view frames Result Recorded at time: 17.579 map Broadcaster: /slam gmapping Average rate: $2\overline{0}.20\overline{2}$ Buffer length: 4.95 Most recent transform: 17.617 Oldest transform: 12.667 odom Broadcaster: /gazebo Average rate: 30.205 Buffer length: 4.966 Most recent transform: 17.563 Oldest transform: 12.597 base footprint Broadcaster: /publisher state Average rate: 10000.0 Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 base link Broadcaster: /publisher state Broadcaster: /robot_state_publisher_turtlebot3 Broadcaster: /publisher state | Broadcaster: /publisher state Broadcaster: /robot state publisher turtlebot3 Average rate: 10000.0 Average rate: 10000.0 Average rate: 4.966 Average rate: 10000.0 Average rate: 4.966 Buffer length: 0.0 Buffer length: 0.0 Buffer length: 0.0 Buffer length: 4.833 Buffer length: 4.833 Most recent transform: 0.0 Most recent transform: 17.531 Most recent transform: 0.0 Most recent transform: 17.531 Most recent transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 Oldest transform: 12.698 Oldest transform: 12.698 imu_link caster back link wheel left link wheel_right_link base_scan