

n linear equations, n unknowns

Row picture

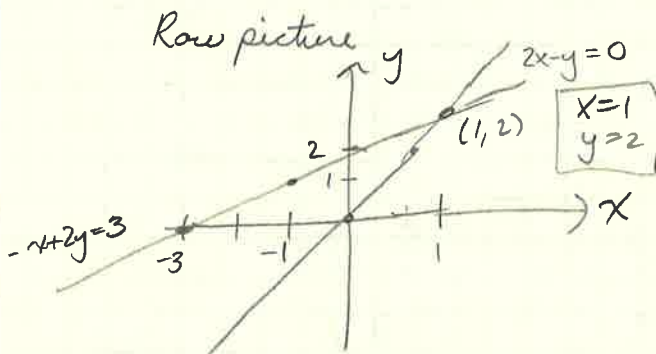
* Column picture

Matrix form

$$2x - y = 0$$

$$-x + 2y = 3$$

$$\underbrace{\begin{bmatrix} 2 & -1 \\ -1 & 2 \end{bmatrix}}_A \underbrace{\begin{bmatrix} x \\ y \end{bmatrix}}_X = \underbrace{\begin{bmatrix} 0 \\ 3 \end{bmatrix}}_b$$

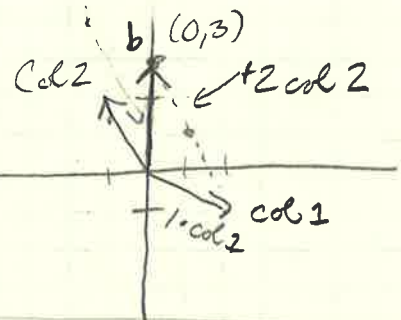


Column picture

$$x \begin{bmatrix} 2 \\ -1 \end{bmatrix} + y \begin{bmatrix} -1 \\ 2 \end{bmatrix} = \begin{bmatrix} 0 \\ 3 \end{bmatrix}$$

Find the linear combination of the columns to produce $\begin{bmatrix} 0 \\ 3 \end{bmatrix}$

Take $x=1$ and $y=2$



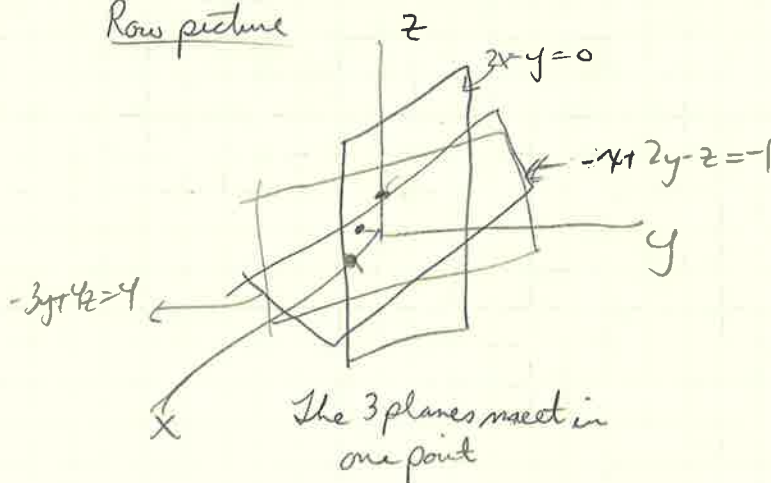
Take all of the combinations

$x \begin{bmatrix} 2 \\ -1 \end{bmatrix} + y \begin{bmatrix} -1 \\ 2 \end{bmatrix}$; which fills the plane

$$\begin{aligned} 2x - y &= 0 \\ -x + 2y - z &= -1 \\ -3y + 4z &= 4 \end{aligned}$$

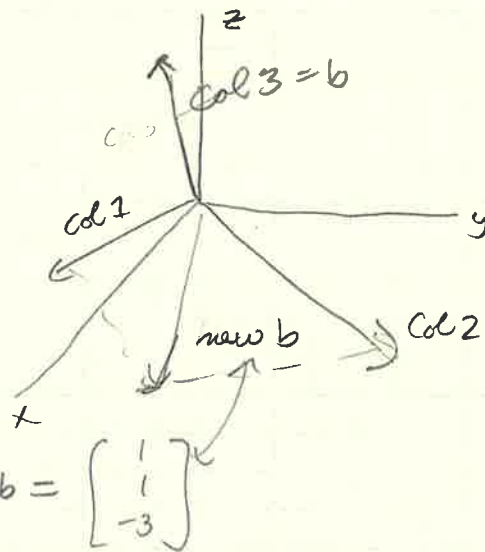
$$A = \begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -3 & 4 \end{bmatrix} \quad b = \begin{bmatrix} 0 \\ -1 \\ 4 \end{bmatrix}$$

Row picture



Column picture

$$x \begin{bmatrix} 2 \\ -1 \\ 0 \end{bmatrix} + y \begin{bmatrix} -1 \\ 2 \\ -3 \end{bmatrix} + z \begin{bmatrix} 0 \\ -1 \\ 4 \end{bmatrix} = \begin{bmatrix} 0 \\ -1 \\ 4 \end{bmatrix}$$

Linear combination
of 3-D vectors

$$x=0, y=0, z=1$$

Suppose $b = \begin{bmatrix} 1 \\ 1 \\ -3 \end{bmatrix}$

$$x \begin{bmatrix} 2 \\ -1 \\ 0 \end{bmatrix} + y \begin{bmatrix} -1 \\ 2 \\ -3 \end{bmatrix} + z \begin{bmatrix} 0 \\ -1 \\ 4 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ -3 \end{bmatrix} \Rightarrow x=1, y=1, z=0$$

Can I solve $Ax=b$ for every b ?

