

# HOMework 3

REGRESSION, GAUSSIAN PROCESSES, AND BOOSTING

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## Problem 1: Gaussian Processes

- (a) A comparison of covariance functions: see figures ??, ??, and ??.
- (b) Increasing  $\sigma^2$  increases the “noisyness” of the output points,  $y_i$ . Figure ?? shows... TODO
- (c) Show  $p(x_1|x_2) \propto p(x_1, x_2)$

$$p(X_1|x_2) = \frac{1}{\text{sqrt}(2\pi)^k |\Sigma_{x_1|x_2}|} \exp\left(-\frac{1}{2}(x - \mu_{x_1|x_2})\right)$$

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \sim N\left(\begin{bmatrix} \mu_1 \\ \mu_2 \end{bmatrix} \begin{bmatrix} \Sigma_{11} & \Sigma_{12} \\ \Sigma_{21} & \Sigma_{22} \end{bmatrix}\right)$$

Let  $\Sigma^{-1} = \Lambda^{-1}$  such that

$$\Sigma^{-1} = \begin{bmatrix} \Sigma_{11} & \Sigma_{12} \\ \Sigma_{21} & \Sigma_{22} \end{bmatrix}^{-1} = \begin{bmatrix} \Lambda_{11} & \Lambda_{12} \\ \Lambda_{21} & \Lambda_{22} \end{bmatrix} = \Lambda$$

We can focus on the exponent since we want to find  $\mu_{x_1|x_2}$  and  $\Sigma_{x_1|x_2}$ .

$$\begin{aligned} \exp &= -\frac{1}{2}(x - \mu)^T \Sigma^{-1}(x - \mu) \\ &= -\frac{1}{2} \begin{bmatrix} x_1 - \mu_1 \\ x_2 - \mu_2 \end{bmatrix}^T \begin{bmatrix} \Sigma_{11} & \Sigma_{12} \\ \Sigma_{21} & \Sigma_{22} \end{bmatrix}^{-1} \begin{bmatrix} x_1 - \mu_1 \\ x_2 - \mu_2 \end{bmatrix} \\ &= -\frac{1}{2} \begin{bmatrix} x_1 - \mu_1 \\ x_2 - \mu_2 \end{bmatrix}^T \begin{bmatrix} \Lambda_{11} & \Lambda_{12} \\ \Lambda_{21} & \Lambda_{22} \end{bmatrix} \begin{bmatrix} x_1 - \mu_1 \\ x_2 - \mu_2 \end{bmatrix} \end{aligned}$$

$$\begin{aligned}
&= -\frac{1}{2}(x_1 - \mu_1)^T \Lambda_{11}(x_1 - \mu_1) - \frac{1}{2}(x_1 - \mu_1)^T \Lambda_{12}(x_2 - \mu_2) \\
&\quad - \frac{1}{2}(x_2 - \mu_2)^T \Lambda_{21}(x_1 - \mu_1) - \frac{1}{2}(x_2 - \mu_2)^T \Lambda_{22}(x_2 - \mu_2)
\end{aligned}$$

We can call the last term,  $-\frac{1}{2}(x_2 - \mu_2)^T \Lambda_{22}(x_2 - \mu_2)$ ,  $C$  since it does not depend on  $x_1$  (constant).

$$= -\frac{1}{2}(x_1 - \mu_1)^T \Lambda_{11}(x_1 - \mu_1) - \frac{1}{2}(x_1 - \mu_1)^T \Lambda_{12}(x_2 - \mu_2) - \frac{1}{2}(x_2 - \mu_2)^T \Lambda_{21}(x_1 - \mu_1) + C$$

$$\begin{aligned}
&= -\frac{1}{2}x_1^T \Lambda_{11}x_1 + \frac{1}{2}x_1^T \Lambda_{11}\mu_1 + \frac{1}{2}\mu_1^T \Lambda_{11}x_1 - \frac{1}{2}\mu_1^T \Lambda_{11}\mu_1 \\
&\quad - \frac{1}{2}x_1^T \Lambda_{12}x_2 + \frac{1}{2}x_1^T \Lambda_{12}\mu_2 + \frac{1}{2}\mu_1^T \Lambda_{12}x_2 - \frac{1}{2}\mu_1^T \Lambda_{12}\mu_2 \\
&\quad - \frac{1}{2}x_2^T \Lambda_{21}x_1 + \frac{1}{2}x_2^T \Lambda_{21}\mu_1 + \frac{1}{2}\mu_2^T \Lambda_{21}x_1 - \frac{1}{2}\mu_2^T \Lambda_{21}\mu_1 + C
\end{aligned}$$

