

HOMework 3

REGRESSION, GAUSSIAN PROCESSES, AND BOOSTING

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Problem 1: Gaussian Processes

- (a) A comparison of covariance functions: see figures 1, 2, and 3.
- (b) Increasing σ^2 increases the “noisyness” of the output points, y_i . Figure 4 shows... TODO
- (c) Show $p(x_1|x_2) \propto p(x_1, x_2)$

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \sim N\left(\begin{bmatrix} \mu_1 \\ \mu_2 \end{bmatrix} \begin{bmatrix} \Sigma_{11} & \Sigma_{12} \\ \Sigma_{21} & \Sigma_{22} \end{bmatrix}\right)$$

Let $\Sigma^{-1} = \Lambda^{-1}$ such that

$$\Sigma^{-1} = \begin{bmatrix} \Sigma_{11} & \Sigma_{12} \\ \Sigma_{21} & \Sigma_{22} \end{bmatrix}^{-1} = \begin{bmatrix} \Lambda_{11} & \Lambda_{12} \\ \Lambda_{21} & \Lambda_{22} \end{bmatrix} = \Lambda$$

We can focus on the exponent since we want to find $\mu_{x_1|x_2}$ and $\Sigma_{x_1|x_2}$.

$$\begin{aligned} exp &= -\frac{1}{2}(x - \mu)^T \Sigma^{-1}(x - \mu) \\ &= -\frac{1}{2} \begin{bmatrix} x_1 - \mu_1 \\ x_2 - \mu_2 \end{bmatrix}^T \begin{bmatrix} \Sigma_{11} & \Sigma_{12} \\ \Sigma_{21} & \Sigma_{22} \end{bmatrix}^{-1} \begin{bmatrix} x_1 - \mu_1 \\ x_2 - \mu_2 \end{bmatrix} \\ &= -\frac{1}{2} \begin{bmatrix} x_1 - \mu_1 \\ x_2 - \mu_2 \end{bmatrix}^T \begin{bmatrix} \Lambda_{11} & \Lambda_{12} \\ \Lambda_{21} & \Lambda_{22} \end{bmatrix} \begin{bmatrix} x_1 - \mu_1 \\ x_2 - \mu_2 \end{bmatrix} \end{aligned}$$

$$\begin{aligned}
&= -\frac{1}{2}(x_1 - \mu_1)^T \Lambda_{11}(x_1 - \mu_1) - \frac{1}{2}(x_1 - \mu_1)^T \Lambda_{12}(x_2 - \mu_2) \\
&\quad - \frac{1}{2}(x_2 - \mu_2)^T \Lambda_{21}(x_1 - \mu_1) - \frac{1}{2}(x_2 - \mu_2)^T \Lambda_{22}(x_2 - \mu_2)
\end{aligned}$$

We can call the last term, $-\frac{1}{2}(x_2 - \mu_2)^T \Lambda_{22}(x_2 - \mu_2)$, C since it does not depend on x_1 (constant).

$$= -\frac{1}{2}(x_1 - \mu_1)^T \Lambda_{11}(x_1 - \mu_1) - \frac{1}{2}(x_1 - \mu_1)^T \Lambda_{12}(x_2 - \mu_2) - \frac{1}{2}(x_2 - \mu_2)^T \Lambda_{21}(x_1 - \mu_1) + C$$

$$\begin{aligned}
&= -\frac{1}{2}x_1^T \Lambda_{11}x_1 + \frac{1}{2}x_1^T \Lambda_{11}\mu_1 + \frac{1}{2}\mu_1^T \Lambda_{11}x_1 - \frac{1}{2}\mu_1^T \Lambda_{11}\mu_1 \\
&\quad - \frac{1}{2}x_1^T \Lambda_{12}x_2 + \frac{1}{2}x_1^T \Lambda_{12}\mu_2 + \frac{1}{2}\mu_1^T \Lambda_{12}x_2 - \frac{1}{2}\mu_1^T \Lambda_{12}\mu_2 \\
&\quad - \frac{1}{2}x_2^T \Lambda_{21}x_1 + \frac{1}{2}x_2^T \Lambda_{21}\mu_1 + \frac{1}{2}\mu_2^T \Lambda_{21}x_1 - \frac{1}{2}\mu_2^T \Lambda_{21}\mu_1 + C
\end{aligned}$$

Again, include any constants that do not depend on x_1 in C .

