# Running Probabilistic Programs Backward

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**Abstract.** To be useful in Bayesian practice, a probabilistic language must support conditioning: imposing constraints in a way that preserves the relative probabilities of program outputs. Every language to date that supports probabilistic conditioning also places seemingly artificial restrictions on legal programs, such as disallowing recursion and restricting conditions to simple equality constraints such as x=2.

We develop a semantics for a first-order language with recursion, probabilistic choice and conditioning. Distributions over program outputs are defined by the probabilities of their preimages, a measure-theoretic approach that ensures the language is not artificially limited.

Preimages are generally uncomputable, so we derive an approximating semantics for computing rectangular covers of preimages. We implement the approximating semantics directly in Typed Racket and Haskell.

**Keywords:** Probability, Semantics, Domain-Specific Languages

## 1 Introduction

It is primarily Bayesian practice that drives probabilistic language development. To be useful, a probabilistic language must support **conditioning**, or imposing constraints in a way that preserves the relative probabilities of outputs.

Unfortunately, there is currently no efficient probabilistic language implementation that supports conditioning and does not restrict legal programs. Most commonly, languages that support conditioning disallow recursion, allow only discrete or continuous distributions, and restrict conditions to the form x = c.

These common language restrictions arise from reasoning about probability using **densities**, which are functions from random values to *changes* in probability. While simple and convenient, densities have many limitations. For example, densities for random values with different dimension are incomparable, and they cannot be defined on infinite products. Either limitation rules out recursion.

Densities generally cannot define distributions for the outputs of discontinuous functions. For example, suppose we want to model a thermometer that reports in the range [0, 100], and that the temperature it would report (if it could) is distributed according to a bell curve. We might encode the process as

$$\mathsf{t}' := \mathsf{let} \ \mathsf{t} := \mathsf{normal} \ \mu \ 1$$
 in max 0 (min 100 t)

While t's distribution has a density, the distribution of t' does not.

Densities do not allow reasoning about arbitrary conditions. Bayes' law for densities gives the density of x given a condition y in terms of other densities:

$$p_x(x | y) = \frac{p_y(y | x) \cdot \pi_x(x)}{\int p_y(y | x) \cdot \pi_x(x) dx}$$
 (2)

Bayesians interpret probabilistic processes as defining right-hand side densities  $p_y$  and  $\pi_x$ , and use (2) to discover the density of x given y=c for some observed value c. While x given  $\sin(y)=-1$  and x given x+y=0 are perfectly sensible to reason about, Bayes' law for densities cannot express them. Thus, reasoning with densities disallows all but the simplest conditions.

#### 1.1 Probability Measures

Measure-theoretic probability [13] is widely believed to be able to define every reasonable distribution that densities cannot. It mainly does this by assigning probabilities to sets instead of assigning changes in probability to values. Functions that do so are probability **measures**. In contrast to densities, probabilities of sets of values with different dimension are comparable, and probability measures can be defined on infinite products.

If a probability measure P assigns probabilities to subsets of X and  $f: X \to Y$ , then **preimage measure** defines the distribution over subsets of Y:

$$\Pr[B] = P(f^{-1}(B)) \tag{3}$$

The preimage  $f^{-1}(B) = \{a \in X \mid f(a) \in B\}$  is the subset of X for which f yields a value in B. These are well-defined regardless of f's discontinuities.

Measure-theoretic probability supports any kind of condition. If Pr[B] > 0, the probability of  $B' \subseteq Y$  given  $B \subseteq Y$  is

$$\Pr[B' \mid B] = \Pr[B' \cap B] / \Pr[B] \tag{4}$$

If  $\Pr[B] = 0$ , conditional probabilities can be calculated by applying (4) to decending sequences  $B_1 \supseteq B_2 \supseteq B_3 \supseteq \cdots$  of positive-probability sets whose intersection is B, and taking a limit. If  $Y = \mathbb{R} \times \mathbb{R}$ , for example, the distribution over  $\langle x, y \rangle \in Y$  given that x + y = 0 can be calculated using a descending sequence of sets defined by  $B_n = \{\langle x, y \rangle \in Y \mid |x + y| < 2^{-n}\}$ .

Unfortunately, there is a complicated technical restriction: only measurable subsets of X and Y can be assigned probabilities. This and having to take limits tend to drive practitioners to densities, even though they are so limited.

#### 1.2 Measure-Theoretic Semantics

Because purely functional languages do not allow side effects (except usually nontermination), programmers must write probabilistic programs as functions

from random sources to outputs. Monads and other categorical classes such as idioms (i.e. applicative functors) can make doing so easier [9, 24].

It seems this approach should make it easy to interpret probabilistic programs measure-theoretically. For a probabilistic program  $f: X \to Y$ , the probability measure on output sets  $B \subseteq Y$  should be defined by preimages of B under f and the probability measure on X. Unfortunately, it is difficult to turn this simple-sounding idea into a compositional semantics, for the following reasons.

- 1. Preimages can be defined only for functions with observable domains, which excludes lambdas.
- 2. If subsets of X and Y must be measurable, taking preimages under f must preserve measurability (we say f itself is measurable). Proving the conditions under which this is true is difficult, especially if f may not terminate.
- 3. It is very difficult to define probability measures for arbitrary spaces of measurable functions [2].

Implementing a language based on such a semantics is complicated because

- 4. Contemporary mathematics is unlike any implementation's host language.
- 5. It requires running Turing-equivalent programs backward, efficiently, on possibly uncountable sets of outputs.