Again, include any constants that do not depend on  $x_1$  in  $C$ .

$$= -\frac{1}{2}x_1^T \Lambda_{11}x_1 + \frac{1}{2}x_1^T \Lambda_{11}\mu_1 + \frac{1}{2}\mu_1^T \Lambda_{11}x_1 - \frac{1}{2}x_1^T \Lambda_{12}x_2 + \frac{1}{2}x_1^T \Lambda_{12}\mu_2 - \frac{1}{2}x_2^T \Lambda_{21}x_1 + \frac{1}{2}\mu_2^T \Lambda_{21}x_1 + C$$

We can use the fact that  $\Lambda_{21} = \Lambda_{12}^T$  to reduce the equation.

$$= -\frac{1}{2}x_1^T \Lambda_{11}x_1 + x_1^T \Lambda_{11}\mu_1 - x_1^T \Lambda_{12}x_2 + x_1^T \Lambda_{12}\mu_2 + C$$

(d)

(e) A comparison of covariance functions sampled from  $p(f(X)|Y_*)$ : see figures ??, ??, and ??.

(f) TODO

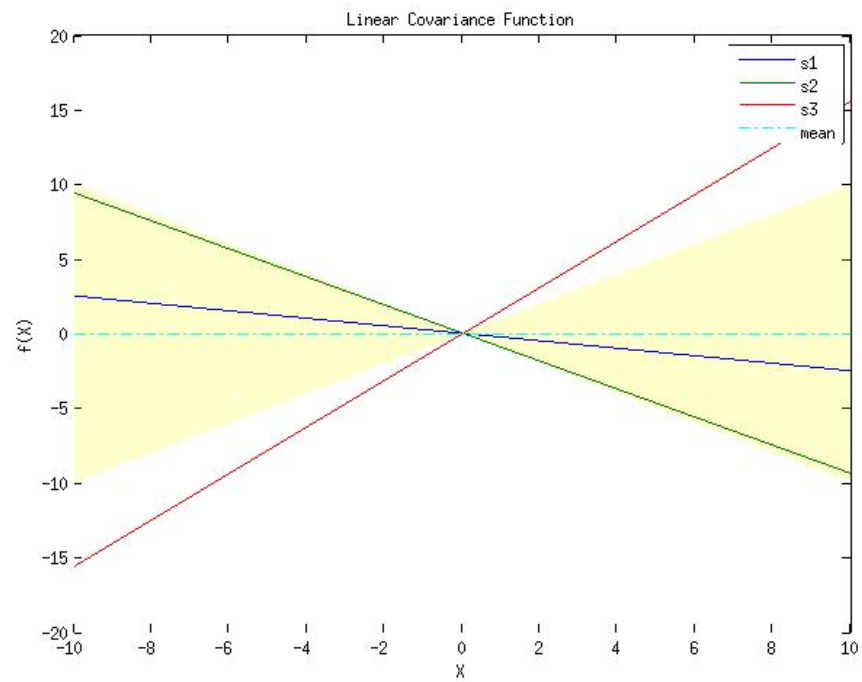


Figure 1: Linear Covariance Function

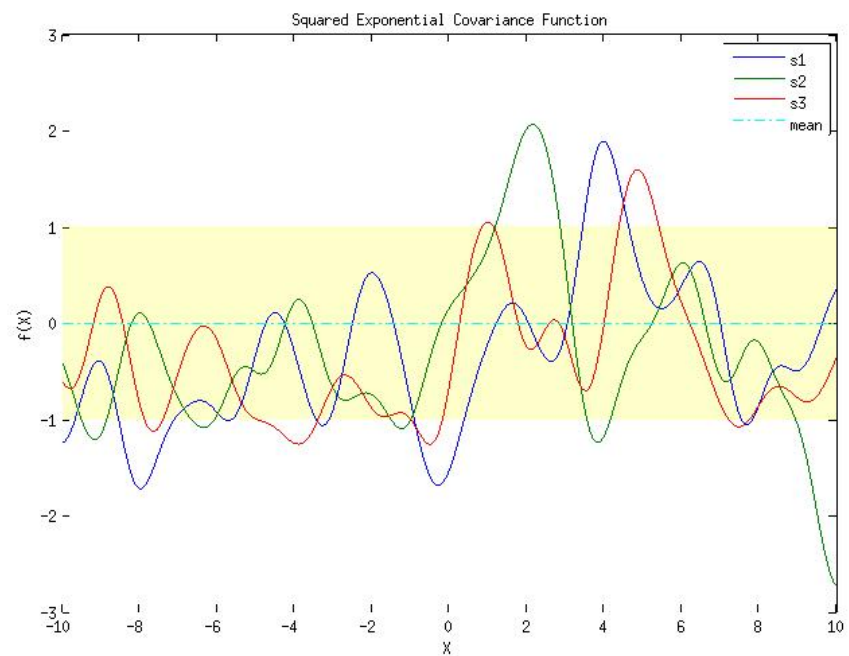


Figure 2: Square Exponential Covariance Function

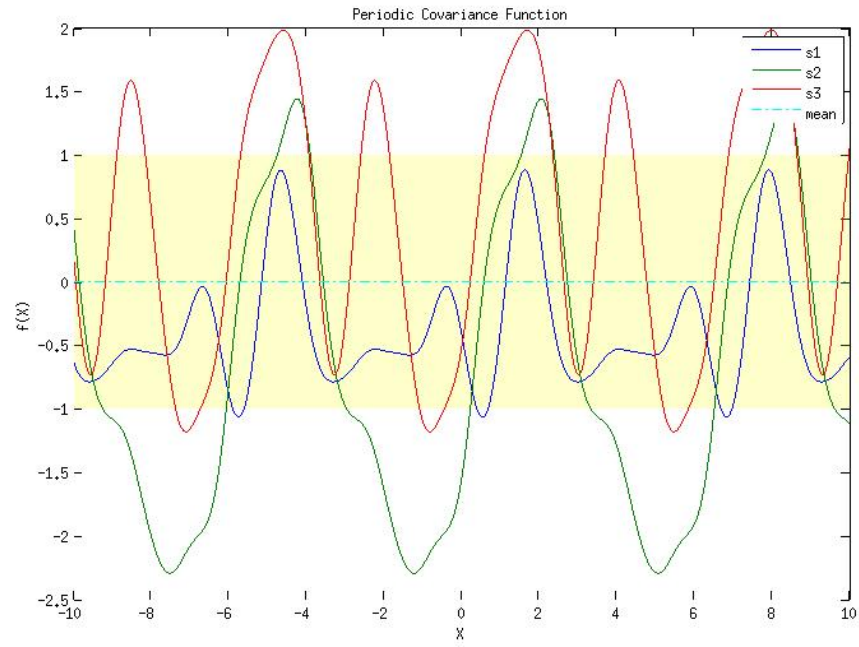


Figure 3: Periodic Covariance Function

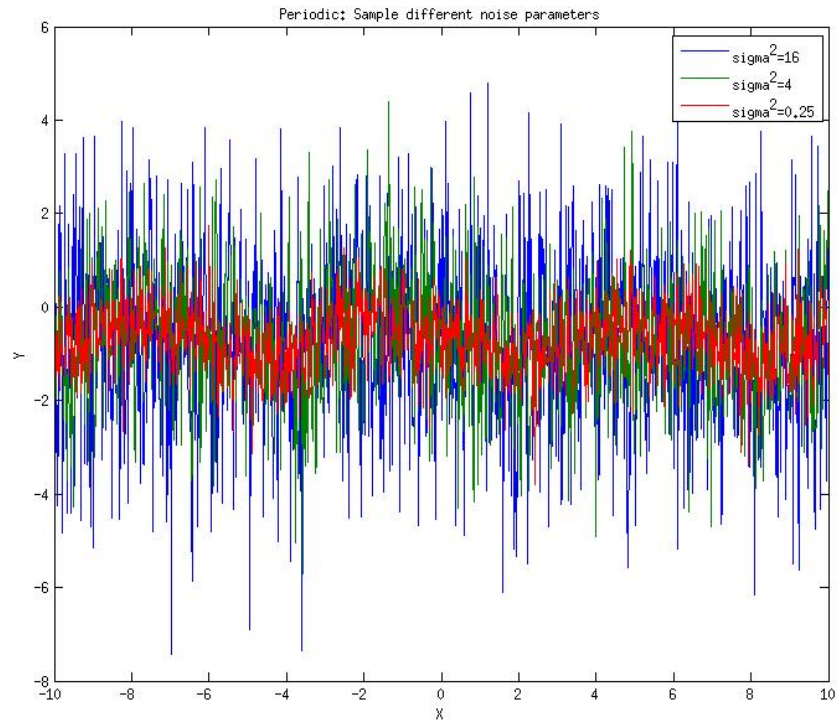


Figure 4: Sampling Different Gaussian Noise Parameters Using a Periodic Covariance Function

