Lec-3.1:Sublayers of Datalink Layer

Data Link Layer (Sub-layers)

Application Layer

Presentation Layer

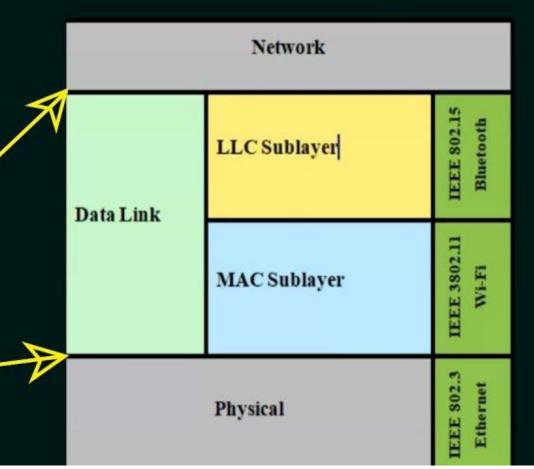
Session Layer

Transport Layer

Network Layer

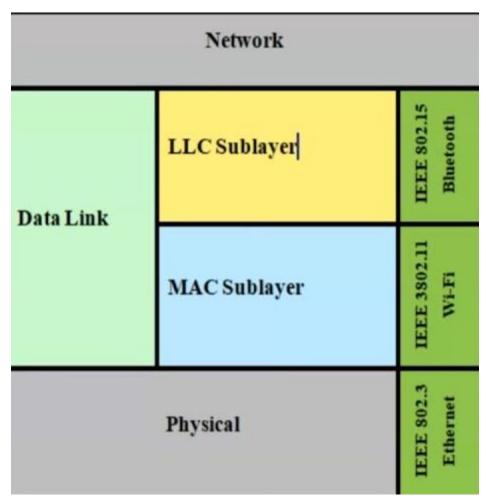
Data Link Layer

Physical Layer



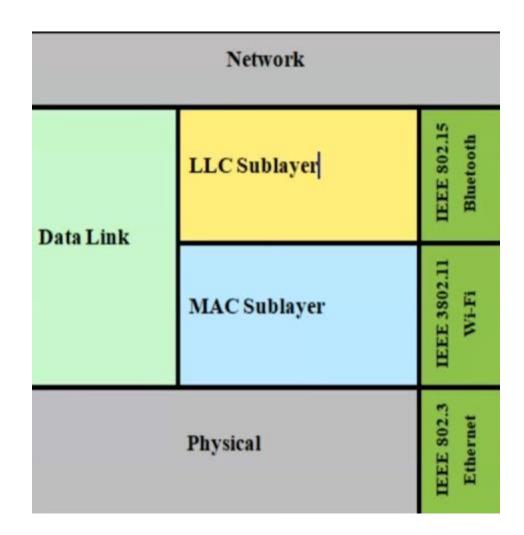
Logical Link Control (LLC) or Data Link Control (DLC)

- Handles communication between upper layer and lower layers
- Specific roles: Takes network protocol data and adds control information to help deliver packets to destination (flow control). Layer deals with the information of network layer.



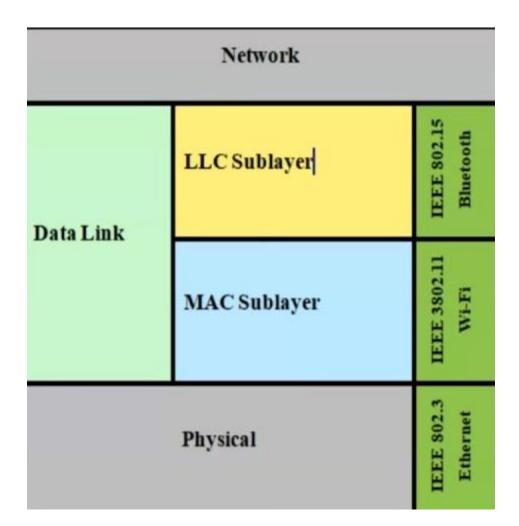
MAC Sublayer

- Constitutes lower sublayer of datalink layer
- Implemented by computer hardware, typically in the computer NIC (MAC address)
- Direct interactivity with physical layer
- Two responsibilities
 - Data Encapsulation: frame assemble before transmission and disassembly upon reception
 - Adds header and trailer information to the network layer PDU
 - Media Access Control
- Three primary functions
 - i. Framing
 - ii. Physical Addressing
 - iii. Error Control



MAC Sublayer

- Upon creation of frame MAC sublayer responsible for placement and removal of frames information on and from media
- Communicates directly to physical layer