$$= -\frac{1}{2}x_1^T \Lambda_{11}x_1 + \frac{1}{2}x_1^T \Lambda_{11}\mu_1 + \frac{1}{2}\mu_1^T \Lambda_{11}x_1 - \frac{1}{2}x_1^T \Lambda_{12}x_2 + \frac{1}{2}x_1^T \Lambda_{12}\mu_2 - \frac{1}{2}x_2^T \Lambda_{21}x_1 + \frac{1}{2}\mu_2^T \Lambda_{21}x_1 + C$$

We can use the fact that $\Lambda_{21} = \Lambda_{12}^T$ to reduce the equation.

$$= -\frac{1}{2}x_1^T \Lambda_{11}x_1 + x_1^T \Lambda_{11}\mu_1 - x_1^T \Lambda_{12}x_2 + x_1^T \Lambda_{12}\mu_2 + C$$

(d)

(e) A comparison of covariance functions sampled from $p(f(X)|Y_*)$: see figures 5, 6, and 7.

(f) TODO

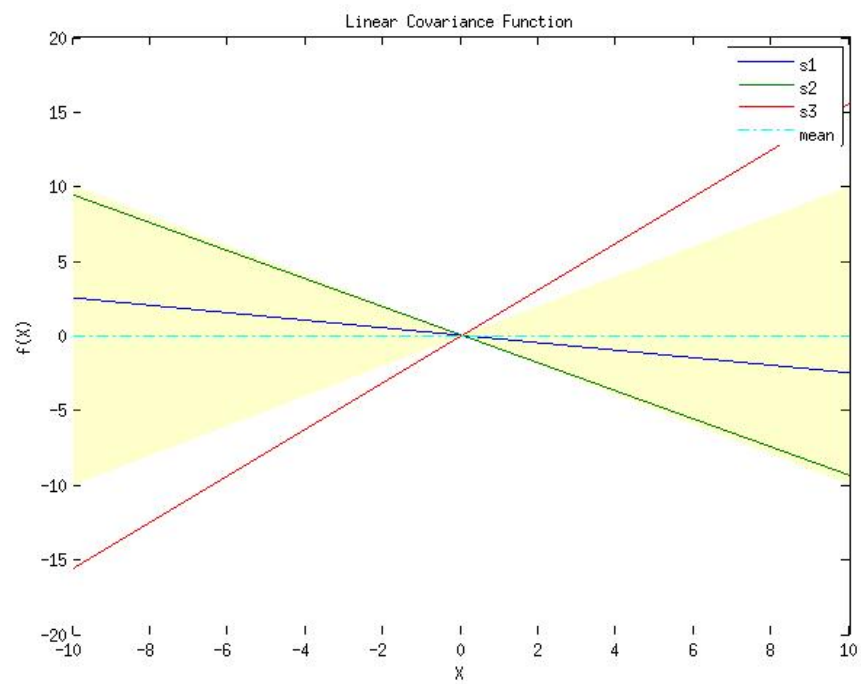


Figure 1: Linear Covariance Function

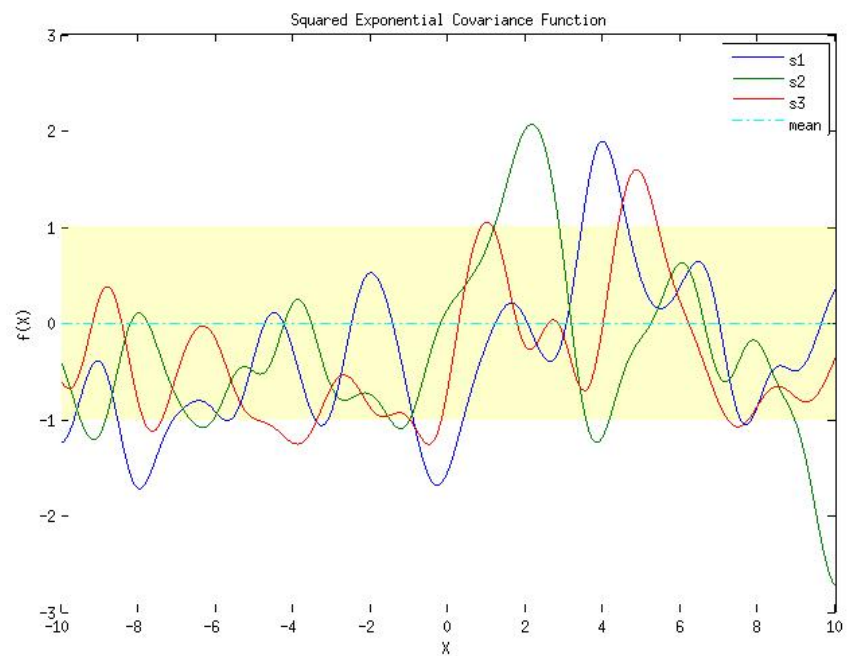


Figure 2: Square Exponential Covariance Function

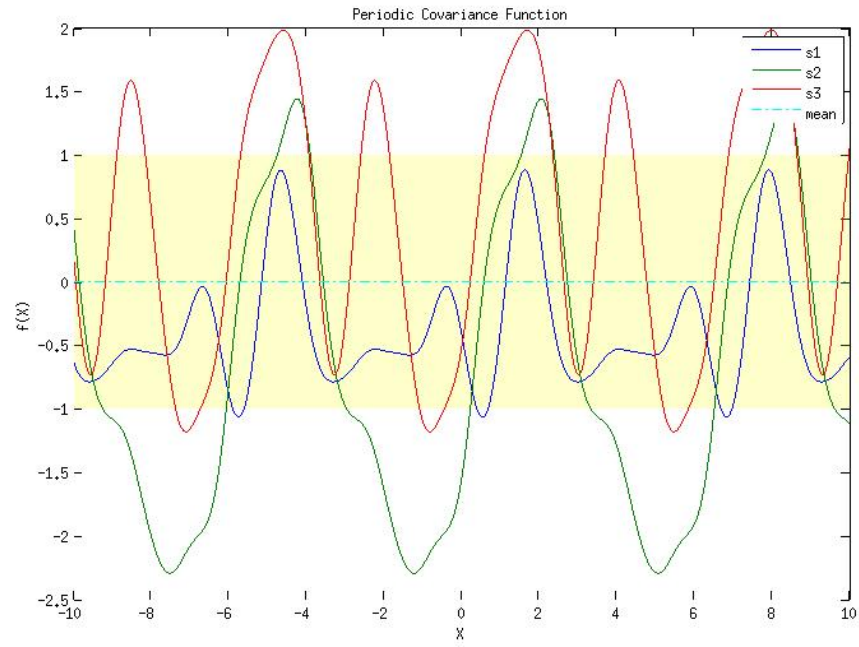


Figure 3: Periodic Covariance Function

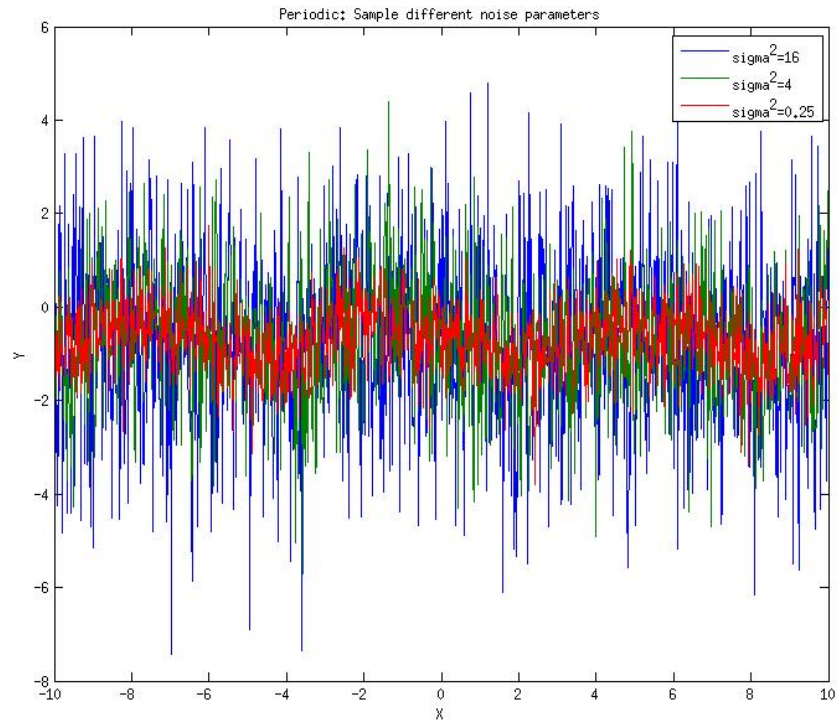


Figure 4: Sampling Different Gaussian Noise Parameters Using a Periodic Covariance Function

