

2072U Computational Science I

Winter 2022

Week	Topic
1	Introduction
1–2	Solving nonlinear equations in one variable
3–4	Solving systems of (non)linear equations
5–6	Computational complexity
6–8	Interpolation and least squares
8–10	Integration & differentiation
10–12	Additional Topics

1. Newton-Raphson iteration

2. Pseudo-code

3. Trivial test

Newton iteration can be generalized to n equations with n unknowns.

Alternative derivation in 1D:

$$f(x + \delta x) \approx f(x) + f'(x)\delta x = 0 \Rightarrow \delta x = -\frac{f(x)}{f'(x)}$$

Now in 2D. We want to find x_1 and x_2 such that

$$f_1(x_1, x_2) = 0$$

$$f_2(x_1, x_2) = 0$$

Note that, in general, we need **the same number of equations and unknowns** to find (isolated) solutions. . .

$$f_1(x_1 + \delta x_1, x_2 + \delta x_2) \approx f_1(x_1, x_2) + \frac{\partial f_1}{\partial x_1}(x_1, x_2)\delta x_1 + \frac{\partial f_1}{\partial x_2}(x_1, x_2)\delta x_2$$

$$f_2(x_1 + \delta x_1, x_2 + \delta x_2) \approx f_2(x_1, x_2) + \frac{\partial f_2}{\partial x_1}(x_1, x_2)\delta x_1 + \frac{\partial f_2}{\partial x_2}(x_1, x_2)\delta x_2$$

In matrix form:

$$\begin{pmatrix} \frac{\partial f_1}{\partial x_1}(x_1, x_2) & \frac{\partial f_1}{\partial x_2}(x_1, x_2) \\ \frac{\partial f_2}{\partial x_1}(x_1, x_2) & \frac{\partial f_2}{\partial x_2}(x_1, x_2) \end{pmatrix} \begin{pmatrix} \delta x_1 \\ \delta x_2 \end{pmatrix} = - \begin{pmatrix} f_1(x_1, x_2) \\ f_2(x_1, x_2) \end{pmatrix}$$

Problem statement: *given a function $\mathbf{f} : \mathbb{R}^n \rightarrow \mathbb{R}^n$ and an initial guess $\mathbf{x}^{(0)} \in \mathbb{R}^n$, find an approximate solution to $\mathbf{f}(\mathbf{x}) = 0$.*

The derivation of the iterative method is similar to that of Newton iteration:

$$f(x+\delta x) \approx f(x) + f'(x)\delta x = 0 \Rightarrow \delta x = -\frac{f(x)}{f'(x)} \text{ for } f(x), x, \delta x \in \mathbb{R}$$

becomes

$$\mathbf{f}(\mathbf{x}+\delta \mathbf{x}) \approx \mathbf{f}(\mathbf{x}) + D\mathbf{f}\delta \mathbf{x} = 0 \Rightarrow D\mathbf{f}\delta \mathbf{x} = -\mathbf{f}(\mathbf{x}) \text{ for } \mathbf{f}(\mathbf{x}), \mathbf{x}, \delta \mathbf{x} \in \mathbb{R}^n$$

That is, the update $\delta \mathbf{x}$ is found from the linear system:

$$D\mathbf{f}\delta \mathbf{x} = \begin{pmatrix} \partial_{x_1} f_1(\mathbf{x}) & \partial_{x_2} f_1(\mathbf{x}) & \cdots & \partial_{x_n} f_1(\mathbf{x}) \\ \partial_{x_1} f_2(\mathbf{x}) & \partial_{x_2} f_2(\mathbf{x}) & \cdots & \partial_{x_n} f_2(\mathbf{x}) \\ \vdots & \vdots & & \vdots \\ \partial_{x_1} f_n(\mathbf{x}) & \partial_{x_2} f_n(\mathbf{x}) & \cdots & \partial_{x_n} f_n(\mathbf{x}) \end{pmatrix} \begin{pmatrix} \delta x_1 \\ \delta x_2 \\ \vdots \\ \delta x_n \end{pmatrix} = - \begin{pmatrix} f_1(\mathbf{x}) \\ f_2(\mathbf{x}) \\ \vdots \\ f_n(\mathbf{x}) \end{pmatrix}$$

Function NewtonSystem

Input:

Output:

Initializations:

- 1.
2. For $k =$
 - Evaluate the residual vector:
 - a. Evaluate the Jacobian:
 - b. Solve the linear system:
 - c. Update the solution:
 - d. Check for convergence:
 - e.
- end for

First test problem:

$$f_1(x_1, x_2) = 2 \exp(x_1 x_2) - 2x_1 + 2x_2 - 2 = 0$$

$$f_2(x_1, x_2) = x_1^5 + x_1 x_2^5 - 2x_2 = 0$$

with the exact solution $\mathbf{x}^* = (0, 0)^t$. In matrix form:

$$J = \begin{pmatrix} \frac{\partial f_1}{\partial x_1} & \frac{\partial f_1}{\partial x_2} \\ \frac{\partial f_2}{\partial x_1} & \frac{\partial f_2}{\partial x_2} \end{pmatrix}$$

$$J =$$