

**Diagnosing Kaypro Problems
using the
Kaypro Emergency Monitor ROM**
June 3, 2023

Table of Contents

Introduction.....	1
Memory/CPU Checks.....	2
High-level Analysis.....	2
I/O Port Select Signals.....	3
SysPort Usage.....	5
Model */83 SysPort.....	5
Models */84 and 10 SysPort.....	6
Display Issues.....	6
Model */83 Display.....	6
Model */84 and 10 Display.....	7
Floppy Issues.....	8
Harddisk Issues.....	12
HDD Testing.....	12
SysPort Issues.....	13
Display Issues.....	14
Keyboard Issues.....	14
Main Memory Issues.....	15

Introduction

Throughout this document, examples are shown using underlined text to indicate what the user types, and the token (*CR*) indicates pressing the RETURN or Enter key.

Diagnosing a broken Kaypro can be a complex and overwhelming task. This document attempts to break-down the task into steps, and gives examples of how to use the Emergency Monitor ROM to further diagnose problems.

This document picks up where the Emergency Monitor ROM documentation leaves off. That document should be read first.

The first step for a newly acquired Kaypro in unknown condition is to examine the electronics for signs of physical failure. A common failure is in electrolytic capacitors (as well as the RIFA capacitors). A thorough examination and testing of the power supplies and associated power components is beyond the scope of this document. This document begins once the power has been verified and the machine is safe to power-on and run.

In addition, a working CPU and main memory is required. One basic check for that is to run the Emergency Memory Test ROM. If the memory test is able to run but detects an error in RAM, then

RAM should be replaced. If the memory test is unable to even run, that may indicate a bad CPU, which must be replaced. However, this could also indicate a more-fundamental problem that requires diagnostics at an electronics level.

Be aware that earlier Kaypro models do not have sockets for all ICs. While the major ICs are socketed, many – include RAM – are not. This makes replacement much more difficult, at least the first time (until a socket is installed after desoldering the IC).

Memory/CPU Checks

One way to determine if basic CPU, ROM, and RAM are functional is to try the Emergency Memory Test ROM. This ROM will send output on the serial port as well as provide visual indicators that are visible from the front of the Kaypro. If neither the serial output nor the visual indicators are working, it may point to a CPU issue, or an issue addressing the ROM, or multiple failures of the serial port and the visual indicator for the Kaypro model being tested. These will require diagnostic methods not covered in this document.

High-level Analysis

Determining “where to start looking” requires a basic understanding of the sequence of events performed by the boot ROM, combined with the symptoms presented by the machine. While different ROM versions perform different steps, the basic sequence is:

1. Initialize SIO1 (keyboard and serial data)
2. Initialize/clear display
3. Setup common (BIOS) memory
4. Display signon message on screen
5. Initialize floppy, and boot if diskette present
6. [Kaypro 10] Initialize harddisk, and boot.
7. Fallback for failed boot (varies)

A general idea of how far the system gets can be guessed by checking for progress. For example, the video display RAM will power-on with garbage, so if the screen displays garbage characters then one can assume that the clear screen step was not completed. However, */83 machines have a video circuitry that requires no initialization and is always “on”, in contrast to the */84 and 10 models that have a CRT controller chip which must be initialized before video will be enabled. If the CRTC has not been initialized and started, there will be no raster scan visible when the brightness is turned up.

Certainly, if the ROM signon message appears on the screen, the system has passed step 4 and it can be assumed that the CRTC and video is working.

Progress on booting from the floppy can be determined by observation. When attempting to boot, the ROM will select drive A and the drive motors will be spinning.

Also be aware that failure to boot could be caused by bad media or media that does not have the matching bootstrap code (or CP/M) for the ROM version.

I/O Port Select Signals

One common question that arises when devices are not functioning is whether the chip-select signal is reaching the device. On the monitor, a simple program can be poked into memory and executed that will continuously pulse the desired chip-select, and then an oscilloscope can be used to confirm that the device is getting the select signal. The following example show the program, where the “XX” value should be replaced by the desire I/O port for the device to test.

```
: S 8000(CR)
8000 00 DB(CR)      (INPUT op-code)
8001 00 XX(CR)      (replace XX with desired port)
8002 00 C3(CR)      (JUMP op-code)
8003 00 00(CR)      (low byte of 8000H)
8004 00 80(CR)      (high byte of 8000H)
8005 00 ÷
: G 8000(CR)
GO 8000 ?Y
```

It will be necessary to RESET the Kaypro in order to get back to the monitor prompt.

