

# Lecture 9: The GMM Estimator - Part I

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# Intro

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## Example I: Consumption-Based Asset Pricing (Part 1)

### The Model:

A representative agent maximizes expected lifetime utility:

$$\max_{\{C_t\}_t^{\text{inf}}} E_0 \sum_{t=0}^{\infty} \beta^t u(C_t)$$

subject to the budget constraint:

$$W_{t+1} = (1 + r_{t+1})(W_t - C_t)$$

where:

- **Endogenous variables:**  $C_t$  (consumption),  $W_t$  (wealth)
- **Exogenous variables:**  $r_{t+1}$  (gross return on assets, observable)
- **Parameters:**  $\beta$  (discount factor),  $\gamma$  (risk aversion coefficient)



## Example I: Consumption-Based Asset Pricing (Part 2)

**First-order condition (Euler equation):**

$$u'(C_t) = \beta E_t[(1 + r_{t+1})u'(C_{t+1})]$$

With CRRA utility  $u(C) = \frac{C^{1-\gamma}}{1-\gamma}$ , we have  $u'(C) = C^{-\gamma}$ :

$$C_t^{-\gamma} = \beta E_t[(1 + r_{t+1})C_{t+1}^{-\gamma}]$$

**Moment conditions:**

$$E_t \left[ \underbrace{\beta(1 + r_{t+1}) \left( \frac{C_{t+1}}{C_t} \right)^{-\gamma} - 1}_{\equiv h_{Macro}(\text{parameters, data})} \right] = 0 \implies \mathbb{E}[h_{Macro}(\text{parameters, data})] = 0$$



## Example II: Discrete Choice - Binary Logit Model (Part 1)

### The Model:

Individual  $i$  chooses between two products ( $j = 0, 1$ ). The utility from product  $j$  is:

$$U_{ij} = X_j' \beta_i + \varepsilon_{ij}$$

where:

- $X_j$  are observed product characteristics (e.g., price, quality, features)
- $\beta_i$  are preference parameters for individual  $i$  (potentially heterogeneous)
- $\varepsilon_{ij}$  are i.i.d. Type-I extreme value distributed (some weird stuff IO people like);

Individual chooses product 1 if  $U_{i1} > U_{i0}$ . Normalize  $X_0 = 0$  (outside option).



## Example II: Discrete Choice - Binary Logit Model (Part 2)

**Choice probability:** Let  $Y_i$  be the decision taken by individual  $i$ ;

$$P(Y_i = 1|X_1, \beta_i) = \frac{\exp(X_1' \beta_i)}{1 + \exp(X_1' \beta_i)} \equiv \Lambda(X_1' \beta_i)$$

where  $\Lambda(\cdot)$  is the logistic CDF and  $Y_i = 1$  if individual  $i$  chooses product 1.



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where  $\Lambda(\cdot)$  is the logistic CDF and  $Y_i = 1$  if individual  $i$  chooses product 1.

**Moment condition:** Assume  $\beta_i = \beta$  (homogeneous preferences).

Define the “error” as  $\eta_i = Y_i - \Lambda(X_1' \beta)$ . Under correct specification:

$$E[\eta_i|X_1] = 0$$

This implies:

$$\underbrace{E[X_1 \cdot (Y_i - \Lambda(X_1' \beta))]}_{\equiv h_{IO}(\text{parameters}, \text{data})} = 0 \implies \mathbb{E}[h_{IO}(\text{parameters}, \text{data})] = 0$$



## Example III: Mean-Variance Portfolio Choice (Part 1)

### The Model:

An investor allocates wealth between a risky asset (stock) and a risk-free asset (bond). The optimal portfolio weight  $w$  on the risky asset solves:

$$\max_w E[R_p] - \frac{\lambda}{2} \text{Var}(R_p)$$

where:

- $R_p = w \cdot r_s + (1 - w) \cdot r_f$  is the portfolio return
- $r_s$  is the risky asset return (random)
- $r_f$  is the risk-free rate (known)
- $\lambda$  is the risk aversion parameter (to be estimated)