\Rightarrow Do the linear combinations of the columns fill 3-D space?
For this A , the answer is yes.

$$Ax=b$$

$$\begin{bmatrix} 2 & 5 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix} = 1 \begin{bmatrix} 2 \\ 1 \end{bmatrix} + 2 \begin{bmatrix} 5 \\ 3 \end{bmatrix} = \begin{bmatrix} 12 \\ 7 \end{bmatrix}$$

Ax is a combination of the columns of A

Lecture 2

Elimination $\begin{cases} \text{Success} \\ \text{failure} \end{cases}$

Back-Substitution
Elimination Matrices
Matrix Multiplication

$$\begin{aligned} x + 2y + z &= 2 \\ 3x + 8y + z &= 12 \\ 4y + z &= 2 \end{aligned}$$

$$\begin{array}{c} \text{first pivot} \end{array} \begin{bmatrix} 1 & 2 & 1 \\ 3 & 8 & 1 \\ 0 & 4 & 1 \end{bmatrix} \xrightarrow[\substack{(2,1) \\ (3,1)}]{\substack{R_2 - 3R_1 \\ R_3 - 0R_1}} \begin{bmatrix} 1 & 2 & 1 \\ 0 & 2 & -2 \\ 0 & 4 & 1 \end{bmatrix} \xrightarrow[\substack{(3,2)}]{R_3 - 2R_2} \begin{bmatrix} 1 & 2 & 1 \\ 0 & 2 & -2 \\ 0 & 0 & 5 \end{bmatrix}$$

$\xrightarrow{\text{second pivot}} \quad \quad \quad \xrightarrow{\text{third pivot}}$

U (upper triangular)

Elimination failure (not getting 3 pivots)

Back Substitution

$$\left[\begin{array}{ccc|c} 1 & 2 & 1 & 2 \\ 3 & 8 & 1 & 12 \\ 0 & 4 & 1 & 2 \end{array} \right] \xrightarrow{\substack{R_2 - 3R_1 \\ R_3 - 0R_1}} \left[\begin{array}{ccc|c} 1 & 2 & 1 & 2 \\ 0 & 2 & -2 & 6 \\ 0 & 4 & 1 & 2 \end{array} \right] \xrightarrow{R_3 - 2R_2} \left[\begin{array}{ccc|c} 1 & 2 & 1 & 2 \\ 0 & 2 & -2 & 6 \\ 0 & 0 & 5 & -10 \end{array} \right]$$

$\underbrace{\quad\quad\quad}_A \quad \underbrace{\quad}_b \quad \underbrace{\quad\quad\quad}_U \quad \underbrace{\quad}_C$

$$Ux = C: \quad \begin{array}{lcl} x + 2y + z = 2 & , & x = 2 \\ 2y - 2z = 6 & , & y = 1 \\ 5z = -10 & , & z = -2 \end{array}$$

Elimination Matrices

$$\begin{bmatrix} - & - & - \\ - & - & - \\ - & - & - \end{bmatrix} \begin{bmatrix} 3 \\ 4 \\ 5 \end{bmatrix} = 3 \cdot \text{col } 1 + 4 \cdot \text{col } 2 + 5 \cdot \text{col } 3$$

Matrix \times column = column

$$\begin{bmatrix} 1 & 2 & 7 \end{bmatrix} \begin{bmatrix} - & - & - \\ - & - & - \\ - & - & - \end{bmatrix} = 1 \cdot \text{row } 1 + 2 \cdot \text{row } 2 + 7 \cdot \text{row } 3$$

$1 \times 3 \quad \quad \quad 3 \times 3$

row \times matrix = row

$$\xrightarrow{E_{21}} \begin{bmatrix} 1 & 0 & 0 \\ -3 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 & 1 \\ 3 & 8 & 1 \\ 0 & 4 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 2 & 1 \\ 0 & 2 & -2 \\ 0 & 4 & 1 \end{bmatrix}$$

Step 1:
Subtract 3 row 1 from row 2
and gives new row 2

$$\xrightarrow{E_{32}} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -2 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 & 1 \\ 0 & 2 & -2 \\ 0 & 4 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 2 & 1 \\ 0 & 2 & -2 \\ 0 & 0 & 5 \end{bmatrix}$$

Step 2:
Subtract 2 row 2 from
row 3 to get new row 3

$$E_{32}(E_{21}A) = U \Rightarrow \text{associativity}$$

$$(E_{32}E_{21})A = U$$

Permutation matrix \Rightarrow Exchange rows

$$\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} c & d \\ a & b \end{bmatrix}$$

$\uparrow P$

Multiply on left
does row operations

Exchange columns

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} b & a \\ d & c \end{bmatrix}$$

Multiply on right
does column operations $AB \neq BA$ in general (not commutative in general)Inverses

$$\begin{bmatrix} 1 & 0 & 0 \\ 3 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ -3 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$E^{-1} \quad E \quad I$

add 3 row 1 to row 2

Lecture 3

Matrix Multiplication (4 ways!)

Inverse of A , AB , A^T Gauss-Jordan / find A^{-1}

$$\text{row 3} \begin{bmatrix} a_{31} & a_{32} & \dots & a_{3n} \end{bmatrix} \begin{bmatrix} b_{14} \text{ col 4} \\ b_{24} \\ \vdots \\ b_{n4} \end{bmatrix} = \begin{bmatrix} c_{34} \end{bmatrix}$$

$A_{m \times n} \quad B_{n \times p} \quad C = AB_{m \times p}$

$$c_{34} = (\text{row 3 of } A) \cdot (\text{col 4 of } B) = a_{31}b_{14} + a_{32}b_{24} + \dots = \sum_{k=1}^n a_{3k}b_{k4}$$

$$\begin{bmatrix} \text{---} \\ \text{---} \\ \text{---} \end{bmatrix} \begin{bmatrix} \text{---} \\ \text{---} \\ \text{---} \end{bmatrix} = \begin{bmatrix} | & | & \dots & | \\ A \cdot \text{col}_1 B & A \cdot \text{col}_2 B & \dots & A \cdot \text{col}_p B \\ | & | & \dots & | \end{bmatrix}$$

$A_{m \times n} \quad B_{n \times p} \quad C_{m \times p}$

Columns of C are combinations
of columns of A

$$\begin{bmatrix} \text{---} \\ \text{---} \\ \text{---} \end{bmatrix} \begin{bmatrix} \text{---} \\ \text{---} \\ \text{---} \end{bmatrix} = \begin{bmatrix} \text{row } A \cdot B \\ \text{---} \\ \text{---} \end{bmatrix}$$