Here are the I/O ports for the various Kaypro models. Note that some Kaypro 10s are fitted with the */84 mainboard. Also note that some */84 models do not have the PIO, RTC, and Modem electronics.

Port Adr	*/83		10		*/84	
	Device	Function	Device	Function	Device	Function
00	WD1943 Baud Gen. Serial I/O	baud	WD1943 Baud Gen. Serial Data	baud	WD1943 Baud Gen. Serial Data	baud
01						
02						
03						
04	Z80-SIO Serial I/O Keyboard	ch A data	Z80-SIO #1 Serial Data Keyboard	ch A data	Z80-SIO #1 Serial Data Keyboard	ch A data
05		ch B data		ch B data		ch B data
06		ch A ctl		ch A ctl		ch A ctl
07		ch B ctl		ch B ctl		ch B ctl
08	Z80-PIO #1 Printer	ch A data	WD1943 Baud Gen. Serial Printer	baud	WD1943 Baud Gen. Serial Printer	baud
09		ch B data				
0A		ch A ctl				
0B		ch B ctl				
0C	WD1943 Baud Gen. Keyboard	baud	Z80-SIO #2 Serial Printer	ch A data	Z80-SIO #2 Serial Printer Modem	ch A data
0D				ch B data		ch B data
0E				ch A ctl		ch A ctl
0F				ch B ctl		ch B ctl

Port Adr	*/83		10		*/84	
	Device	Function	Device	Function	Device	Function
10	WD1793 Floppy Controller	cmd/sts	WD1793 Floppy Controller	cmd/sts	WD1793 Floppy Controller	cmd/sts
11		track		track		track
12		sector		sector		sector
13		data		data		data
14	N/C		SysPort	sysprt	SysPort	sysprt
15						
16						
17						
18	N/C		Parallel Printer	data out	Parallel Printer	data out
19						
1A						
1B						
1C	Z80-PIO #2 SysPort	ch A data	6545A-1 CRT Controller	ctl/sts	6545A-1 CRT Controller	ctl/sts
1D		ch B data		data		data
1E		ch A ctl				
1F		ch B ctl		vid RAM		vid RAM
20	N/C		N/C		Z80-PIO RTC Modem	ch A data
21						ch B data
22						ch A ctl
23						ch B ctl
24	N/C		N/C		RTC	data
25						
26						
27						
80	N/C		WD1002- HDO Controller	data	N/C	
81				error		
82				sec count		
83				sector		
84				cyl low		
85				cyl high		
86				SDH		
87				cmd/sts		

When doing chip-select testing, a specific port should be chosen for the least side-effects. For example, reading from most ports has no serious side-effect, but writing to a port could significantly alter the system behavior.

SysPort Usage

Note that the sysport contains the “bank” control on bit 7. It is imperative that this bit never be set to “0” (unless by a special program running in high memory), as that would make the ROM code disappear and the system would crash.

The general practice with SysPort is to read the current value, modify it, then write the new value. In this environment, there should be no hidden changes to the port and so it is reasonable to just know what the right value is without reading the port.

The main operations needed on the sysport are to turn on/off the motors and select a drive (or deselect all). While the sysport bit numbers involved with these actions are same for all models, the actual values used are not.

