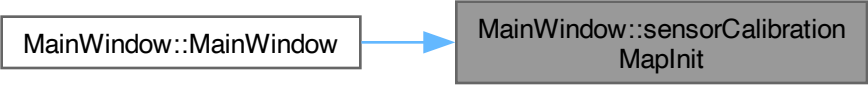


MainWindow::MainWindow



```
graph LR; A[MainWindow::MainWindow] --> B[MainWindow::sensorCalibrationMapInit]
```

The diagram consists of two rectangular boxes connected by a blue arrow pointing from left to right. The left box is white with a black border and contains the text 'MainWindow::MainWindow'. The right box is gray with a black border and contains the text 'MainWindow::sensorCalibrationMapInit' on two lines. The arrow is a solid blue line with a triangular head pointing towards the right box.

MainWindow::sensorCalibration
MapInit