

6

Modelling catchment hydrogeomorphic sensitivity to rainfall spatial distribution

6.1 Introduction

Landscape evolution at the catchment scale is punctuated by intense erosive episodes driven by flood events (Wolman and Miller, 1960; Newson, 1980; Costa and O'Connor, 1995) interspersed with periods of relative calm and little geomorphic change, an idea that harks back to the early ideas of geological ‘catastrophism’ (Cuvier, ?). It is these erosive events, driven by intense rainfall in temperate climates, separated by long periods of stasis, that cumulatively sculpt the landscape over geological time. The importance of these rare but formative events has been revisited by recent work such as Huang and Niemann (2006), looking at the long term implications of different geomorphically effective event discharges on fluvial incision; Gupta et al., (2007); Lamb and Fonstad (2010); and Baynes et al., (2015) where the amount of bedrock erosion during a single large flood event was quantified. Still, our understanding of catchment scale landscape evolution is far from complete - the role of individual events is highly variable. Anton (2014) report that rapid gorge formation can be driven primarily by small to moderate sized floods, rather than floods of extreme magnitude. Further, there was no observed relationship between flood magnitude and erosion rate. Turowski et al. (2011) report that streams within catchments can exhibit different

behaviour in response to the same flood event – some streams may erode during high flows, whereas others may deposit during high flows. During small–medium flows their respective behaviour is reversed. Wong et al. (2015) establish through numerical modelling that geomorphic changes in channel geometry during severe flood events are substantial enough to change hydrological response of a river catchment. Catchment-scale erosional dynamics are complex, and except in the simplest cases depend on other forcings other than the magnitude alone of single flood events. The understanding of hydrogeomorphic processes during single storm events is not only important for the long-term evolution of landscapes, but also for prediction of how catchments will respond to changing hydro-meteorological conditions that may accompany climate change (Kendon et al., 2014).

The focus in this paper is to quantify the sensitivity of catchment-scale erosional processes to the spatial distribution of rainfall during flood events. The assumption of uniform rainfall over a river catchment is argued to hold true for small catchments (Solyom and Tucker 2004; Tucker 2010), but even over small areas, mesoscale rainfall features, such as localized convective storm cells, can result in spatially and temporally uneven input of precipitation into the catchment. In the case of intense convective precipitation, individual storm cells can be as small as 10km^2 in areal extent (Weisman and Klemp, 1986; Von Hardenberg et al., 2003). Over larger catchments, or those with steep topographic gradients, precipitation is almost certain to vary spatially, due to orographic enhancement of rainfall (Roe, 2005). As such, rainfall-runoff generation, local river flow, and erosion rates may vary considerably within individual drainage basins.

Patterns of rainfall distribution across a catchment can affect hydrograph response, including the peak discharge and local water levels (Nicotina et al., 2008). As many geomorphic processes are threshold dependent (Schumm, 1979), such as fluvial incision into bedrock (Sklar and Dietrich, 2001; Snyder et al., 2003), there is potential for the spatial distribution of rainfall to control local erosion rates within a catchment. Non-linearity in geomorphic process laws (e.g. Coulthard et al., 1998; Phillips, 2003; Coulthard and Van de Wiel, 2007) should dictate that catchments are also geomorphically sensitive to the spatial distribution of rainfall.

Numerical models of landscape evolution usually omit a realistic distribution of

rainfall input in favour of uniform, homogenised precipitation across the landscape. When precipitation is ‘lumped’, either spatially or temporally in a catchment, local minima and maxima of precipitation are lost, and with discharge being a function of rainfall rate, this uncertainty propagates through to local discharges and erosion rates. The uncertainty in erosion rates is potentially exacerbated by the non-linearity and threshold dependence of erosive processes. The variability of precipitation is considered in many cases to be as important as total precipitation amount in determining erosional effectiveness (Tucker and Bras, 2000; Tucker, 2010). What is currently lacking in landscape evolution studies is a fuller understanding of how landscapes erode during individual storms, and in particular how erosional processes are sensitive to the details of precipitation across a catchment.

In numerical models of landscape evolution, resolving the precise temporal and spatial details of rain storms and the hydrological response is often computationally prohibitive, especially over long timescales, and as such modellers have taken to using simpler parametrisations of storm characteristics, such as using simple stochastic models to generate rainfall inputs and rainfall timeseries (Eagleson, 1978; Tucker et al., 2001). In studies of long term landscape evolution, the sensitivity of landscapes to the spatial distribution of rainfall has been investigated to some extent – particularly the imprint of orographic precipitation on landscapes (e.g. Roe 2002; Anders 2008; Han and Gasparini, 2015).

Rainfall resolution has been demonstrated to exert a control over sediment yields over seasonal and decadal timescales (Coulthard and Skinner, 2016). In a numerical modelling study of the River Swale catchment, Coulthard and Skinner show that local as well as catchment-wide sediment yields were predicted to increase by orders of magnitude as rainfall data resolution increases. The study looked at the effects of rainfall spatial data resolution as well the temporal resolution of data, showing both to demonstrate a control over sediment fluxes in a catchment.

In contrast to previous studies, this paper looks at the effects of individual severe rainfall events using a range of erosional end-member models. The study investigates the sensitivity of catchment-scale erosion to the spatial details of severe rain storms – the agents of long term landscape evolution. Landscape response is investigated using a numerical landscape evolution model that incorporates a dynamic (non steady-state)

water-routing component and a range of fluvial incision and sediment transport laws. A series of model experiments is presented to test how sensitive real landscapes are to the catchment-scale details of precipitation during intense rainfall events. The simulations are each based on selected severe storms in Great Britain occurring in the past decade, which left significant flooding, damage, and geomorphic change in their wake.

The following questions are explored through the use of numerical modelling simulations;

- Are fluvial erosion and sediment transport processes sensitive to the details of precipitation at the catchment scale during single storm events?
- Does the choice of erosional model operating within the catchment influence sensitivity to rainfall patterns?
- What are the implications of this for longer term landscape evolution?

6.2 Theory

In our conceptual model of landscape evolution, fluvial processes – erosion and deposition of sediment and bedrock by flowing water – are assumed to be the dominant geomorphic processes at work. The numerical model used to simulate these processes uses established hydrological and geomorphic process laws, which are briefly reviewed here in the following sections.

6.2.1 Rainfall-runoff and flow routing

From rainfall input, runoff is calculated using an adaptation of the Beven and Kirby (1979) TOPMODEL. Total surface and subsurface discharge is given by:

$$Q_{tot} = \frac{m}{T} \log \left(\frac{(r - j_t) + j_t \exp \left(\frac{rT}{m} \right)}{r} \right) \quad (6.1)$$

where T is the time step in seconds, r is the rainfall rate, j_t is a function that describes soil moisture store, and m is a parameter that controls the rise and fall of

this soil moisture store in j_t . These adapted TOPMODEL equations are given fully in Coulthard (2002), equations (1) and (2).

The amount of water partitioned between surface and subsurface flow is determined by a simple infiltration threshold, given by:

$$I_t = KS(Dx)^2 \quad (6.2)$$

where K is hydraulic conductivity, S is the slope, and Dx is the width of the grid cell or horizontal grid spacing. The infiltration threshold is subtracted from Q_{tot} to give the portion of water routed over the surface.

Surface water and channel flow is an important driver in catchment scale erosional processes. The amount and velocity of water flow is a variable in both the sediment transport and bedrock erosion laws. The water flow equations are based on a simplified form of the shallow water flow equations, a simplification first derived by Bates (2010) and incorporated into the landscape evolution model by Coulthard et al (2013). The flow between cells is calculated by:

$$Q = \frac{q - gh_{flow}\Delta T \frac{\Delta(h+z)}{\Delta x}}{1 + gh_{flow}\Delta t n^2 |q| / h_{flow}^{10/3}} \Delta x \quad (6.3)$$

where q is the water flux between cells from the previous iteration, g is acceleration due to gravity, h_{flow} is the maximum depth of flow between cells (m), t is time (s), h is depth of water, z is elevation, x is the grid well width, and n is Manning's roughness coefficient. The full implementation details are given in Coulthard (2013), and the derivation from the shallow water equations is given in Bates (2010).