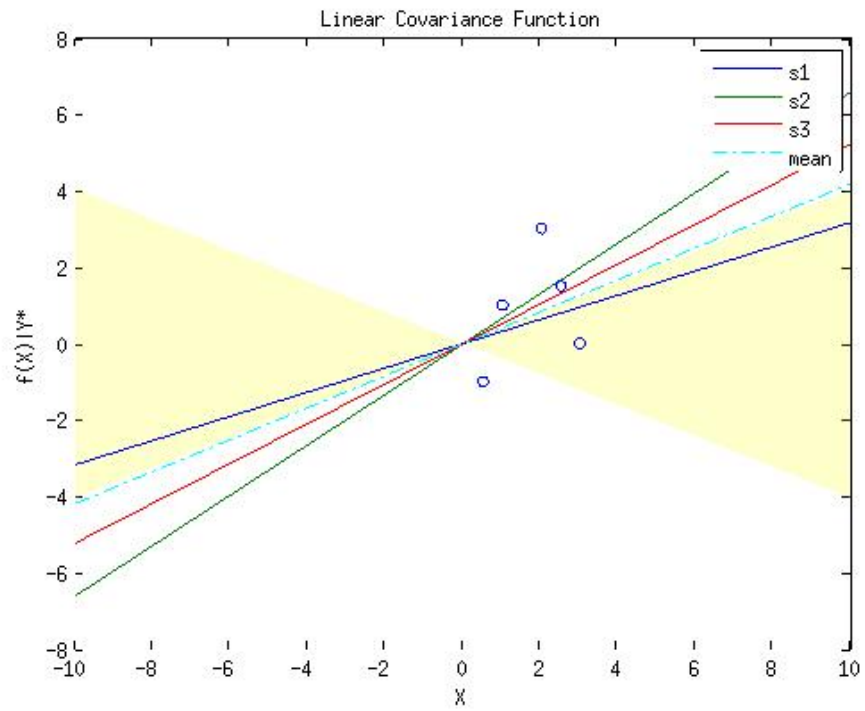


Figure 5: Linear Covariance Function

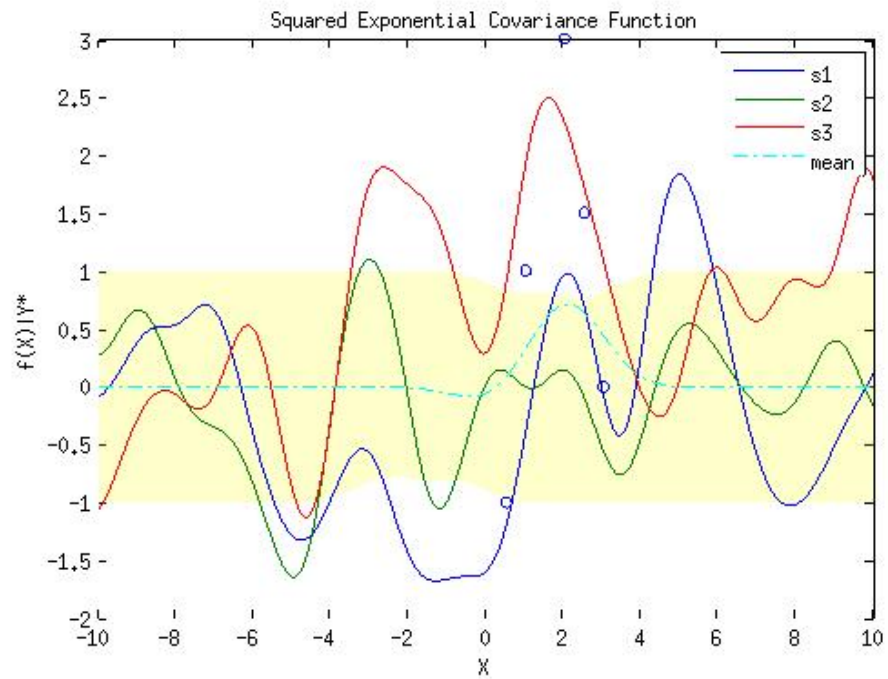


Figure 6: Square Exponential Covariance Function