$A_{m \times n} \quad B_{n \times p} \quad C_{m \times p}$

← rows of C are combinations
of rows of B

Column of A \times row of B
 $(m \times 1)$ $(1 \times p)$

4th way

$AB = \text{Sum of (columns of } A) \times (\text{rows of } B)$

$$\begin{bmatrix} 2 \\ 3 \\ 4 \end{bmatrix} \begin{bmatrix} 1 & 6 \end{bmatrix} = \begin{bmatrix} 2 & 12 \\ 3 & 18 \\ 4 & 24 \end{bmatrix}$$

$$\begin{bmatrix} 2 & 7 \\ 3 & 8 \\ 4 & 9 \end{bmatrix} \begin{bmatrix} 1 & 6 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 2 \\ 3 \\ 4 \end{bmatrix} \begin{bmatrix} 1 & 6 \end{bmatrix} + \begin{bmatrix} 7 \\ 8 \\ 9 \end{bmatrix} \begin{bmatrix} 0 & 0 \end{bmatrix} = \begin{bmatrix} 2 & 12 \\ 3 & 18 \\ 4 & 24 \end{bmatrix} + \begin{bmatrix} 0 & 0 \\ 0 & 0 \\ 0 & 0 \end{bmatrix}$$

Block Multiplication

$$\begin{bmatrix} A_1 & A_2 \\ A_3 & A_4 \end{bmatrix} \begin{bmatrix} B_1 & B_2 \\ B_3 & B_4 \end{bmatrix} = \begin{bmatrix} A_1 B_1 + A_2 B_3 & A_1 B_2 + A_2 B_4 \\ A_3 B_1 + A_4 B_3 & A_3 B_2 + A_4 B_4 \end{bmatrix}$$

$A \qquad B$

Inverses (square matrices)

$$A^{-1}A = I = AA^{-1} \quad \text{called invertible, nonsingular}$$

\uparrow
if this exists

Singular case: no inverse

$$A = \begin{bmatrix} 1 & 3 \\ 2 & 6 \end{bmatrix} \quad \text{can't form } \begin{bmatrix} 1 \\ 0 \end{bmatrix} \text{ as a linear combination of columns of } A$$

no inverse because we can find a vector $x \neq 0$ with $Ax = 0$

$$Ax = \begin{bmatrix} 1 & 3 \\ 2 & 6 \end{bmatrix} \begin{bmatrix} 3 \\ -1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Rightarrow A^{-1}Ax = A^{-1}0 \Rightarrow x = 0$$

but $x \neq 0$

Back to invertible case

$$\begin{bmatrix} 1 & 3 \\ 2 & 7 \end{bmatrix} \begin{bmatrix} a & c \\ b & d \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$A \qquad A^{-1} \qquad I$

$A \times \text{column}_j A^{-1} = \text{column}_j \text{ of } I$

Gauss-Jordan (solve 2 eqns at once)

$$\begin{bmatrix} 1 & 3 \\ 2 & 7 \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \quad \begin{bmatrix} 1 & 3 \\ 2 & 7 \end{bmatrix} \begin{bmatrix} c \\ d \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$\left[\begin{array}{cc|cc} 1 & 3 & 1 & 0 \\ 2 & 7 & 0 & 1 \end{array} \right] \rightarrow \left[\begin{array}{cc|cc} 1 & 3 & 1 & 0 \\ 0 & 1 & -2 & 1 \end{array} \right] \rightarrow \left[\begin{array}{cc|cc} 1 & 0 & 7 & -3 \\ 0 & 1 & -2 & 1 \end{array} \right]$$

A I

I A⁻¹

$$\begin{bmatrix} 1 & 3 \\ 2 & 7 \end{bmatrix} \begin{bmatrix} 7 & -3 \\ -2 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$E [A \ I] = [EA \ EI] = [I \ A^{-1}] \quad \text{because } EA = I \quad \Leftrightarrow E = A^{-1}$$

↑ product of E's for the elimination steps

Lecture 4

Inverse of AB A^T

Product of Elimination Matrices

A = LU (no row exchanges)

$$AA^{-1} = I = A^{-1}A$$

If AB are both invertible, $ABB^{-1}A^{-1} = AIA^{-1} = I$

$$\Rightarrow (AB)^{-1} = B^{-1}A^{-1}$$

$$B^{-1}A^{-1}AB = B^{-1}IB = B^{-1}B = I$$

$$(AA^{-1})^T = (I)^T$$

$$(A^{-1})^T A^T = I$$

↑ This is the inverse of A^T $\Rightarrow (A^T)^{-1} = (A^{-1})^T$

$$\begin{matrix} E_{21} & A \\ \begin{bmatrix} 1 & 0 \\ -4 & 1 \end{bmatrix} & \begin{bmatrix} 2 & 1 \\ 8 & 7 \end{bmatrix} \end{matrix} = \begin{matrix} U \\ \begin{bmatrix} 2 & 1 \\ 0 & 3 \end{bmatrix} \end{matrix}$$

$$\begin{matrix} A \\ \begin{bmatrix} 2 & 1 \\ 8 & 7 \end{bmatrix} \end{matrix} = \begin{matrix} L = E_{21}^{-1} & U \\ \begin{bmatrix} 1 & 0 \\ 4 & 1 \end{bmatrix} & \begin{bmatrix} 2 & 1 \\ 0 & 3 \end{bmatrix} \end{matrix}$$

$$= \begin{matrix} L & D & U \\ \begin{bmatrix} 1 & 0 \\ 4 & 1 \end{bmatrix} & \begin{bmatrix} 2 & 0 \\ 0 & 3 \end{bmatrix} & \begin{bmatrix} 1 & 1/2 \\ 0 & 1 \end{bmatrix} \end{matrix}$$

$$E_{32} E_{31} E_{21} A = U \quad (3 \times 3 \text{ no row exchanges})$$

$$A = \underbrace{E_{21}^{-1} E_{31}^{-1} E_{32}^{-1}}_L U$$

$$\begin{matrix} E_{32} & E_{31} & E_{21} \\ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 5 & 1 \end{bmatrix} & \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} & \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \end{matrix} = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 10 & -5 & 1 \end{bmatrix} \quad EA = U$$