6.2.2 Sediment transport

Transport of loose sediment within the model is governed by the ? sediment transport model. The Wilcock and Crowe model represents transport of mixed sand/gravel fractions based on the surface sediment composition. The rate of sediment transport, q_i , is given as:

$$q_i = \frac{F_i U_*^3 W_i^*}{(s-1)g} \quad (6.4)$$

where F_i is the fractional volume of sediment, for a given sediment fraction, i , U^* is the shear velocity, s is the ratio of sediment to water density. W_i^* is a function relating fractional transport rate to total transport rate (see ? for a full derivation of this equation). The usage of this sediment transport model is extrapolated here to account for finer particles such as silts (?), as well as the sand-gravel mixture it was originally designed for.

6.2.3 Bedrock incision

A simple model of bedrock incision based on the excess shear stress model (Citations) is implemented in the numerical model. The rate of bedrock incision is determined by the amount of shear stress acting on the bedrock, above a threshold level of stress required to initiate substrate removal (e.g. Snyder (2003)). When bedrock material is removed, it is distributed amongst the sediment fractions according to the fractional proportions set by the user. The rate of bedrock erosion according to the excess shear stress model is given by:

$$\varepsilon = k_e(\tau_b - \tau_c)^{P_b} \quad (6.5)$$

where k_e is the bedrock erodibility coefficient, τ_b is the basal shear stress on the channel bed, τ_c , is the critical shear stress threshold, P_b is the shear stress exponent. (Cite Howard or Whipple?)

6.3 Experimental design and case study descriptions

Three upland catchments in the UK were selected to represent a range of catchment sizes and shapes. The catchments were also chosen on the basis that they had experienced a severe rain storm which could be used as a basis for the experiments, such that it could be considered ‘extreme’ in the typical return period of flooding events for each particular catchment. Peak discharges for each of the following flood events exceed the 99th percentile for their respective catchments. The catchments and respective severe rain events chosen were located in: Ryedale, North Yorkshire, 2005; Eden, Cumbria

Catchment Name	Eden	Ryedale	Valency
Catchment Area	2286km ²	270km ²	18km ²
Catchment Type	Upland-Lowland	Upland, Moor/Peaty	Upland, Pasture
Storm Date	2005-01-07	2005-06-19	2004-08-16
Peak Rainfall (mm hr ⁻¹)		125	c.400
Peak Discharge			
Meteorological Setting		Split-front, convective system	Quasi-stationary convective system
3hr Rainfall Return Period	(tbc)	330yr (Wass et al. 2008)	1300yr (Burt, 2005)

Table 6.1: Table showing key characteristics of each storm event.

2012; and Boscastle, Cornwall, 2004. An overview map of their locations is given in Figure ???. A table (Table 6.1) summarises the key features of each catchment and associated storm.

6.3.1 Meteorological setting

Boscastle, Cornwall storm 2004

The Boscastle storm took place on the 16th August 2004 leading to flooding within the River Valency catchment and the village of Boscastle. The extreme rainfall accumulations of up to 200 mm in the upper Valency catchment resulted from prolonged rainfall between the hours of 1200 – 1600 UTC. Rainfall rates were thought to have reached almost 400 mm hr⁻¹ (?), after correcting for under-reporting from rain gauges in the vicinity of the catchment. (Burt, 2006).

The meteorological conditions that enabled such prolonged heavy rainfall were a combination of large-scale synoptic conditions moving in from the Atlantic, with moist lower atmospheric layers readily forming convective cloud. Repeated initiation of convection along the north Cornish coast lead to what appeared to be relative stationary convective cells over the Valency catchment. Later authors refer to this type of convective storm as a 'Boscastle-type' or quasi-stationary convective storm (cite the reading person).

Ryedale, North York Moors storm 2005

The Ryedale storm occurred on 19 June 2005. Intense rainfall throughout the afternoon lead to total accumulated rainfall amounts of up to 89mm in the Ryedale valley, between the hours of 1400 – 1800 UTC. Peak instantaneous rainfall rates were estimated to have been around 32.5mm hr⁻¹ (Sibley et al., 2009) to 59.4 mm hr⁻¹ (Hopkins et al. 2010), though one report states they reached as high as 125 mm hr

$-^1$ (Cinderley, 2005). The antecedent conditions had been dry for a prolonged spell, leading to cracking of the surface peat in the higher elevations of the catchment.

The meteorological conditions leading to such heavy rainfall was a combination of a cold, upper-level air mass advecting over a warm moist boundary layer, leading to unstable conditions that enabled a convective thunderstorm to develop in the late afternoon. The instability was enhanced by a split-frontal system. [More? Too much met here?]. The conditions led to a particularly high amount of precipitable water present in the atmosphere which was subsequently washed out into the landscape during intense rainfall.

Eden Valley, Carlisle, 2005

6.3.2 Numerical model set-up

The landscape evolution model developed in Chapter 3 (Working name: HAIL-CAESAR) is used to carry out numerical simulations based on the three catchments and corresponding storm events. HAIL-CAESAR is a cellular automaton landscape evolution model based on the CAESAR-Lisflood model (Coulthard et al., 2013). The HAIL-CAESAR model simulates a range of fluvial erosion and sediment transport laws. The model also interpolates and downscals rainfall input data to higher resolutions and this feature is used in the group of simulations with the 5m interpolated radar rainfall data.

Erosion model choice

A variety of erosion laws exist describing how landscapes erode from fluvial incision. The choice of erosion law for a given catchment depends on a variety of factors, such as the characteristic substrate material in the catchment – is it predominantly loose sediment or cohesive, solid bedrock? In reality, landscapes are often a mixture of these two extremes, incorporating loose sediment on top of solid bedrock. Catchments also often exhibit a transition from rockier upland headwaters, to more thickly soil-mantled flood plains. In order to address the uncertainty in choosing which erosion model applies for each catchment (Section ??), two erosion model end-members are used, with each one representing a different conceptual model of fluvial incision and sediment transport. These include: i) a purely sediment transport-limited model, ii) a

detachment-limited bedrock incision model. The equations describing the transport-limited and detachment-limited models are discussed in Section ???. Further models were considered, such as a hybrid transport-detachment limited erosion model, but it was deemed beyond the scope of this study, which is to focus on the sensitivity of rainfall resolution, rather than wide range of erosion and sediment transport models.

A set of control simulations modelling only runoff and water routing (no erosional model) were also carried out for comparison against the two erosion end-member simulations. In total a series of 9 simulations were carried out – three for each of the three catchments.

Rainfall spatial resolution

In order to assess the sensitivity of each erosional model to the spatial details of precipitation, three different spatial resolutions of rainfall input are used in each simulation. All three are based on the same original rainfall source data - the UK NIMROD radar data product. Only the spatial distribution and resolution of rainfall is assessed in this study – other studies have previously investigated the effects of the temporal resolution of rainfall data on discharge and erosion rates (e.g Nicotina et al., 2008; Coulthard and Skinner, 2015; Coulthard, 2013b). Three levels of rainfall detail are used:

- Uniform or 'lumped' precipitation – radar-derived rainfall rates across the catchment are spatially-averaged to produce a basin-wide average rainfall rate.
- Gridded rainfall input. The rainfall is input from a overlying gridded mesh of raincells, at the same resolution as the radar product (1km).
- Interpolated rainfall input. The radar data is interpolated to the same resolution as the topography grid (i.e. 50m). (*Interpolation method TBC - but see study by Tait et al (2006) and perhaps implement their method*)

The reason for running a simulation with an interpolated rainfall data set is to reduce the effect of harsh gradients between adjacent cells, as is sometimes apparent when using the rainfall data at its native resolution of 1km. Figure ?? gives an indicative illustration of this. A matrix of experiments is shown in Table ??.

