# Machine Learning Approach

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## ML approach

- Most data mining algorithms try to summarize the data to help decision making.
- "Machine learning" algorithms not only summarize the data, but also provide a model to reason about future data.
  - Unsupervised learning: building a model from data without "label".
  - Supervised learning: building a model from data with labels.

## Supervised Learning

Data is given as a set of pairs  $\{x, y\}$  where:

- x is a vector of *features*. Each feature could be *categorical* (such as {red, green, blue}) or *numerical*.
- y is the label. The value of y could be anything.

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  - ▶ If y is a discrete value  $\Rightarrow$  classification problem.

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We typically split the data into two sets: a training set and a test set.

- The training set is used to train the model, i.e, find parameters of the model.
- The test set is used to test the performance of the trained model.

Why do we need to do so?

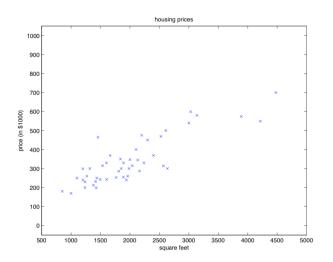
Let's start with (linear) regression.

# Linear Regression - A Motivating Example<sup>1</sup>

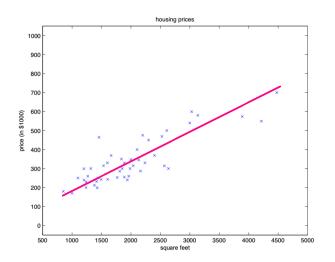
Living area (feet <sup>2</sup> )	Price (1000\$)
1204	400
1600	330
2400	369
1416	232
3000	540

<sup>&</sup>lt;sup>1</sup>From Andrew Ng note http://cs229.stanford.edu/notes/cs229-notes1.pdf

### Linear Regression - A Motivating Example



### Linear Regression - A Motivating Example



## Linear Regression - A Toy Example

Given four points (1,2), (2,1), (3,4), (4,3), find a line  $y=a \cdot x+b$  that best fits these points.

Here best fit means the sum of squares of vertical off-sets is minimum:

$$f(a,b) = (a+b-2)^2 + (2a+b-1)^2 + (3a+b-4)^2 + (4a+b-3)^2$$
(1)

# Optimization by solving equations

#### Solving Equation Approach

A (local) minimizer  $\mathbf{w}_0$  of a differentiable function f(.) satisfies:

$$\nabla f(\mathbf{w}_0) = 0 \tag{2}$$

Recall that given a differentiable function:

$$f: \mathbb{R}^d \to \mathbb{R}$$

$$\mathbf{w} \mapsto f(\mathbf{w})$$
(3)

Then:

$$\nabla f = \begin{bmatrix} \partial f/\partial w_1 \\ \partial f/\partial w_2 \\ \dots \\ \partial f/\partial w_d \end{bmatrix} \tag{4}$$

### Back to our toy example

Find (a, b) that minimizes:

$$f(a,b) = (a+b-2)^2 + (2a+b-1)^2 + (3a+b-4)^2 + (4a+b-3)^2$$

## Back to our toy example

Find (a, b) that minimizes:

$$f(a,b) = (a+b-2)^2 + (2a+b-1)^2 + (3a+b-4)^2 + (4a+b-3)^2$$
$$\frac{\partial f(a,b)}{\partial a} = 60a + 20b - 56$$
$$\frac{\partial f(a,b)}{\partial b} = 20a + 8b - 20$$

Solving  $\nabla f(.) = 0$ , we get a = 3/5, b = 1.

You are given a set of n data points  $\mathcal{D} = \{(\mathbf{x}_1, y_1), \mathbf{x}_2, y_y), \dots, (\mathbf{x}_n, y_n)\}$  where each  $\mathbf{x}_i \in \mathbb{R}^d$  and  $y_i \in \mathbb{R}$ . Find a hyperplane  $y = \mathbf{w}^t \mathbf{x} + w_0$  such that:

$$J(\mathbf{w}) = \frac{1}{2} \sum_{i=1}^{n} (y_i - \mathbf{w}^T \mathbf{x}_i - w_0)^2$$

is minimized.

Before we go into details of solving equations, we will "clean it up".

1st trick:

- add an extra dimension d+1 and add 1 to each  $\mathbf{x}_i$  in the new dimension so that  $\mathbf{x}_i$  becomes  $\begin{bmatrix} \mathbf{x}_i \\ 1 \end{bmatrix}$ .
- $ext{2}$  also  $extbf{w}$  becomes  $extbf{w}_0$

That implies:  $y = \mathbf{w}^T \mathbf{x} + w_0$  is equivalent to  $y = \mathbf{w}^T \mathbf{x}$  in the new space.

$$J(\mathbf{w}) = \frac{1}{2} \sum_{i=1}^{n} (y_i - \mathbf{w}^T \mathbf{x}_i)$$
 (5)

in the new space.

