

Avoiding Pathologies in Very Deep Networks

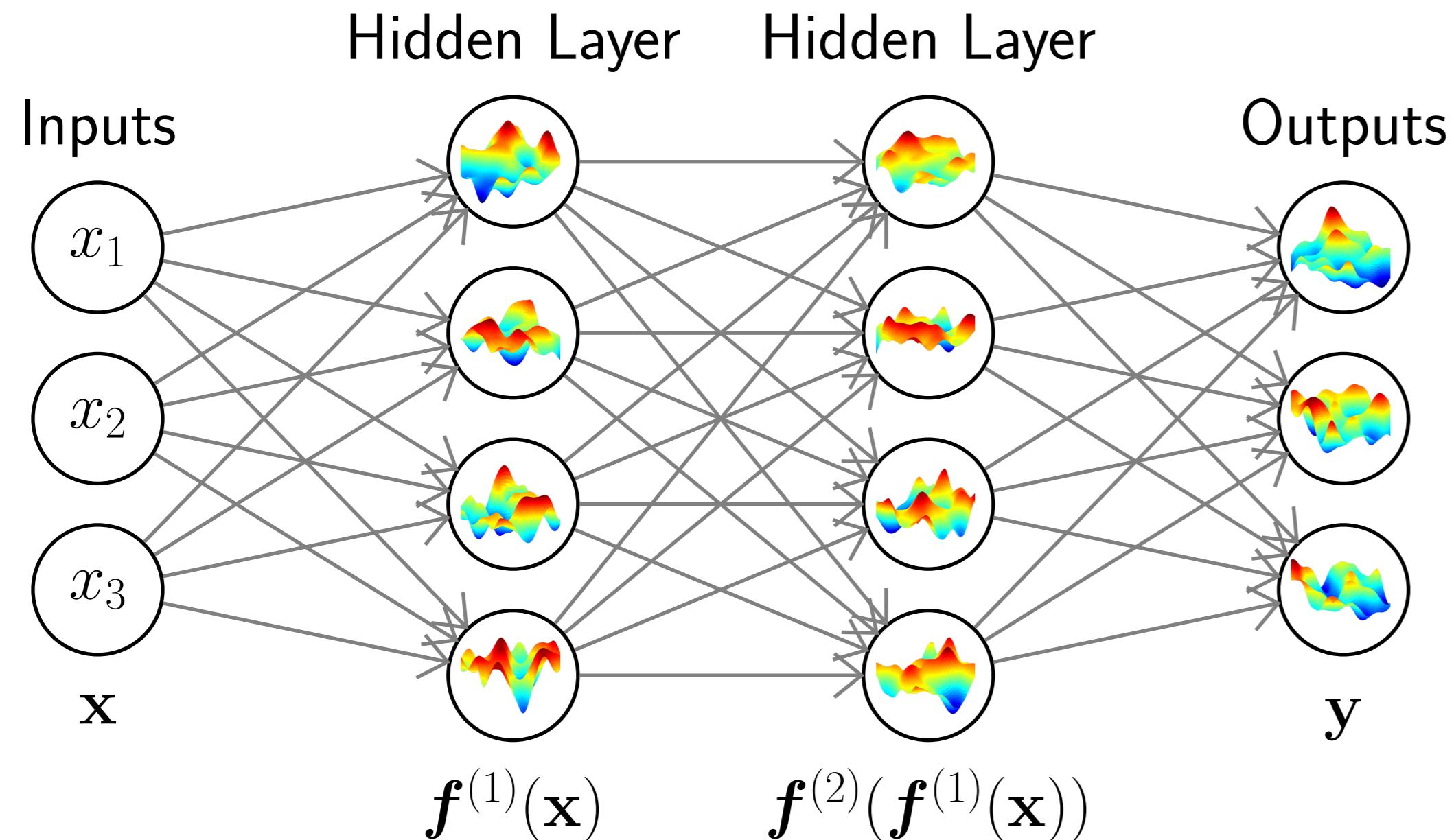
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Main Idea

- We compare network architectures by analyzing priors on deep nets.
- We characterize a pathology in standard architectures.
- A simple alternative architecture fixes the problem.