Catchment	TOPMODEL m parameter
Boscastle	
Ryedale	0.03, 0.04, 0.05, 0.06, 0.07, 0.08, 0.09, 0.1, 0.15, 0.2

Table 6.2: TOPMODEL m parameter values used to run sensitivity simulations for each catchment.

6.4 Sensitivity analysis

There are numerous user defined parameters in the HAIL-CAESAR model, and in landscape evolution models in general, that have a wide range of potential values. Parameter selection in environmental modelling comes with a degree of uncertainty, and resulting outputs from models can be highly sensitive to the user's choice of input parameters for a given simulation (Pelletier, 2012). Initial testing of the HAIL-CAESAR model, and studies using the CAESAR-Lisflood model that it is based upon show it is particularly sensitive to the TOPMODEL m parameter, a parameter that controls the rise and fall of the soil moisture store, and hence how a river catchment responds to rainfall input (?).

To assess the sensitivity of the model to the choice of TOPMODEL- m parameter, a series of simulations were carried out with a range of m values for both test cases. Simulations of each flood event were carried out with the m values shown in table 6.2.

6.5 Results

I intend to discuss the spatial differences in erosion, as well as any differences in basin-wide average erosion rates, and explain these differences by referring back to the Theory section.

The discussion will be aided by figures showing (for each of the three rainfall input variations for each catchment):

- Total accumulated rainfall maps for each storm (Figure ??).
- Profiles of erosion along main channels in each catchment (Figure ??).
- Plots of the hydrographs and sediment yields for each storm (Figure ??).
- 2D Planform maps of distribution of erosion (and deposition if applicable).

Indicative figures. Note these will change in the final version as I have decided to re-run some simulations after tweaking the model set-up.

6.5.1 TOPMODEL sensitivity

The model exhibited a strong sensitivity to the choice of the TOPMODEL m parameter. In the results presented in figure 6.1 peak river discharge ranged from XX at an m value of 0.003 to XX with an m value of 0.008. The measured peak discharge reported for the 2005 storm at the Ness gauging station was 105 cumecs. In the sensitivity simulations, a value of $m = 0.005$ produced a flood peak most closely matching the observed value, peaking at XX cumecs (Note the time as well.).

There were differences between the hydrographs of the observed and simulated discharges in terms of peak discharge timing and recession limb shape. The observed hydrograph showed a sharp rise at around 50 hours after the start of the study period. (UTC XX XX XX to X). Lower m values ($m < 0.005$) resulted in a prediction of the flood peak being too early compared to the observed timing, with values > 0.005 predicting the flood peak timing too late. Most of the simulations failed to capture the extended duration of peak discharge, which lasted approximately 5–6 hours, before receding back to low flow levels. The simulation with $m = 0.006$ came closest to predicting this hydrograph shape, but failed to predict the magnitude of water discharge correctly, underestimating the peak flow by almost 50%.

For Ryedale simulations, it was decided to use an m value of 0.005, providing the closest possible match to the flood peak discharge, though not the true shape of the hydrograph and the receding limb. As the catchment simulations include a representation of erosion and sediment transport processes, which are often threshold dependent, it was felt necessary to match the discharge peak more closely over choosing to match the hydrograph shape precisely.

6.5.2 Catchment hydrology

At the catchment scale, hydrological response was sensitive to both the rainfall resolution and the choice of erosional model. For all catchments, higher resolution rainfall input data resulted in a flashier storm hydrograph, with catchments reaching their peak discharge sooner than the uniform rainfall cases. Maximum river discharges were

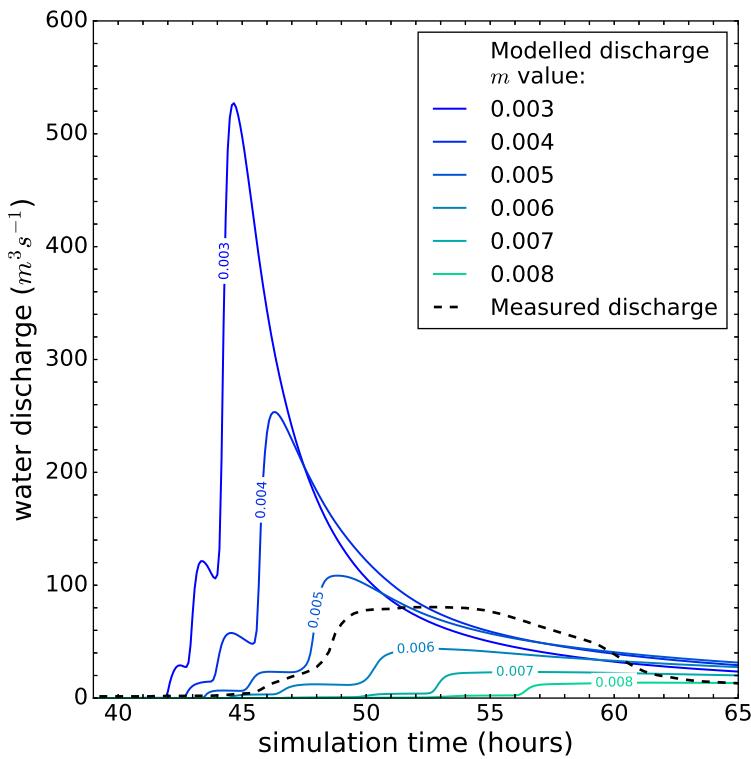


Figure 6.1: Discharge at Ryedale catchment outlet for varying values of the TOP-MODEL m parameter. The measured discharge at the catchment gauging station is overlain in dashed line. The results from the simulations with $m > 0.008$ are omitted for clarity due to the low peak discharges they produced.

also higher when using higher resolution rainfall data. The choice of erosion model also influenced the hydrograph response. When catchment erosion was modelled using a transport-limited case, peak discharges were higher, but the timing of hydrograph peaks remained very similar for each case. The difference in peak discharges were minimal when comparing the detachment-limited cases to the hydrological-only models.

6.5.3 Catchment sediment flux

Sediment flux followed a similar pattern to that observed in water discharge from the catchment. For all catchments and events simulated, sediment flux from the catchment was higher in the simulations using higher resolution rainfall input data. The patterns of peak sediment discharge also mirrored that of water discharge, with sediment flux peaking earlier in the simulations with higher resolution rainfall inputs.