Model */83 SysPort

The */83 models use a different system port (Z80-PIO) than the others, and this port must be initialized before it can be used. Do not perform this initialization on a */84 or 10 model, as it will corrupt the CRTC registers. The Z80-PIO resets to a state where all data lines are inputs, effectively causing them to float “1”. This places the lines, especially BANK, in the correct state for the system to run until the sysport is configured and enabled. The safe way to enable the */83 sysport is:

: 0 1C C0(CR) (make certain BANK stays on)

: 0 1D CF 08(CR) (init and activate PIO ch A)

:

This sequence leaves motor off and no drive selected. The floppy-related sysport bits (expressed as hexadecimal mask) are:

*/83 (PIO 1CH)	Drive A select	01	1=select
	Drive B select	02	1=select
	Side select	04	1=side-1
	DD enable	20	0=DD
	Motor control	40	0=ON

Models */84 and 10 SysPort

On */84 and 10 models, the sysport RESETs (and powers on) to a special state where all outputs are tri-state and float high (“1”). The first write to sysport will also turn off this state and enable the sysport outputs. So, the first read of sysport (before any write) will return the tri-state values – not the actual state of the bits in the latch. Also note that the parallel printer “ready” bit will never read as the state of the “A12 CH” output. This bit may initially read “0” or “1” depending on whether there is a printer connected, and powered on, at the parallel printer port. The “A12 CH” output is generally not functional (“don’t care”), unless a special character generator ROM has been install for the CRTC.

Here are the disk-related sysport bits (expressed as hexadecimal mask) for the two families:

Kaypro 10 (port 14H)	Drive A select	01	0=select
	WD1002 reset	02	1=reset
	Side select	04	0=side-1
	Motor control	10	1=ON
	DD enable	20	0=DD
*/84 (port 14H)	Drive A select	01	0=select
	Drive B select	02	0=select
	Side select	04	0=side-1
	Motor control	10	1=ON
	DD enable	20	0=DD

Note that the main difference between models 10 and */84 is the re-assignment of Drive B select to WD1002 RESET.

Display Issues

Model */83 Display

The model */83 video display is made using discrete logic (there is no controller chip). The system powers on with video enabled, and should be producing a raster on the CRT immediately. Diagnosing the video circuitry (no raster, or malformed raster) is beyond the scope of this document. If the display does start up correctly, probably the most likely issue would be video RAM and should be noticeable by incorrect characters on the screen. With the monitor ROM installed, the video RAM is not cleared on power-up or RESET and so will contain garbage (or the previous contents). The video RAM may be accessed directly from the monitor, and so various patterns can be written to video RAM and the effects can be viewed on the display. Typically, the F(ill), S(ubstitute), and M(ove) commands are useful for exploring video RAM, in addition to D(ump) for verifying contents.

Model */84 and 10 Display

The model */84 and 10 systems use a 6545A-1 CRT Controller chip. This chip powers-up with video disabled, and no raster will be present on the screen until the CRTC is programmed. The video RAM is not directly accessible from the monitor, but will be filled with garbage after power-on.

The first test is to program the CRTC and see whether the screen lights up with garbage characters.

: N_CRTC(CR) (display should light up)

If the display does not light up after this command, then the CRTC will need to be further tested to determine where the problem might be. The first test is to check if the CRTC “Update” status working correctly. This is used by the Kaypro ROMs to read or write video RAM without disrupting the display. This command checks whether the Update status is seen to toggle through three update cycles:

: T_CRTC(CR)
Wait... Update Update Update

This command will “hang” if an update does not occur, but may be interrupted by pressing any key.

The next step would be to check that the vertical retrace is occurring, and at the correct rate. This generally confirms that all other timing is correct.

: T_VRT(CR)
80 001C
A0 064B
80 06AF
A0 0CDE
80 0D42
A0 1371
80 13D5
A0 1A03
80 1A68
A0 2096

This command does not normally run the full cycle (iteration count FFFF), instead stopping after 10 status register changes. If it does reach the FFFF count, it probably indicates a problem in the CRTC. Vertical retrace is in bit 5 (20 hex) of the status register. The above data shows that we see retrace at 064B and 0CDE (among other times). Subtracting those gives 0693 hex or 1683 decimal. That computes to approximately 20 mS which matches the desired 50Hz vertical retrace rate.

If all these tests pass and the display is still not working, there may be problems outboard of the CRTC, possibly on the video board. Beware of high voltage.

There is a command that will fill video Ram with a character, and also set the attributes. This can be used to do some testing of the video RAM, but setting certain values and observing whether the display looks correct. The general command syntax is:

T CRTF [*char* [*attr*]]

Where *char* is the hexadecimal value to put in all character locations and *attr* is the hexadecimal attributes value to apply to all locations. Attribute bits are: 01=reverse, 02=dim, 04=blink, 08=underline. The defaults are the blank space character and 00 attributes, effectively a clear screen.

