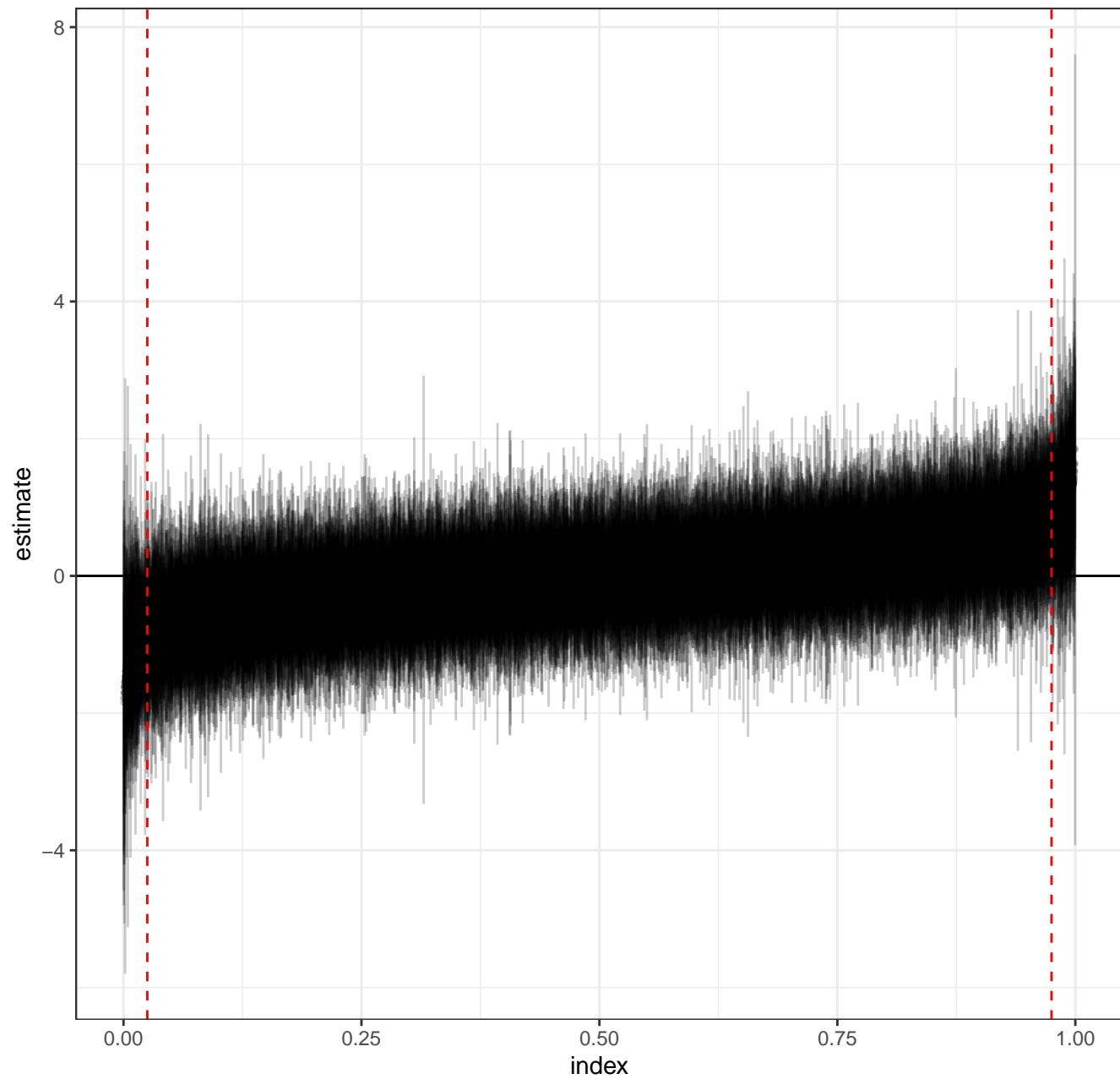
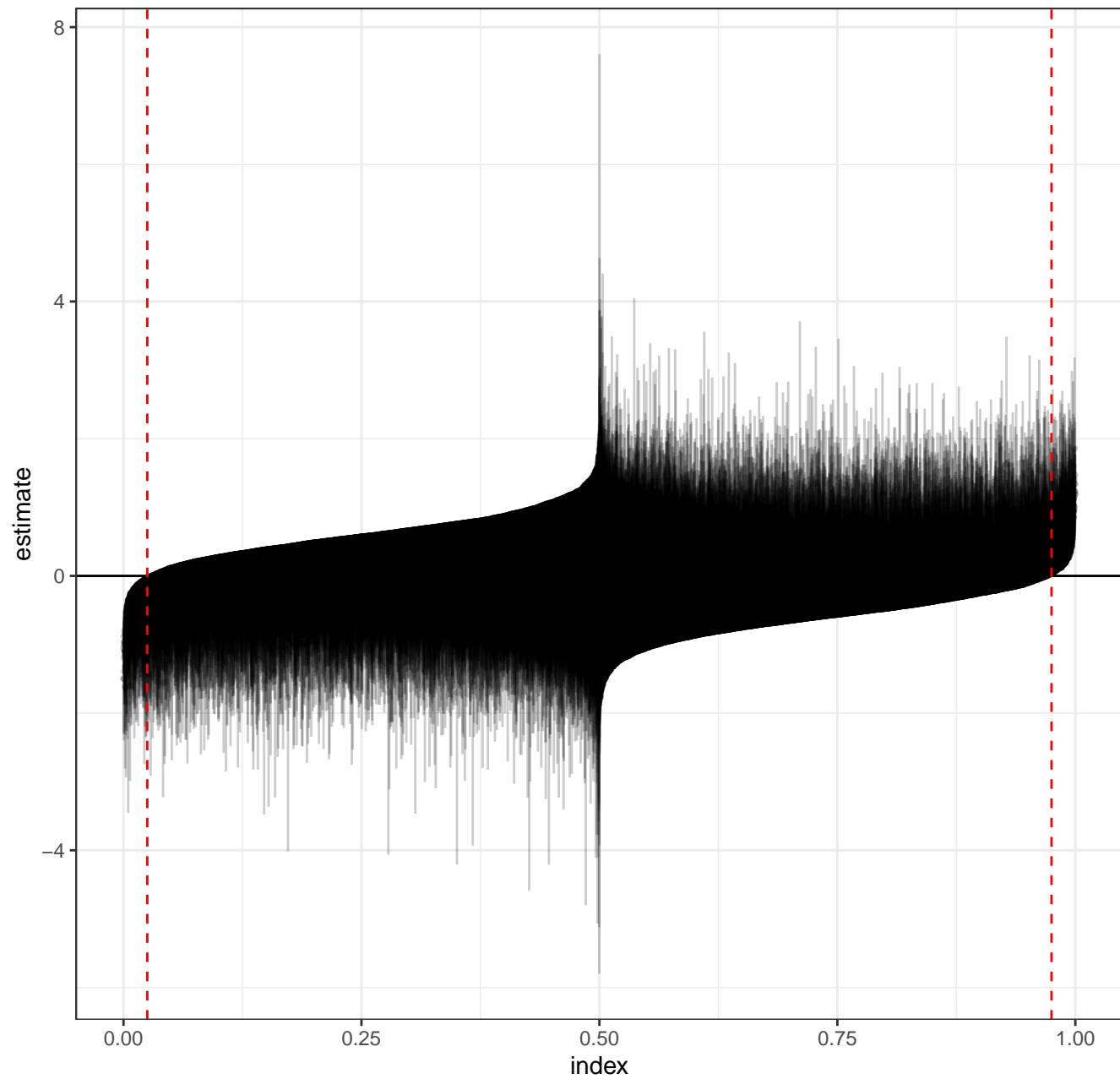