A nonparametric prior on deep neural networks

We examine deep Gaussian processes (Damianou and Lawrence, 2012)

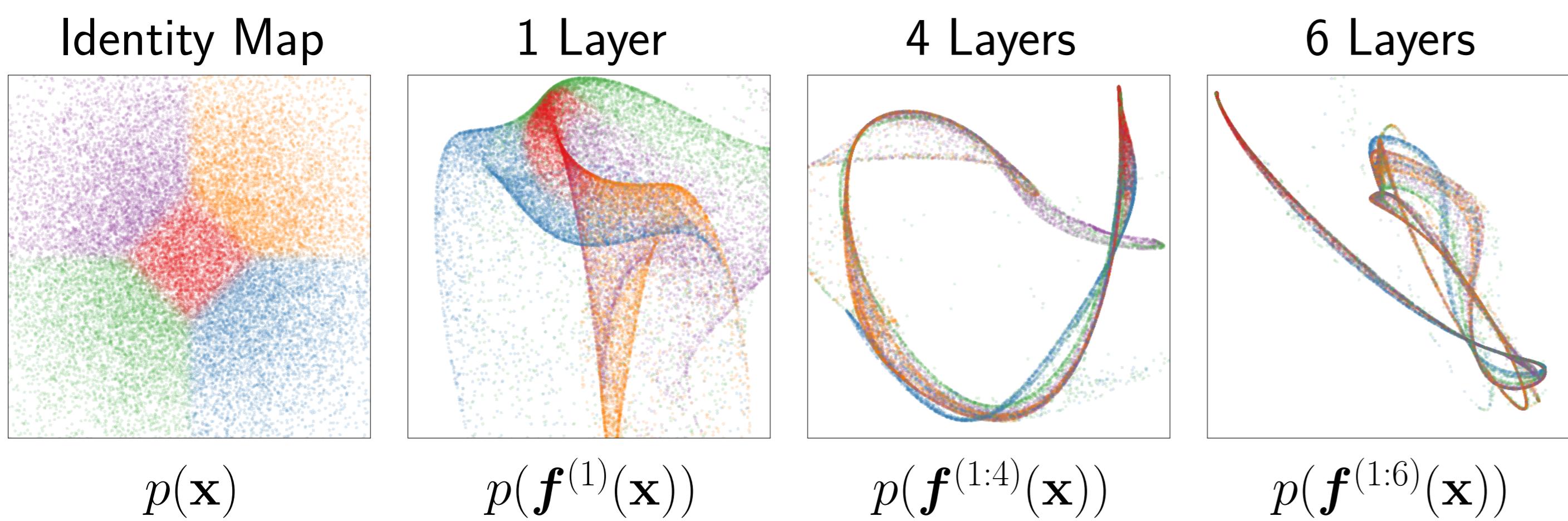


Deep GPs are compositions of functions, each $f^{(\ell)} \stackrel{\text{ind}}{\sim} \mathcal{GP}(0, k(\mathbf{x}, \mathbf{x}'))$.

$$f^{(1:L)}(\mathbf{x}) = f^{(L)}(f^{(L-1)}(\dots f^{(2)}(f^{(1)}(\mathbf{x})) \dots))$$