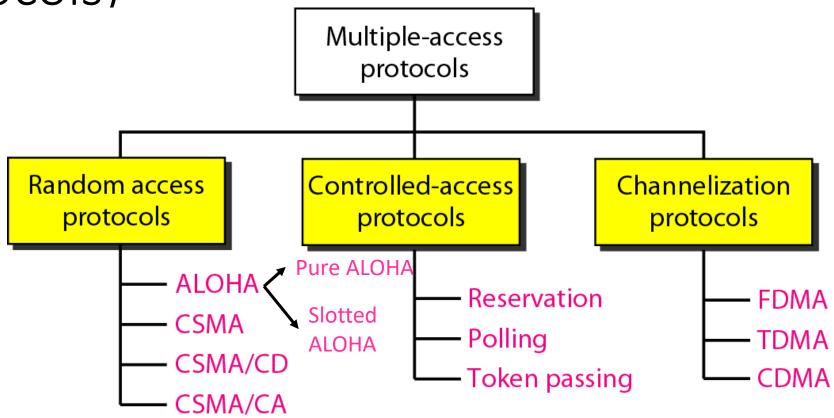


Complete the following task

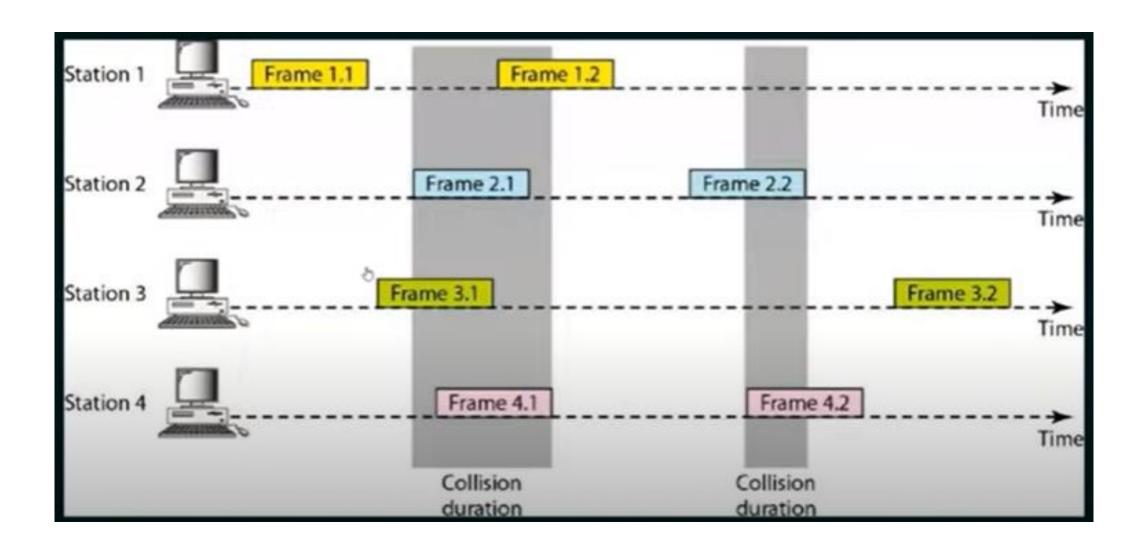
Service	Sublayer
Flow Control	
Framing	
Physical Addressing	
Error Control	
Access Control	

Service	Sublayer
Flow Control	LLC or DLC
Framing	MAC
Physical Addressing	MAC
Error Control	MAC
Access Control	MAC

Multiple Access Control Protocol (MAC Protocols)

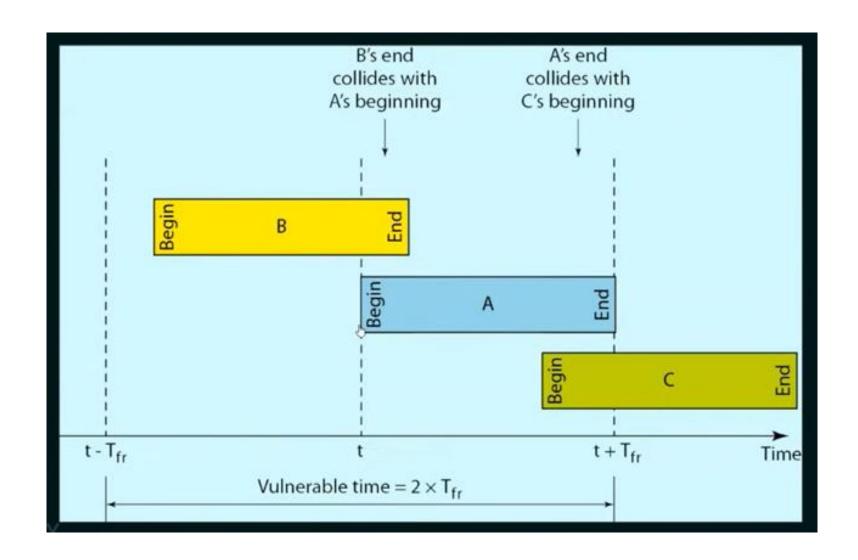


- Random Access Protocol
- Acknowledgement is there
- LAN based
- Only transmission time
- No propagation time
- Vulnerable time, $V_t = 2*T_t$
- Efficiency, $\eta = G^*e^{-2G}$



- Pure ALOHA allows stations to transmit whenever they have data to be sent.
- ★ When a station sends data it waits for an acknowledgement.
- ★ If the acknowledgement doesn't come within the allotted time then the station waits for a random amount of time called back-off time (Tb) and re-sends the data.
- ★ Since different stations wait for different amount of time, the probability of further collision decreases.
- The throughput of pure aloha is maximized when frames are of uniform length.

- ★ Whenever two frames try to occupy the channel at the same time, there will be a collision and both will be garbled.
- ★ If the first bit of a new frame overlaps with just the last bit of a frame almost finished, both frames will be totally destroyed and both will have to be retransmitted later.



- ★ Whenever two frames try to occupy the channel at the same time, there will be a collision and both will be garbled.
- ★ If the first bit of a new frame overlaps with just the last bit of a frame almost finished, both frames will be totally destroyed and both will have to be retransmitted later.

Vulnerable Time = 2^*T_f Throughput = $G \times e^{-2G}$; Where G is the number of stations wish to transmit in the same time.

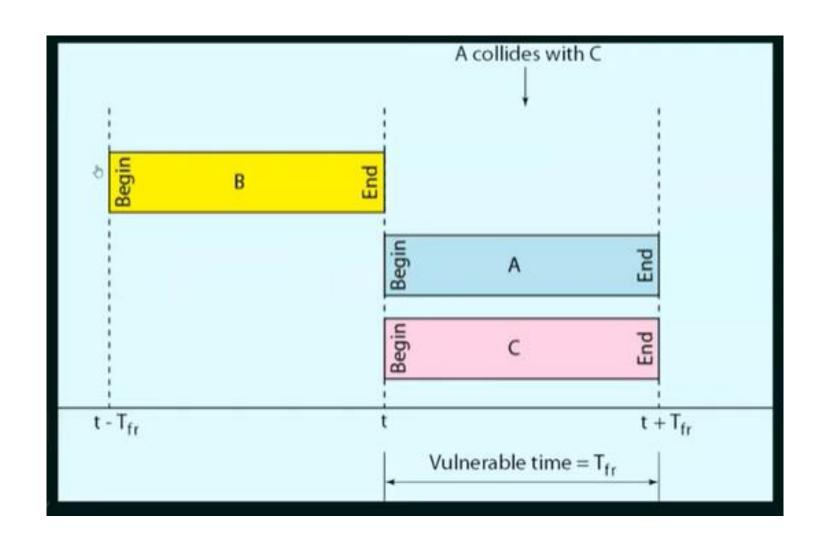
Maximum throughput = 0.184 for G=0.5 (1/2)