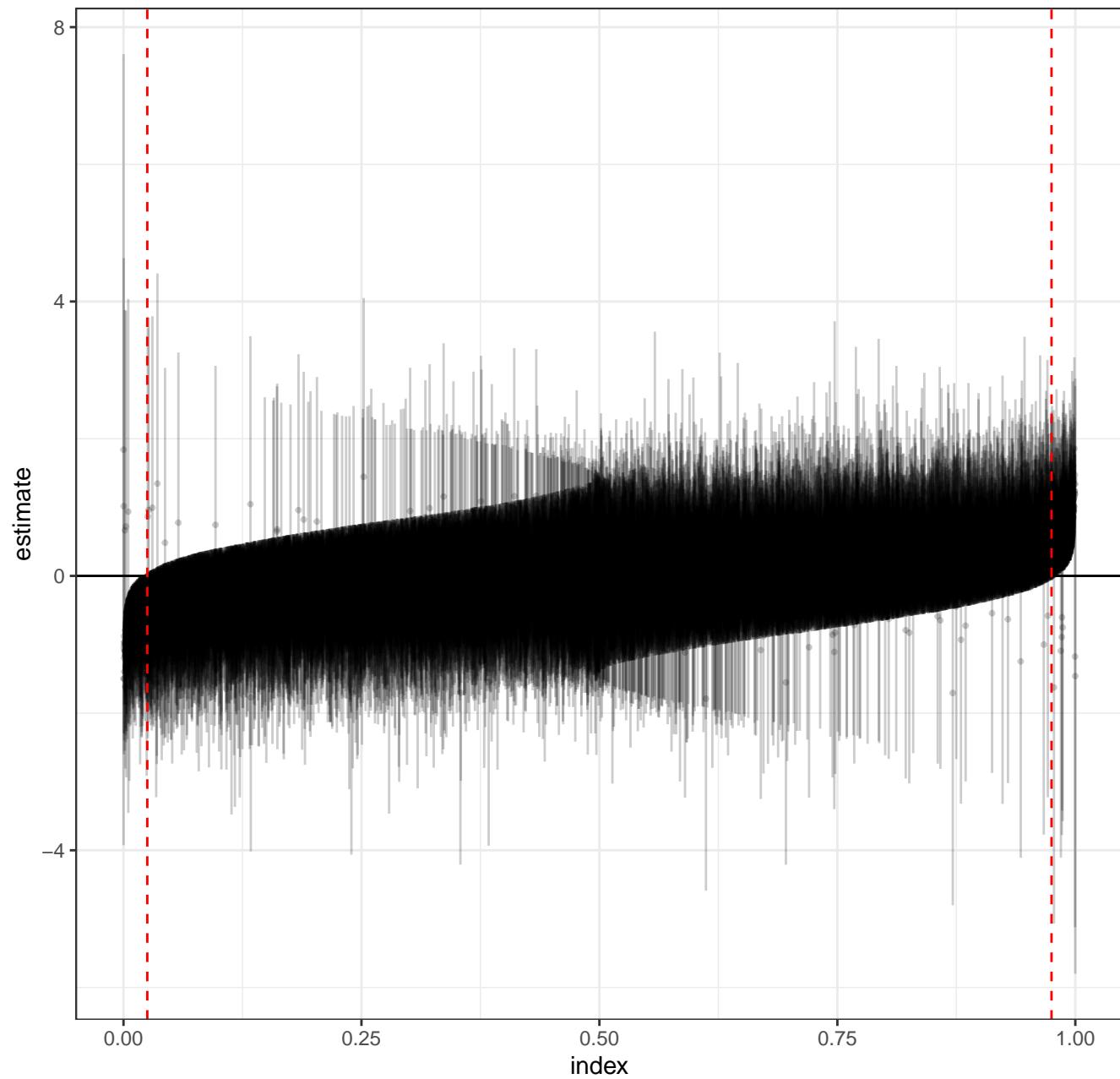
$t_6$



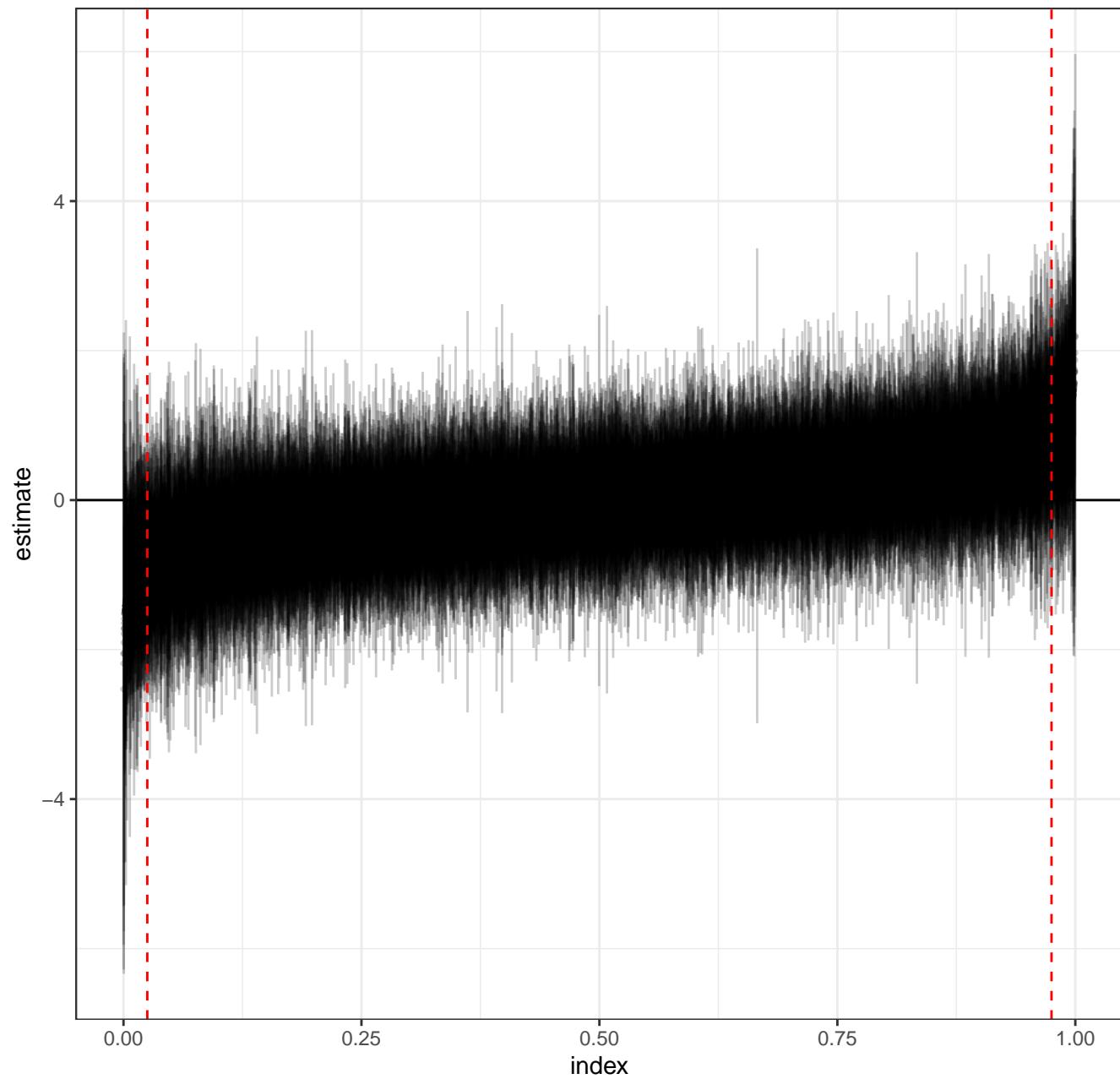
