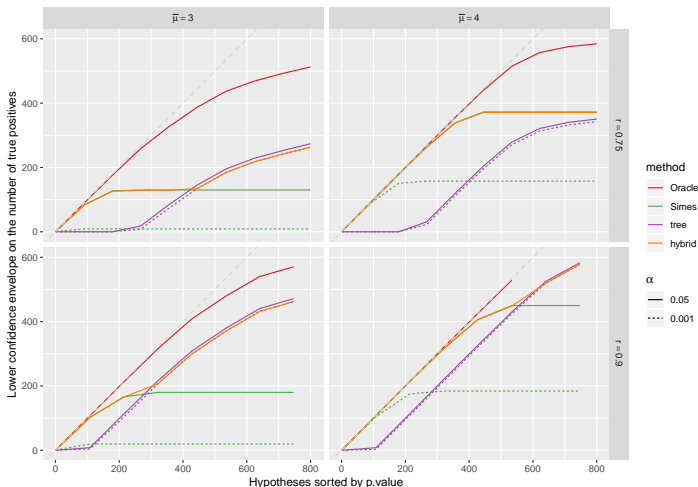
Comparison of 3 bounds

Influence of α



New hybrid bound suggested by the simulations

- ▶ $V_{\text{hybrid}}^{\gamma}(\alpha, S) = \min(V_{\text{Simes}}((1 - \gamma)\alpha, S), V_{\text{tree}}(\gamma\alpha, S))$
- ▶ $\gamma = 0.02$: favors Simes, not a problem because V_{tree} is little sensitive to small α



Classical theory

Family-Wise Error Rate (FWER)

- ▶ $\text{FWER}(R) = \mathbb{P}(V(R) > 0)$
- ▶ Bonferroni method: reject all $p_i \leq \frac{\alpha}{m}$ (union bound)
- ▶ Variant: $k\text{-FWER}(R) = \mathbb{P}(V(R) \geq k)$
 - ▶ Choice of k ? Often post hoc!

False Discovery Rate (FDR)

- ▶ $\text{FDR}(R) = \mathbb{E} \left[\frac{V(R)}{|R| \vee 1} \right]$
- ▶ Benjamini-Hochberg method for positive dependence
 - ▶ Reject all $p_i \leq \frac{\alpha \hat{k}}{m}$
 - ▶ $\hat{k} = \max \{ k : p_{(k)} \leq \frac{\alpha k}{m} \}, p_{(1)} \leq \dots \leq p_{(m)}$

Closed testing for post hoc inference

Designed for FWER control [Marcus et al. (1976)]

- ▶ Form $H_{0,I} = \bigcap_{i \in I} H_{0,i}$ all intersection hypotheses
- ▶ Have a collection of α level local test ϕ_I
- ▶ Examples:
 - ▶ Bonferroni test $\phi_I = 1$ if $\exists i \in I : p_i \leq \alpha/|I|$
 - ▶ Simes test $\phi_I = 1$ if $\exists i \in I : p_{(i:I)} \leq \alpha i/|I|$ (under PRDS)
- ▶ Test $H_{0,I}$ only if all $H_{0,J}$, $J \supseteq I$, are rejected
- ▶ Reject the individual hypotheses $H_{0,i}$ such that $H_{0,\{i\}}$ has been rejected that way
- ▶ Then $\text{FWER}(\text{Closed testing}) \leq \alpha$

Closed testing for post hoc inference

[Goeman and Solari (2011)]

Main idea

The closed testing provides more information than just the individual rejects:

- ▶ Let \mathcal{X} the set of all I such that we rejected $H_{0,I}$
- ▶ Simultaneous guarantee over all $H_{0,I}$, $I \in \mathcal{X}$:

$$\mathbb{P}(\forall I \in \mathcal{X}, H_{0,I} \text{ is false}) \geq 1 - \alpha$$

Confidence bound derivation:

- ▶ $V_{\text{GS}}(S) = \max_{\substack{I \subseteq S \\ I \notin \mathcal{X}}} |I|$ is a confidence bound because

$$\begin{aligned} \exists S, |S \cap \mathcal{H}_0| > V_{\text{GS}}(S) &\implies \exists S, S \cap \mathcal{H}_0 \in \mathcal{X} \\ &\implies \exists I \in \mathcal{X}, H_{0,I} \text{ is true} \end{aligned}$$

- ▶ $V_{\text{GS}}(S) = V_{\mathfrak{R}}^*(S)$ with $\mathfrak{R} = (I, |I| - 1)_{I \in \mathcal{X}}$

DKWM use

- ▶ Let $S \subset \mathbb{N}_m$
- ▶ $N_t(S) = \sum_{i \in S} \mathbf{1}\{p_i(X) > t\}$
- ▶ $v = |S \cap \mathcal{H}_0|$

$$v \leq \min_{t \in [0,1)} \left(\frac{\sqrt{\log(1/\lambda)/2}}{2(1-t)} + \left\{ \frac{\log(1/\lambda)/2}{4(1-t)^2} + \frac{N_t(S)}{1-t} \right\}^{1/2} \right)^2$$

comes from

$$v^{-1} \sum_{i=1}^v \mathbf{1}\{U_i > t\} - (1-t) \geq -\sqrt{\log(1/\lambda)/(2v)}, \quad \forall t \in [0,1],$$

with probability at least $1 - \lambda$ (U_1, \dots, U_v i.i.d. uniform, $N_t(S)$ dominates $\sum_{i=1}^v \mathbf{1}\{U_i > t\}$ by independence)

- ▶ $S = R_k$ and $\lambda = \alpha/K$ (union bound)

Forest algorithm

Computation of $V_{\mathfrak{R}}^*(S)$

Data: $\mathfrak{R} = (L_{i:j}, \zeta_{i:j})_{(i,j) \in \mathcal{K}}$ and $S \subset \mathbb{N}_m$.

Result: $V_{\mathfrak{R}}^*(S)$.

$\mathfrak{R} \leftarrow \mathfrak{R}^\oplus$; $\mathcal{K} \leftarrow \mathcal{K}^\oplus$ (completion);

$H \leftarrow \max_{k \in \mathcal{K}} \phi(k)$ (max depth);

$V \leftarrow (\zeta_k \wedge |S \cap R_k|)_{k \in \mathcal{K}^H}$;

for $h \in \{H-1, \dots, 1\}$ **do**

$newV \leftarrow (0)_{k \in \mathcal{K}^h}$;

for $k \in \mathcal{K}^h$ **do**

$Succ_k \leftarrow \{k' \in \mathcal{K}^{h+1} : R_{k'} \subset R_k\}$;

$newV_k \leftarrow \min \left(\zeta_k \wedge |S \cap R_k|, \sum_{k' \in Succ_k} V_{k'} \right)$;

end

$V \leftarrow newV$;

end

return $\sum_{k \in \mathcal{K}^1} V_k$.