Inverses

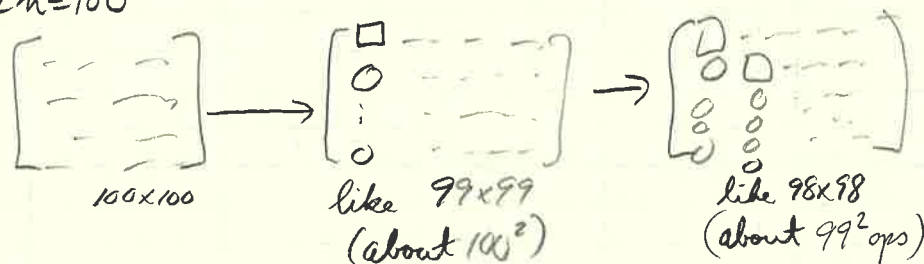
$$\begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 5 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 5 & 1 \end{bmatrix} = L \quad A = LU$$

$$A = LU$$

If no row exchanges, the multipliers go directly into L .

How many operations on an $n \times n$ matrix A ?
(multiply + subtract)

Take $n=100$



$$\# \text{ of ops} \sim n^2 + (n-1)^2 + \dots + 3^2 + 2^2 + 1^2 \approx \frac{1}{3} n^3 \text{ on } A$$

Cost for every RHS is n^2

Permutations 3×3

$$I = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}, P_{12} = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}, P_{13} = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix}, P_{23} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix},$$

Switch rows 1 & 2

$$P_{123} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix}, P_{132} = \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$$

↑ cycle

Group of 6 matrices

$$P_{12}^{-1} = P_{12}$$

$$P^{-1} = P^T \text{ for permutation matrices}$$

$$\# \text{ } 4 \times 4 \text{ permutation matrices} = 24$$

Section 2.7 $PA=LU$

Section 3.1 Vector Spaces and Subspaces

Permutations P : explicit row exchanges

$$A=LU = \begin{bmatrix} 1 & 1 & 0 \\ * & 1 & 1 \\ & & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & * & 0 \\ 0 & 0 & 1 \end{bmatrix} \text{ (no row exchanges)}$$

becomes $PA=LU$ (with row exchanges)
for any invertible A

 P = identity matrix with reordered rows. $n!$ permutation matrices of size n .

$$P^{-1} = P^T \Leftrightarrow P^T P = I$$

Transposes

$$R^T \rightarrow \begin{bmatrix} 1 & 3 \\ 2 & 3 \\ 4 & 1 \end{bmatrix}^T = \begin{bmatrix} 1 & 2 & 4 \\ 3 & 3 & 1 \end{bmatrix} \quad \nwarrow R$$

 $R^T R$ is always symmetric

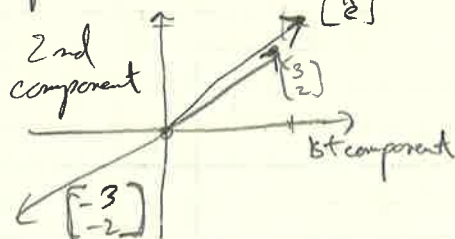
$$(A^T)_{ij} = A_{ji}$$

$$\begin{bmatrix} 1 & 3 \\ 2 & 3 \\ 4 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 & 4 \\ 3 & 3 & 1 \end{bmatrix} = \begin{bmatrix} 10 & 11 & 7 \\ 11 & 13 & 11 \\ 7 & 11 & 12 \end{bmatrix}$$

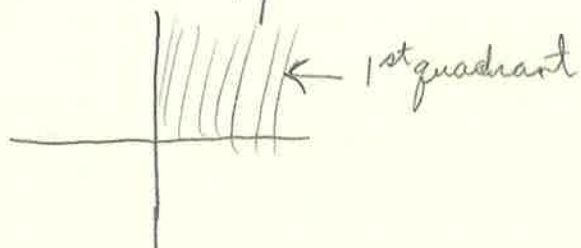
Symmetric Matrices: $A^T = A$

Ex. $\begin{bmatrix} 3 & 1 & 7 \\ 1 & 2 & 9 \\ 7 & 9 & 4 \end{bmatrix}$

$$(R^T R)^T = R^T R^{TT} = R^T R$$

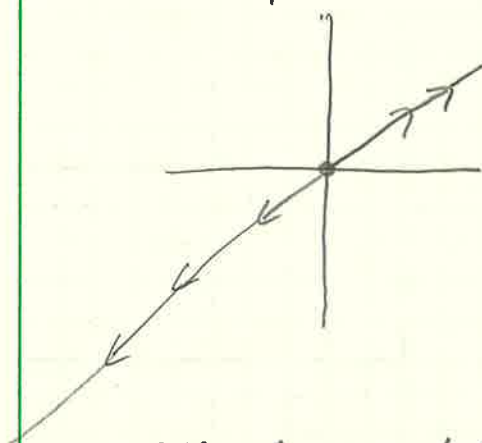
Vector SpacesExamples: \mathbb{R}^2 = all 2-dim. real vectors such as $\begin{bmatrix} 3 \\ 2 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \end{bmatrix}, \begin{bmatrix} \pi \\ e \end{bmatrix}$. \mathbb{R}^2 = "x-y plane" \mathbb{R}^3 = all vectors with 3 real components $\begin{bmatrix} 3 \\ 2 \\ 0 \end{bmatrix}$ \mathbb{R}^n = all vectors with n real components
↑
column

not a vector space



Can add and stay in the 1st quadrant, but scalar multiplication may bring us out of the space

A vector space inside \mathbb{R}^2 called a subspace of \mathbb{R}^2



a line in \mathbb{R}^2 through the zero vector

All subspaces of \mathbb{R}^2

- ① All of \mathbb{R}^2
- ② any line through $\begin{bmatrix} 0 \\ 0 \end{bmatrix}$, L
- ③ zero vector only, $\overline{0}$

