



Problem Statement

- Develop a CNN Model to use images to classify
 - Images with cracks in pavements (CP)
 - Images with no cracks in pavements (UP)
- Data used in this study is based on SDNET 2018

SDNET2018: A concrete crack image dataset for machine learning applications

Marc Maguire, Utah State University

Follow

Sattar Dorafshan, Utah State University

Follow

Robert J. Thomas, Utah State University

Follow

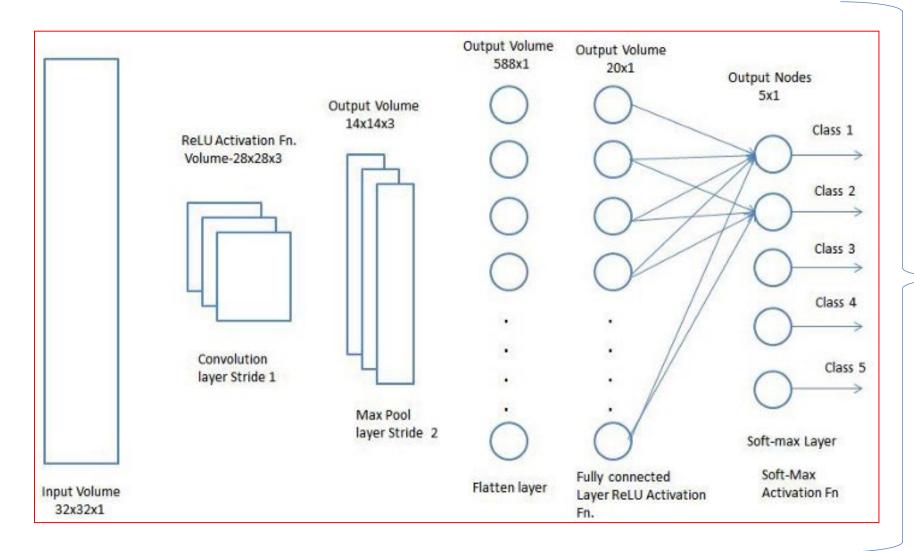
Description

SDNET2018 is an annotated image dataset for training, validation, and benchmarking of artificial intelligence based crack detection algorithms for concrete. SDNET2018 contains over 56,000 images of cracked and non-cracked concrete bridge decks, walls, and pavements. The dataset includes cracks as narrow as 0.06 mm and as wide as 25 mm. The dataset also includes images with a variety of obstructions, including shadows, surface roughness, scaling, edges, holes, and background debris. SDNET2018 will be useful for the continued development of concrete crack detection algorithms based on deep learning convolutional neural networks, which are a subject of continued research in the field of structural health monitoring. .jpe

OCLC

1078404353

Implementation of CNNs



Tensorflow Keras has high-end tools for Implementing CNNs

Data Sampling

- The database comprised of approximately
 - 2600 images of cracks in pavements
 - 22000 images of uncracked pavement surfaces
- Images taken with a 19 MP Nikon Camera
- Approximately 2600 images of uncracked pavements were randomly sampled
 - To match the same number of cracked pavement images
- The images were randomly split into 80% training + 10% resting and 10% validation

Sampled data were organized into two folders CP and UP for Train, Test and Validation datasets which were in separate folders





Python Implementation - Steps

import random

import seaborn as sns

import matplotlib.pyplot as plt

- Step 1: Load Required Libraries and Modules
 - We will need preprocessing layers, models and optimizers modules from tensorflow keras

Metrics from sklearn and plotting from seaborn and matplotlib

Load Libraries and Modules import os import tensorflow as tf from tensorflow import keras from tensorflow.keras.models import Sequential from tensorflow.keras.layers import Activation, Dense, Flatten from tensorflow.keras.layers import BatchNormalization, Conv2D, MaxPool2D from tensorflow.keras.optimizers import Adam from tensorflow.keras.metrics import categorical crossentropy import sklearn.metrics from tensorflow.keras.preprocessing.image import ImageDataGenerator import numpy as np import itertools import os