$t_6$



$t_6$

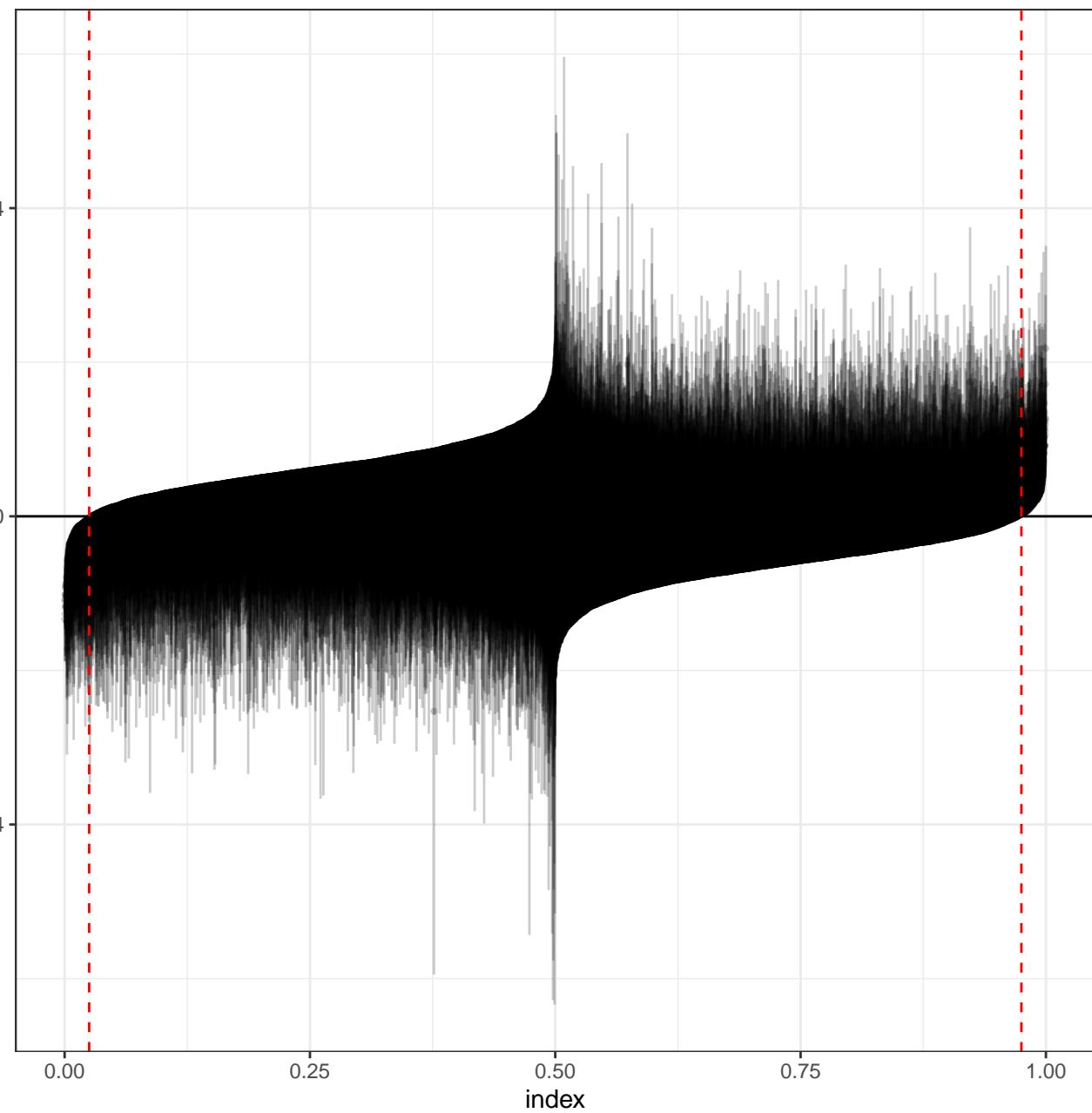


$t_5$

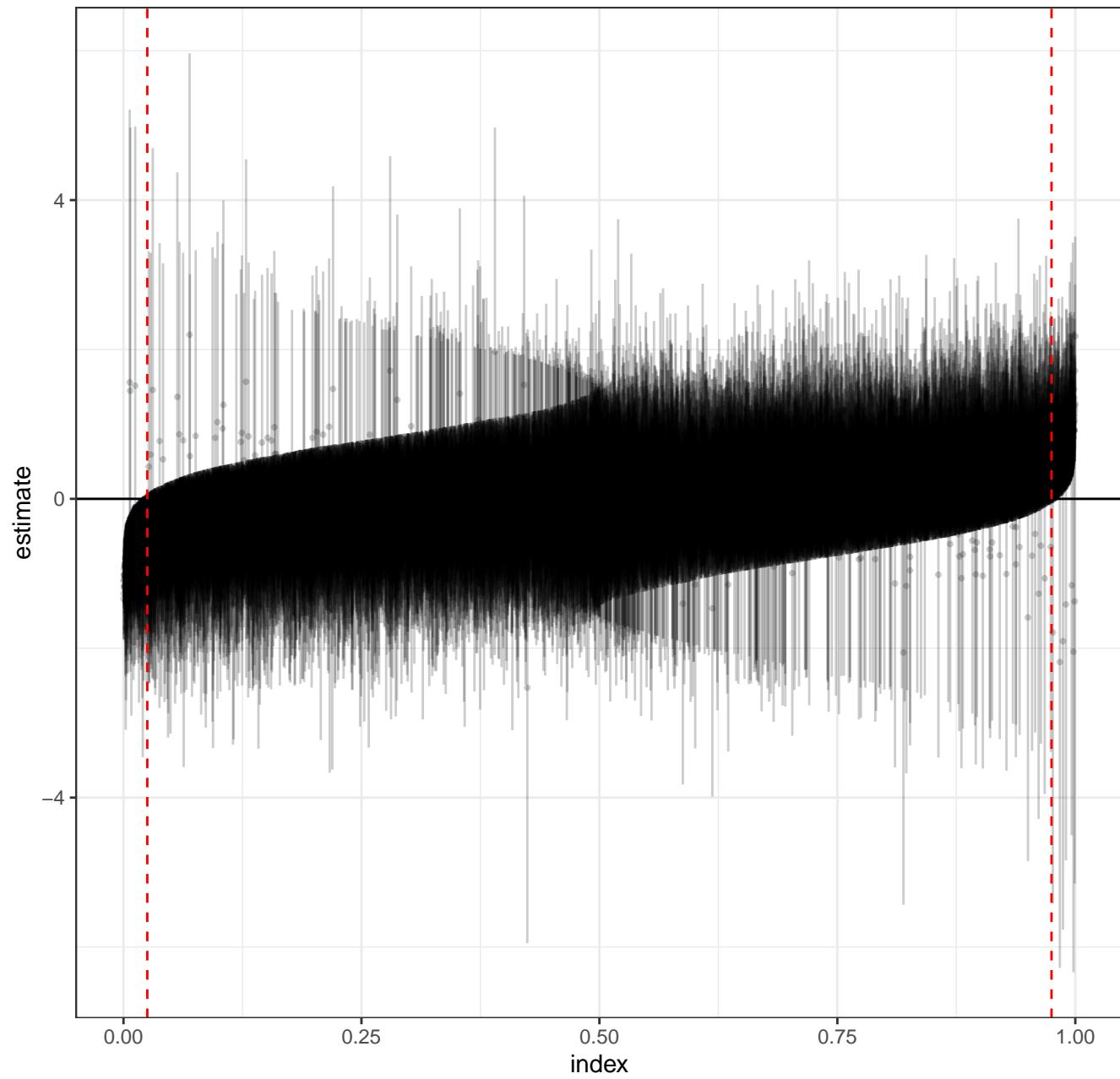