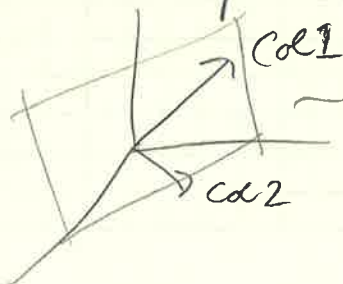
All subspaces of \mathbb{R}^3

- ① All of \mathbb{R}^3
- ② any line through $\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$
- ③ any plane through $\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$
- ④ zero vector only

$$A = \begin{bmatrix} 1 & 3 \\ 2 & 3 \\ 4 & 1 \end{bmatrix}$$

columns in \mathbb{R}^3

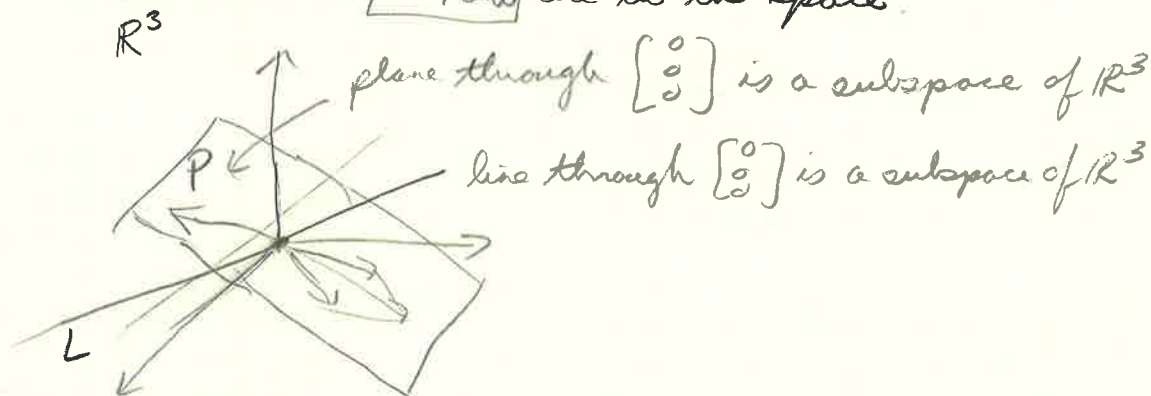
all their linear combinations form a subspace called the column space $C(A)$



→ this space is a plane

Vector Spaces and Subspaces
 Column space of A : Solving $Ax=b$
 Null space of A

Vector Space requirements: $v+w$ and cv are in the space
 all combinations $cv+dw$ are in the space.



2 subspaces: P and L

$P \cup L$ = all vectors in P or L or both

This ~~is~~ (is not) a subspace

$P \cap L$ = all vectors in both P and L

This is a vector space

Subspaces S and T : $S \cap T$ is a subspace

$C(A)$: Column Space of A (is a subspace of \mathbb{R}^4 here)

$$A = \begin{bmatrix} 1 & 1 & 2 \\ 2 & 1 & 3 \\ 3 & 1 & 4 \\ 4 & 1 & 5 \end{bmatrix}$$

$C(A)$ = all linear combinations of the columns

Does $Ax=b$ have a solution for every b ? No

$$Ax = \begin{bmatrix} 1 & 1 & 2 \\ 2 & 1 & 3 \\ 3 & 1 & 4 \\ 4 & 1 & 5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \\ b_4 \end{bmatrix}$$

For some RHS b this can be solved.

Which b allow this system to be solved?? $b=0$ always

$$b = \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix}, x = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \text{ works} \quad b = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}, x = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \text{ works}$$

Exactly when $b \in C(A)$

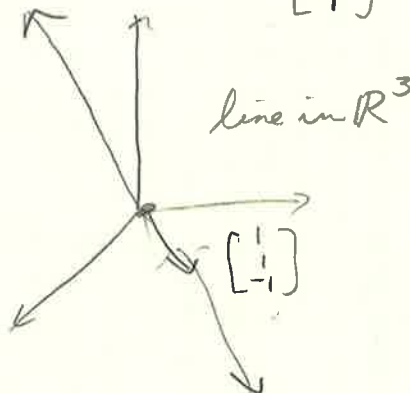
In this case $C(A)$ is a 2-D subspace of \mathbb{R}^4

$N(A)$: Nullspace of A = all x 's that solve $Ax=0$ (in \mathbb{R}^3 here)

$$Ax = \begin{bmatrix} 1 & 1 & 2 \\ 2 & 1 & 3 \\ 3 & 1 & 4 \\ 4 & 1 & 5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} \quad N(A) \text{ contains } \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix}, \begin{bmatrix} c \\ c \\ -c \end{bmatrix}$$

$0 \in N(A)$ always

$N(A)$ contains $c \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix}$ for any c



Check that solutions to $Ax=0$ always give a subspace

If $Av=0$ and $Aw=0$ then $A(v+w)=0$

$$A(v+w) = Av + Aw = 0 + 0 = 0 \quad \checkmark$$

If $Av=0$ then $A(cv)=0$

$$A(cv) = cAv = c0 = 0 \quad \checkmark$$

$$Ax = \begin{bmatrix} 1 & 1 & 2 \\ 2 & 1 & 3 \\ 3 & 1 & 4 \\ 4 & 1 & 5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix}$$

Do the solutions form a subspace? No

No 0-vector to start

$$x = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \text{ is a solution}$$

$$x = \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix} \text{ is a solution}$$

Lecture 7

Computing the nullspace ($Ax=0$)

Pivot variables - free variables

Special solutions - $\text{rref}(A) = R$

$$A = \begin{bmatrix} 1 & 2 & 2 & 2 \\ 2 & 4 & 6 & 8 \\ 3 & 6 & 8 & 10 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 2 & 2 \\ 0 & 0 & 2 & 4 \\ 0 & 0 & 2 & 4 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 2 & 2 \\ 0 & 0 & 2 & 4 \\ 0 & 0 & 0 & 0 \end{bmatrix} = U$$

echelon form \leftarrow

$\uparrow \quad \uparrow$
2 pivot columns

The rank of A = number of pivots = 2 in this case

$$\begin{bmatrix} 1 & 2 & 2 & 2 \\ 0 & 0 & 2 & 4 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