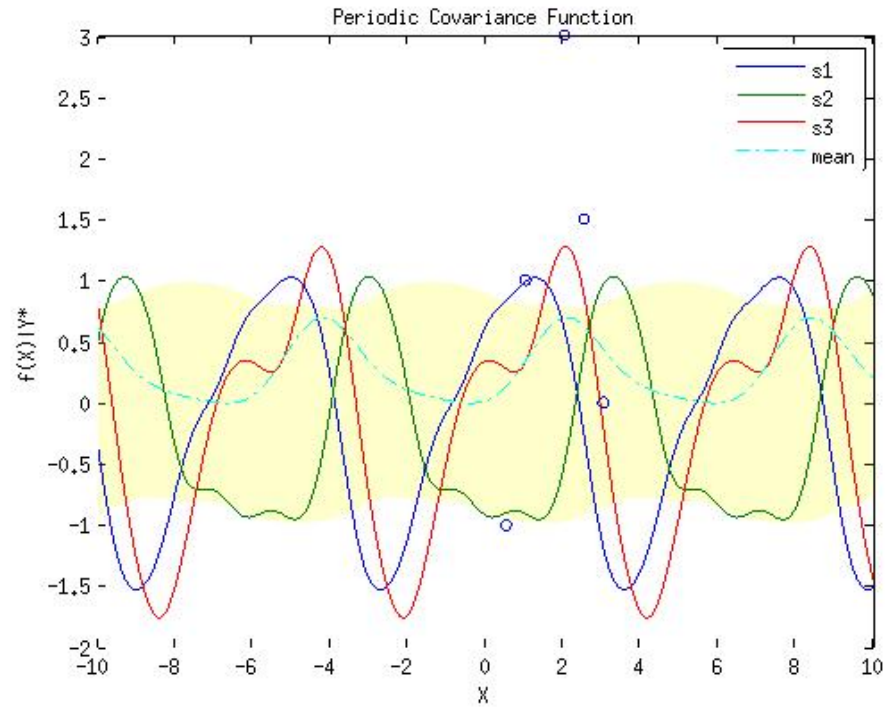


Figure 7: Periodic Covariance Function

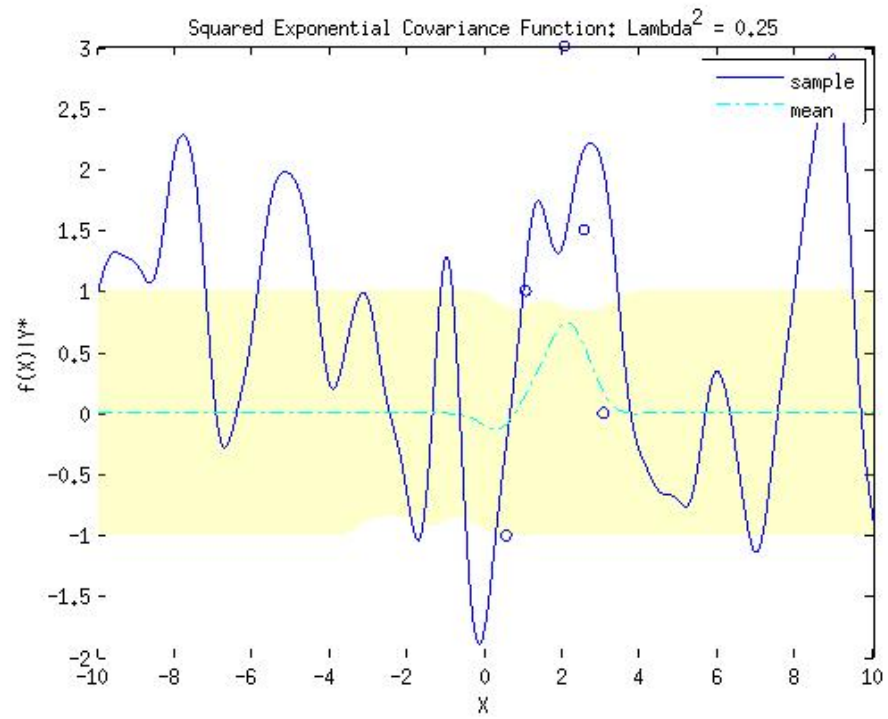


Figure 8: Sampling Different λ^2 Parameters Using the Squared Exponential Function