$t_5$

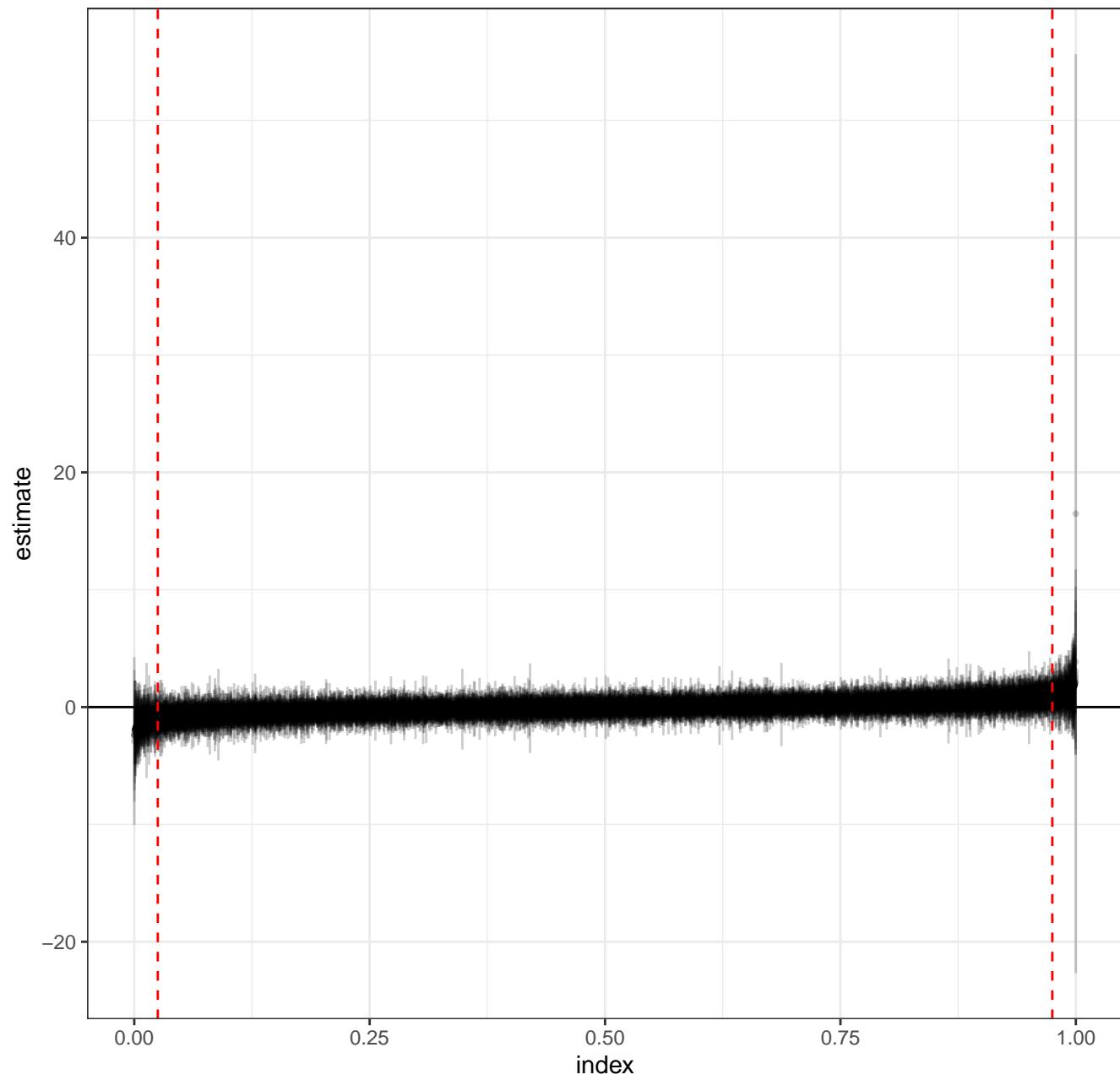
estimate



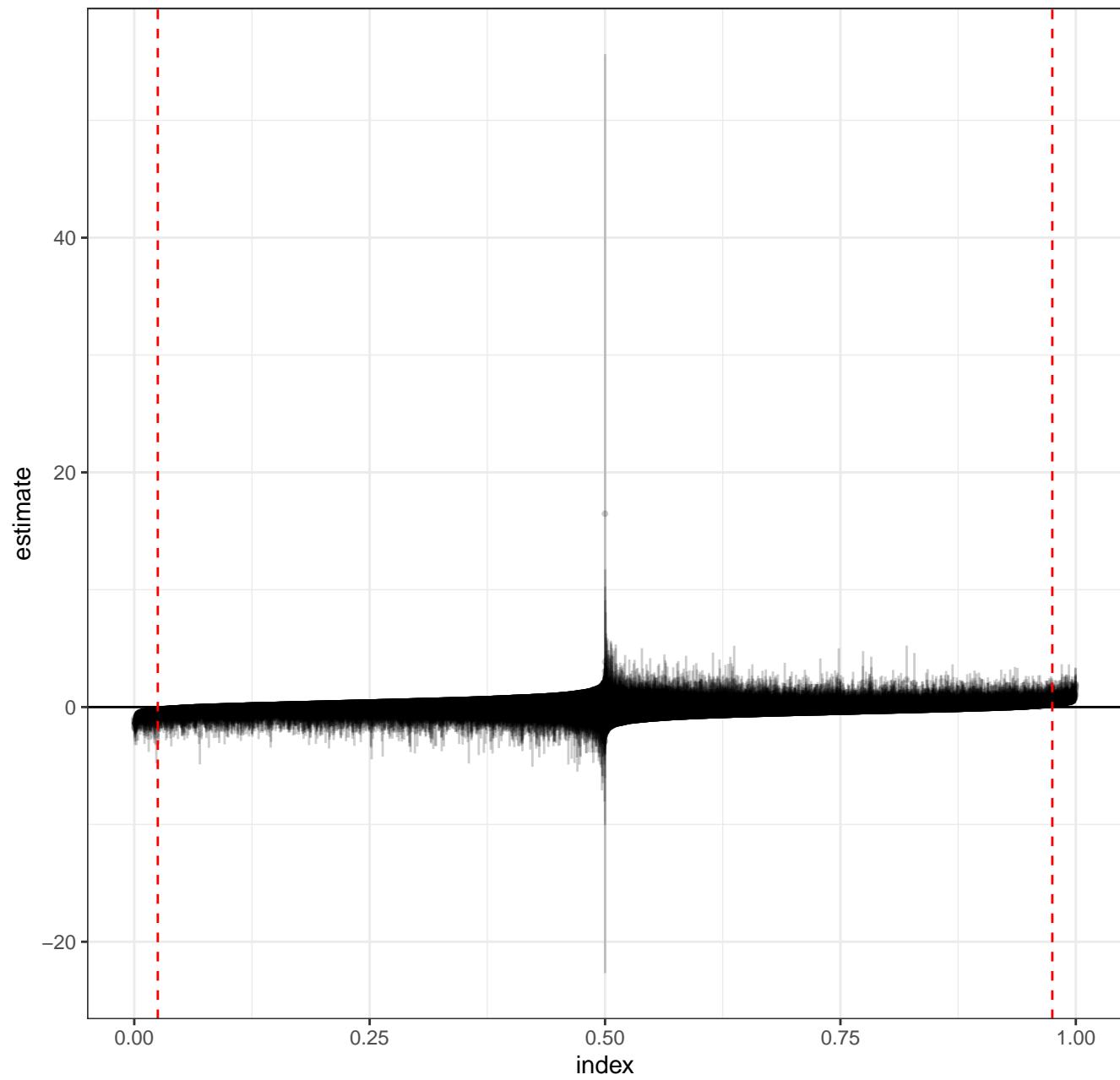