↑ ↑
free columns

$$x = \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \end{bmatrix} \in N(A) \quad \begin{aligned} x_1 + 2x_2 + 2x_3 + 2x_4 &= 0 \\ " \quad 2x_3 + 4x_4 &= 0 \end{aligned}$$

$$x_3 = -2x_4$$

$$x_1 + 2 = 0$$

$$c \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \end{bmatrix} \in N(A)$$

Choose $x_2 = 0, x_4 = 1 \Rightarrow$

$$\begin{aligned} x_1 + 2x_3 + 2 &= 0 \\ 2x_3 + 4 &= 0 \end{aligned}$$

$$x = \begin{bmatrix} 2 \\ 0 \\ -2 \\ 1 \end{bmatrix} \in N(A)$$

$$x_3 = -2$$

$$x_1 - 4 + 2 = 0 \Rightarrow x_1 = 2$$

$$d \begin{bmatrix} 2 \\ 0 \\ -2 \\ 1 \end{bmatrix} \in N(A)$$

$$c \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \end{bmatrix} + d \begin{bmatrix} 2 \\ 0 \\ -2 \\ 1 \end{bmatrix} \in N(A)$$

Rank $r = 2 = \#$ of pivot variables

$$n - r = 4 - 2 = 2 \text{ free variables}$$

$R =$ reduced row echelon form has zeros above and below

$$\begin{bmatrix} 1 & 2 & 2 & 2 \\ 0 & 0 & 2 & 4 \\ 0 & 0 & 0 & 0 \end{bmatrix} \xrightarrow{\text{the pivots}} \begin{bmatrix} 1 & 2 & 0 & -2 \\ 0 & 0 & 2 & 4 \\ 0 & 0 & 0 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 0 & -2 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 \end{bmatrix} = R$$

Notice $\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = I$ in pivot rows and columns

$$\begin{aligned} x_1 + 2x_2 - 2x_4 &= 0 \\ x_3 + 2x_4 &= 0 \end{aligned} \quad Rx = 0$$

$$I \rightarrow \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 2 & -2 \\ 0 & 2 \end{bmatrix} \quad \begin{matrix} \text{pivot cols} & \text{free cols} \end{matrix}$$

Signs are flipped for free variables

ref form

$$R = \begin{bmatrix} I & F \\ 0 & 0 \end{bmatrix} \quad \begin{matrix} r \text{ pivot rows} \\ \uparrow \\ r \text{ pivot cols} \end{matrix} \quad \begin{matrix} \uparrow \\ n-r \text{ free cols} \end{matrix}$$

$$Rx = 0$$

nullspace matrix N
(columns are special solutions)

$$RN=0$$

$$N = \begin{bmatrix} -F \\ I \end{bmatrix}$$

$$Rx=0$$

$$[I \ F] \begin{bmatrix} x_{\text{pivot}} \\ x_{\text{free}} \end{bmatrix} = 0$$

$$x_{\text{pivot}} = -F x_{\text{free}}$$

$$A^T = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 4 & 6 \\ 2 & 6 & 8 \\ 2 & 8 & 10 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 3 \\ 0 & 0 & 0 \\ 0 & 2 & 2 \\ 0 & 4 & 4 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 3 \\ 0 & 2 & 2 \\ 0 & 0 & 0 \\ 0 & 4 & 4 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 3 \\ 0 & 2 & 2 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} = U$$

Rank $r=2$
again!

$\uparrow \uparrow \uparrow$
pivot free
cols cols

$$n-r=3-2=1$$

set free var to 1

$$x = \begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix}$$

$$x_1 + 2x_2 + 3x_3 = 0 \Rightarrow x_1 = -1$$

$$2x_2 + 2x_3 = 0 \Rightarrow x_2 = -1$$

$$C \begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix} = N(A^T) = \text{a line in } \mathbb{R}^3$$

$$\begin{bmatrix} 1 & 2 & 3 \\ 0 & 2 & 2 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \xrightarrow{I \ F} \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} = R$$

$$C \begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix} = C \begin{bmatrix} -F \\ I \end{bmatrix} \xrightarrow{N}$$

Lecture 8

Complete Solution of $Ax=b$

Rank r

$r < n$: Solution exists

$r = n$: Solution is unique

$$x_1 + 2x_2 + 2x_3 + 2x_4 = b_1$$

$$2x_1 + 4x_2 + 6x_3 + 8x_4 = b_2$$

$$3x_1 + 6x_2 + 8x_3 + 10x_4 = b_3$$

$$\left[\begin{array}{cccc|c} 1 & 2 & 2 & 2 & b_1 \\ 2 & 4 & 6 & 8 & b_2 \\ 3 & 6 & 8 & 10 & b_3 \end{array} \right] \rightarrow \left[\begin{array}{cccc|c} 1 & 2 & 2 & 2 & b_1 \\ 0 & 0 & 2 & 4 & b_2 - 2b_1 \\ 0 & 0 & 2 & 4 & b_3 - 3b_1 \end{array} \right]$$

Augmented matrix $[A \ b]$

\uparrow pivot cols \uparrow

$$\left[\begin{array}{cccc|c} 1 & 2 & 2 & 2 & b_1 \\ 0 & 0 & 2 & 4 & b_2 - 2b_1 \\ 0 & 0 & 0 & 0 & b_3 - b_2 - b_1 \end{array} \right]$$

$$0 = b_3 - b_2 - b_1$$

$$b = \begin{bmatrix} 1 \\ 5 \\ 6 \end{bmatrix}$$

$$\rightarrow \left[\begin{array}{cccc|c} 1 & 2 & 2 & 2 & 1 \\ 0 & 0 & 2 & 4 & 3 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right]$$

$$b = \begin{bmatrix} 1 \\ 5 \\ 6 \end{bmatrix} \text{ is OK}$$

Solvability: Condition on b $Ax=b$ is solvable iff $b \in C(A)$ If a combination of the rows of A gives a zero row, then the same combination of the entries of b must give 0.To find the complete solution to $Ax=b$ ① $X_{\text{particular}}$: Set all free variables to zero. Solve $Ax=b$ for pivot variables
 $x_2=0, x_4=0$

$$x_1 + 2x_3 = 1$$

$$2x_3 = 3 \Rightarrow x_3 = 3/2 \text{ and } x_1 = -2$$

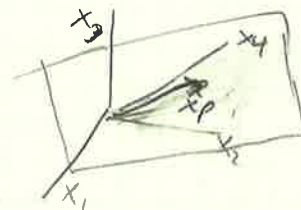
$$X_p = \begin{bmatrix} -2 \\ 0 \\ 3/2 \\ 0 \end{bmatrix}$$