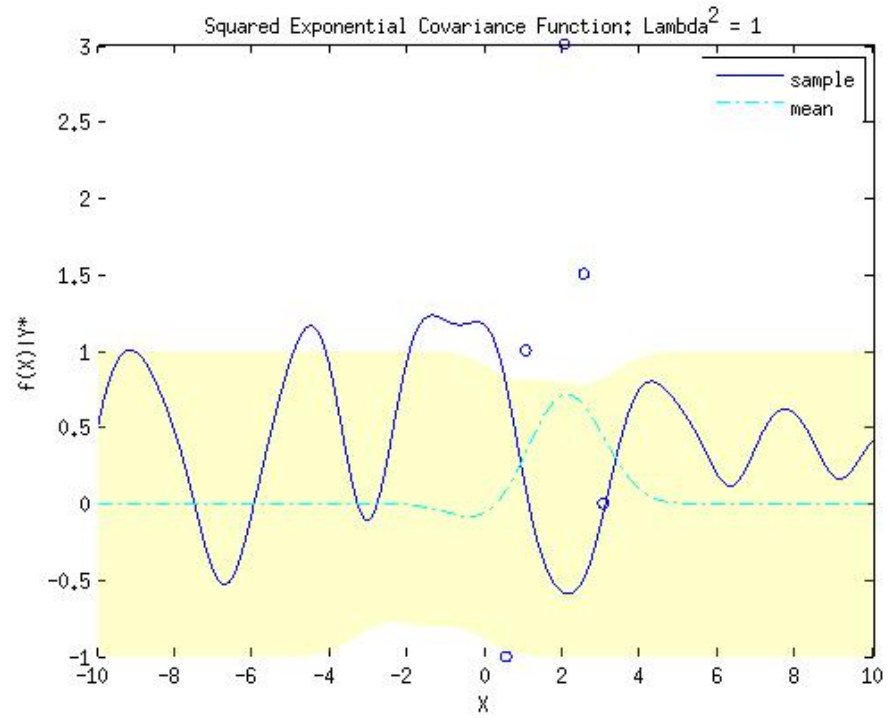


Figure 9: Sampling Different λ^2 Parameters Using the Squared Exponential Function

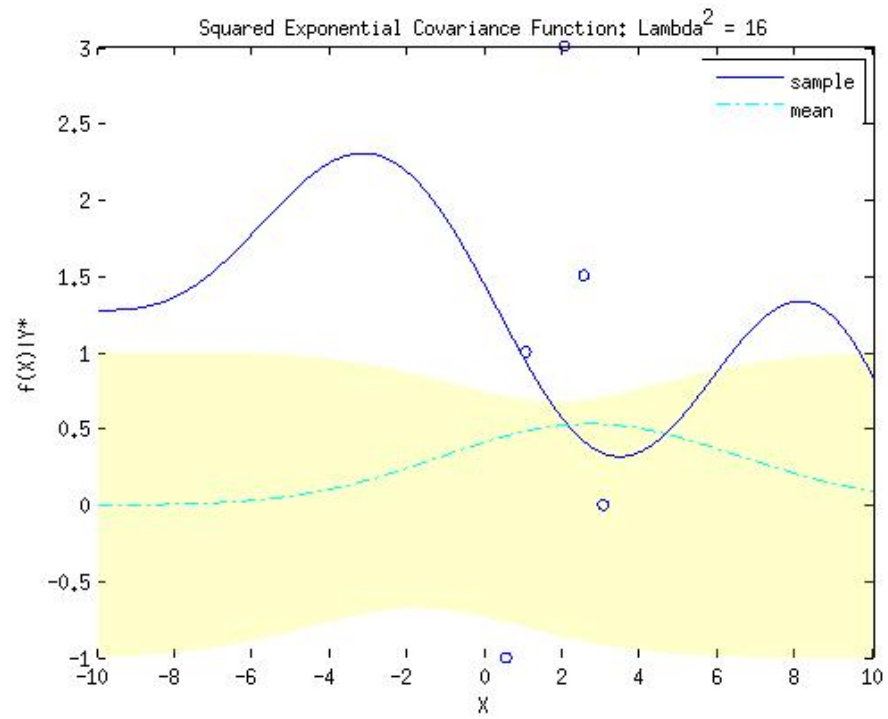


Figure 10: Sampling Different λ^2 Parameters Using the Squared Exponential Function