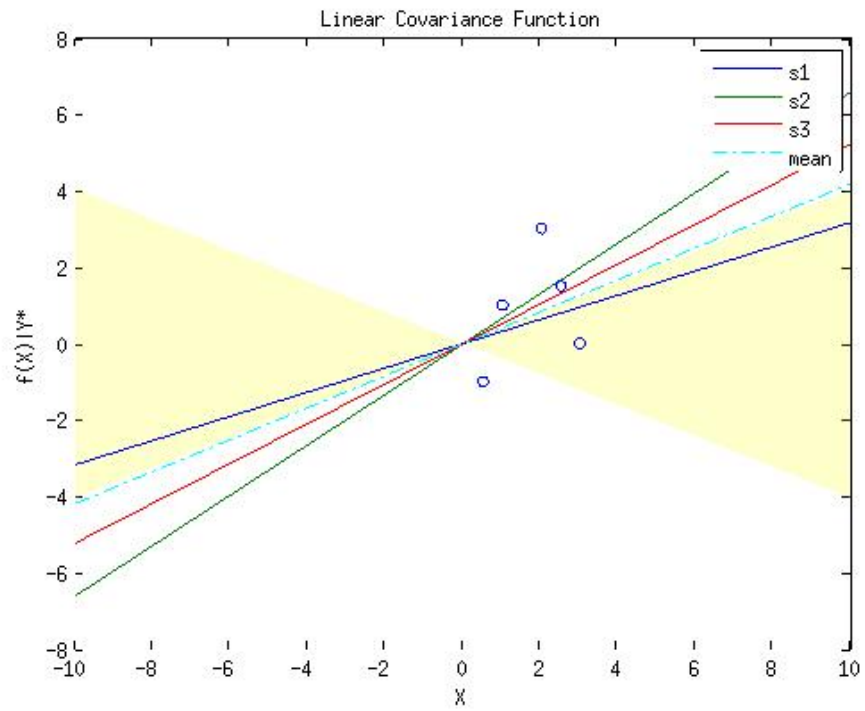


Figure 5: Linear Covariance Function

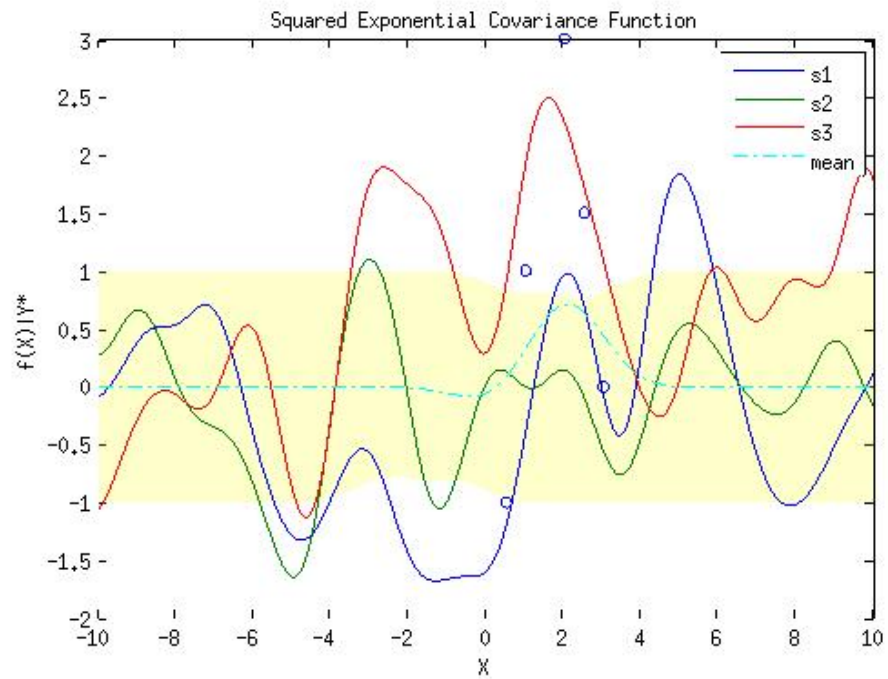


Figure 6: Square Exponential Covariance Function

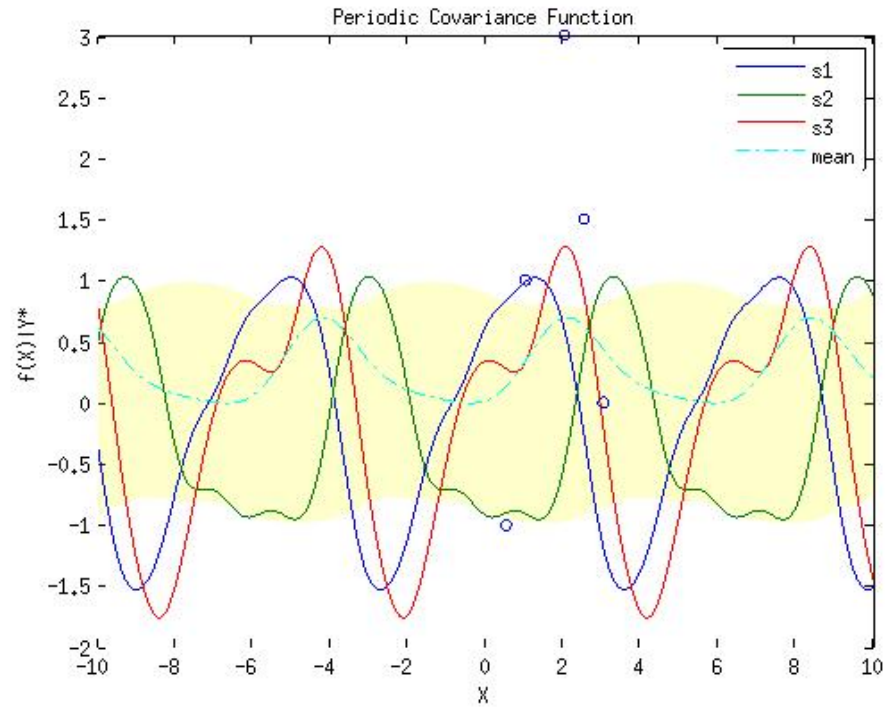