## Example III: Mean-Variance Portfolio Choice (Part 2)

**First-order condition:**

$$E[r_s - r_f] - \lambda \cdot w \cdot \text{Var}(r_s) = 0$$

Solving for the optimal weight:

$$w^* = \frac{E[r_s - r_f]}{\lambda \cdot \text{Var}(r_s)}$$



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$$w^* = \frac{E[r_s - r_f]}{\lambda \cdot \text{Var}(r_s)}$$

**Moment condition:** If we observe portfolio weights  $w_i$  for individual  $i$ , we can use:

$$E \left[ \underbrace{w_i - \frac{E[r_s - r_f]}{\lambda \cdot \text{Var}(r_s)}}_{\equiv h_{Finance}(\text{parameters}, \text{data})} \right] = 0 \implies \mathbb{E}[h_{Finance}(\text{parameters}, \text{data})] = 0$$



# The General Framework

- Many instances of Economics generate *moments conditions*;
- These are restrictions data **and parameters** should be respect;
- Typically, economic models restrict moments, not distributions. MLE requires *a lot...*



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- Many instances of Economics generate *moments conditions*;
- These are restrictions data **and parameters** should be respect;
- Typically, economic models restrict moments, not distributions. MLE requires *a lot...*
- Let  $\mathbf{w}_t$  be a  $p \times 1$  vector of variables observed at time  $t$  (data);
- Let  $\boldsymbol{\theta}$  be an  $a \times 1$  vector of parameters to be estimated;
- Let  $\mathbf{h} : \mathbb{R}^a \times \mathbb{R}^p \rightarrow \mathbb{R}^r$  be a vector-valued **known** function;
- We assume that there is a true value  $\boldsymbol{\theta}_0$  such that:

$$\mathbb{E}[\mathbf{h}(\boldsymbol{\theta}_0, \mathbf{w}_t)] = \mathbf{0}_{r \times 1}$$



# The General Framework

- Since the data is taken as random,  $\mathbf{m}(\boldsymbol{\theta}) \equiv \mathbb{E}[\mathbf{h}(\boldsymbol{\theta}, \mathbf{w}_t)]$  is just a function of  $\boldsymbol{\theta}$ ;
- Idea: let's try to find a root of  $\mathbf{m}(\boldsymbol{\theta})$ !
- What are the problems with this idea?
- Two major issues:
  1. We do not know how to compute that expectation, in general;
  2. There may be no solution (or many) to  $\mathbf{m}(\boldsymbol{\theta}) = 0$  (think about  $a > r$ ,  $a = r$ , and  $a < r$ ).;



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  2. There may be no solution (or many) to  $\mathbf{m}(\boldsymbol{\theta}) = 0$  (think about  $a > r$ ,  $a = r$ , and  $a < r$ ).;
- Hansen (1982) proposed a very clever way to deal with these issues...
- First: let's approximate the expectation by the sample analog:

$$\hat{\mathbf{m}}_T(\boldsymbol{\theta}, \mathcal{W}_T) = \frac{1}{T} \sum_{t=1}^T \mathbf{h}(\boldsymbol{\theta}, \mathbf{w}_t), \text{ where } \mathcal{W}_T = (\mathbf{w}_1, \dots, \mathbf{w}_T)$$



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- Second: instead of making it equal to zero (unfeasible), let's *minimize* its distance to zero!



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- Second: instead of making it equal to zero (unfeasible), let's *minimize* its distance to zero!
- Let  $\mathbf{W}_T$  be a  $r \times r$  positive definite matrix;
- Consider the following scalar:

$$Q_T(\boldsymbol{\theta}, \mathcal{W}_T) \equiv \hat{\mathbf{m}}_T(\boldsymbol{\theta}, \mathcal{W}_T)' \mathbf{W}_T \hat{\mathbf{m}}_T(\boldsymbol{\theta}, \mathcal{W}_T)$$

- Obviously,  $Q_T(\boldsymbol{\theta}, \mathcal{W}_T) \geq 0$  for all  $\boldsymbol{\theta}$ ;
- Hansen (1982) proposed minimizing this criterion function to estimate  $\boldsymbol{\theta}_0$ :

$$\hat{\boldsymbol{\theta}}(\mathbf{W}_T) \equiv \arg \min_{\boldsymbol{\theta} \in \Theta} Q_T(\boldsymbol{\theta}, \mathcal{W}_T)$$