Floppy Issues

If floppy drive select and motor control seem to be working, the next step would be to confirm that the controller chip is functioning at a basic level. This can be done by performing the FLPY test command, which will issue a FORCE INTERRUPT command to the controller and watch for the expected results.

At this point, an overview of the WD1793 status register bits is in order. The status registers bits may have one of two possible meanings depending on the command that was last run. After head-movement commands, and force-interrupt, the status register bits are:

7	6	5	4	3	2	1	0
NRDY	WP	HLD	SEEK ERR	CRC ERR	TRK00	INDEX	BUSY

For read/write commands, the status register bits are:

7	6	5	4	3	2	1	0
NRDY	WP	FAULT*	RNF	CRC ERR	LOST DAT	DRQ	BUSY

Note that the Kaypro hard-wires the READY and HLD signals, so NRDY should always be “0”.

Here are the expected results of running the FLPY command when no drive is selected:

```
: T_FLPY(CR)
01 0002
00 0003
00 FFFF
```

The expected results, above, show that the BUSY bit went on briefly in response to the command, and then stayed off. The key result is that the BUSY bit is still off when the iteration count FFFF is reached.

If this controller is handling the FORCE INTERRUPT command correctly, there may some issue with signals from the drives reaching, and passing through, the controller. The first of these is the TRK00 signal, which indicates that the selected drive’s heads are on track 0. This will require that a drive be selected, but no diskette need be in the drive (the head protectors should be removed, though). The test involves performing a RESTORE command and confirming that the TRK00 signal shows up in the status register, then stepping in and confirming that TRK00 goes off, then RESTORE again and confirming TRK00 is back on:


```

: 0 10 03(CR)      (RESTORE - make sure drive is at track 0)

: I 10(CR)
Input 10 = 46      (confirm TRK00 bit (04) is on)

: T FLPY 53(CR)    (send STEP IN command)
47 0002           (BUSY on, TRK00 on)
43 00A4           (TRK00 goes off as head steps away)
42 09A8           (command done)
42 FFFF

: T FLPY 03(CR)    (send RESTORE command)
43 0002           (BUSY on)
47 28C4           (TRK00 on)
46 30FD           (command done)
46 FFFF

```

Note that the INDEX signal (02) and WP (40) are always on in this case, because there is no diskette in the drive and the sensors are not obstructed.

If the TRK00 signal is not working correctly, it will be necessary to trace that signal to the WD1793 pin 34 from the drive (pin 26 on the drive connector)

The next check is for the INDEX signal from a spinning diskette. The Kaypro boot ROMs check this signal before deciding to boot. Insert a diskette into the drive and close the door. The diskette need not be formatted.

The following command watches the status register and records any changes, which should only involve the INDEX signal.

```

: T FLPY(CR)      (issue default command, FORCE INTR)
05 0002           (BUSY on for command)
04 0003           (BUSY off)
06 1441           (INDEX (02) on)
04 159D           (INDEX off)
06 5572           (INDEX on)
04 56CE
06 96A3
04 97FF
06 D7D4
04 D930
04 FFFF

```

If the output shows the INDEX signal working, a further test is to measure the time between INDEX pulses. In this case, we see INDEX start at 1441 and 5572. We subtract those to get 4131 hex, or 16689 decimal. This computes out to 200.268 mS (4MHz Z80), which is plenty close enough to 5 RPM.

The next step is to try and read the boot sector off the diskette. With the heads at track 0, set the side and double-density bits correctly (typically double-density, always side 0). This diskette must be bootable in order to see a valid boot sector, and (of course) must be formatted at the very least.

For drive A on a model */84 or 10, the sysport value would be DE. For drive A on model */83, the sysport value would be 81.