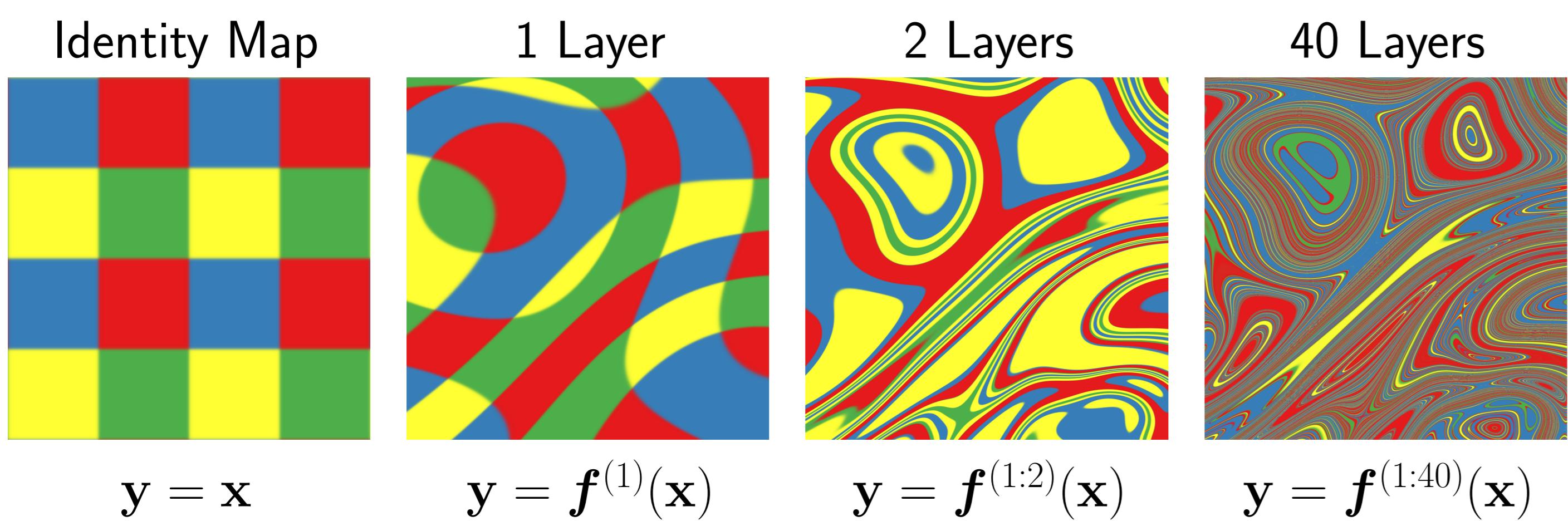
Random deep nets vary in few directions

A density warped by a deep-GP distributed function:



As depth increases, density concentrates along one-dimensional filaments.

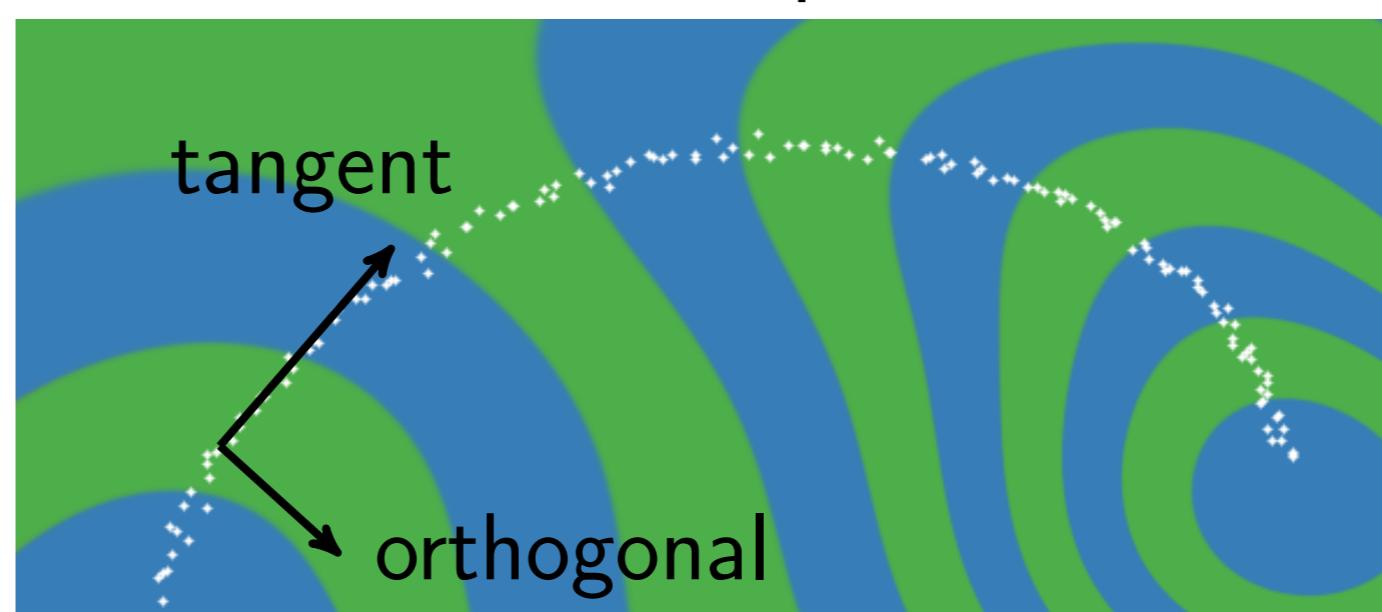
Sampled mappings illustrate properties of this prior on functions:



As depth increases, there is usually only one direction we can move \mathbf{x} to change \mathbf{y} .

Good representations vary along the data manifold

Contours of a representation

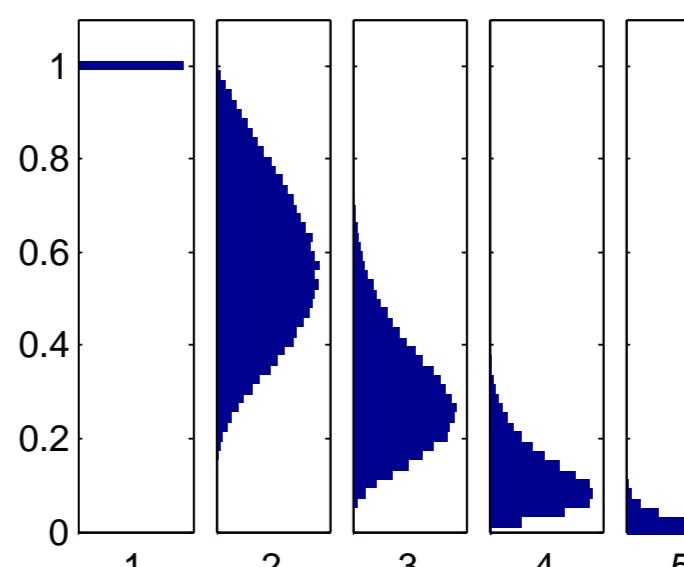


Representation $\mathbf{y} = f(\mathbf{x})$ must vary in at least as many directions as the number of dimensions of the data manifold.
(Rifai et. al., 2011)

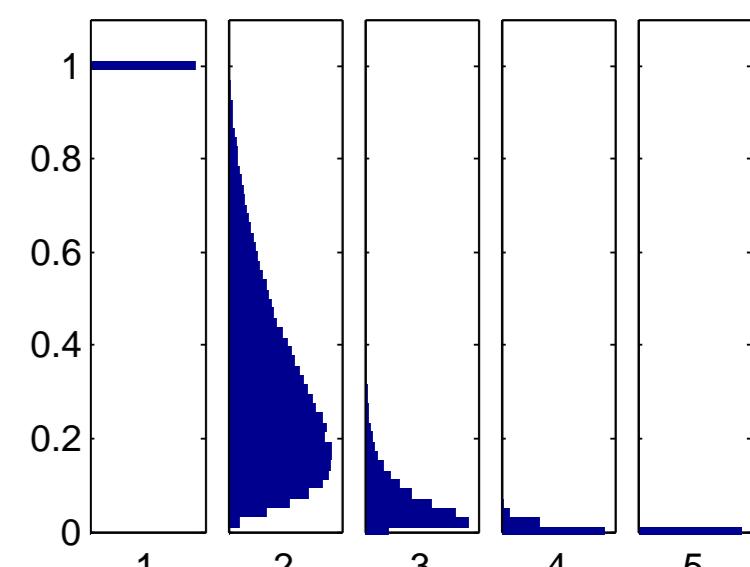
Explaining the pathology

- The Jacobian of a deep GP is a product of independent Gaussian matrices.
- Singular value spectrum shows relative size of derivatives.
- As the net deepens, the derivative in one direction becomes much larger than all the others.