Slotted ALOHA

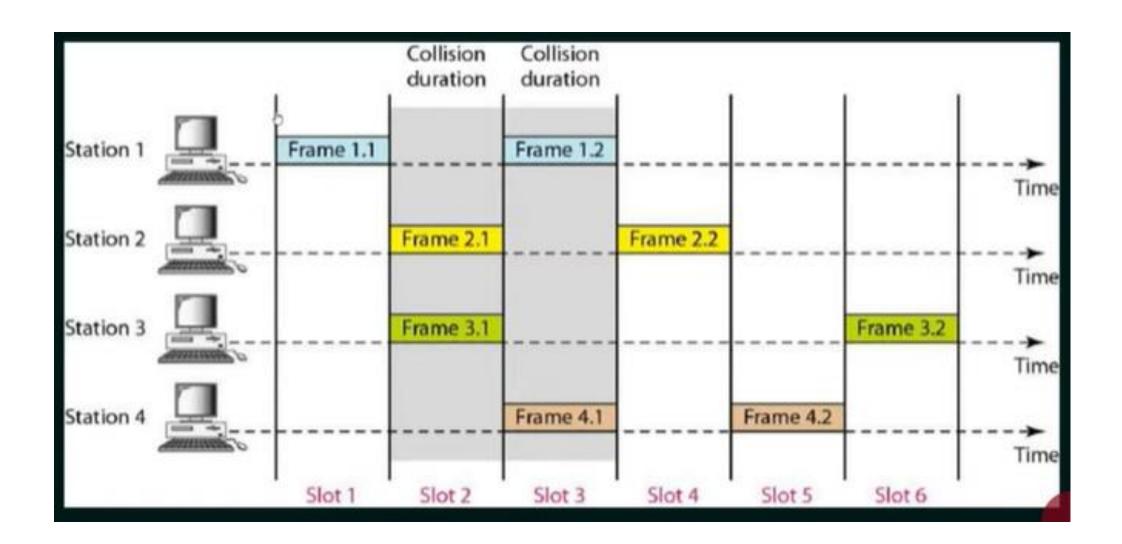
- ★ It was developed just to improve the efficiency of pure aloha as the chances for collision in pure aloha are high.
- ★ The time of the shared channel is divided into discrete time intervals called slots.
- ★ Sending of data is allowed only at the beginning of these slots.
- ★ If a station misses out the allowed time, it must wait for the next slot.

 This reduces the probability of collision.

Slotted ALOHA



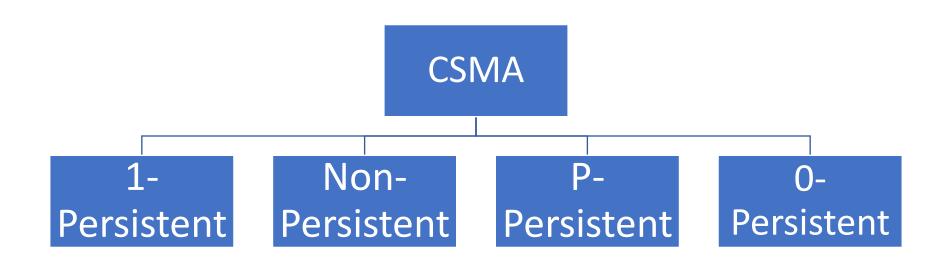
Slotted ALOHA



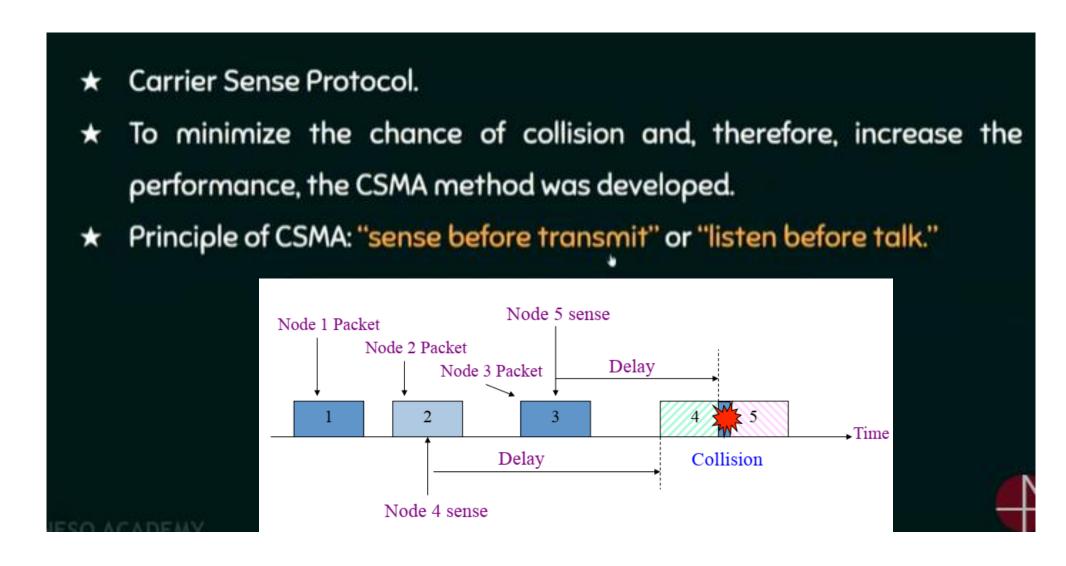
Pure ALOHA vs. Slotted ALOHA

Pure Aloha	Slotted Aloha		
Any station can transmit the data at any time.	Any station can transmit the data at the beginning of any time slot.		
The time is continuous and not globally synchronized.	The time is discrete and globally synchronized.		
Vulnerable time in which collision may occur = 2 x T _{Fr}	Vulnerable time in which collision may occur = T _{Fr}		
Probability of successful transmission of data packet= G x e ^{-2G}	Probability of successful transmission of data ρ acket= $G \times e^{-G}$		
Maximum efficiency = 18.4% (Occurs at G = 1/2)	Maximum efficiency = 36.8% (Occurs at G = 1)		
Main advantage: Simplicity in implementation.	Main advantage: It reduces the number of collisions to half and doubles the efficiency of pure aloha.		