- The argmin depends on the weighting matrix  $\mathbf{W}_T$ , by the way;
- Intuition: if  $\boldsymbol{\theta} \approx \boldsymbol{\theta}_0$ , then  $Q_T(\boldsymbol{\theta}, \mathcal{W}_T) \approx 0$  by the LLN if  $\mathbf{h}(\cdot, \cdot)$  is smooth enough;



**Questions?**



## The First-Order Conditions

For a differentiable  $\mathbf{h}(\boldsymbol{\theta}, \mathbf{w}_t)$ , the FOC for the GMM estimator is:

$$\frac{\partial Q_T(\hat{\boldsymbol{\theta}}(\mathbf{W}_T), \mathcal{W}_T)}{\partial \boldsymbol{\theta}} = 2 \cdot \underbrace{\left[ \frac{1}{T} \sum_{t=1}^T \frac{\partial \mathbf{h}(\hat{\boldsymbol{\theta}}(\mathbf{W}_T), \mathbf{w}_t)}{\partial \boldsymbol{\theta}} \right]'}_{\frac{\partial \hat{\mathbf{m}}_T(\hat{\boldsymbol{\theta}}(\mathbf{W}_T))}{\partial \boldsymbol{\theta}}} \mathbf{W}_T \underbrace{\left[ \frac{1}{T} \sum_{t=1}^T \mathbf{h}(\hat{\boldsymbol{\theta}}(\mathbf{W}_T), \mathbf{w}_t) \right]}_{\hat{\mathbf{m}}_T(\hat{\boldsymbol{\theta}}(\mathbf{W}_T))} = \mathbf{0}_{a \times 1}$$



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- Even for a fixed  $\mathbf{W}_T$ , mild conditions guarantee a consistent estimator;
- See Newey and McFadden (1994) for all details you would ever want to know;
- The proofs of consistency are fairly similar to the consistency of the ML estimator;



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- Even for a fixed  $\mathbf{W}_T$ , mild conditions guarantee a consistent estimator;
- See Newey and McFadden (1994) for all details you would ever want to know;
- The proofs of consistency are fairly similar to the consistency of the ML estimator;
- From here on, I will assume that  $\hat{\boldsymbol{\theta}}(\mathbf{W}_T) \xrightarrow{p} \boldsymbol{\theta}_0$ . We will carefully study the asymptotic distribution
- Easy to generalize this to the case of a convergent sequence of weighting matrices;



**Questions?**



# Asymptotic Theory

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- Our goal is to derive the asymptotic distribution of  $\hat{\boldsymbol{\theta}}(\mathbf{W}_T)$ ;
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- Recall that  $\hat{\mathbf{m}}_T(\boldsymbol{\theta}, \mathcal{W}_T) = \frac{1}{T} \sum_{t=1}^T \mathbf{h}(\boldsymbol{\theta}, \mathbf{w}_t)$ ;
- Let's denote as  $\hat{m}_{i,T}(\boldsymbol{\theta}, \mathcal{W}_T)$  the  $i$ -th element of the sample analog  $\hat{\mathbf{m}}_T(\boldsymbol{\theta}, \mathcal{W}_T)$ ;
- We assume that each entry is continuously differentiable with respect to  $\boldsymbol{\theta}$ ;
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- Also denote as  $\hat{\boldsymbol{\theta}}_T$  the argmin for a fixed  $\mathbf{W}_T$  to ease notation;
- We apply the mean value theorem to each entry of  $\hat{\mathbf{m}}_T(\boldsymbol{\theta}, \mathcal{W}_T)$ :

$$\hat{m}_{i,T}(\hat{\boldsymbol{\theta}}_T, \mathcal{W}_T) = \hat{m}_{i,T}(\boldsymbol{\theta}_0, \mathcal{W}_T) + \left[ \frac{\partial \hat{m}_{i,T}(\tilde{\boldsymbol{\theta}}_{i,T}, \mathcal{W}_T)}{\partial \boldsymbol{\theta}} \right]' (\hat{\boldsymbol{\theta}}_T - \boldsymbol{\theta}_0)$$

where  $\tilde{\boldsymbol{\theta}}_{i,T}$  is a point between  $\hat{\boldsymbol{\theta}}_T$  and  $\boldsymbol{\theta}_0$ ;