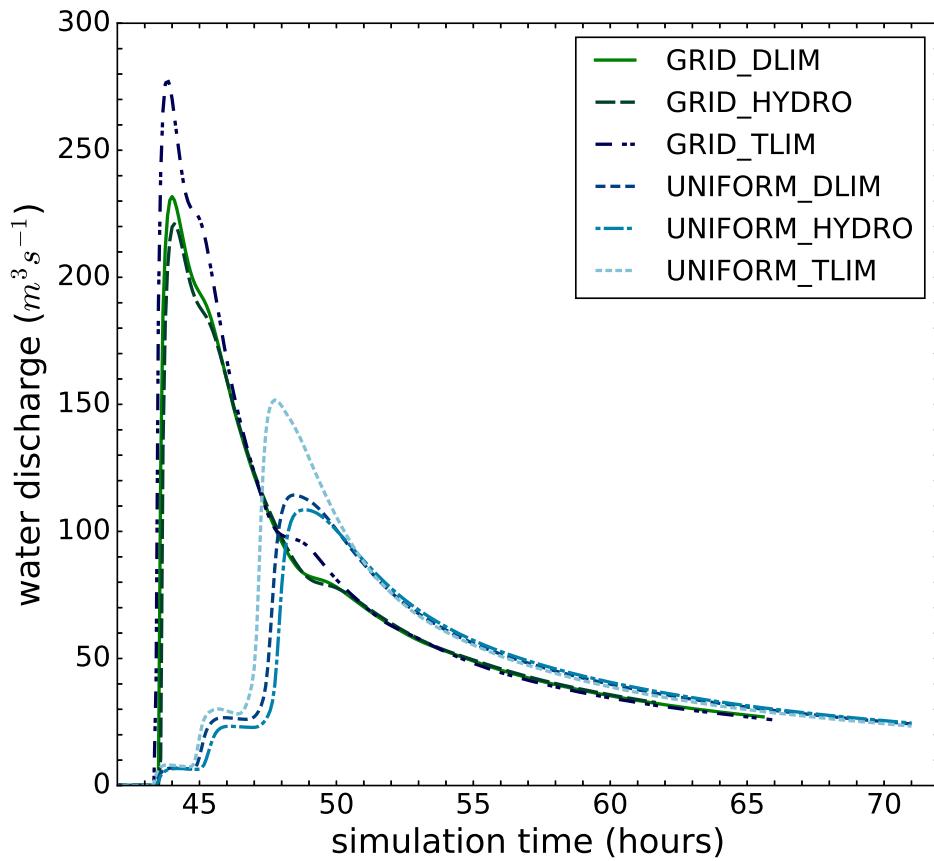


Figure 6.2: Hydrographs (discharge over time at catchment outlet) for each simulation of the 2005 Ryedale event listed in table XXX.

6.5.4 Spatial variations in flood inundation

6.5.5 Spatial variations in sediment and bedrock erosion

6.6 Discussion

6.6.1 Implications for longer-term landscape evolution

Some discussion on how these results scale-up to longer term landscape evolution. I.e. How many storms of similar magnitude would be needed to reach longer term erosion rates? Does this correspond to known longer term erosion rates of similar upland landscapes?

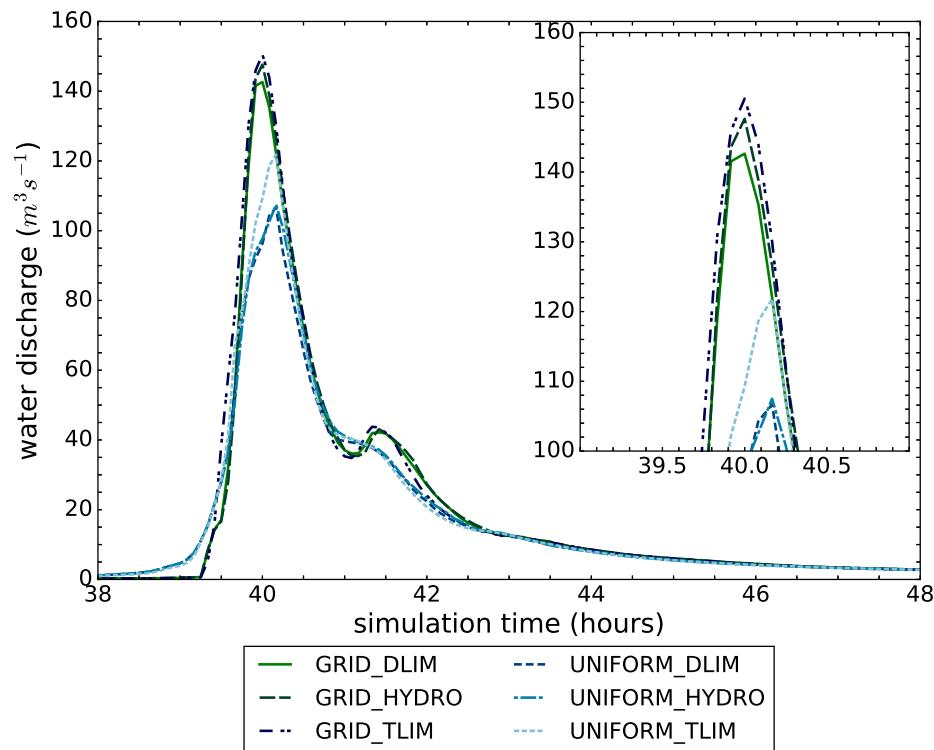


Figure 6.3: Hydrographs (discharge over time at catchment outlet) for each simulation of the 2004 Boscastle event listed in table XXX.

6.7 Conclusions

Text.

6.8 Fixed parameters

A table showing the other parameters used in the simulations (All of which remain fixed for each simulation)

The following table lists the parameters that were held constant for all simulations.

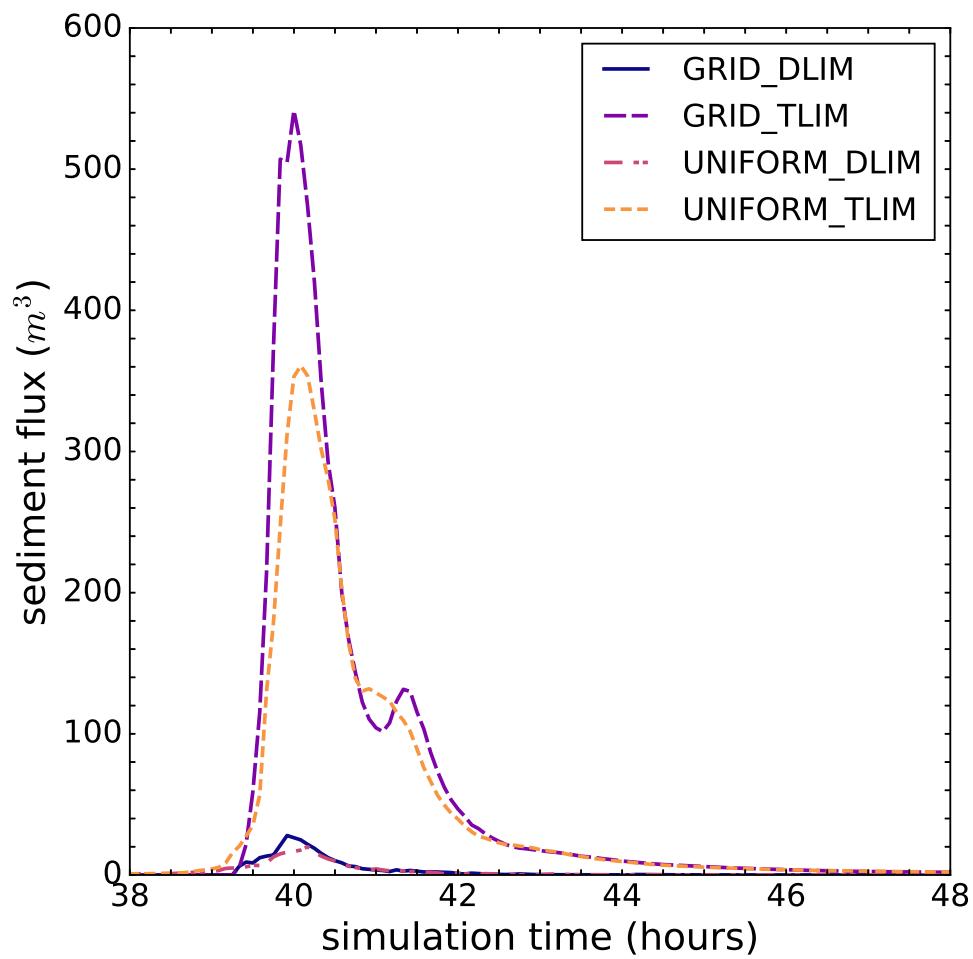


Figure 6.4: Sediment flux (Total sediment volume output per hour at catchment outlet for each erosion-enabled simulation of the 2004 Boscastle event listed in table XXX.