Carrier Sense Multiple Access (CSMA)



Carrier Sense Multiple Access (CSMA)

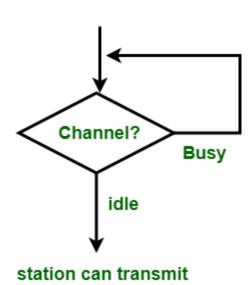


Carrier Sense Multiple Access (CSMA)

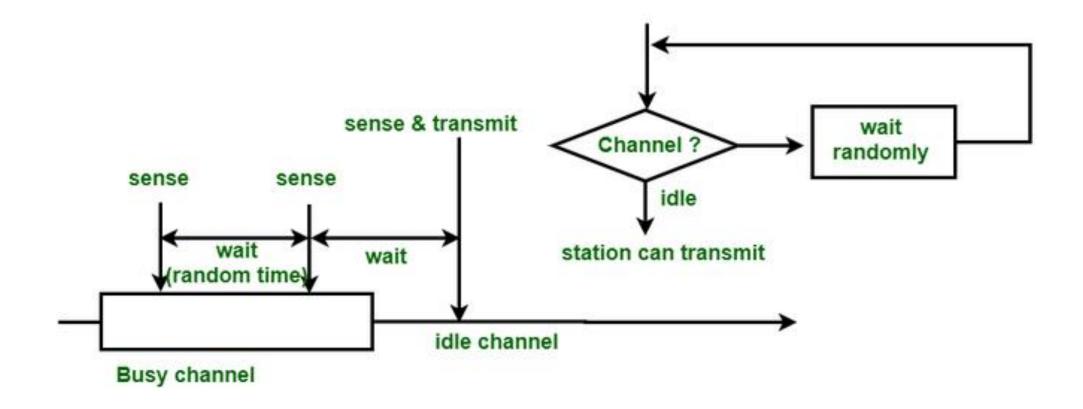
- ★ Carrier Sense Protocol.
- ★ To minimize the chance of collision and, therefore, increase the performance, the CSMA method was developed.
- ★ Principle of CSMA: "sense before transmit" or "listen before talk."
- ★ Carrier busy = Transmission is taking place.
- ★ Carrier idle = No transmission currently taking place.
- The possibility of collision still exists because of propagation delay; a station may sense the medium and find it idle, only because the first bit sent by another station has not yet been received.

1-Persistent CSMA

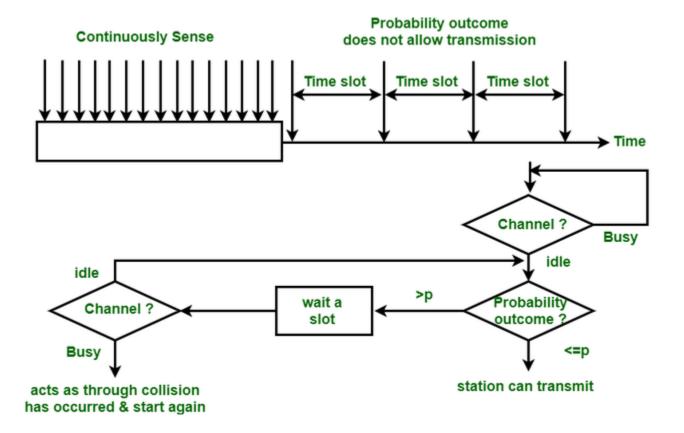
Continously sense Time Busy channel



Non-Persistent CSMA

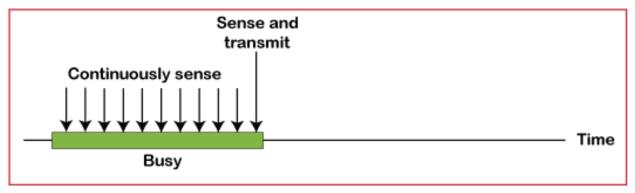


P-Persistent CSMA

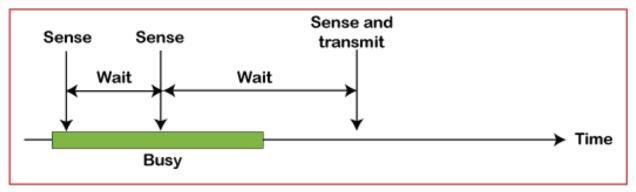


- Each node senses the channel, and if the channel is inactive, it sends a frame with a P probability
- If the data is not transmitted, it waits for a (q = 1-p probability) random time and resumes the frame with the next time slot

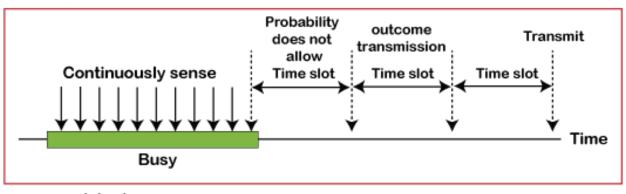
Behavior of Three Persistent Methods



a. 1-persistent



b. Nonpersistent



c. p-persistent

Difference between 1-persistent, P-persistent and Non-

persistent CSMA :				
Parameter	1-persistent CSMA	p-persistent CSMA	Non-persistent CSMA	
Carrier Sense	It sends with the probability of 1 when channel is idle.	It sends with the probability of p when channel is idle.	It send when channel is idle.	

probability p.

idle.

It waits for the next time slot.

Less chances as compared to 1-

persistence and non-persistence.

It's utilization is depend upon the

It is large when p is small as station

It is large when the probability p of

and channel is rarely idle.

sending is small when channel is idle

will not always send when channel is

It will wait for the random amount of time

Less chances as compared to 1-persistence

It's utilization is above 1-persistent as not

but more than the p-persistence.

all the stations constantly check the

It is small as station will send whenever

channel is found idle but longer than 1-

persistent since it checks for the random

It is longer than 1-persistent as channel is

checked randomly when busy.

channel at the same time.

time when busy.

to check the carrier.

It continuously senses the channel or

There is highest chances of collision

It's utilization is above ALOHA as

It is low as frames are sent when the

frames are only sent when the

carrier.

in this.

channel is idle.

channel become idle.

It is high due to collision.