② $X_{\text{nullspace}} (X_n)$ ③ Complete solution $X = X_p + X_n$

$$\begin{aligned} Ax_p &= b \\ + Ax_n &= 0 \end{aligned}$$

$$A(X_p + X_n) = b$$

$$X = \begin{bmatrix} -2 \\ 0 \\ 3/2 \\ 0 \end{bmatrix} + C_1 \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \end{bmatrix} + C_2 \begin{bmatrix} 2 \\ 0 \\ -2 \\ 1 \end{bmatrix}$$

Plot all solutions x in \mathbb{R}^4 

Solution is not a subspace

 m by n matrix A of rank r (know $r \leq m, r \leq n$)Full column rank means $r=n$: no free variables $N(A) = \{0\}$, Solution to $Ax=b$: $X=X_p$ unique if it exists

either 0 or 1 solutions.

$$A = \begin{bmatrix} 1 & 3 \\ 2 & 1 \\ 6 & 1 \\ 5 & 1 \end{bmatrix} \rightarrow R = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \\ 0 & 0 \end{bmatrix} \text{ if } b = \begin{bmatrix} 4 \\ 3 \\ 7 \\ 6 \end{bmatrix} \Rightarrow x_p = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

Full row rank means $r=m$: m pivotsCan solve $Ax=b$ for every b ExistsLeft with $n-r$ free variables ($n-m$)

$$A = \begin{bmatrix} 1 & 2 & 6 & 5 \\ 3 & 1 & 1 & 1 \end{bmatrix} \text{ rank } r=2, R = \begin{bmatrix} 1 & 0 & - & - \\ 0 & 1 & - & - \end{bmatrix}$$

$$r=m=n \text{ (Invertible)}$$

$$A = \begin{bmatrix} 1 & 2 \\ 3 & 1 \end{bmatrix} \quad R = I \quad N(A) = \{0\}$$

b can be anything

$$r=m=n \\ R=I \\ 1 \text{ solution} \\ \text{to } Ax=b$$

$$r=n < m \\ R = \begin{bmatrix} I \\ 0 \end{bmatrix} \\ 0 \text{ or } 1 \text{ solution} \\ \text{to } Ax=b$$

$$r=m < n \\ R = \begin{bmatrix} I & F \end{bmatrix} \text{ columns mixed} \\ \infty \text{ solutions to } Ax=b$$

$$r < m, r < n$$

$$R = \begin{bmatrix} I & F \\ 0 & 0 \end{bmatrix} \text{ columns mixed} \\ 0 \text{ or } \infty \text{ solutions to } Ax=b$$

Lecture 9

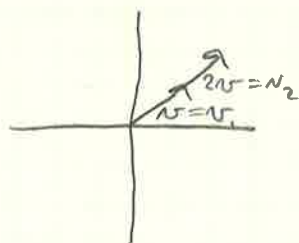
Linear independence
Spanning a space
Basis and dimension

Suppose A is m by n with $m < n$, then there are nonzero solutions to $Ax=0$.
More unknowns than equations

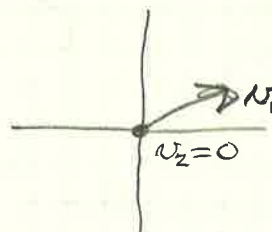
Reason: There will be at least one free variable!! ($n-m$ free variables)

Independence Vectors x_1, x_2, \dots, x_n are linearly independent if no combination gives the zero vector except for the zero combination (all $c_i=0$)

$$c_1 x_1 + c_2 x_2 + \dots + c_n x_n \neq 0 \text{ for all } c_i \neq 0$$



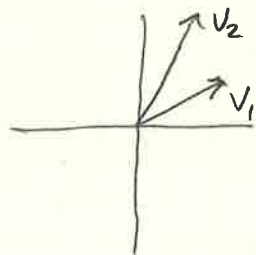
$$2v_1 - v_2 = 0 \\ \text{dependent}$$



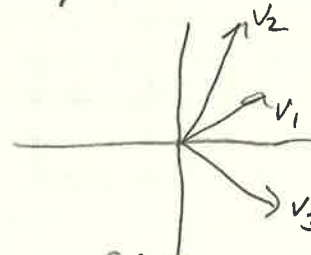
$$0v_1 + cv_2 = 0$$

$$v_2 = 0$$

If any of the v_i are 0, then they are dependent



independent



dependent

$$A = [v_1 \ v_2 \ v_3] \\ = \begin{bmatrix} 2 & 1 & 2.5 \\ 1 & 2 & -1 \end{bmatrix}$$

dependence $\Leftrightarrow N(A)$ is more than $\{0\}$

$$\begin{bmatrix} 2 & 1 & 2.5 \\ 1 & 2 & -1 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Repeat when v_1, \dots, v_n are columns of A . They are independent if $N(A)$ is $\{0\}$. They are dependent if $AC=0$ for some nonzero $C \in N(A)$.
 $\text{rank} = n$ and $N(A) = \{0\}$ for independence.
 $\text{rank} < n$ and yes free variables \Leftrightarrow dependence

Spanning a Space

Vectors v_1, \dots, v_k span a space means that the space consists of all combinations of those vectors.