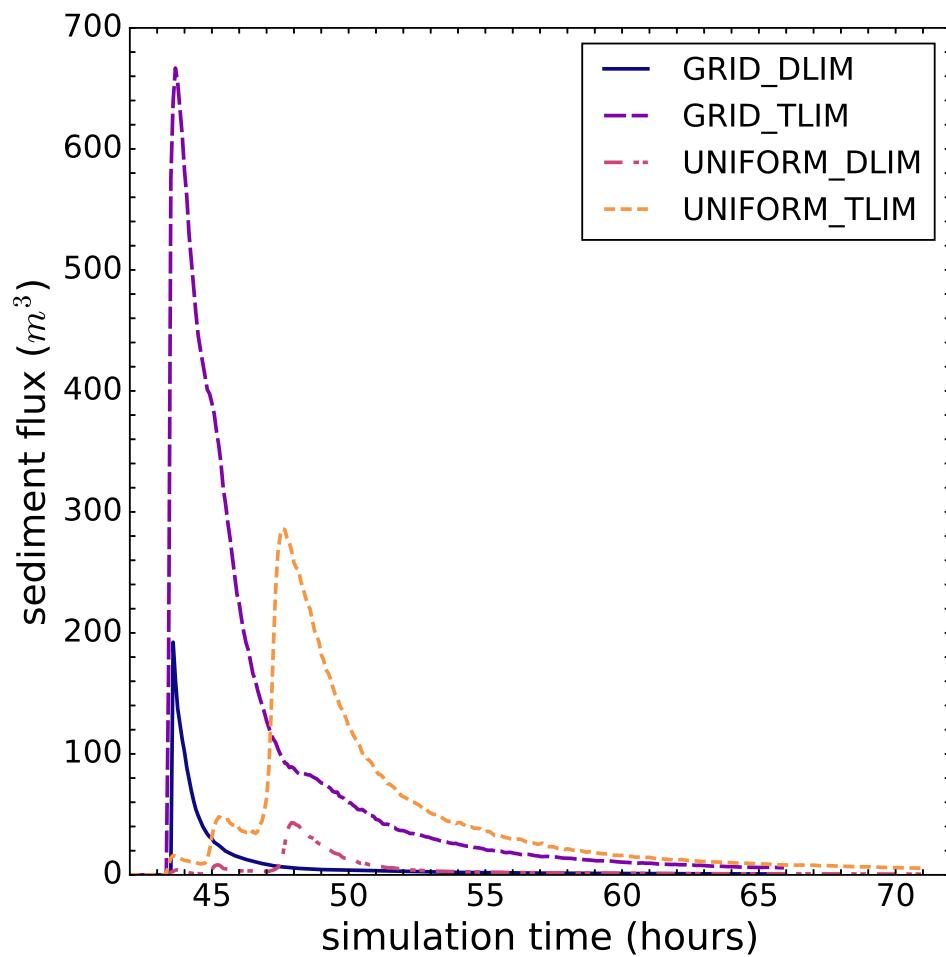


Figure 6.5: Sediment flux (Total sediment volume output per hour at catchment outlet) for each erosion-enabled simulation of the 2005 Ryedale event listed in table XXX.

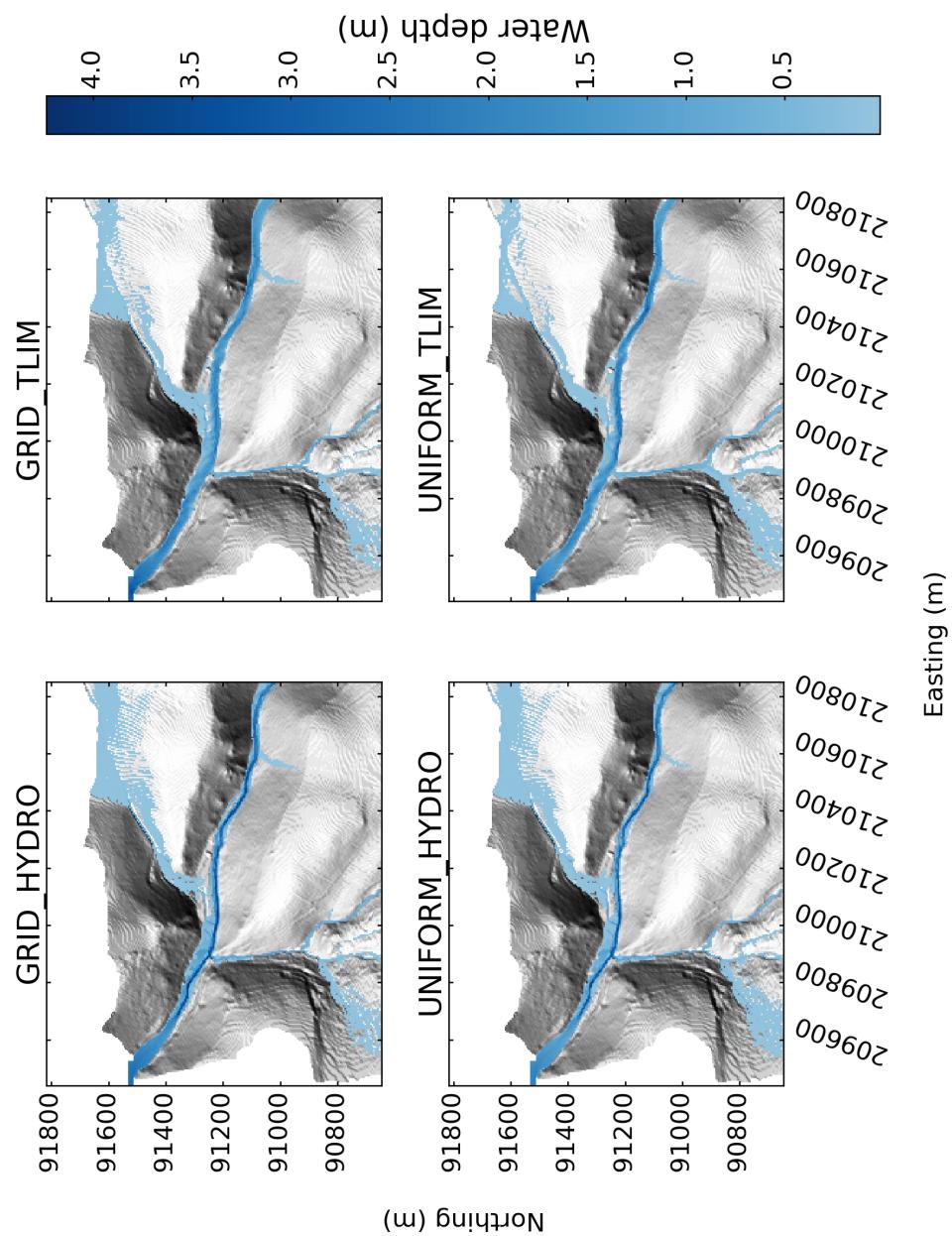


Figure 6.6: Flood extents in the Boscastle catchment at the time of maximum river discharge for each simulation.