Waiting

Utilization

Delay Low Load

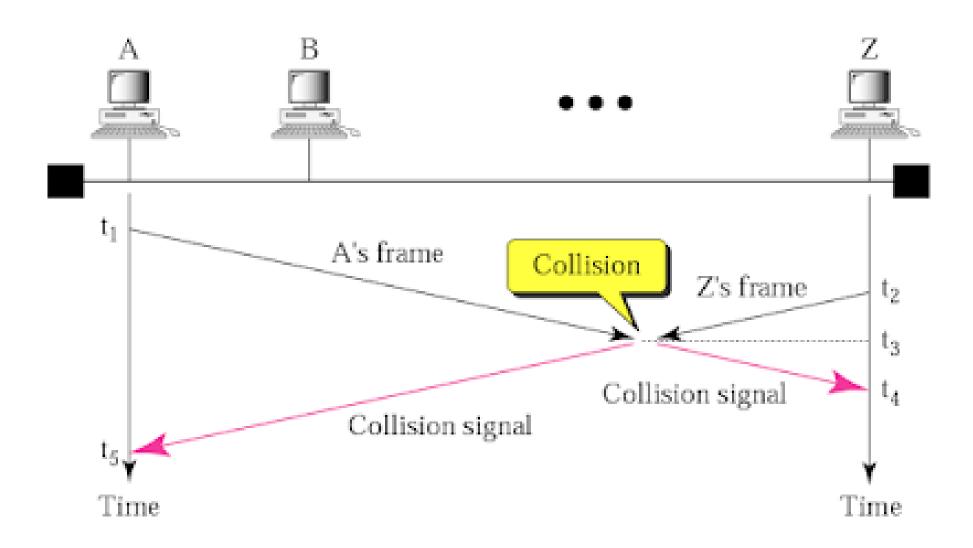
Delay High Load

Chances of Collision

Modified version of CSMA

- 1. CSMA/CD
- 2. CSMA/CA

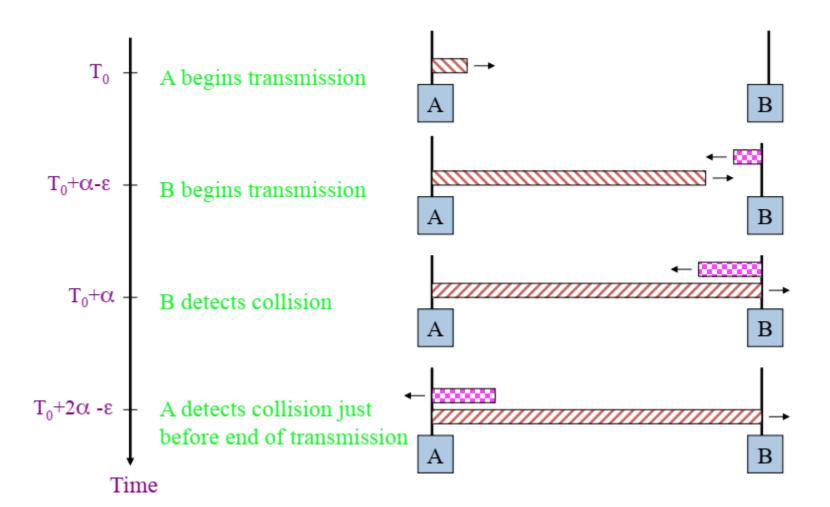
- i. Every station has an equal right on the medium.
- ii. Every station senses the medium before sending a frame and if the medium is idle only then the station sends the frame.
- iii. It may happen, that two stations senses the medium at a time and find it idle and send frame. This time a collision will occur. That's why the protocol forces the stations to sense the medium even after the sending has begun and the stations are able to sense the collision. After sensing the collision the stations send a jam signal which destroys the frames on the line and the stations wait for some random amount of time and re-send their frames avoiding the collision.



Procedure

- Listen to medium and wait until it is free
- Then start talking, but listen to see if someone else starts talking too
- If a collision occurs, stop and then start talking after a random back off time
- This scheme is used for hub based Ethernet
- Advantages
 - More efficient than basic CSMA
- Disadvantages
 - Requires ability to detect collisions

- In CSMA, if 2 terminals begin sending packet at the sa me time, each will transmit its complete packet (although collision is taking place).
- Wasting medium for an entire packet time.
- CSMA/CD
 - Step 1: If the medium is idle, transmit
 - Step 2: If the medium is busy, continue to listen until the channel is idle then transmit
 - Step 3: If a collision is detected during transmission, cease transmitting
 - Step 4: Wait a random amount of time and repeats the same algorithm



Transmission time, $T_t > 2*T_p$ $T_t = L/B$ Transmission time, $L/B \ge 2*$ T_p Message length, $L \ge B*2*T_p$

So, in order to detect a collision, the minimum size of the packet should be 2*Tp*B

CSMA/CA(WLAN i.e IEEE 802.11 wi-fi)

- ★ Carrier-sense multiple access with collision avoidance (CSMA/CA) is a network multiple access method in which carrier sensing is used, but nodes attempt to avoid collisions by beginning transmission only after the channel is sensed to be "idle".
- ★ It is particularly important for wireless networks, where the collision detection of the alternative CSMA/CD is not possible due to wireless transmitters desensing their receivers during packet transmission.
- ★ CSMA/CA is unreliable due to the hidden node problem and exposed terminal problem.
- ★ Solution: RTS/CTS exchange.

CSMA/CA(WLAN i.e IEEE 802.11 wi-fi)

Procedure

- Similar to CSMA but instead of sending packets control frames are exchanged
- RTS = request to send
- CTS = clear to send
- DATA = actual packet
- ACK = acknowledgement



• IFS – Interframe Space

 DCF – Distributed Coordination Function

DIFS

Collision

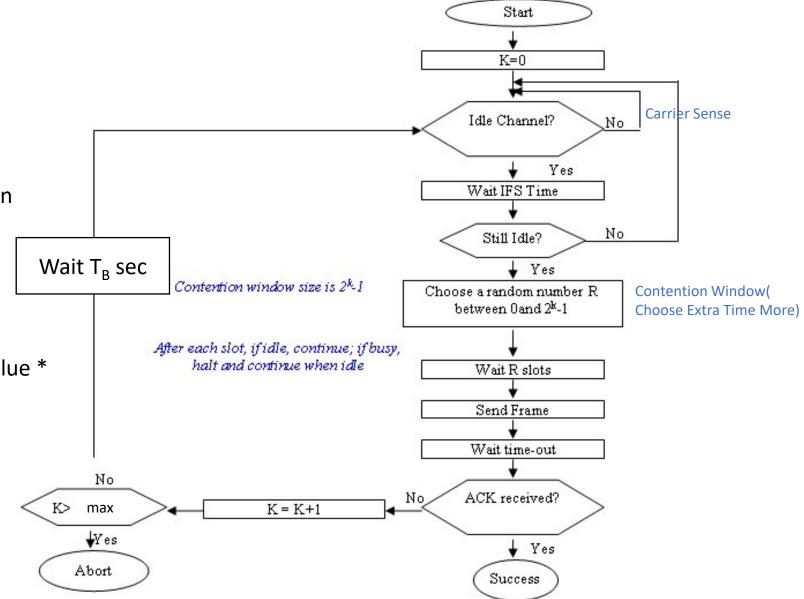
ACK

• K = no. of attempts

 T_B = Backoff Time (Random value * Slot time)