- If we do this operation for all  $i = 1, \dots, r$  and stack the results, we can write:

$$\hat{\mathbf{m}}_T(\hat{\boldsymbol{\theta}}_T, \mathcal{W}_T) = \hat{\mathbf{m}}_T(\boldsymbol{\theta}_0, \mathcal{W}_T) + \mathbf{D}'_T(\hat{\boldsymbol{\theta}}_T - \boldsymbol{\theta}_0), \quad \mathbf{D}'_T \equiv \begin{bmatrix} \frac{\partial \hat{m}_{1,T}(\tilde{\boldsymbol{\theta}}_{1,T}, \mathcal{W}_T)}{\partial \boldsymbol{\theta}'} \\ \vdots \\ \frac{\partial \hat{m}_{r,T}(\tilde{\boldsymbol{\theta}}_{r,T}, \mathcal{W}_T)}{\partial \boldsymbol{\theta}'} \end{bmatrix}$$

- In general,  $\mathbf{D}_T$  is **not** equal to the Jacobian of  $\hat{\mathbf{m}}_T(\hat{\boldsymbol{\theta}}_T, \mathcal{W}_T)$ . Why?



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- But each  $\tilde{\boldsymbol{\theta}}_{i,T}$  is between  $\hat{\boldsymbol{\theta}}_T$  and  $\boldsymbol{\theta}_0$ . Since  $\hat{\boldsymbol{\theta}}_T \xrightarrow{p} \boldsymbol{\theta}_0$ , we have that  $\tilde{\boldsymbol{\theta}}_{i,T} \xrightarrow{p} \boldsymbol{\theta}_{i,0}$  for all  $i$ ;
- Now we assume that  $\mathbf{D}_T \xrightarrow{p} \mathbf{D}_{a \times r} \equiv \frac{\partial \mathbf{m}(\boldsymbol{\theta})}{\partial \boldsymbol{\theta}'}|_{\boldsymbol{\theta}=\boldsymbol{\theta}_0}$ , which is full-column rank;



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- Exchanging differentiation and expectation is possible if we assume a certain uniform convergence – see Newey and McFadden (1994);



- Now we multiply both sides by  $\left[ \underbrace{\frac{1}{T} \sum_{t=1}^T \frac{\partial \mathbf{h}(\hat{\boldsymbol{\theta}}(\mathbf{W}_T), \mathbf{w}_t)}{\partial \boldsymbol{\theta}}}_{\frac{\partial \hat{\mathbf{m}}_T(\hat{\boldsymbol{\theta}}(\mathbf{W}_T))}{\partial \boldsymbol{\theta}}} \right]' \mathbf{W}_T$  and use the FOC to get:

$$\begin{aligned} \left[ \frac{1}{T} \sum_{t=1}^T \frac{\partial \mathbf{h}(\hat{\boldsymbol{\theta}}(\mathbf{W}_T), \mathbf{w}_t)}{\partial \boldsymbol{\theta}} \right]' \mathbf{W}_T \hat{\mathbf{m}}_T(\hat{\boldsymbol{\theta}}_T, \mathcal{W}_T) &= \left[ \frac{1}{T} \sum_{t=1}^T \frac{\partial \mathbf{h}(\hat{\boldsymbol{\theta}}(\mathbf{W}_T), \mathbf{w}_t)}{\partial \boldsymbol{\theta}} \right]' \mathbf{W}_T \hat{\mathbf{m}}_T(\boldsymbol{\theta}_0, \mathcal{W}_T) \\ &\quad + \left[ \frac{1}{T} \sum_{t=1}^T \frac{\partial \mathbf{h}(\hat{\boldsymbol{\theta}}(\mathbf{W}_T), \mathbf{w}_t)}{\partial \boldsymbol{\theta}} \right]' \mathbf{W}_T \mathbf{D}'_T(\hat{\boldsymbol{\theta}}_T - \boldsymbol{\theta}_0) \end{aligned}$$



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- But the LHS is zero by the FOC!!!