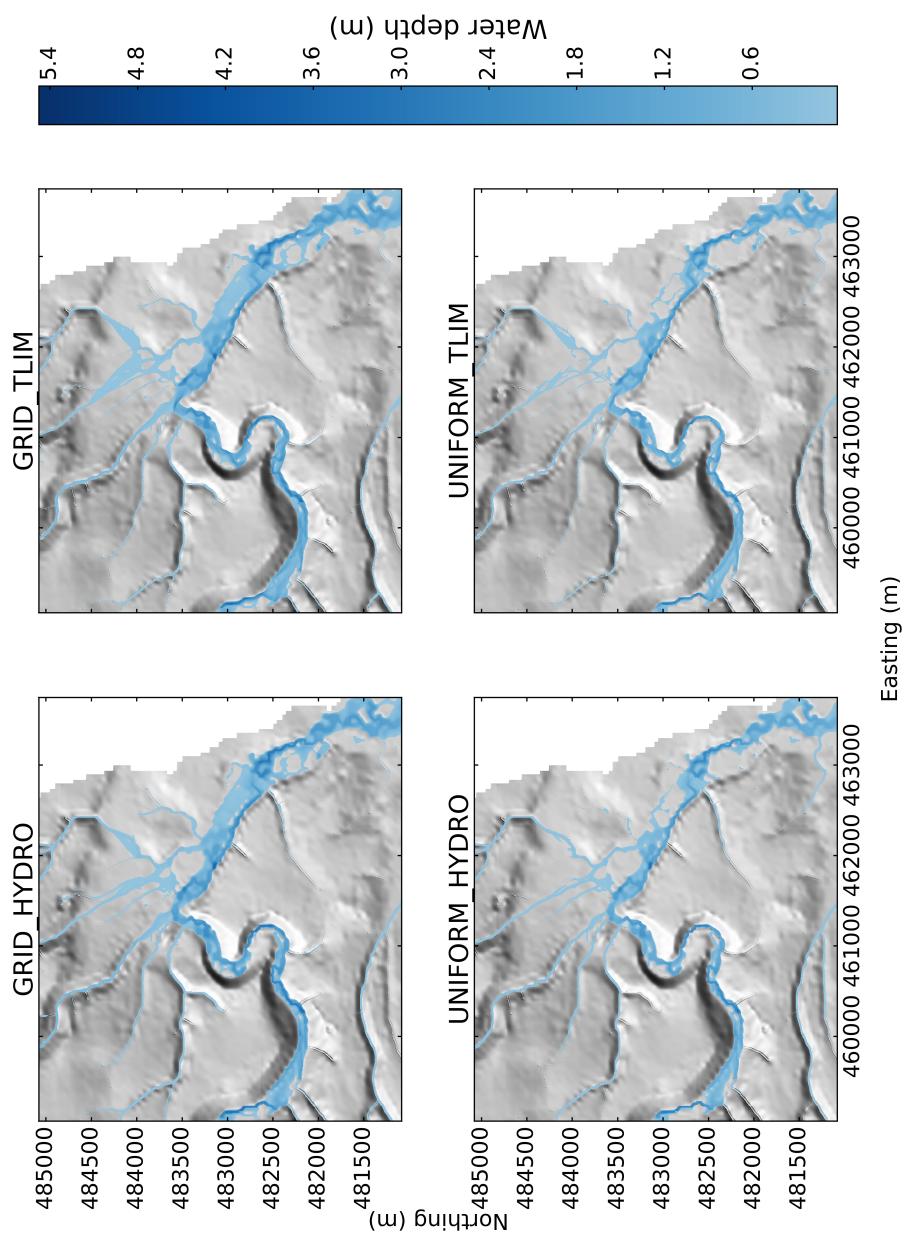


Figure 6.7: Flood extents in the Ryedale catchment at the time of maximum river discharge for each simulation.

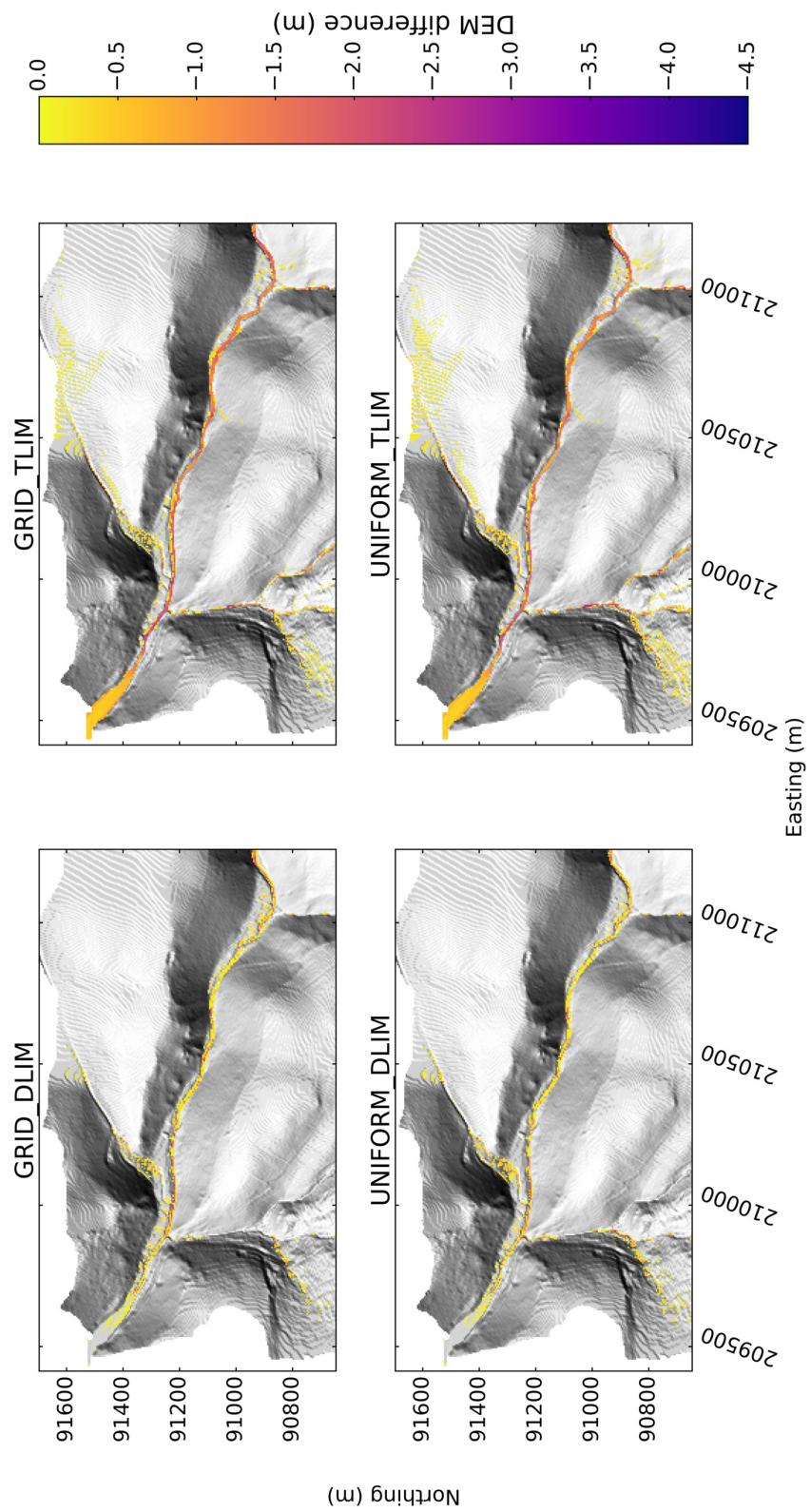


Figure 6.8: Boscastle. Erosion.

