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Homework 5

Chapter 5.1

- 5.1.3 True or false, with a reason if true or a counterexample if false:
 - (a) The determinant of I + A is $1 + \det A$.

False,
$$A = \begin{bmatrix} 7 & 1 & 3 \\ 0 & 4 & 7 \\ 0 & 0 & 1 \end{bmatrix}$$
 $A + I = \begin{bmatrix} 8 & 1 & 3 \\ 0 & 5 & 7 \\ 0 & 0 & 2 \end{bmatrix}$ $1 + |A| = 29 \neq |I + A| = 80$

(b) The determinant of ABC is |A||B||C|.

True, because of property #9.

(c) The determinant of 4A is 4|A|.

False, det
$$\left(4\begin{bmatrix}2&0\\0&2\end{bmatrix}\right)=8*8\neq 4\begin{vmatrix}2&0\\0&2\end{vmatrix}=4*4.$$

(d) The determinant of AB - BA is zero. Try an example with $A = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$.

False,
$$A = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$$
 $B = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$ $AB - BA = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$ which is invertible, meaning the determinant is not zero.

5.1.24 Elimination reduces A to U. Then A = LU:

$$A = \begin{bmatrix} 3 & 3 & 4 \\ 6 & 8 & 7 \\ -3 & 5 & -9 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ -1 & 4 & 1 \end{bmatrix} \begin{bmatrix} 3 & 3 & 4 \\ 0 & 2 & -1 \\ 0 & 0 & -1 \end{bmatrix} = LU.$$

Find the determinants of $L, U, A, U^{-1}, L^{-1}, and U^{-1}L^{-1}A$.

If one reduces L to its reduced row echelon form it becomes I. So |L| = 1

$$|U| = 3 * 2 * 1 = -1$$

$$|A| = |U| = -6$$

$$|U^{-1}L^{-1}| = \frac{1}{|U|} * \frac{1}{|L|} = -\frac{1}{6}$$

$$|U^{-1}L^{-1}A| = |A| = 1$$

5.1.27 Compute the determinants of these matrices by row operations:

$$A = \begin{bmatrix} 0 & a & 0 \\ 0 & 0 & b \\ c & 0 & 0 \end{bmatrix} \qquad \text{and} \qquad B = \begin{bmatrix} 0 & a & 0 & 0 \\ 0 & 0 & b & 0 \\ 0 & 0 & 0 & c \\ d & 0 & 0 & 0 \end{bmatrix} \qquad \text{and} \qquad C = \begin{bmatrix} a & a & a \\ a & b & b \\ a & b & c \end{bmatrix}.$$

A: Two row swaps are required to get A in the form $\begin{bmatrix} a & 0 & 0 \\ 0 & b & 0 \\ 0 & 0 & c \end{bmatrix}$ so |A| = (-1)(-1)abc = abc.

$$B{:}\ \, \text{Three row swaps are required to get}\,\, B\,\, \text{in the form}\, \begin{bmatrix} d & 0 & 0 & 0 \\ 0 & a & 0 & 0 \\ 0 & 0 & b & 0 \\ 0 & 0 & 0 & c \end{bmatrix}$$

so
$$|B| = (-1)(-1)(-1)abcd = abcd$$
.

C: You get RREF(C) as
$$\begin{bmatrix} a & 0 & 0 \\ 0 & b-a & 0 \\ 0 & 0 & c-b \end{bmatrix}$$
 so $|C| = a(b-a)(c-b)$.

- 5.1.28 True or false (give a reason if true or a 2 by 2 example if false):
 - (a) If A is not invertible then AB is not invertible.

True,
$$det(AB) = det(A)*det(B) = 0*det(B) = 0$$
.

(b) The determinant of A is always the products of its pivots.

False, $\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$ requires a row swap therefore the product is the products of its pivots times -1.

(c) The determinant of A - B equals det(A) - det(B).

False,
$$\begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix} - \begin{bmatrix} 0 & -1 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} = 0 \neq \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix} - \begin{bmatrix} 0 & -1 \\ 0 & 0 \end{bmatrix} = 1 - 0 = 1$$

(d) AB and BA have the same determinant.

True, since multiplication is commutative. |AB| = |A||B| = |B||A| = |BA|

Chapter 5.2

- 5.2.9 Show that 4 is the largest determinant for a 3 by 3 matrix of 1's and -1's.
- 5.2.23 With 2 by 2 blocks in 4 by 4 matrices, you cannot always use block determinants:

$$\begin{vmatrix} A & B \\ 0 & D \end{vmatrix} = |A| |D| \qquad \begin{vmatrix} A & B \\ C & D \end{vmatrix} \neq |A| |D| - |C| |B|.$$

- (a) Why is the first statement true? Somehow B doesn't enter.
- (b) Show by example that equality fails (as shown) when C enters.
- (c) Show by example that the answer $\det(AD CB)$ is also wrong.
- 5.2.33 The symmetric Pascal matrices have determinant 1. If I subtract 1 from the n, n entry, why does the determinant become zero? (Use rule 3 or cofactors.)