The following commands read and dump the boot sector. The exact contents of this sector will vary between CP/M versions, but should look similar.

```
: T FDRD 00(CR)    (perform READ of sector 0)
00                (no error detected)
: D8000 81FF(CR)    (dump sector buffer)
8000 18 FE 00 E4 00 FA 30 00 00 00 00 00 00 00 00 00 .....0.....
8010 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 .....
8020 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 .....
8030 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 .....
8040 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 .....
8050 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 .....
8060 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 .....
8070 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 .....
8080 C3 5C E7 C3 58 E7 7F 01 44 00 20 20 20 20 20 20 .\..X...D.
8090 20 20 20 20 20 20 20 20 20 43 4F 50 59 52 49 47 48          COPYRIGHT
80A0 54 20 28 43 29 20 31 39 37 39 2C 20 44 49 47 49 T (C) 1979, DIGI
80B0 54 41 4C 20 52 45 53 45 41 52 43 48 20 20 00 00 TAL RESEARCH ..
80C0 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 .....
80D0 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 .....
80E0 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 .....
80F0 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 .....
8100 00 00 00 00 00 00 00 00 00 08 E4 00 00 5F 0E 02 C3 ....._...
8110 05 00 C5 CD 8C E4 C1 C9 3E 0D CD 92 E4 3E 0A C3 .....>...>..
8120 92 E4 3E 20 C3 92 E4 C5 CD 98 E4 E1 7E B7 C8 23 ..> .....~..#
8130 E5 CD 8C E4 E1 C3 AC E4 0E 0D C3 05 00 5F 0E 0E ....._...
8140 C3 05 00 CD 05 00 32 EE EB 3C C9 0E 0F C3 C3 E4 .....2...<.....
8150 AF 32 ED EB 11 CD EB C3 CB E4 0E 10 C3 C3 E4 0E .2.....
8160 11 C3 C3 E4 0E 12 C3 C3 E4 11 CD EB C3 DF E4 0E .....
8170 13 C3 05 00 CD 05 00 B7 C9 0E 14 C3 F4 E4 11 CD .....
8180 EB C3 F9 E4 0E 15 C3 F4 E4 0E 16 C3 C3 E4 0E 17 .....
8190 C3 05 00 1E FF 0E 20 C3 05 00 CD 13 E5 87 87 87 .....
81A0 87 21 EF EB B6 32 04 00 C9 3A EF EB 32 04 00 C9 .!...2...:..2...
81B0 FE 61 D8 FE 7B D0 E6 5F C9 3A AB EB B7 CA 96 E5 .a...{..._...:.....
81C0 3A EF EB B7 3E 00 C4 BD E4 11 AC EB CD CB E4 CA :...>.....
81D0 96 E5 3A BB EB 3D 32 CC EB 11 AC EB CD F9 E4 C2 .....=2.....
81E0 96 E5 11 07 E4 21 80 00 06 80 CD 42 E8 21 BA EB .....!.....B.!...
81F0 36 00 23 35 11 AC EB CD DA E4 CA 96 E5 3A EF EB 6.#5.....:...
```