Working Directory and File Paths

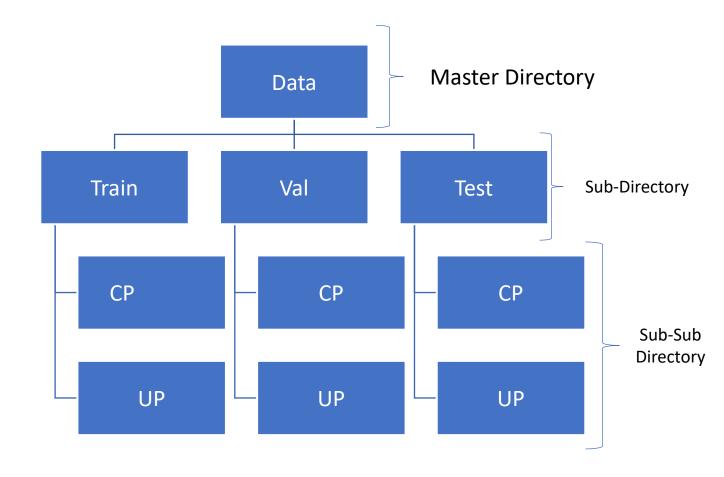
- Step 2: Set up working directory and File paths for image data
- In image processing file paths are important
 - These are paths to train, test and validation datasets

```
# Set working direcgtory
dir = '/home/vuddameri/CE5319/CNN/Pavement/FinalData'
os.chdir(dir)

#set path for train, test and validate datasets
train_path =
"/home/vuddameri/CE5319/CNN/Pavement/FinalData/train"
test_path = "/home/vuddameri/CE5319/CNN/Pavement/FinalData/test"
valid_path = "/home/vuddameri/CE5319/CNN/Pavement/FinalData/val"
```

Python Implementation - Steps

- Image datasets have to be stored in a hierarchical manner
 - Folder (Master data folder)
 - Subfolder (Train, Val and Test sub-folders
 - Sub-Subfolder (CP and UP)
 - CP Cracked pavement pictures
 - UP Uncracked pavement pictures



Reading Data

- There is an ImageDataGenerator function in keras pre-processing module
 - It will help instantiate an generator object
- The ImageDataGenerator has an iterator that can loop through images and read them into memory
 - flow_from_directory method of ImageDataGenerator

Data are read in batches. This allows data is managed efficiently (not loading a lot of data into memory and also allows manipulating data till it is read into the memory

Reading Data

```
# Preprocess images and make them keras ready
classz = ['CP', 'UP'] # identify classes
batchsize = 10 # Can be changed
train batches = ImageDataGenerator()
train batches = train batches.flow from directory(directory=train path,
                  target_size=(224,224), classes=classz,
                   batch size=batchsize)
valid batches = ImageDataGenerator()
valid batches = valid batches.flow from directory(directory=valid path,
                  target_size=(224,224), classes=classz,
                   batch size=10)
test_batches = ImageDataGenerator()
test batches = test batches.flow from directory(directory=test path,
                  target size=(224,224), classes=classz,
                  batch size=10, shuffle=False)
```

Specify the Model

- This will require some trial-and-error
- Use sequential(),
- Use Conv2D, MaxPool2D in earlier laters
- Flatten() before passing to Dense ANN Layer

Compile Model

 Specify which optimizer to use, which loss function, which metric to track

```
# Compile model model.compile(optimizer=Adam(learning_rate=0.0001), loss='categorical_crossentropy', metrics=['accuracy'])
```

Fit the Model

- Make sure all Programs are closed before fitting the model
 - THIS IS A MEMORY INTENSIVE OPERATION!!

```
model.fit(
    x = train_batches,
    steps_per_epoch=train_batches.samples // batchsize,
    epochs=10,
    validation_data=valid_batches,
    validation_steps=valid_batches.samples // batchsize,
    verbose=2)
```

