HPC Tools – Final Assignment

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GitHub: https://github.com/dussauttho/hpctools

The source code for the task3 solver is available here:

https://github.com/dussauttho/hpctools/blob/master/Task3 solver.c.

Section 0 – Valgrind

Valgrind found a total of 126.616 MB of memory leak (for a matrix size of 300x300), on 19 spots of the source code.

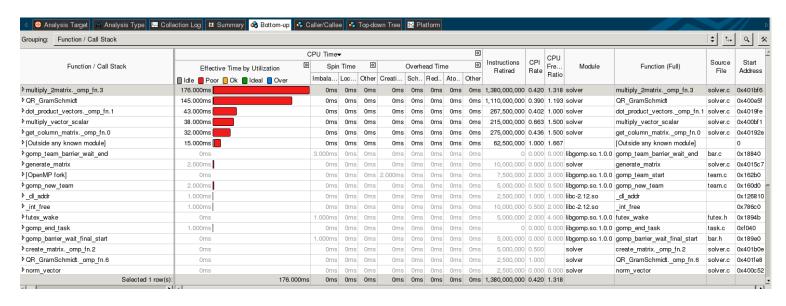
To reduce memory leaks, I modified the <code>get_column_matrix</code> function. Now, I pass the existing <code>double* v</code> as an argument of the new <code>get_column_matrix</code> and modify it directly in it, without creating a new vector and then return the new value. I applied the same principle everywhere else in the program in order to reduce memory leaks. Moreover, by freeing all the variables when they became useless everywhere in the program, I also reduced the memory leaks.

Section 1 – OpenMP parallelization

In order to parallelize the algorithm, I simply put "#pragma omp parallel" sections and "#pragma omp for" before each for loop that was suitable for parallelization. Here are the execution time and speed-up I got for a 20x20 matrix:

Number of processors	Execution Time	Speed-Up
1	0.135 sec	/
4	0.032 sec	4.22
8	0.014 sec	9.64

Section 2 – Intel VTune Amplifier



Like we can see on this screenshot, the two main hotspots are the *multiply_2matrix* and *QR_GramSchmidt* functions. With more than 1.3 million iterations, we can be surprised that the matrix product function is actually the most used function in the program, instead of the core function *QR_GramSchimdt*.

Section 3 – Intel Advisor

I wasn't able to run Intel Advisor because the software kept crashing on my personal computer, even if I was following the instructions on the tutorial video. When launching Advisor directly on ft6.cesga.es, I was kicked from the resources affected to my session after a few minutes, also causing Advisor to crash.

Section 4 – Extrae / Paraver N/D