If no problem has been found, one last thing to check here is that side 1 is also readable (and returns different data). Here we will read the first directory sector of the drive. This requires changing the sysport value to select side 1. For model */84 and 10, the value should be DA. For */83, it should be 85. The sector number also changes to 0A.

```

: T FDRD 0A(CR)
00
: D8000 81FF(CR)
8000 00 4D 4F 56 43 50 4D 20 20 43 4F 4D 00 00 00 4C .MOVCPM COM...L
8010 02 03 04 05 06 00 00 00 00 00 00 00 00 00 00 .....
8020 00 50 49 50 20 20 20 20 20 43 4F 4D 00 00 00 3A .PIP COM...:
8030 07 08 09 0A 00 00 00 00 00 00 00 00 00 00 00 .....
8040 00 53 55 42 4D 49 54 20 20 43 4F 4D 00 00 00 0A .SUBMIT COM....
8050 0B 00 00 00 00 00 00 00 00 00 00 00 00 00 00 .....
8060 00 58 53 55 42 20 20 20 20 43 4F 4D 00 00 00 06 .XSUB COM....
8070 0C 00 00 00 00 00 00 00 00 00 00 00 00 00 00 .....
8080 00 45 44 20 20 20 20 20 20 43 4F 4D 00 00 00 34 .ED COM...4
8090 0D 0E 0F 10 00 00 00 00 00 00 00 00 00 00 00 .....
80A0 00 41 53 4D 20 20 20 20 20 43 4F 4D 00 00 00 40 .ASM COM...@
80B0 11 12 13 14 00 00 00 00 00 00 00 00 00 00 00 .....
80C0 00 44 44 54 20 20 20 20 20 43 4F 4D 00 00 00 26 .DDT COM...&
80D0 15 16 17 00 00 00 00 00 00 00 00 00 00 00 00 .....
80E0 00 53 54 41 54 20 20 20 20 43 4F 4D 00 00 00 29 .STAT COM... )
80F0 18 19 1A 00 00 00 00 00 00 00 00 00 00 00 00 .....
8100 00 53 59 53 47 45 4E 20 20 43 4F 4D 00 00 00 08 .SYSGEN COM....
8110 1B 00 00 00 00 00 00 00 00 00 00 00 00 00 00 .....
8120 00 44 55 4D 50 20 20 20 20 41 53 4D 00 00 00 21 .DUMP ASM...!
8130 1C 1D 1E 00 00 00 00 00 00 00 00 00 00 00 00 .....
8140 00 43 4F 50 59 20 20 20 20 43 4F 4D 00 00 00 3C .COPY COM...<
8150 1F 20 21 22 00 00 00 00 00 00 00 00 00 00 00 . !".....
8160 00 53 53 43 4F 50 59 20 20 43 4F 4D 00 00 00 3C .SSCOPY COM...<
8170 23 24 25 26 00 00 00 00 00 00 00 00 00 00 00 # $ % & .....
8180 00 54 45 52 4D 20 20 20 20 43 4F 4D 00 00 00 06 .TERM COM....
8190 27 00 00 00 00 00 00 00 00 00 00 00 00 00 00 ' .....
81A0 00 53 42 41 53 49 43 20 20 43 4F 4D 01 00 00 4C .SBASIC COM...L
81B0 28 29 2A 2B 2C 2D 2E 2F 30 31 32 33 34 00 00 00 ( ) * + , - . / 0 1 2 3 4 ...
81C0 00 4F 56 45 52 4C 41 59 42 43 4F 4D 00 00 00 36 .OVERLAYBCOM...6
81D0 35 36 37 38 00 00 00 00 00 00 00 00 00 00 00 5678.....
81E0 00 42 41 53 49 43 4C 49 42 52 45 4C 01 00 00 80 .BASICLIBREL....
81F0 39 3A 3B 3C 3D 3E 3F 40 41 42 43 44 45 46 47 48 9 : ; < = > ? @ A B C D E F G H

```

The exact data returned will depend on the contents of the directory, and may not contain any file names at all if the diskette is empty. But, the data should be different than the boot sector. Since sectors are numbered differently between side 0 and side 1, it should not be possible to read the wrong side (e.g. if the side-select signal were broken or shorted). The error from the FDRD command in that case would normally be 10 (record not found).

Failure to read media could be caused by many things, but perhaps the most common is a failure of the WD9216 data separator. If a drive is selected, motor on, and diskette inserted there should be a continuous stream of read data transmitted. It should be possible to probe along the read data path with an oscilloscope and perhaps determine where things are going wrong. A signal integrity problem may be more difficult to track down.

***** END OF CURRENT DOCUMENT *****

Harddisk Issues

Similar to the FDC tests, the output is a list of changes observed in the status register, along with the time reference (iterations) where change occurred. This is followed by the (final) contents of the error register. The initialization command (“N HDD”) performs the RESET function and then captures status register changes. The test command (“T HDD [cmd [limit]]”) issues the command (default is Self Test) and captures status register changes.

Note that this interface to the HDD does not differentiate between the A: and B: logical drives, it accesses the disk as one large image. Depending on the ROM version used to setup the system, the locations of the directories change. The primary boot sector is always at head 0, cylinder 0, sector 0.

The standard SDH (register/port 86H) value used by Kaypro is 101001hhhB, where “hhh” are the head select bits (e.g. A8H for head 0). The disk on Kaypro is always unit 1 (not 0).