2nd trick: write  $J(\mathbf{w})$  in matrix-vector notation:

$$\mathbf{X} = \begin{bmatrix} \mathbf{x}_1^T & \mathbf{x}_2^T \\ \mathbf{x}_2^T & \mathbf{x}_n^T \\ \vdots & \ddots \\ \mathbf{x}_n^T & \mathbf{x}_n^T \end{bmatrix}$$
(6)

$$J(\mathbf{w}) = \frac{1}{2} (\mathbf{X} \mathbf{w} - \mathbf{y})^{T} (\mathbf{X} \mathbf{w} - \mathbf{y})$$
 (7)

3nd trick: traces and matrix derivatives.

• If 
$$A = [A_{ij}]_{n \times n}$$
, then  $Tr(A = \sum_i A_{ii})$ .

$$\operatorname{Tr}(a) = a \quad a \in \mathbb{R}$$
 $\operatorname{Tr}(aB) = a\operatorname{Tr}(B) \quad a \in \mathbb{R}$ 
 $\operatorname{Tr}(A+B) = \operatorname{Tr}(A) + \operatorname{Tr}(B)$ 
 $\operatorname{Tr}(AB) = \operatorname{Tr}(BA)$ 
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$$\nabla_{A} \operatorname{Tr}(AB) = B^{T}$$

$$\nabla_{A} \operatorname{Tr}(ABA^{T}C) = CAB + C^{T}AB^{T}$$

$$\nabla_{A^{T}} f(A) = (\nabla_{A} f(A))^{T}$$
(9)

Apply the 3nd trick to  $J(\mathbf{w})$ :

$$J(\mathbf{w}) = \frac{1}{2} (\mathbf{X} \mathbf{w} - \mathbf{y})^{T} (\mathbf{X} \mathbf{w} - \mathbf{y})$$

$$\Rightarrow \nabla_{\mathbf{w}} J(\mathbf{w}) = \mathbf{X}^{T} \mathbf{X} \mathbf{w} - \mathbf{X}^{T} \mathbf{y}$$
(10)

(See the board calculation)

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Solving  $\nabla_{\mathbf{w}} J(\mathbf{w}) = 0$  (so-called the *normal equation*), we get:

$$\mathbf{w} = (\mathbf{X}^{\mathsf{T}}\mathbf{X})^{-1}(\mathbf{X}^{\mathsf{T}}y) \tag{11}$$

Running time and memory?

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Running time and memory?

- Running time  $O(d^3 + d^2n)$
- Memory:  $O(d^2 + nd)$

### Optimization by Gradient Descent

minimize 
$$f(\mathbf{x})$$
 (12)

where  $f: \mathbb{R}^d \to \mathbf{R}$  is differentiable.

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```
\begin{split} & \text{GradientDescent}(f(.)) \\ & \text{initialize value for } \mathbf{w} \text{ randomly} \\ & \text{choose a small constant } \eta \\ & \text{repeat} \\ & \mathbf{w} \leftarrow \mathbf{w} - \eta \nabla_{\mathbf{w}} f(\mathbf{w}) \\ & \text{until a chosen convergent criterion satisfied} \end{split}
```

## Back to Multivariate Linear Regression

We have:

$$J(\mathbf{w}) = \frac{1}{2n} (\mathbf{X}\mathbf{w} - \mathbf{y})^T (\mathbf{X}\mathbf{w} - \mathbf{y})$$
$$\nabla_{\mathbf{w}} J(\mathbf{w}) = \frac{1}{n} \mathbf{X}^T \mathbf{X} \mathbf{w} - \mathbf{X}^T \mathbf{y}$$

Note here that we add the factor  $\frac{1}{n}$  to  $J(\mathbf{w})$  to for numerical stability.

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GRADIENT DESCENT (f(.))initialize  $\mathbf{w}$  randomly
choose a small constant  $\eta$ repeat  $\mathbf{w} \leftarrow \mathbf{w} - \frac{\eta}{n} (\mathbf{X}^T \mathbf{X} \mathbf{w} - \mathbf{X}^T \mathbf{y})$ until a chosen convergent criterion satisfied

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Running time and memory?

- Running time  $O(Td^2n)$  where T is the number of updates.
- Memory: O(dn).

Let's look back to the original form of  $J(\mathbf{w})$ 

$$J(\mathbf{w}) = \frac{1}{2n} \sum_{i=1}^{n} (y_i - \mathbf{w}^T \mathbf{x}_i)^2$$

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We have:

$$\frac{\partial J(\mathbf{w})}{\partial w_j} = \frac{1}{n} \sum_{i=1}^n (y_i - \mathbf{w}^T \mathbf{x}_i) \mathbf{x}_i[j]$$
$$= \frac{1}{n} \sum_{i=1}^n (y_i - \hat{y}_i) \mathbf{x}_i[j]$$

where  $\hat{y}_i = \mathbf{w}^T \mathbf{x}_i$  is the predicted version of  $y_i$ .