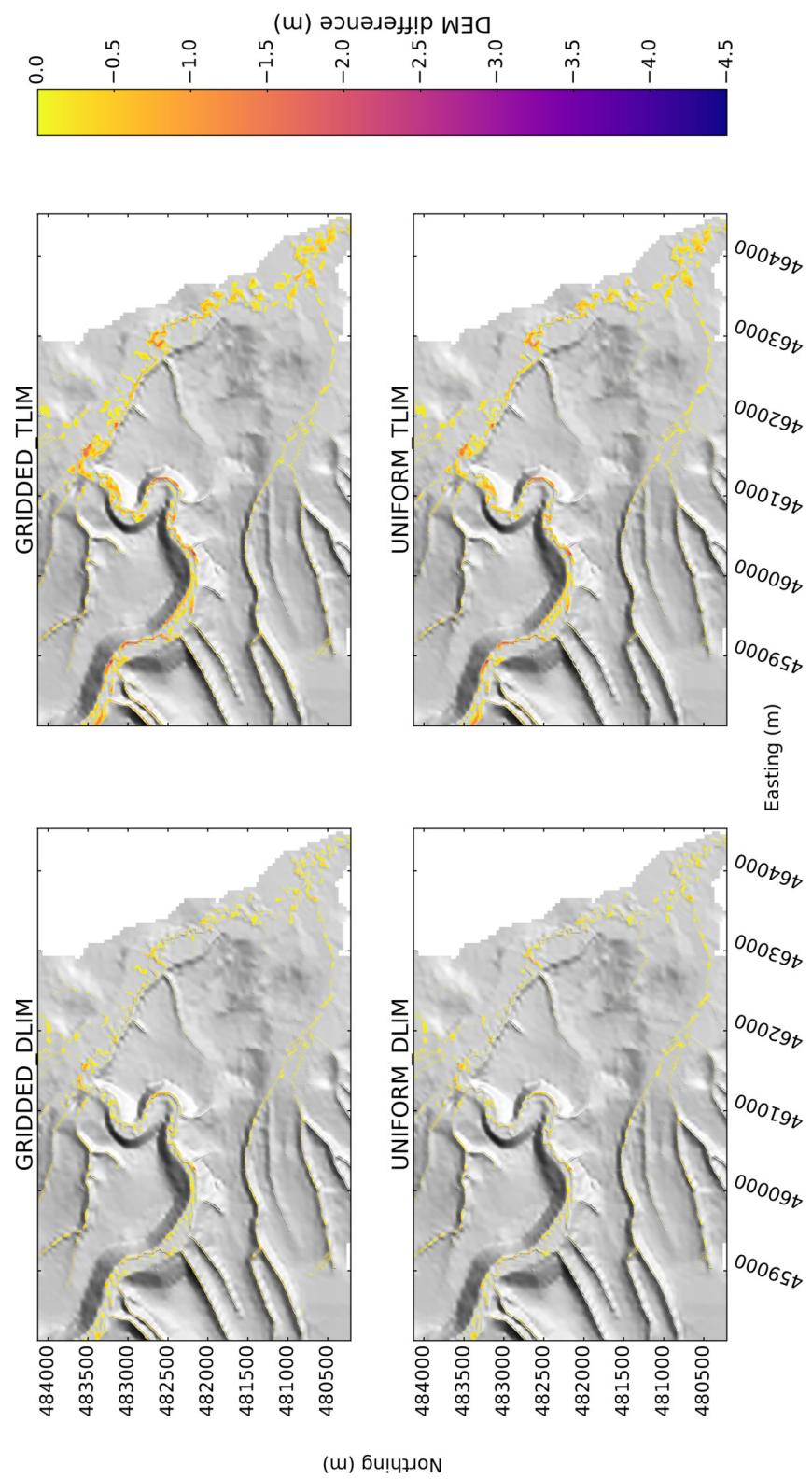


Figure 6.9: Ryedale. Erosion.

Bibliography

- F Ahnert. Brief description of a comprehensive three-dimensional process-response model of landform development. *Z. Geomorphol. Suppl.*, 25:29–49, 1976.
- Gene M Amdahl. Validity of the single processor approach to achieving large scale computing capabilities. In *Proceedings of the April 18-20, 1967, spring joint computer conference*, pages 483–485. ACM, 1967.
- John Aycock. A brief history of just-in-time. *ACM Computing Surveys (CSUR)*, 35(2):97–113, 2003.
- Paul D Bates, Matthew S Horritt, and Timothy J Fewtrell. A simple inertial formulation of the shallow water equations for efficient two-dimensional flood inundation modelling. *Journal of Hydrology*, 387(1):33–45, 2010.
- PD Bates, KJ Marks, and MS Horritt. Optimal use of high-resolution topographic data in flood inundation models. *Hydrological Processes*, 17(3):537–557, 2003.
- KJ Beven and Michael J Kirkby. A physically based, variable contributing area model of basin hydrology/un modèle à base physique de zone d'appel variable de l'hydrologie du bassin versant. *Hydrological Sciences Journal*, 24(1):43–69, 1979.
- Rafael L Bras, Gregory E Tucker, and Vanessa Teles. Six myths about mathematical modeling in geomorphology. *Prediction in geomorphology*, pages 63–79, 2003.
- A Casas, Gerardo Benito, VR Thorndycraft, and M Rico. The topographic data source of digital terrain models as a key element in the accuracy of hydraulic flood modelling. *Earth Surface Processes and Landforms*, 31(4):444–456, 2006.
- Michael Church. What is a geomorphological prediction? *Prediction in Geomorphology*, pages 183–194, 2003.

- Fiona J Clubb, Simon M Mudd, David T Milodowski, Martin D Hurst, and Louise J Slater. Objective extraction of channel heads from high-resolution topographic data. *Water Resources Research*, 50(5):4283–4304, 2014.
- Robert Colwell. The chip design game at the end of moore’s law. In *2013 IEEE Hot Chips 25 Symposium (HCS)*, pages 1–16. IEEE, 2013.
- T J Coulthard. Landscape Evolution Models: a software review. *Hydrological Processes*, 173(15):165–173, 2001.
- TJ Coulthard, MG Macklin, and MJ Kirkby. A cellular model of holocene upland river basin and alluvial fan evolution. *Earth Surface Processes and Landforms*, 27(3):269–288, 2002.
- Tom J. Coulthard, Jeff C. Neal, Paul D. Bates, Jorge Ramirez, Gustavo a. M. de Almeida, and Greg R. Hancock. Integrating the LISFLOOD-FP 2D hydrodynamic model with the CAESAR model: implications for modelling landscape evolution. *Earth Surface Processes and Landforms*, 38(15):1897–1906, dec 2013. ISSN 01979337. doi: 10.1002/esp.3478. URL <http://doi.wiley.com/10.1002/esp.3478>.
- Leonardo Dagum and Ramesh Menon. Openmp: an industry standard api for shared-memory programming. *IEEE computational science and engineering*, 5(1):46–55, 1998.
- William E Dietrich, Dino G Bellugi, Leonard S Sklar, Jonathan D Stock, Arjun M Heimsath, and Joshua J Roering. Geomorphic transport laws for predicting landscape form and dynamics. *Prediction in geomorphology*, pages 103–132, 2003.
- Dean Gesch, Michael Oimoen, Susan Greenlee, Charles Nelson, Michael Steuck, and Dean Tyler. The national elevation dataset. *Photogrammetric engineering and remote sensing*, 68(1):5–32, 2002.
- Susan L Graham, Peter B Kessler, and Marshall K Mckusick. Gprof: A call graph execution profiler. In *ACM Sigplan Notices*, volume 17, pages 120–126. ACM, 1982.
- John L Gustafson. Reevaluating amdahl’s law. *Communications of the ACM*, 31(5):532–533, 1988.

Mark D Hill and Michael R Marty. Amdahl's law in the multicore era. *Computer*, 41(7):33–38, 2008.

Daniel EJ Hobley, Jordan M Adams, Sai Siddhartha Nudurupati, Eric WH Hutton, Nicole M Gasparini, Erkan Istanbulluoglu, and Gregory E Tucker. Creative computing with landlab: an open-source toolkit for building, coupling, and exploring two-dimensional numerical models of earth-surface dynamics, earth surf. *Earth Surface Dynam. Discuss.*, 10, 2016.