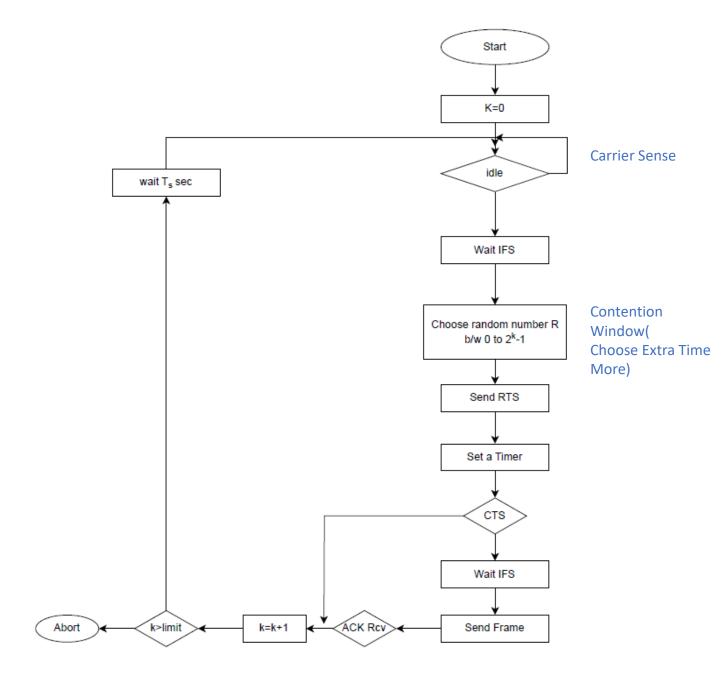
RTS = Ready to Send

CTS = Clear To Send

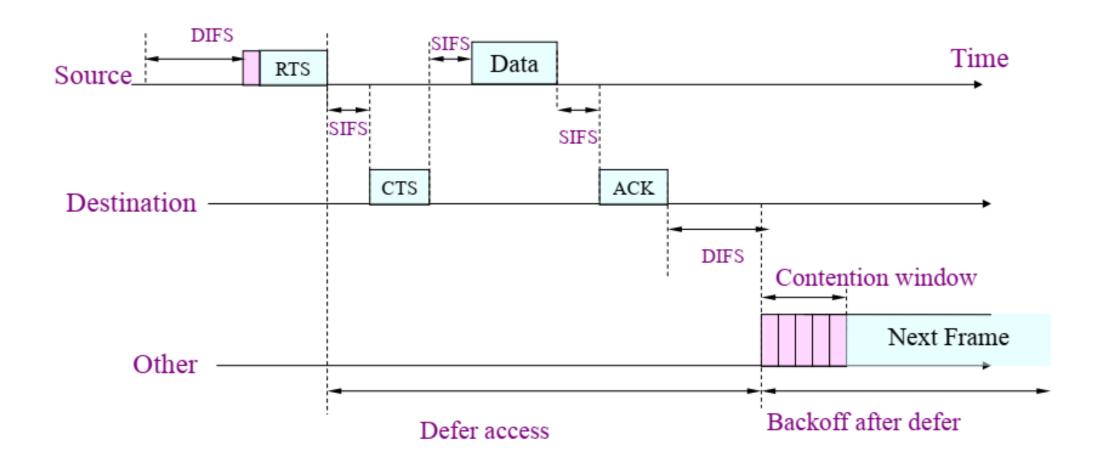


CSMA/CA

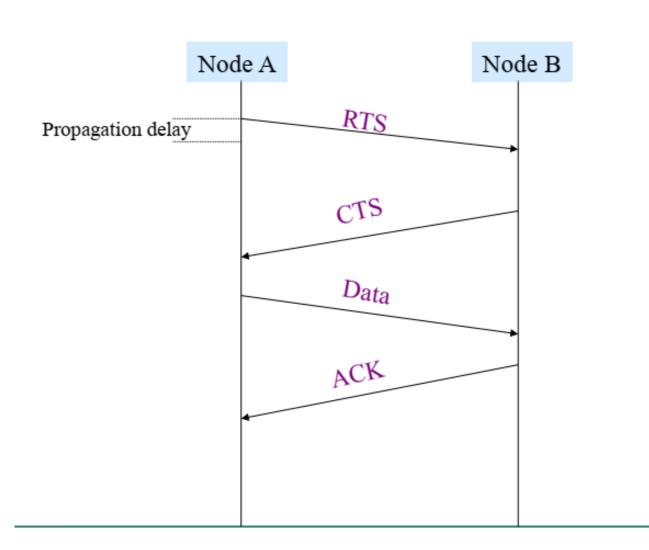
- IFS Interframe Space
- DCF Distributed Coordination Function
- DIFS
- Collision
- ACK
- K = no. of attempts
- T_B = Backoff Time (Random value * Slot time)
- RTS = Ready to Send
- CTS = Clear To Send



CSMA/CA with RTS/CTS



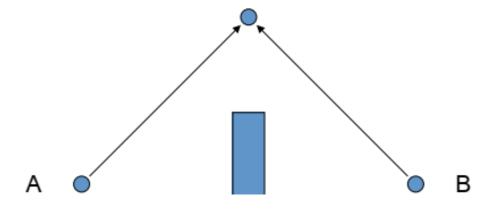
CSMA/CA with RTS/CTS



CSMA/CA(WLAN i.e IEEE 802.11 wi-fi)

Advantages

- Small control frames lessen the cost of collisions (when data is large)
- RTS + CTS provide "virtual" carrier sense which protects against hidden terminal collisions (where A can't hear B)



CSMA/CA(WLAN i.e IEEE 802.11 wi-fi)

- 1. Sometime CSMA/CA takes much waiting time as usual to transmit the data packet.
- 2.It consumes more bandwidth by each station.
- 3.Its efficiency is less than a CSMA CD.