Rearrange the previous expression to get:

$$\begin{aligned}\sqrt{T}(\hat{\boldsymbol{\theta}}_T - \boldsymbol{\theta}_0) = & - \left\{ \left[ \frac{1}{T} \sum_{t=1}^T \frac{\partial \mathbf{h}(\hat{\boldsymbol{\theta}}(\mathbf{W}_T), \mathbf{w}_t)}{\partial \boldsymbol{\theta}} \right]' \mathbf{W}_T \mathbf{D}'_T \right\}^{-1} \\ & \times \left[ \frac{1}{T} \sum_{t=1}^T \frac{\partial \mathbf{h}(\hat{\boldsymbol{\theta}}(\mathbf{W}_T), \mathbf{w}_t)}{\partial \boldsymbol{\theta}} \right]' \mathbf{W}_T \sqrt{T} \cdot \hat{\mathbf{m}}_T(\boldsymbol{\theta}_0, \mathcal{W}_T)\end{aligned}$$



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- We assume that  $\left[ \frac{1}{T} \sum_{t=1}^T \frac{\partial \mathbf{h}(\hat{\boldsymbol{\theta}}(\mathbf{W}_T), \mathbf{w}_t)}{\partial \boldsymbol{\theta}} \right] \xrightarrow{p} \mathbf{D}_{a \times r}$ . Why isn't this trivial?



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- We will also assume that  $\mathbf{W}_T \rightarrow \mathbf{W}$ , which is positive definite;
- Then, by Slutsky's theorem, we have that

$$\left[ \frac{1}{T} \sum_{t=1}^T \frac{\partial \mathbf{h}(\hat{\boldsymbol{\theta}}(\mathbf{W}_T), \mathbf{w}_t)}{\partial \boldsymbol{\theta}} \right]' \mathbf{W}_T \mathbf{D}'_T \xrightarrow{p} \mathbf{D}' \mathbf{W} \mathbf{D}$$



- Now we need to study the distribution of  $\sqrt{T} \cdot \hat{\mathbf{m}}_T(\boldsymbol{\theta}_0, \mathcal{W}_T) = \frac{1}{\sqrt{T}} \sum_{t=1}^T \mathbf{h}(\boldsymbol{\theta}_0, \mathbf{w}_t)$ ;
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- If  $\{\mathbf{w}_t\}$  is an i.i.d. sequence, then we use the classical CLT to get:

$$\mathbf{S} = \mathbb{E}[\mathbf{h}(\boldsymbol{\theta}_0, \mathbf{w}_t) \mathbf{h}(\boldsymbol{\theta}_0, \mathbf{w}_t)']$$



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- The same result holds true if  $\{\mathbf{w}_t\}$  is a Martingale Difference Sequence;



- In the general case of dependent data, we have to use a more general version of the CLT;
- Under the conditions of one of theorems we covered for correlated series, we have:

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- Very important: the asymptotic variance depends on the weighting matrix  $\mathbf{W}$ !;
- Consistency holds for any positive definite  $\mathbf{W}$ ;



**Questions?**



## The Optimal Weighting Matrix

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## A Thought Experiment

Let's do a thought experiment:

- Suppose you want to know where an enemy plane is and you have independent radars;
- They are both consistent “estimators”, but radar 1 more noise than radar 2;
- What's the optimal thing to do? Use only information from radar 1? Radar 2? Both?