Figure 7: Periodic Covariance Function

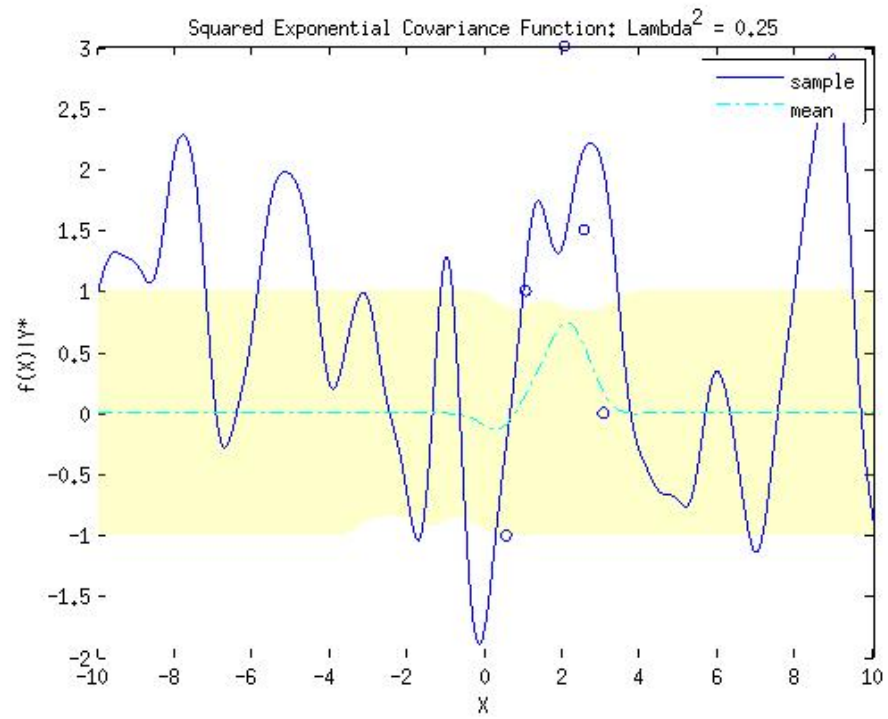


Figure 8: Sampling Different  $\lambda^2$  Parameters Using the Squared Exponential Function