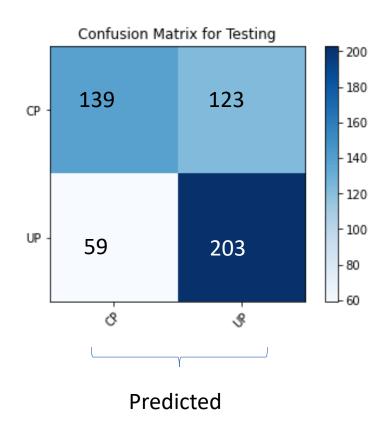
Evaluate the Model

- There are two types of predictions provided
 - Predict provides the probabilities
 - Used for computing AUC
 - Predict_class classifies based on maximum probability
 - Used for computing contingency tables and analysis
 - Deprecated and will be removed after 01-01-2021
 - DO NOT USE

Make Predictions for probabilities and classes predictions = model.predict(x = test_batches, verbose=0) predict_class = np.argmax(predictions, axis=-1)

Create Confusion Matrix

```
# Make confusion matrix and plot it
cm = sklearn.metrics.confusion_matrix(y_true=test_batches.classes,
            y pred=predict class)
tn, fp, fn, tp = confusion_matrix([0, 1, 0, 1], [1, 1, 1, 0]).ravel()
tn, fp, fn, tp # Write data for each element
cmap = 'Blues'
plt.imshow(cm, interpolation='nearest', cmap=cmap)
plt.title("Confusion Matrix for Testing")
plt.colorbar()
tick marks = np.arange(len(classz))
plt.xticks(tick marks, classz, rotation=45)
plt.yticks(tick_marks, classz)
```



Confusion Matrix Metrics

```
# Evaluate usng accuracy, precision, recall print("Accuracy:",metrics.accuracy_score(Y_test, predict_class)) print("Precision:",metrics.precision_score(Y_test, predict_class)) print("Recall:",metrics.recall_score(Y_test, predict_class))
```

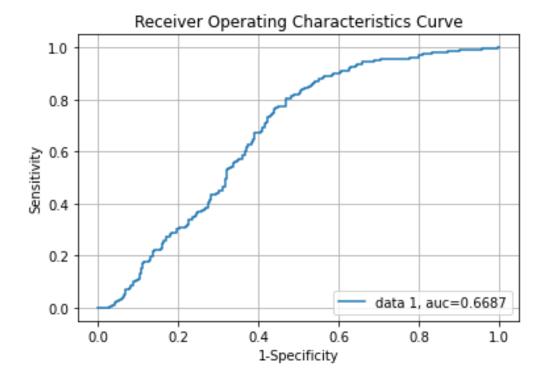
$$N = (TP+FP+FN+TP)$$
 $Accuracy = (TN + TP) / N$
 $Precision = TP/(TP + FP)$
 $Recall = TP/(TP + FN)$

Predicted

		Negative	Positive	
Actual	Negative	True Negative	False Positive	
	Positive	False Negative	True Positive	

AUC Curve

```
#Construct ROC Curve and Plot it
y_proba = predictions[::,1]
fpr, tpr, _ = metrics.roc_curve(Y_test, y_proba)
auc = metrics.roc_auc_score(Y_test, y_proba)
plt.plot(fpr,tpr,label="data 1, auc="+str(round(auc,4)))
plt.legend(loc=4)
plt.title('Receiver Operating Characteristics Curve')
plt.xlabel('1-Specificity')
plt.ylabel('Sensitivity')
plt.grid() # Plot the grid
plt.show() #show the curve
```



You should know

- What are CNNs
- How to implement them in Python
- How to arrange the image data into appropriate folders
 - Train, Test and Val
 - Sub-Sub-Folders of each category in each layer
- How to setup the model
 - Model Specification
 - Model Compilation
 - Model Fitting
- How to evaluate the model
 - Contingency table and ROC curve