2 layer spectrum



6 layer spectrum



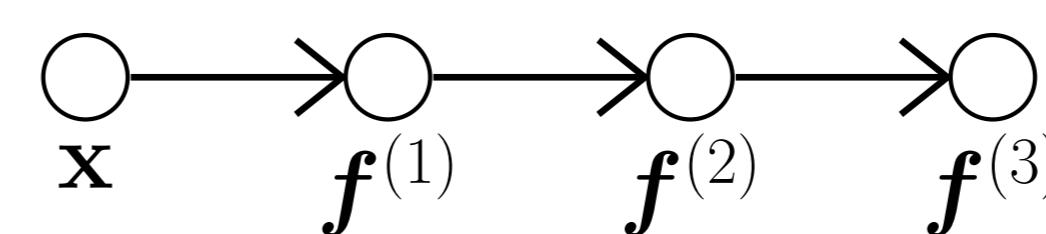
Singular values of 5D mapping

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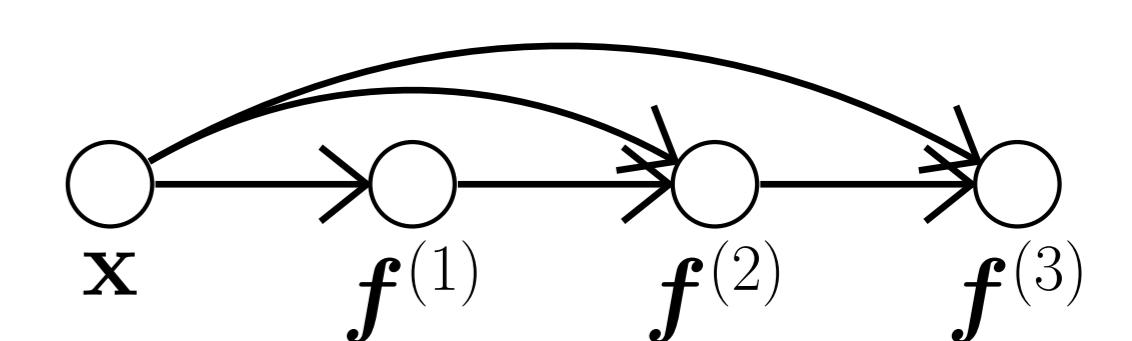
Fixing the pathology

- As in (Neal, 1995) we connect the input to every layer:

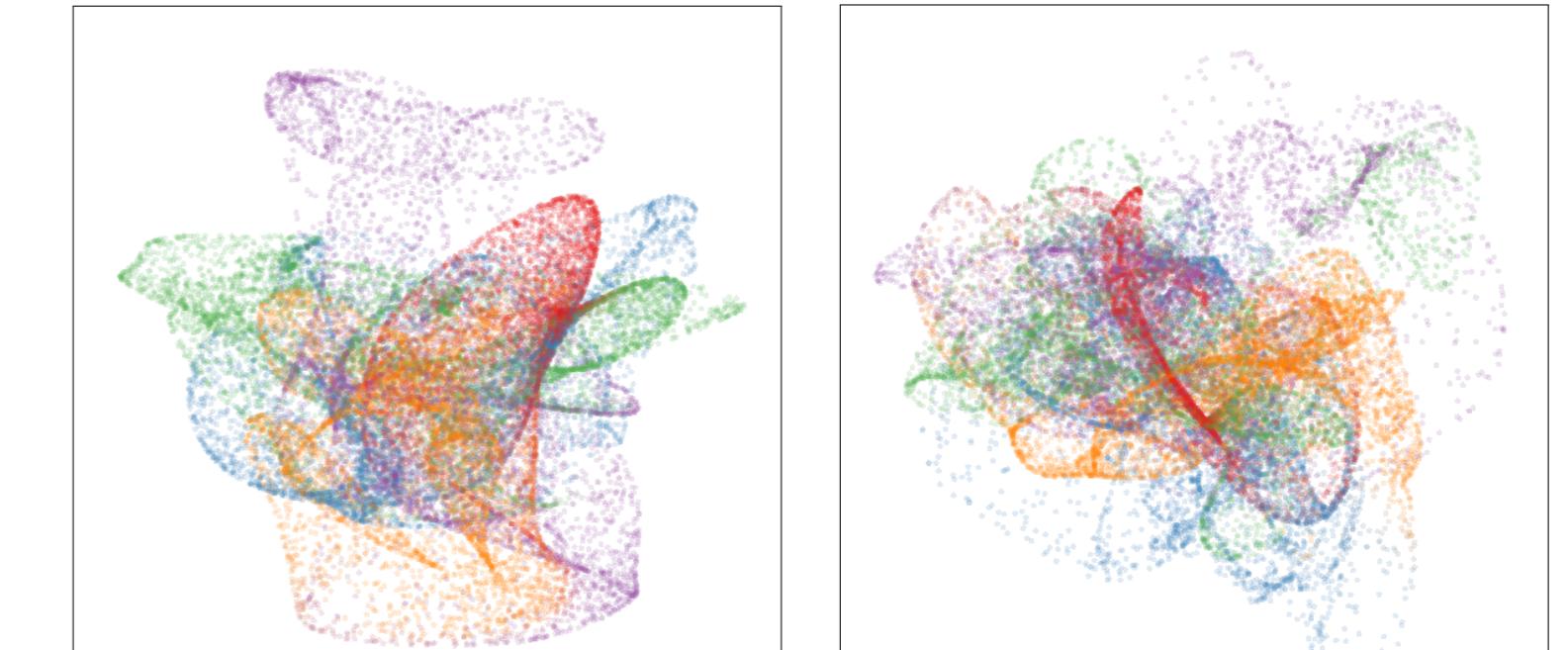
Standard deep net architecture



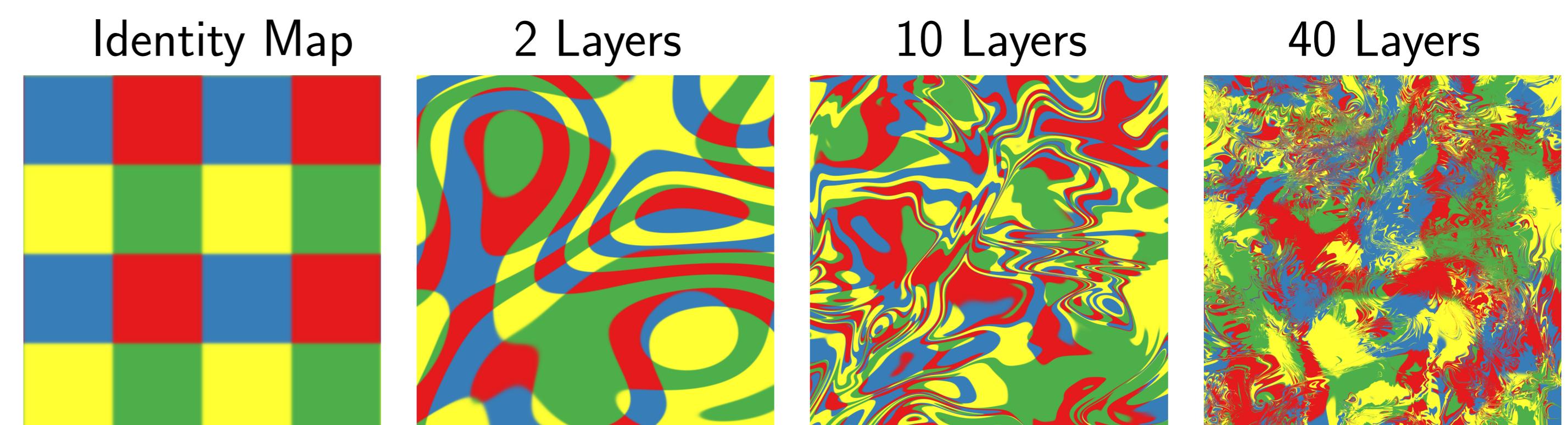
Input-connected architecture



4 Layers 5 Layers



Pathology is now resolved in deep density models: Density does not concentrate along filaments when the input connects to all layers.



Locally up to D degrees of freedom, at any depth.