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- They are both consistent “estimators”, but radar 1 more noise than radar 2;
- What's the optimal thing to do? Use only information from radar 1? Radar 2? Both?
- Ok, you'd probably use both radars, but give more weight to radar 2 (less noisy);
- This is exactly the idea behind the optimal weighting matrix in GMM!
- How far each sample moment condition is from zero = your radar when looking for  $\theta_0$ ;
- How you combine them = weighting matrix  $\mathbf{W}$ ;



## How to combine the radars?

- Intuition: give more weight to “more precise” moment conditions;
- But how to measure precision?
- Answer: variance-covariance matrix of the moment conditions;
- If moment conditions are uncorrelated, just use inverse of variances;
- If correlated, use inverse of variance-covariance matrix;
- This is exactly what Hansen (1982) proposed!
- Notice that nothing related to this intuition is related to i.i.d. vs dependent data;



- Recall that the asymptotic variance of the GMM estimator is:

$$\mathbf{V} \equiv (\mathbf{D}'\mathbf{W}\mathbf{D})^{-1}\mathbf{D}'\mathbf{W}\mathbf{S}\mathbf{W}\mathbf{D}(\mathbf{D}'\mathbf{W}\mathbf{D})^{-1}$$

- In case  $\mathbf{W} = \mathbf{S}^{-1}$ , we have:

$$\mathbf{V}^* = (\mathbf{D}'\mathbf{S}^{-1}\mathbf{D})^{-1}\mathbf{D}'\mathbf{S}^{-1}\mathbf{S}\mathbf{S}^{-1}\mathbf{D}(\mathbf{D}'\mathbf{S}^{-1}\mathbf{D})^{-1} = (\mathbf{D}'\mathbf{S}^{-1}\mathbf{D})^{-1}$$

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- How can we compare how “large” are  $\mathbf{V}$  and  $\mathbf{V}^*$ ?
- We will write “ $\mathbf{V} \geq \mathbf{V}^*$ ” if, and only if,  $\mathbf{V} - \mathbf{V}^*$  is positive semidefinite;



## Let's Do The Math

$$\begin{aligned} \mathbf{V} - \mathbf{V}^* &= (\mathbf{D}'\mathbf{W}\mathbf{D})^{-1}\mathbf{D}'\mathbf{W}\mathbf{S}\mathbf{W}\mathbf{D}(\mathbf{D}'\mathbf{W}\mathbf{D})^{-1} - (\mathbf{D}'\mathbf{S}^{-1}\mathbf{D})^{-1} \\ &= (\mathbf{D}'\mathbf{W}\mathbf{D})^{-1} [\mathbf{D}'\mathbf{W}\mathbf{S}\mathbf{W}\mathbf{D} - (\mathbf{D}'\mathbf{W}\mathbf{D})(\mathbf{D}'\mathbf{S}^{-1}\mathbf{D})^{-1}(\mathbf{D}'\mathbf{W}\mathbf{D})] (\mathbf{D}'\mathbf{W}\mathbf{D})^{-1} \\ &= (\mathbf{D}'\mathbf{W}\mathbf{D})^{-1}\mathbf{D}'\mathbf{W} [\mathbf{S} - \mathbf{D}(\mathbf{D}'\mathbf{S}^{-1}\mathbf{D})^{-1}\mathbf{D}'] \mathbf{W}\mathbf{D}(\mathbf{D}'\mathbf{W}\mathbf{D})^{-1} \end{aligned}$$



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- Now we write:

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- It is enough now to show that  $[\mathbf{I} - \mathbf{S}^{-1/2}\mathbf{D}(\mathbf{D}'\mathbf{S}^{-1}\mathbf{D})^{-1}\mathbf{D}'\mathbf{S}^{-1/2}]$  is positive semidefinite;



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In any case:  $\mathbf{V} - \mathbf{V}^* = \mathbf{A}(\mathbf{I} - \mathbf{B})\mathbf{A}' \geq 0 \implies \mathbf{W} = \mathbf{S}^{-1}$  is the optimal weighting matrix!



Questions?



- The GMM estimator is the minimizer of a quadratic form of sample moment conditions;
- We derived its asymptotic distribution under general conditions;
- We showed that the optimal weighting matrix is the inverse of the covariance matrix of the moment conditions;
- Consistency does *not* require the optimal weighting matrix;



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- We showed that the optimal weighting matrix is the inverse of the covariance matrix of the moment conditions;
- Consistency does *not* require the optimal weighting matrix;
- Major problem: we do not know  $\mathbf{S}$  in practice...
- Next class: how to implement GMM in practice?



**The End**



- Checkout Chapter 14 from Hamilton's book;
- Also checkout Chapter 13 from Hansen's book;