$t_5$



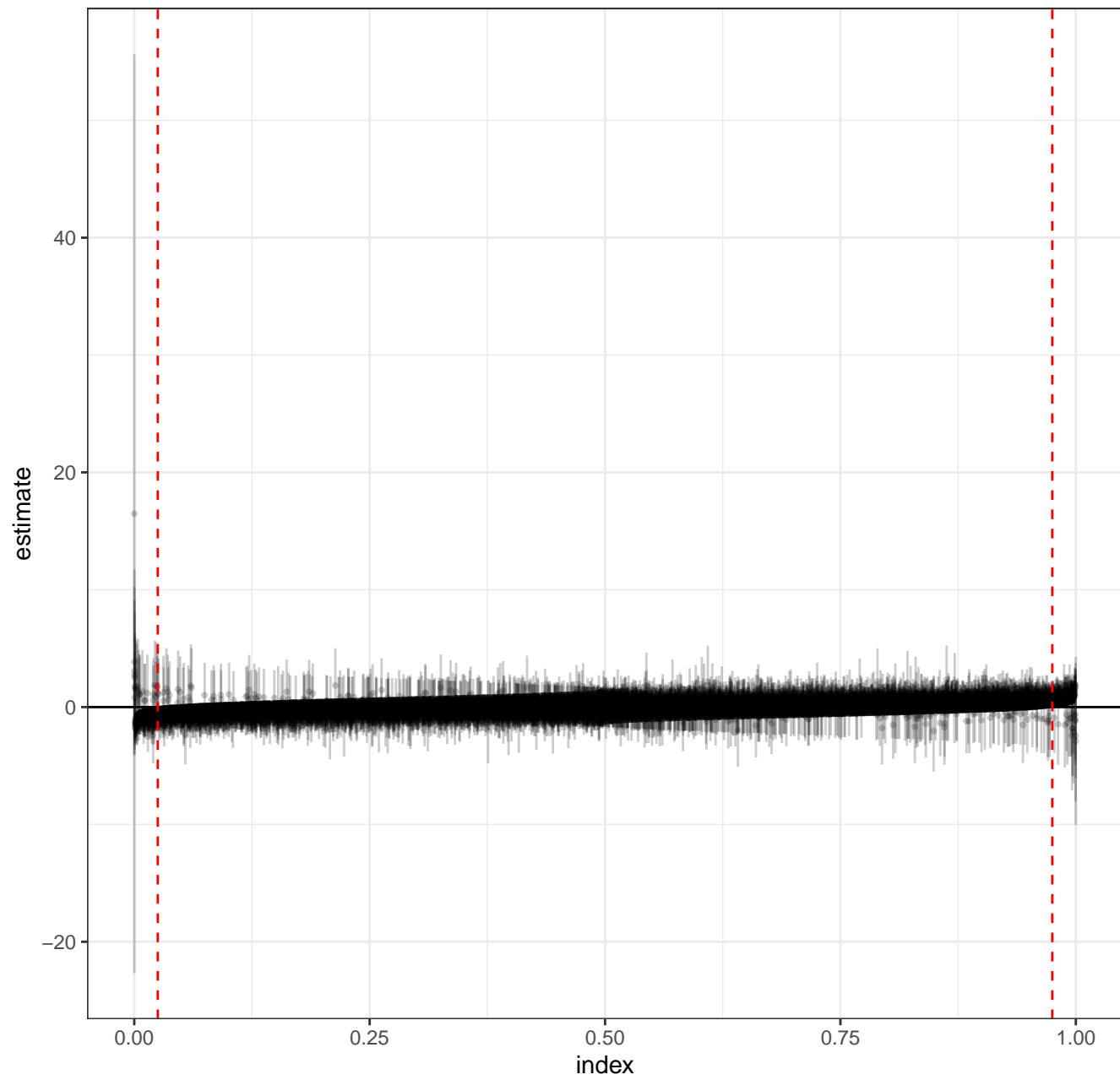
t\_4