The harddisk used by Kaypro has 306 cylinders, 4 heads, and 17 sectors per track, 512B sectors. Cylinder 305 is not used for data, as that is where the heads are parked when shutting down the system. Logical drive A: uses heads 0 and 1, logical drive B: uses heads 2 and 3. The logical order of tracks on drive A: is C0H0, C0H1, C1H0, ... and similarly for B:. The boot image is contained in C0H0.

With the 81-302 ROM, the CP/M directory for drive A: is in C2H0, C3H1, C4H0, C5H1 with the interleaving tracks serving as a mirror image of the directory (for possible recovery purposes). Similarly, drive B: directory is C2H2, C3H3, C4H2, C5H3. The data blocks of drive A: start at C6H0 and B: at C6H2. There is no mirroring of data blocks. The boot area is mirrored to C0H1.

With the 81-478 ROM, the CP/M directory for A: is in C7H0, C7H1, C8H0, C8H1 and for B: is in C7H2, C7H3, C8H2, C8H3. The directories (and boot area?) are not mirrored. There are spare tracks reserved between the boot area and the directories. The spares table (C0H0S16) also contains partitioning information.

HDD Testing

Here is an example of the commands needed to test reading of the first boot sector. This example is taken from a run on the Kaypro simulator, so the timings of the commands is not what would be seen on real hardware. This example is for a disk SYSGEN’ed with CP/M 2.2u (ROM 81-478).

```
: N HDD(CR)           (reset WD1002)
D0 0000
50 0003
01                    (normal error, Kaypro WD1002 has no floppy controller)
: 0 86 A8(CR)         (set SDH value for head 0)

: 0 82 01(CR)         (set sector count 1)

: 0 83 00(CR)         (set sector 0)
```

```

: 0 84 00(CR)      (set cylinder low 0)

: 0 85 00(CR)      (set cylinder high 0)

: T HDD 20(CR)      (issue READ command)
58 0000             (status bit 08 is DRQ)
00
: T HDRD(CR)        (load WD1002 data buffer into 8000H)
8200
: D 8000 81FF(CR)   (dump buffer, CP/M 2.2u boot sector)
8000 18 FE 00 D8 00 EE 37 00 00 00 00 00 00 00 00 00 .....7.....
8010 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 .....
8020 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 .....
8030 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 .....
8040 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 .....
8050 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 .....
8060 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 .....
8070 00 00 00 00 00 00 00 00 00 00 00 00 00 00 13 03 .....
8080 C3 5C DB C3 58 DB 7F 00 20 20 20 20 20 20 20 00 .\...X...
8090 20 4D 41 53 4D 45 4E 55 00 43 4F 50 59 52 49 47 MASMENU.COPYRIG
80A0 48 54 20 28 43 29 20 31 39 37 39 2C 20 44 49 47 HT (C) 1979, DIG
80B0 49 54 41 4C 20 52 45 53 45 41 52 43 48 20 00 00 ITAL RESEARCH ..
80C0 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 .....
80D0 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 .....
80E0 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 .....
80F0 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 .....
8100 00 00 00 00 00 00 00 00 00 08 D8 00 00 5F 0E 02 C3 ....._...
8110 05 00 C5 CD 8C D8 C1 C9 3E 0D CD 92 D8 3E 0A C3 .....>...>..
8120 92 D8 3E 20 C3 92 D8 C5 CD 98 D8 E1 7E B7 C8 23 ..> .....~...#
8130 E5 CD 8C D8 E1 C3 AC D8 0E 0D C3 05 00 5F 0E 0E ....._...
8140 C3 05 00 CD 05 00 32 EE DF 3C C9 0E 0F C3 C3 D8 .....2..<.....
8150 AF 32 ED DF 11 CD DF C3 3F EE 0E 10 C3 C3 D8 0E .2.....?.....
8160 11 C3 C3 D8 0E 12 C3 C3 D8 11 CD DF C3 DF D8 0E .....
8170 13 C3 05 00 CD 05 00 B7 C9 0E 14 C3 F4 D8 11 CD .....
8180 DF C3 F9 D8 0E 15 C3 F4 D8 0E 16 C3 C3 D8 0E 17 .....
8190 C3 05 00 1E FF 0E 20 C3 05 00 CD 13 D9 87 87 87 .....
81A0 87 21 EF DF B6 32 04 00 C9 3A EF DF 32 04 00 C9 .!...2....2...
81B0 FE 61 D8 FE 7B D0 E6 5F C9 3A AB DF B7 CA 96 D9 .a...{.._!.....
81C0 3A EF DF B7 3E 00 C4 BD D8 11 AC DF CD CB D8 CA :...>.....
81D0 96 D9 3A BB DF 3D 32 CC DF 11 AC DF CD F9 D8 C2 ...:=2.....
81E0 96 D9 11 07 D8 21 80 00 06 80 CD 42 DC 21 BA DF .....!.....B.!...
81F0 36 00 23 35 11 AC DF CD DA D8 CA 96 D9 3A EF DF 6.#5.....:..
:

```

SysPort Issues

Initializes the PIO channel A for use as the sysport, then alternately selects drive B and drive A.

```

: 0 1C 81(CR)      (make certain BANK stays on)

: 0 1D CF 08(CR)   (init and activate PIO ch A)

```

```

: 0 1C 82(CR)      (turn on drive B LED)
: 0 1C 81(CR)      (turn on drive A LED)
: 0 1C 80(CR)      (turn off both LEDs)

```

Display Issues

The CRT Controller chip, 6545 or sometimes 6845E, exists only on models */84 and 10. It powers-on and RESETs to a state where the video is disabled. The following commands may be used to initialize the core video functionality, and test for the “update” status (which is used to read/write the video RAM). The first command initializes the CRTC and enables video. After this command, the display should light up and be filled with random/garbage characters (whatever is in the video RAM after power-up). The second command runs a quick test to see if the video update status bit is working. In the case that it is not working, the command will hang. Pressing any key should abort and get back to the monitor prompt.

```

: N CRTC(CR)      (display should light up)
: T CRTC(CR)
wait... Update Update Update
:

```

An additional test is to check that vertical retrace is happening, and at about 50Hz. With the CRT initialized:

```

: T VRT(CR)
80 001C
A0 064B
80 06AF
A0 0CDE
80 0D42
A0 1371
80 13D5
A0 1A03
80 1A68
A0 2096
:

```

The VRT bit mask is 20 (hex), and we see that we get a pulse about every 0693H iterations (1683 decimal). At 12 uS per iteration, this computes to approximately 20 mS which is 50Hz.

Keyboard Issues

The keyboard uses SIO channel B on the same Z80-SIO chip as this monitor port is using, so that part is likely to also work. However, the keyboard itself may be tested by initializing the SIO port and running a test that will show the received codes for keys pressed on the keyboard. The keyboard initialization is slightly different for */83 models, so use the appropriate command syntax for the Kaypro model being tested. The Kaypro keyboard contains the “beep” functionality, which is activated

by sending a Ctrl-D character out to the keyboard. This can be tested using the Output command as shown in the example.

```
: N KB84(CR)      (initialize keyboard port on */84 and 10 models)
: T KBD(CR)       (start keyboard test, press keys on keyboard)
Wait... 61 73 64 66 77 65 65 72 F3 F4 (CR)Abort
: 0 05 04(CR)     (keyboard beeps)
:
```

Main Memory Issues

The memory test binary image may be downloaded here:

<http://sebhcdurgadas.com/kaypro/memtest.bin>

This image does not depend on RAM to operate (uses no stack or RAM variables) but it does use the serial port for progress (output) only. It does a memory test in the range 8000H-FFFFH and will alternate drive A and B LEDs (*/84 and 10 models) or cycle through '0' to '9' in the first character of the display (*/83 models). If a memory error is detected, it will flash the drive A LED or alternate 'E' and 'R' in the first character of the display (depending on the Kaypro model).

Serial port output begins with a signon message showing the test version. During the test, it will output the current "seed" value being run (00-99 BCD). If an error is encountered, it will print the error address, expected value, and actual value (and "Error").

The test method is to write a BCD value 00-99H to each memory location. The seed value dictates the value put in location 8000H, with each successive location receiving the previous value +1 (BCD). On each pass, the seed value is incremented (BCD).