Differences between ALOHA, CSMA/CD, and CSMA/CA

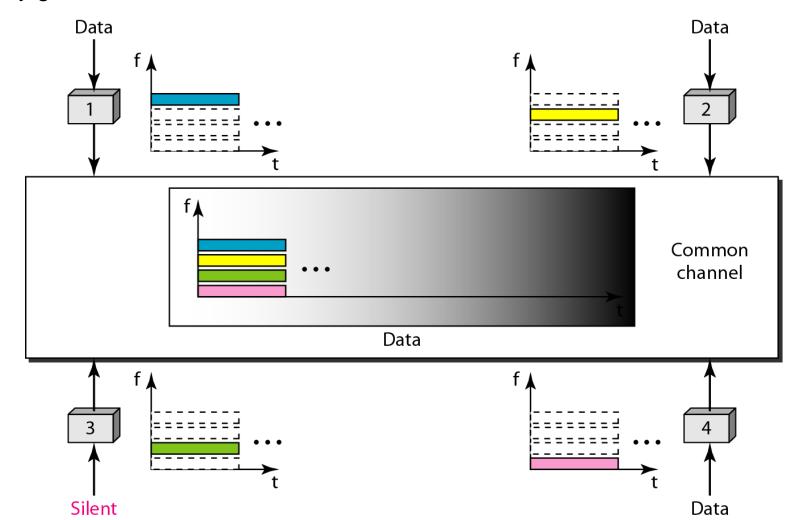
Protocol	Transmission behavior	Collision detection method	Efficiency	Use cases
Pure ALOHA	Sends frames immediately	No collision detection	Low	Low-traffic networks
Slotted ALOHA	Sends frames at specific time slots	No collision detection	Better than pure ALOHA	Low-traffic networks
CSMA/CD	Monitors medium after sending a frame, retransmits if necessary	Collision detection by monitoring transmissions	High	Wired networks with moderate to high traffic
CSMA/CA	Monitors medium while transmitting, adjusts behavior to avoid collisions	Collision avoidance through random backoff time intervals	High	Wireless networks with moderate to high traffic and high error rates

Channelization

 Channelization is a multiple-access method in which the available bandwidth of a link is shared in time, frequency, or through code, between different stations.

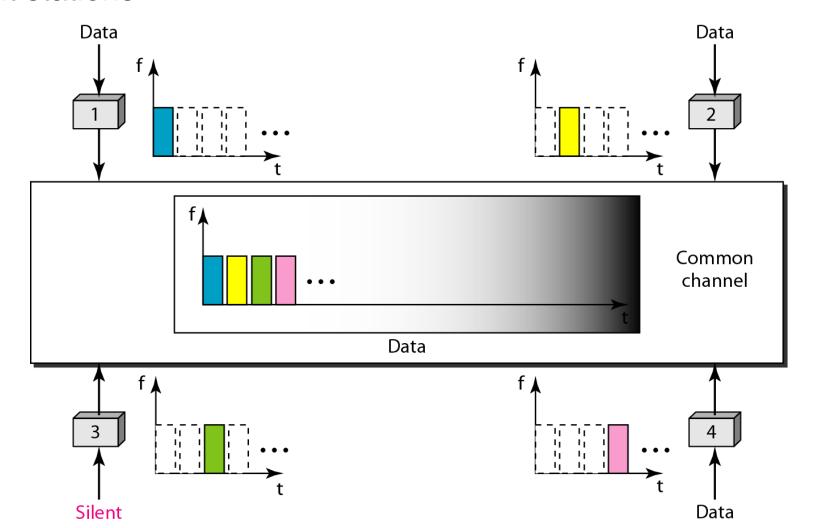
Frequency Division Multiple Access (FDMA)

 In FDMA, the available bandwidth of the common channel is divided into bands that are separated by guard bands.



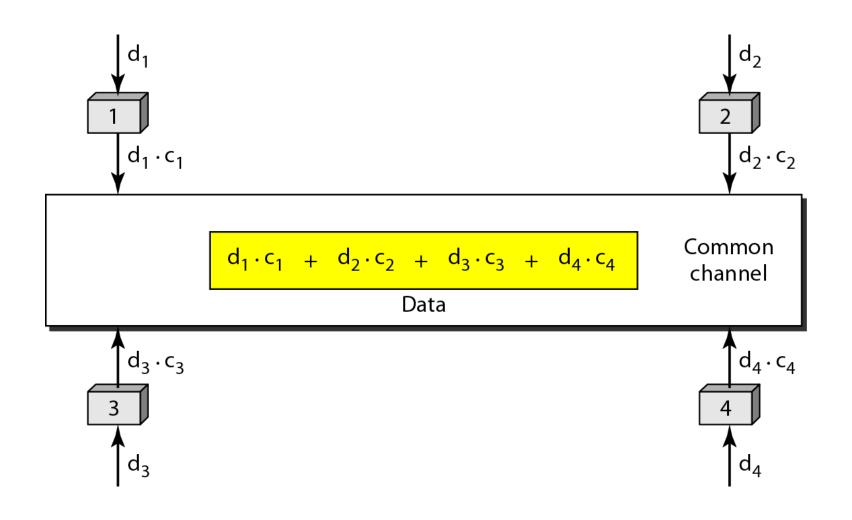
Time Division Multiple Access (TDMA)

In TDMA, the bandwidth is just one channel that is timeshared between different stations.