$$\det \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 2 & 3 & 4 \\ 1 & 3 & 6 & 10 \\ 1 & 4 & 10 & 20 \end{bmatrix} = 1 \text{ (known)} \qquad \det \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 2 & 3 & 4 \\ 1 & 3 & 6 & 10 \\ 1 & 4 & 10 & \mathbf{19} \end{bmatrix} = \mathbf{0} \text{ (to explain)}.$$

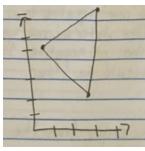
Chapter 5.3

5.3.16 (a) Find the area of the parallelogram with edges v = (3,2) and w = (1,4)

area =
$$\begin{vmatrix} 3 & 2 \\ 1 & 4 \end{vmatrix}$$
 = 12 - 2 = 10

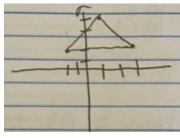
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(b) Find the area of the triangle with sides v, w, and v + w. Draw it.



area =
$$\frac{1}{2} \begin{vmatrix} 3 & 2 & 1 \\ 1 & 4 & 1 \\ 4 & 6 & 1 \end{vmatrix} = \frac{1}{2} (3(-2) + 2(3) - 10) = -5 = |-5| = 5$$

(c) find the area of the triangle with sides v, w, and w - v. Draw it



area =
$$\frac{1}{2} \begin{vmatrix} 3 & 2 & 1 \\ 1 & 4 & 1 \\ -2 & 2 & 1 \end{vmatrix} = \frac{1}{2}(3(2) + 2(-3) - 10) = -5 = |-5| = 5$$

5.3.20 The Hadamard matrix H has orthogonal rows. The box is hypercube!

5.3.21 If the columns of a 4 by 4 matrix have lengths L_1, L_2, L_3, L_4 , what is the largest possible value for the determinant (based on volumne)? If all entries of the matrix are 1 or -1, what are those lengths and the maximum determinant?

$$L_1=(1,1,1,1),\ L_2=(1,1,-1,-1),\ L_3=(1,-1,-1,1),\ L_4=(1,-1,1,-1)$$
 max det = 16

5.3.27 Polar coordinates satisfy $x = r\cos\theta$ and $y = r\sin\theta$. Polar area is $J dr d\theta$:

$$J = \begin{vmatrix} \frac{\partial x}{\partial r} & \frac{\partial x}{\partial \theta} \\ \frac{\partial y}{\partial r} & \frac{\partial y}{\partial \theta} \end{vmatrix} = \begin{vmatrix} \cos\theta & -r\sin\theta \\ \sin\theta & r\cos\theta \end{vmatrix}$$

The two columns are orthogonal. Their lengths are ____. Thus $J = _{__}$.

1 and
$$r$$
, $J = r$

5.3.28 Spherical coordinates ρ, ϕ, θ satisfy $x = \rho sin\phi cos\theta$ and $y = \rho sin\phi sin\theta$ and $z = \rho cos\phi$. Find the 3 by 3 matrix of partial derivatives: $\partial x/\partial \rho$, $\partial x/\partial \phi$, $\partial x/\partial \theta$ in row 1. Simplify its determinant to $J = \rho^2 sin\phi$. Then dV in spherical coordinates is $\rho^2 sin\phi dp d\phi d\theta$, the volume of an infinitesimal "coordinate box".

$$J = \begin{vmatrix} sin\phi cos\theta & \rho cos\phi cos\theta & -\rho sin\phi sin\theta \\ sin\phi sin\theta & \rho cos\phi sin\theta & \rho sin\phi cos\theta \\ cos\theta & -\rho sin\phi & 0 \end{vmatrix} = \rho^2 sin\phi$$

5.3.29 The matrix that connects r, θ to x, y is Problem 27. Invert that 2 by 2 matrix:

$$J^{-1} = \begin{vmatrix} \frac{\partial r}{\partial x} & \frac{\partial r}{\partial y} \\ \frac{\partial \theta}{\partial x} & \frac{\partial \theta}{\partial y} \end{vmatrix} = \begin{vmatrix} \cos \theta & ? \\ ? & ? \end{vmatrix} = ?$$

If is surprising that $\partial r/\partial x = \partial x/\partial r$ (Calculus, Gilbert Strang, p. 501). Multiplying the matrices J and J^{-1} gives the chain rule $\frac{\partial x}{\partial x} = \frac{\partial x}{\partial r} \frac{\partial r}{\partial x} + \frac{\partial x}{\partial \theta} \frac{\partial \theta}{\partial x} = 1$.

$$J^{-1} = \begin{vmatrix} \cos\theta & \sin\theta \\ \frac{-\sin\theta}{r} & \frac{\cos\theta}{r} \end{vmatrix} = \frac{1}{r}\cos^2\theta + \frac{1}{r}\cos^2\theta = \frac{1}{r}$$

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