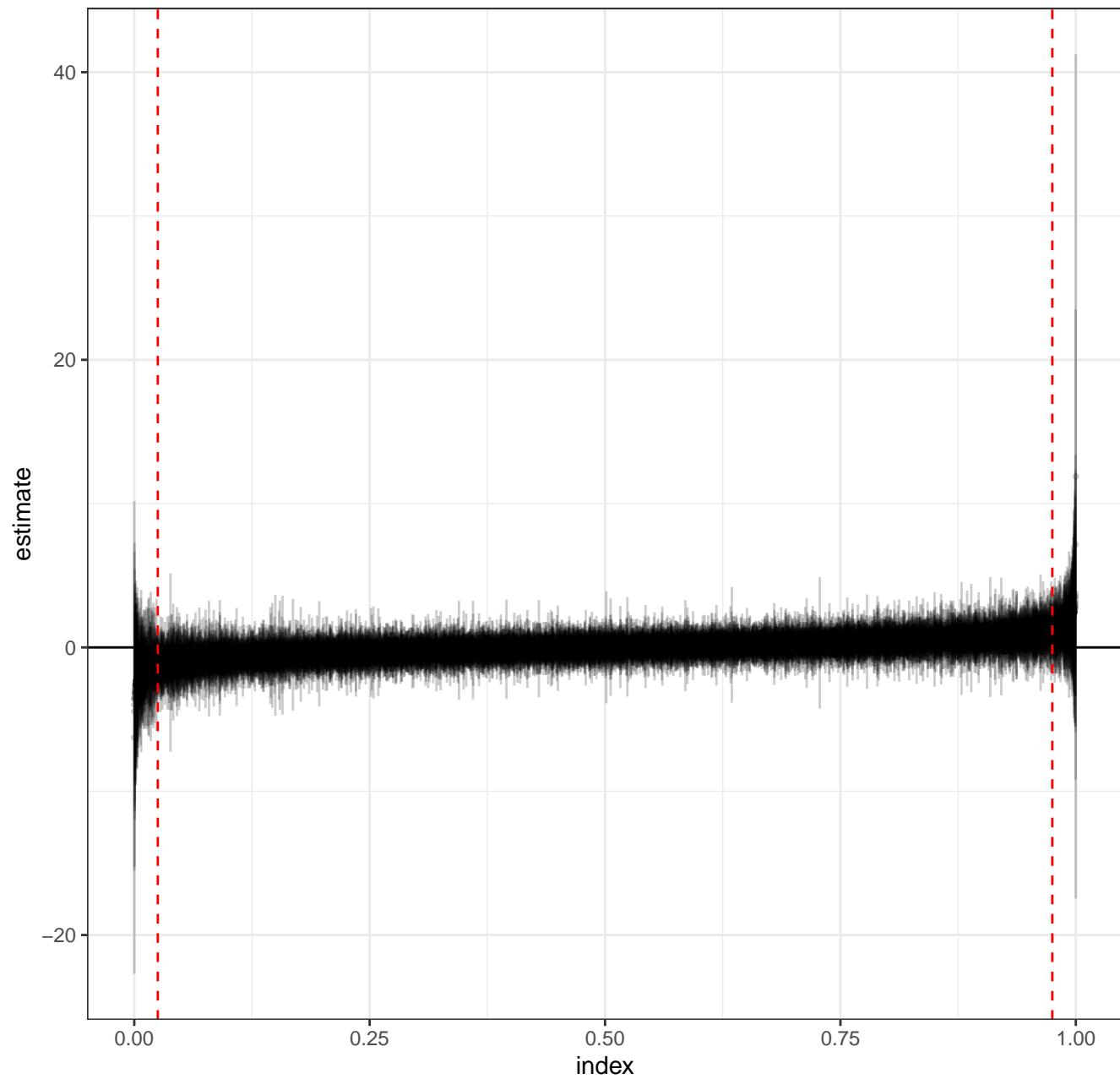
t\_4



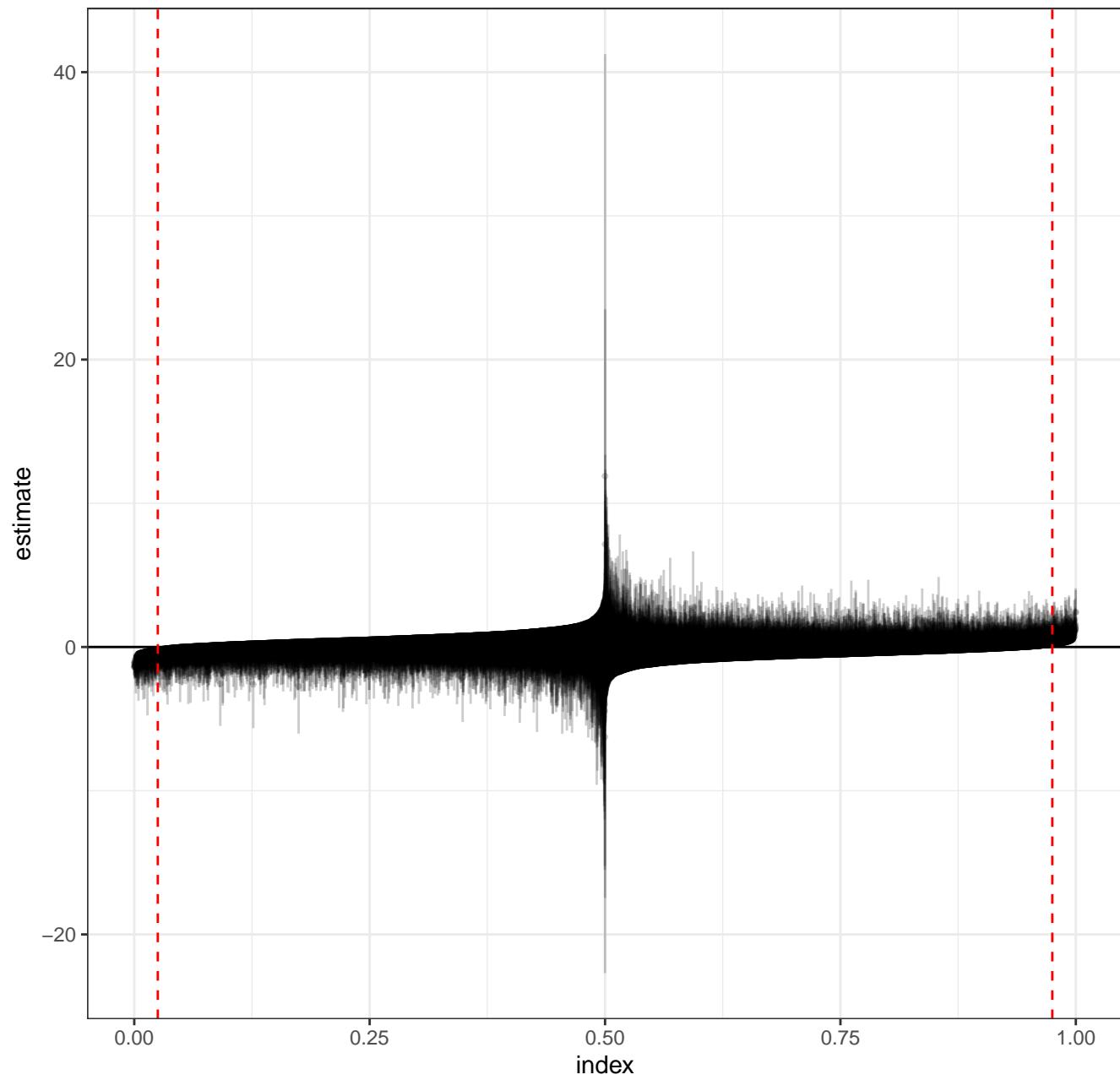
t\_4