Alan D Howard and Gordon Kerby. Channel changes in badlands. *Geological Society of America Bulletin*, 94(6):739–752, 1983. doi: 10.1130/0016-7606(1983)94[739:CCIB]

Valeriy Y Ivanov, Enrique R Vivoni, Rafael L Bras, and Dara Entekhabi. Catchment hydrologic response with a fully distributed triangulated irregular network model. *Water Resources Research*, 40(11), 2004.

Stefan J Kollet, Reed M Maxwell, Carol S Woodward, Steve Smith, Jan Vandeborgh, Harry Vereecken, and Clemens Simmer. Proof of concept of regional scale hydrologic simulations at hydrologic resolution utilizing massively parallel computer resources. *Water resources research*, 46(4), 2010.

Sriram Krishnan, Christopher Crosby, Viswanath Nandigam, Minh Phan, Charles Cowart, Chaitanya Baru, and Ramon Arrowsmith. Opentopography: a services oriented architecture for community access to lidar topography. In *Proceedings of the 2nd International Conference on Computing for Geospatial Research & Applications*, page 7. ACM, 2011.

Qiuhua Liang and Luke S Smith. A high-performance integrated hydrodynamic modelling system for urban flood simulations. *Journal of Hydroinformatics*, 17(4):518–533, 2015.

Charles C Mann. The end of moores law. *Technology Review*, 103(3):42–48, 2000.

Gordon E Moore. Cramming more components onto integrated circuits. *Proceedings of the IEEE*, 86(1), 1998.

Jeffrey Neal, Timothy Fewtrell, and Mark Trigg. Parallelisation of storage cell flood models using openmp. *Environmental Modelling & Software*, 24(7):872–877, 2009.

Stephen L Olivier, Allan K Porterfield, Kyle B Wheeler, Michael Spiegel, and Jan F Prins. Openmp task scheduling strategies for multicore numa systems. *International Journal of High Performance Computing Applications*, page 1094342011434065, 2012.

Paola Passalacqua, Tien Do Trung, Efi Foufoula-Georgiou, Guillermo Sapiro, and William E Dietrich. A geometric framework for channel network extraction from lidar: Nonlinear diffusion and geodesic paths. *Journal of Geophysical Research: Earth Surface*, 115(F1), 2010.

Frank J Pazzaglia. Landscape evolution models. *Development of Quaternary Science*, 1:247–274, 2003. doi: 10.1016/S1571-0866(03)01012-1.

Jon D. Pelletier. Fluvial and slope-wash erosion of soil-mantled landscapes: detachment- or transport-limited? *Earth Surface Processes and Landforms*, 37(1):37–51, jan 2012. ISSN 01979337. doi: 10.1002/esp.2187. URL <http://doi.wiley.com/10.1002/esp.2187>.

Jon D Pelletier, A Brad Murray, Jennifer L Pierce, Paul R Bierman, David D Breshears, Benjamin T Crosby, Michael Ellis, Efi Foufoula-Georgiou, Arjun M Heimsath, Chris Houser, et al. Forecasting the response of earth’s surface to future climatic and land use changes: A review of methods and research needs. *Earth’s Future*, 3(7):220–251, 2015.

Bernhard Rabus, Michael Eineder, Achim Roth, and Richard Bamler. The shuttle radar topography mission—a new class of digital elevation models acquired by spaceborne radar. *ISPRS journal of photogrammetry and remote sensing*, 57(4):241–262, 2003.

Rizos Sakellariou. *On the quest for perfect load balance in loop-based parallel computations*. PhD thesis, University of Manchester, 1996.

Robert R Schaller. Moore’s law: past, present and future. *IEEE spectrum*, 34(6):52–59, 1997.

JM Schoorl, MPW Sonneveld, A Veldkamp, et al. Three-dimensional landscape process modelling: the effect of dem resolution. *Earth Surface Processes and Landforms*, 25(9):1025–1034, 2000.

- Luke S Smith and Qiuhua Liang. Towards a generalised gpu/cpu shallow-flow modelling tool. *Computers & Fluids*, 88:334–343, 2013.
- Luke S Smith, Qiuhua Liang, and Paul F Quinn. Towards a hydrodynamic modelling framework appropriate for applications in urban flood assessment and mitigation using heterogeneous computing. *Urban Water Journal*, 12(1):67–78, 2015.
- Noah P. Snyder. Importance of a stochastic distribution of floods and erosion thresholds in the bedrock river incision problem. *Journal of Geophysical Research*, 108(B2):2117, 2003. ISSN 0148-0227. doi: 10.1029/2001JB001655. URL <http://doi.wiley.com/10.1029/2001JB001655>.
- Xian-He Sun and Yong Chen. Reevaluating amdahl’s law in the multicore era. *Journal of Parallel and Distributed Computing*, 70(2):183–188, 2010.
- Paolo Tarolli, J Ramon Arrowsmith, and Enrique R Vivoni. Understanding earth surface processes from remotely sensed digital terrain models. *Geomorphology*, 113(1):1–3, 2009.
- Gregory Tucker, Stephen Lancaster, Nicole Gasparini, and Rafael Bras. The channel-hillslope integrated landscape development model (child). In *Landscape erosion and evolution modeling*, pages 349–388. Springer, 2001a.
- Gregory E Tucker. Drainage basin sensitivity to tectonic and climatic forcing: Implications of a stochastic model for the role of entrainment and erosion thresholds. *Earth Surface Processes and Landforms*, 29(2):185–205, 2004.
- Gregory E Tucker and Gregory R Hancock. Modelling Landscape Evolution. *Earth Surface Processes and Landforms*, 50:28–50, 2010. doi: 10.1002/esp.
- Gregory E. Tucker, Stephen T. Lancaster, Nicole M. Gasparini, Rafael L. Bras, and Scott M. Rybarczyk. An object-oriented framework for distributed hydrologic and geomorphic modeling using triangulated irregular networks. *Computers & Geosciences*, 27(8):959–973, October 2001b. ISSN 00983004. doi: 10.1016/S0098-3004(00)00134-5. URL <http://linkinghub.elsevier.com/retrieve/pii/S0098300400001345>.

Declan A Valters. Modelling geomorphic systems: Landscape evolution. In *Geomorphological Techniques*, volume 6, pages 5–12. British Society for Geomorphology, 2016.

Marco J Van De Wiel, Tom J Coulthard, Mark G Macklin, and John Lewin. Embedding reach-scale fluvial dynamics within the caesar cellular automaton landscape evolution model. *Geomorphology*, 90(3):283–301, 2007.

Kelin X Whipple and Gregory E Tucker. Dynamics of the stream-power river incision model: Implications for height limits of mountain ranges, landscape response timescales, and research needs. *Journal of Geophysical Research: Solid Earth*, 104(B8):17661–17674, 1999.

Peter R Wilcock and Joanna C Crowe. Surface-based transport model for mixed-size sediment. *Journal of Hydraulic Engineering*, 129(2):120–128, 2003.

Marc H Willebeek-LeMair and Anthony P. Reeves. Strategies for dynamic load balancing on highly parallel computers. *IEEE Transactions on parallel and distributed systems*, 4(9):979–993, 1993.

Garry Willgoose. Mathematical Modeling of Whole Landscape Evolution. *Annual Review of Earth and Planetary Sciences*, 33(1):443–459, may 2005. ISSN 0084-6597. doi: 10.1146/annurev.earth.33.092203.122610. URL <http://www.annualreviews.org/doi/abs/10.1146/annurev.earth.33.092203.122610>.

W Eric Wong, Joseph R Horgan, Saul London, and Hiralal Agrawal. A study of effective regression testing in practice. In *Software Reliability Engineering, 1997. Proceedings., The Eighth International Symposium on*, pages 264–274. IEEE, 1997.

.....