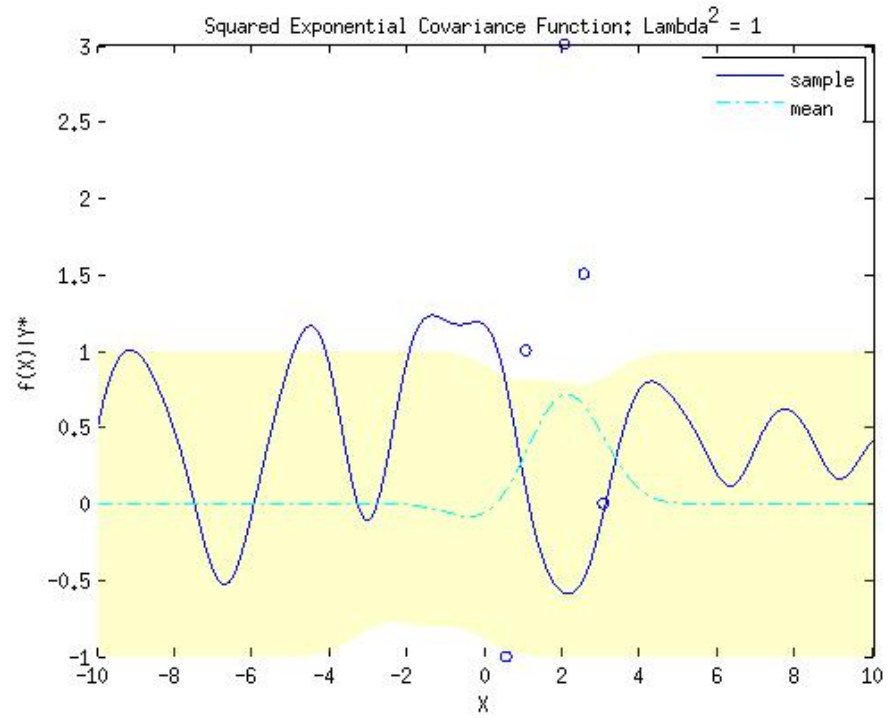


Figure 9: Sampling Different  $\lambda^2$  Parameters Using the Squared Exponential Function

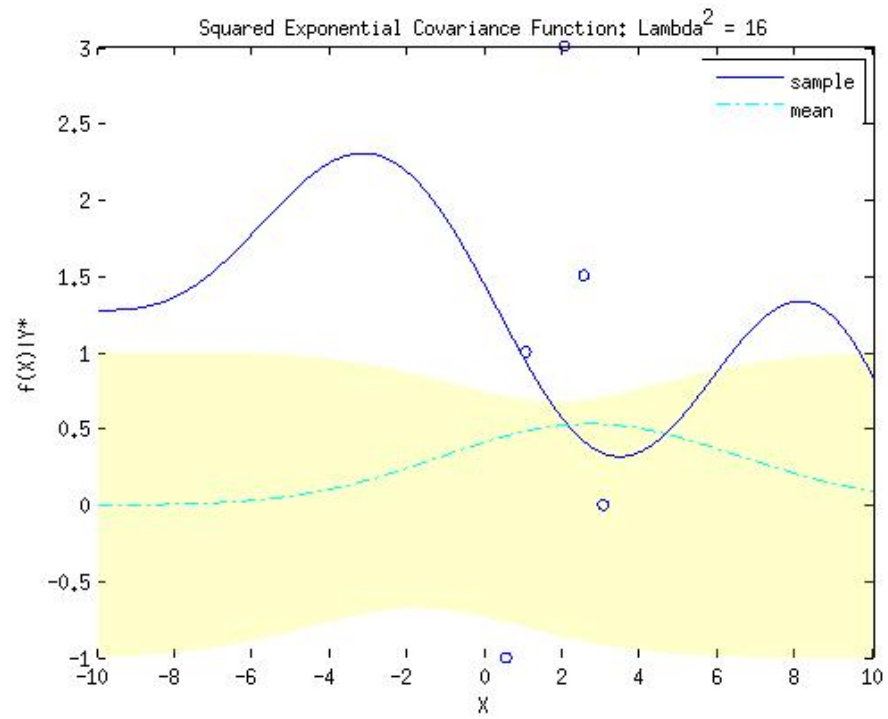


Figure 10: Sampling Different  $\lambda^2$  Parameters Using the Squared Exponential Function