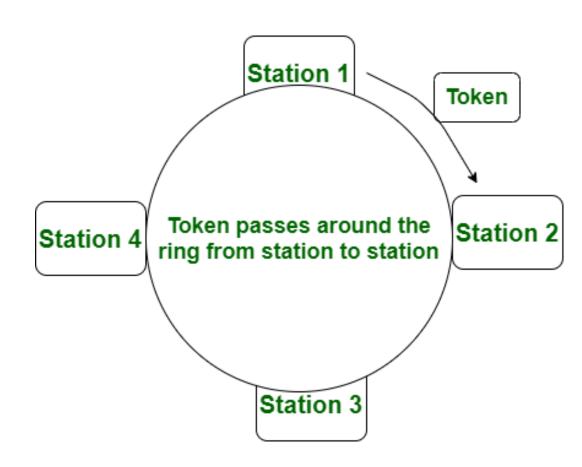


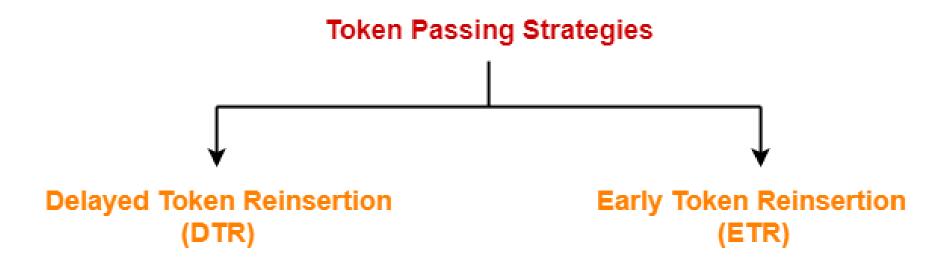
Code Division Multiple Access (CDMA)

In CDMA, one channel carries all transmissions simultaneously.



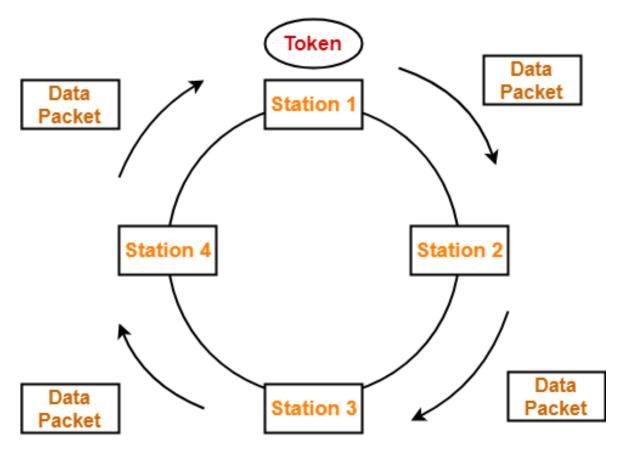
- 1) Ring Topology is used
- Access control method used is token passing
- 3) Token ring is unidirectional (simplex)
- 4) Data rate used is 4Mbps & 16Mbps
- 5) Piggybacking (send ack along with packets) acknowledgement is used
- 6) Differential Manchester encoding is used
- 7) Variable size framing





After a station acquires the token,

- i. It transmits its data packet.
- ii. It holds the token until the data packet reaches back to it.
- iii. After data packet reaches to it, it discards its data packet as its journey is completed.
- iv. It releases the token.



Delayed Token Reinsertion Token Passing

➤ Station releases the token immediately after putting its data packet to be transmitted on the ring.

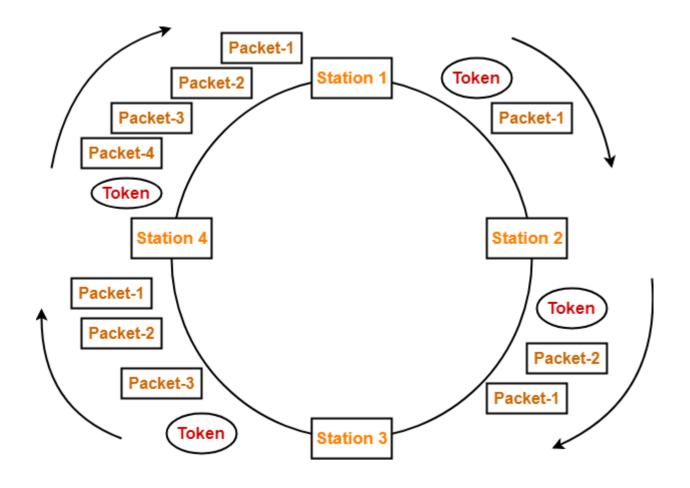
Step-01: At Station-1: Step-02: At Station-2:

Station-1

- Acquires the token
- Transmits packet-1
- Releases the token

Station-2

- Receives packet-1
- Transmits packet-1
- Acquires the token
- Transmits packet-2
- Releases the token



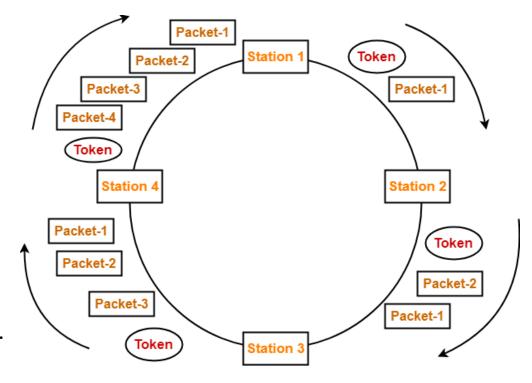
Early Token Reinsertion

Step-03: At Station-3: Step-05: At Station-1:

- Receives packet-1
- Transmits packet-1
- Receives packet-2
- Transmits packet-2
- Acquires the token
- Transmits packet-3
- Releases the token
- Step-04: At Station-4:
- Receives packet-1
- Transmits packet-1
- Receives packet-2
- Transmits packet-2
- Receives packet-3
- Transmits packet-3
- Acquires the token
- Transmits packet-4
- Releases the token

- Receives packet-1
- Discards packet-1 (as its journey is completed)
- Receives packet-2
- Transmits packet-2
- Receives packet-3
- Transmits packet-3
- Receives packet-4
- Transmits packet-4
- Acquires the token
- Transmits packet-1 (new)
- Releases the token

In this manner, the cycle continues.



Early Token Reinsertion

Data Frame

SFD	AC	FC	DA	SA	Data	CRC	ED	FS
1	1	1	6	6	>= 0	1	1	1

- i. SFD = Start Frame Delimiter
- ii. AC = Access Control
- iii. FC = Frame Control
- iv. DA = Destination Address
- v. SA = Source Address
- vi. Data \geq up to Token Holding Time (TH_t)
- vii. CRC = Cyclic Redundancy Check
- viii. ED = End Delimiter
- ix. FS = Frame Status

Token Frame

SFD	AC	ED
1	1	1