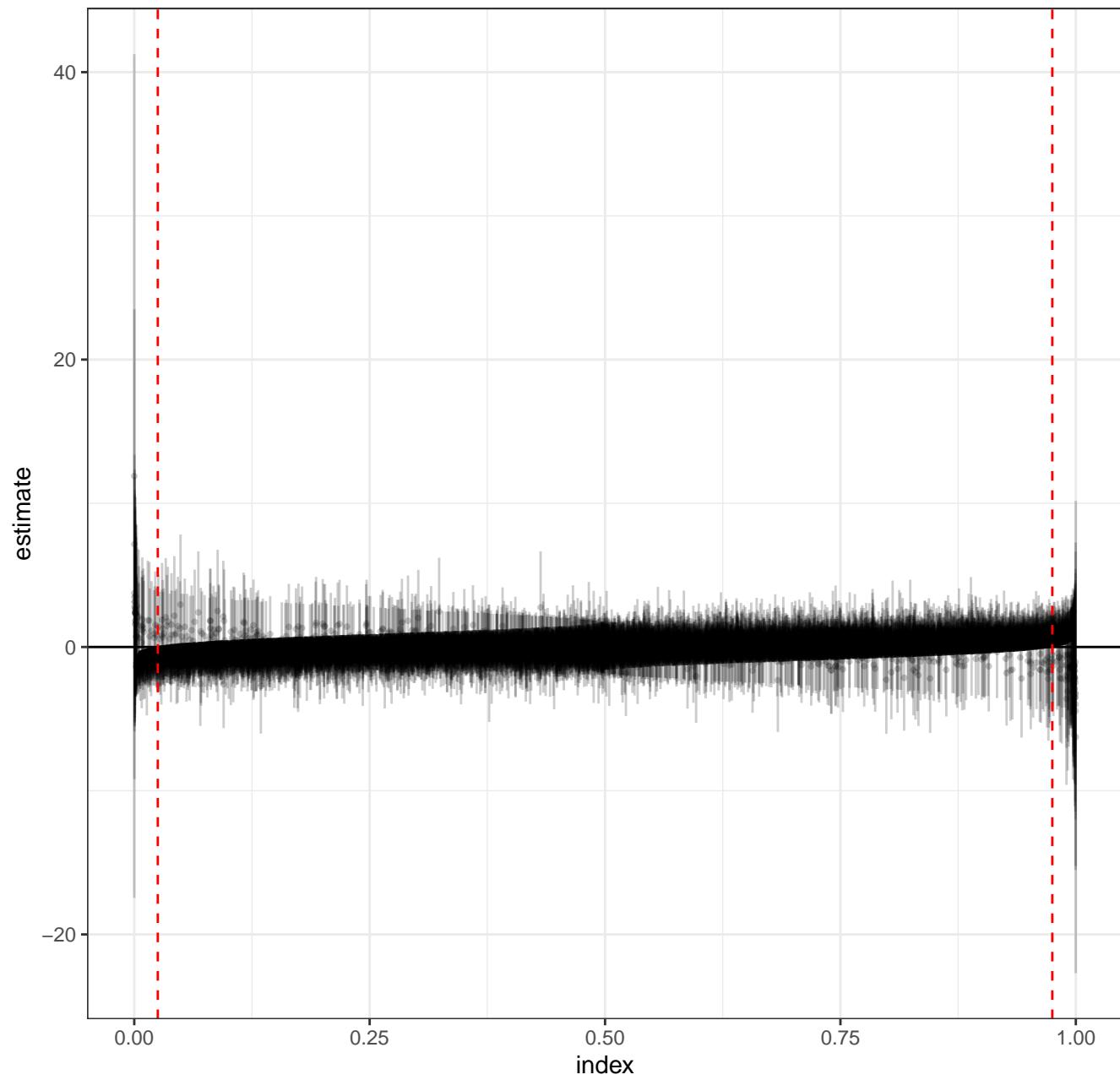
$t_3$



$t_3$

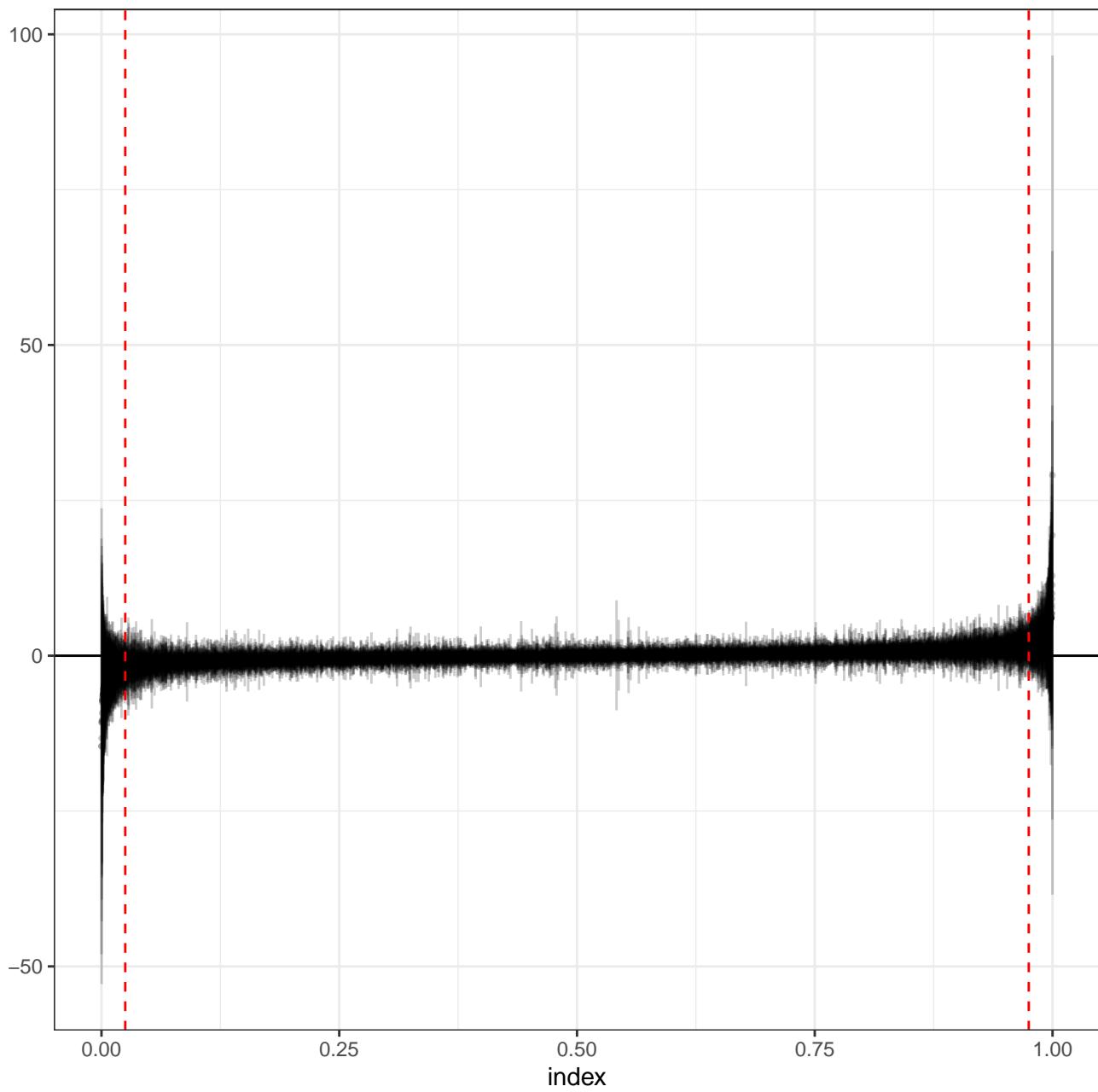


$t_3$