A Basis for a vector space is a sequence of vectors v_1, v_2, \dots, v_k with 2 properties:

- ① They are independent
- ② They span the space

Example:

Space is \mathbb{R}^3 :

One basis is: $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$ $c_1 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + c_2 \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + c_3 \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} = 0$ iff $c_1 = c_2 = c_3 = 0$

$$A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = I, N(I) = \{0\}$$

Another basis $\begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 2 \\ 2 \\ 5 \end{bmatrix}, \begin{bmatrix} 3 \\ 3 \\ 8 \end{bmatrix}$, $A = \begin{bmatrix} 1 & 2 & 3 \\ 1 & 2 & 3 \\ 2 & 5 & 8 \end{bmatrix}$ matrix must be square and invertible

\mathbb{R}^n : n vectors give a basis if the $n \times n$ matrix with those columns is invertible.

Are $\begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 2 \\ 2 \\ 3 \end{bmatrix}$ a basis for any space? They are independent and span a plane
 So yes



Bases are not unique, but they all have the same number of vectors.

Given a space, every basis for the space has the same number of vectors.
 The number is the dimension of the space.

Examples: $C(A)$

$$A = \begin{bmatrix} 1 & 2 & 3 & 1 \\ 1 & 1 & 2 & 1 \\ 1 & 2 & 3 & 1 \end{bmatrix} \quad \begin{bmatrix} -1 \\ -1 \\ 1 \\ 0 \end{bmatrix} \in N(A) \Rightarrow \text{the columns span but are not independent}$$

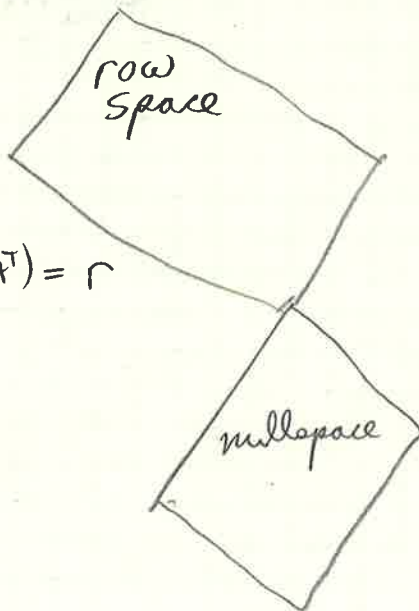
$\uparrow \uparrow \quad \uparrow \uparrow$
 pivot free
 cols

$\text{rank } A = 2$

1) Correct error in Lecture 9

2) Four fundamental subspaces (for matrix A)Example space is \mathbb{R}^3 (from lecture 9)
 $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$ standard basis

Another basis

 $\begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 2 \\ 2 \\ 5 \end{bmatrix}, \begin{bmatrix} 3 \\ 3 \\ 8 \end{bmatrix}$
 $A = \begin{bmatrix} 1 & 2 & 3 \\ 1 & 2 & 3 \\ 2 & 5 & 8 \end{bmatrix}$ is Not invertible
(two equal rows)
4 Fundamental SubspacesColumn space $C(A) \in \mathbb{R}^m$ A is $m \times n$ Nullspace $N(A) \in \mathbb{R}^n$
 Rowspace = all combinations of rows = all combinations of columns of A^T
 $= C(A^T) \in \mathbb{R}^n$
Nullspace of $A^T = N(A^T) =$ left nullspace of $A \in \mathbb{R}^m$ \mathbb{R}^n 

$$\dim C(A^T) = r$$



$$\dim C(A) = \text{rank} = r$$

	$C(A)$	$C(A^T)$	$N(A)$	$N(A^T)$
basis	pivot cols	see below	special solutions for each free variable	See below
dimension	r	r	$n-r$	$m-r$

number of free variables in A

of free variables in A^T

$$A = \begin{bmatrix} 1 & 2 & 3 & 1 \\ 1 & 1 & 2 & 1 \\ 1 & 2 & 3 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 3 & 1 \\ 0 & -1 & -1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\rightarrow \begin{bmatrix} 1 & 2 & 3 & 1 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 1 & 1 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} = R$$

$$C(R) \neq C(A)$$

different column spaces

Basis of row space for A
and R is first r rows
of R (not of A)

same row space

$$N(A^T) : A^T y = 0 \Rightarrow y \in N(A^T)$$

$$\begin{bmatrix} \end{bmatrix} \begin{bmatrix} \end{bmatrix} = \begin{bmatrix} 0 \end{bmatrix} \quad \text{transpose} \quad y^T A = 0^T$$

$$\begin{bmatrix} y^T \end{bmatrix} \begin{bmatrix} A \end{bmatrix} = \begin{bmatrix} 0 \end{bmatrix}$$

$$\text{ref } \begin{bmatrix} A & I_{m \times m} \end{bmatrix} \rightarrow \begin{bmatrix} R & E_{m \times m} \end{bmatrix}$$

$$\Leftrightarrow E \begin{bmatrix} A_{m \times n} & I_{m \times m} \end{bmatrix} \rightarrow \begin{bmatrix} R_{m \times n} & E_{m \times m} \end{bmatrix}$$

$$\Rightarrow EA = R$$

In Chapter 2, R was I and E was A^{-1}

$$\begin{bmatrix} 1 & 2 & 3 & 1 & 1 & 0 & 0 \\ 1 & 1 & 2 & 1 & 0 & 1 & 0 \\ 1 & 2 & 3 & 1 & 0 & 0 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 3 & 1 & 1 & 0 & 0 \\ 0 & -1 & -1 & 0 & -1 & 1 & 0 \\ 0 & 0 & 0 & 0 & -1 & 0 & 1 \end{bmatrix}$$

$$\rightarrow \begin{bmatrix} 1 & 2 & 3 & 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 0 & -1 & 0 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 1 & 1 & -1 & 2 & 0 \\ 0 & 1 & 1 & 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 0 & -1 & 0 & 1 \end{bmatrix}$$

E

$$\begin{bmatrix} -1 & 2 & 0 \\ 1 & -1 & 0 \\ -1 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 & 3 & 1 \\ 1 & 1 & 2 & 1 \\ 1 & 2 & 3 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 1 & 1 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

↑ Basis for $N(A^T)$

New vector space!

M : All 3×3 matrices!!

$A+B, CA$ (not AB for now)

Subspaces of M

{ all upper triangular
all symmetric matrices
all diagonal matrices D : $\dim D = 3$

$$\left\{ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 7 \end{bmatrix} \right\} \text{ is a basis for } D$$