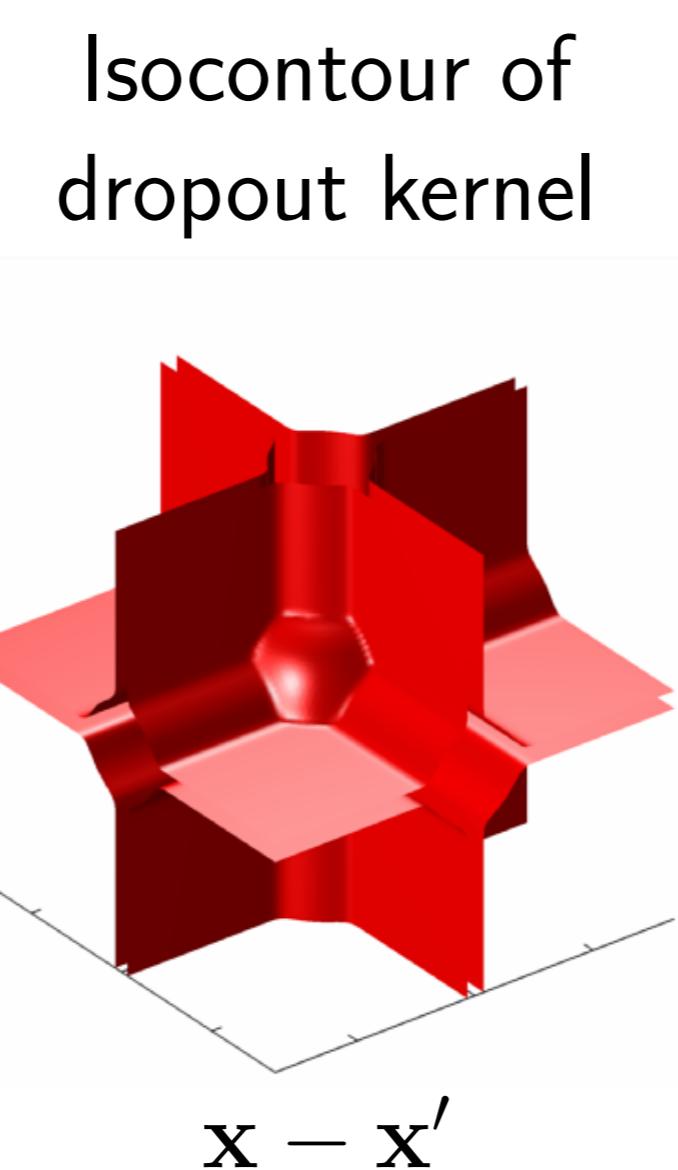
Other Results

Dropout in Gaussian processes

- GPs are infinitely-wide shallow nets.
- Dropping out hidden units has no effect!
- Dropping out inputs gives a mixture of GPs, with tractable covariance:

$$\text{Cov}[f(\mathbf{x}'), f(\mathbf{x})] = \frac{1}{2^D} \sum_{\mathbf{R} \in \{0,1\}^D} \prod_{d=1}^D k_d(\mathbf{x}_d, \mathbf{x}'_d)^{r_d}$$

- Same as additive GPs (Duvenaud et. al. 2011)



Infinitely deep kernels

- Kernels correspond to feature mappings:

$$k_1(\mathbf{x}, \mathbf{x}') = \mathbf{h}(\mathbf{x})^\top \mathbf{h}(\mathbf{x}')$$

- Can compose feature maps to get deep kernels:
(Cho, 2012)

$$k_2(\mathbf{x}, \mathbf{x}') = \mathbf{h}(\mathbf{h}(\mathbf{x}))^\top \mathbf{h}(\mathbf{h}(\mathbf{x}'))$$

Paper at arxiv.org/abs/1402.5836

Code at github.com/duvenaud/deep-limits

Deep connected kernel
 $k_\infty(\mathbf{x}, \mathbf{x}') = \log(k_\infty(\mathbf{x}, \mathbf{x})) + 1 + \frac{1}{2} \|\mathbf{x} - \mathbf{x}'\|_2^2$