```
GRADIENTDESCENT(f(.))
initialize \mathbf{w}_0 randomly
choose a small constant \eta
repeat
\mathbf{for}\ j \leftarrow 1\ \text{to}\ d+1
\mathbf{w}[j] \leftarrow \mathbf{w}[j] - \frac{\eta}{n}(\sum_{i=1}^n (y_i - \hat{y}_i)\mathbf{x}_i[j]
until a chosen convergent criterion satisfied
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Running time and memory and passes?

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Question: Can we reduce T?

Let's look closer at  $J(\mathbf{w})$ 

$$J(\mathbf{w}) = \frac{1}{2n} \sum_{i=1}^{n} (y_i - \mathbf{w}^T \mathbf{x}_i)^2$$

Which can be written as:

$$J(\mathbf{w}) = \frac{1}{n} \sum_{i=1}^{n} L_{\mathbf{w}}(\mathbf{x}_i)$$

where  $L_{\mathbf{w}}(\mathbf{x}_i) = (y_i - \mathbf{w}^T \mathbf{x}_i)^2$  which is the loss contributed by data point i. Thus, we can think of  $J(\mathbf{w})$  as:

$$J(\mathbf{w}) = \mathrm{E}_{\mathbf{x} \sim \mathcal{D}}[L_{\mathbf{w}}(\mathbf{x})]$$

In short,

$$J(\mathbf{w}) = \frac{1}{n} \sum_{i=1}^{n} L_{\mathbf{w}}(\mathbf{x}_{i})$$

$$= \mathbf{E}_{\mathbf{x} \sim \mathcal{D}}[L_{\mathbf{w}}(\mathbf{x})]$$
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(13)

Suppose that you take m random samples  $\mathbf{x}_1', \dots, \mathbf{x}_m'$  from  $\mathcal{D}$  and calculate:

$$\mu = \frac{1}{m} \sum_{i=1}^{m} L_{\mathbf{w}}(\mathbf{x}'_i) \tag{14}$$

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We have:

$$E[\mu] = \frac{1}{m} \sum_{i=1}^{m} E[L_{\mathbf{w}}(\mathbf{x}'_{i})] = \frac{1}{m} \sum_{i=1}^{m} E_{\mathbf{x} \sim \mathcal{D}}[L_{\mathbf{w}}(\mathbf{x})] = E_{\mathbf{x} \sim \mathcal{D}}[L_{\mathbf{w}}(\mathbf{x})]$$
(15)

4D > 4B > 4B > 4B > 900

## SGD for Multivariate Linear Regression

```
STOCHASTICGRADIENTDESCENT(f(.))
      initialize \mathbf{w}_0 randomly
      choose a small constant \eta
      choose m
      repeat
             Divide the data set into \frac{n}{m} random parts of size m
             for each part \mathcal{D}_i
                    for i \leftarrow 1 to d+1
                          \mathbf{w}[j] \leftarrow \mathbf{w}[j] - \frac{\eta}{m} (\sum_{\mathbf{x}_p \in \mathcal{D}_i} (y_p - \hat{y}_p) \mathbf{x}_p[j])
      until a chosen convergent criterion satisfied
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Running time and memory and passes?

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#### Running time and memory and passes?

- Running time  $O(Td^2n)$  where T is the number of epoches.
- ullet Memory: O(d) amd we pass through the data T times.
- The number of parameter updates is  $T\frac{n}{m}$ . In practice,  $m=2^r$  where  $0 \le r \le 10$ .

For very large data set, even  $T \in [1, 20]$  suffices.

## When to stop SGD?

There is no single good criteria as the stopping condition. Several choices are:

- Set a threshold T on the number of epochs.
- When the training loss is not reduced by much after several epochs.
- When the (batch) gradient is sufficiently smaller than a threshold.
- When validation error (require splitting data into {training, validation, testing}) is not reduced after several epochs.
- And many more.