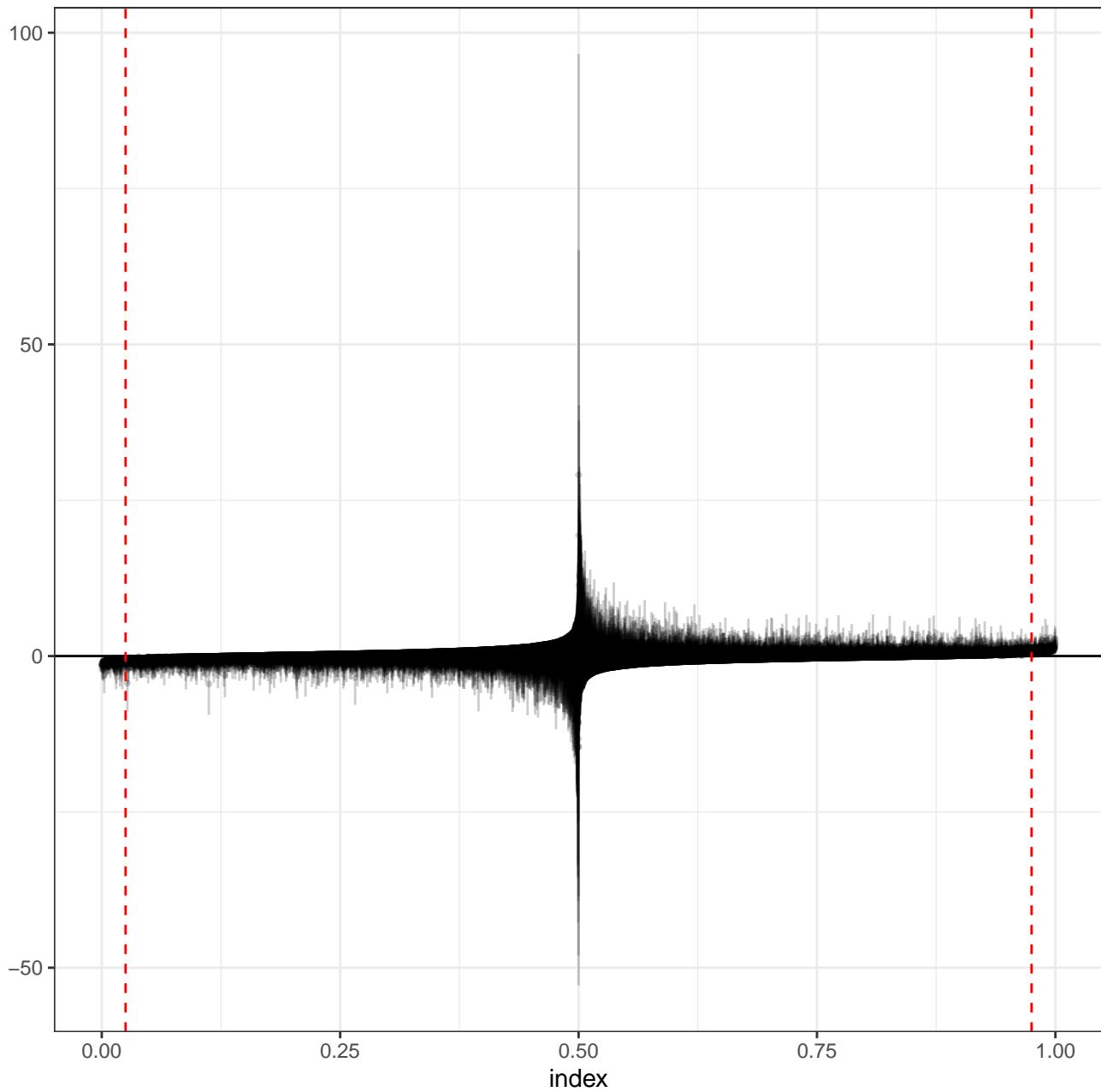
$t_2$

estimate



$t_2$

estimate



$t_2$

estimate