We address 1 and 4 by developing our semantics in  $\lambda_{\rm ZFC}$  [25], a  $\lambda$ -calculus with infinite sets, and both extensional and intensional functions. We address 5 by deriving and implementing a *conservative approximation* of the semantics.

We have addressed difficulty 2 by proving that all programs are measurable if language primitives are measurable, including uncomputable primitives such as limits and real equality, regardless of nontermination. The proof interprets programs as extensional functions and applies well-known theorems from measure theory. Unfortunately, the required machinery does not fit in this paper.

For difficulty 3, we have discovered that the "first-orderness" of arrows [8] is a perfect fit for the "first-orderness" of measure theory.

## 1.3 Arrow Solution Overview

We define an exact and an approximating semantics. The exact consists of

- A semantic function which, like the arrow calculus [16] semantic function, transforms first-order programs into the computations of an arbitrary arrow.
- Arrows for evaluating expressions in different ways.

This commutative diagram describes the relationships among the exact arrows:

$$\begin{array}{ccc}
\mathsf{X} \leadsto_{\perp} \mathsf{Y} & \xrightarrow{\mathsf{lift}_{\mathsf{pre}}} & \mathsf{X} \underset{\mathsf{pre}}{\leadsto} \mathsf{Y} \\
\eta_{\perp^*} \downarrow & & \downarrow \eta_{\mathsf{pre}^*} \\
\mathsf{X} \leadsto_{\perp^*} \mathsf{Y} & \xrightarrow{\mathsf{lift}_{\mathsf{pre}^*}} & \mathsf{X} \underset{\mathsf{pre}^*}{\leadsto} \mathsf{Y}
\end{array} \tag{5}$$

In the top row,  $X \leadsto_{\perp} Y$  arrow computations are functions that may raise errors and  $X \underset{\text{pre}}{\leadsto} Y$  computations compute preimages. The computations of the arrows in the bottom row are like those in the top, except they thread an infinite store of random values, and can be constructed to always terminate. Most of our correctness theorems rely on proofs that every morphism in (5) is a homomorphism.

The approximating semantics consists of the same semantic function and arrows  $X_{pre}$  Y and  $X_{pre}$  Y that compute conservative approximations of preimages. It can be directly implemented, given a rectangular set library.

## 1.4 Operational Metalanguage

We write programs in  $\lambda_{\rm ZFC}$  [25], an untyped, call-by-value  $\lambda$ -calculus designed for deriving implementable programs from contemporary mathematics.

Measure theory in particular is done in **ZFC**: Zermelo-Fraenkel set theory with Choice. ZFC's intensional functions are first-order and it has no general recursion, which makes implementing a language defined by a transformation into ZFC difficult. Targeting  $\lambda_{\rm ZFC}$  instead allows creating an exact semantics and deriving an approximating semantics without changing languages.

In  $\lambda_{\rm ZFC}$ , essentially every set is a value, as well as every lambda and every set of lambdas. All operations, including operations on infinite sets, are assumed to complete instantly if they terminate. Almost everything definable in ZFC can be defined by a finite  $\lambda_{\rm ZFC}$  program, and essentially every ZFC theorem applies to  $\lambda_{\rm ZFC}$ 's set values without alteration. Proofs about  $\lambda_{\rm ZFC}$ 's set values apply directly to ZFC sets, assuming the existence of an inaccessible cardinal.<sup>1</sup>

In  $\lambda_{\rm ZFC}$ , algebraic data structures are encoded as sets; e.g. the pair  $\langle x,y \rangle$  can be encoded as  $\{\{x\},\{x,y\}\}$ . Only the *existence* of encodings into sets is important, as it means data structures inherit a defining characteristic of sets: strictness. More precisely, the lengths of paths to data structure leaves is unbounded, but each path must be finite. Less precisely, data may be "infinitely wide" (such as  $\mathbb{R}$ ) but not "infinitely tall" (such as infinite trees and lists).

Though  $\lambda_{\rm ZFC}$  is untyped, it helps in this work to define an auxiliary type system. It is manually checked, polymorphic, and characterized by these rules:

- A free type variable is universally quantified; if uppercase, it denotes a set.
- A set denotes a member of that set.
- $-x \Rightarrow y$  denotes a partial function.
- $-\langle x,y\rangle$  denotes a pair of values with types x and y.
- Set x denotes a set with members of type x.

Because the type  $Set\ X$  denotes the same values as the set  $\mathcal{P}\ X$  (i.e. subsets of the set X) we regard them as equivalent. Similarly,  $\langle X,Y\rangle$  is equivalent to  $X\times Y$ .

Some  $\lambda_{\rm ZFC}$  primitives are membership ( $\in$ ):  $x \Rightarrow {\sf Set} \ x \Rightarrow {\sf Bool}$ , powerset  $\mathcal{P}: {\sf Set} \ x \Rightarrow {\sf Set} \ ({\sf Set} \ x)$ , big union  $\bigcup : {\sf Set} \ ({\sf Set} \ x) \Rightarrow {\sf Set} \ x$ , and the map-like image:  $(x \Rightarrow y) \Rightarrow {\sf Set} \ x \Rightarrow {\sf Set} \ y$ . We use heavily sugared syntax, with automatic currying, binding forms such as indexed unions  $\bigcup_{x \in e_A} e$ , destructuring binds as

<sup>&</sup>lt;sup>1</sup> A mild assumption, as ZFC+ $\kappa$  is a smaller theory than Coq's [3].

in swap  $\langle x, y \rangle := \langle y, x \rangle$ , and comprehensions like  $\{x \in A \mid x \in B\}$ . We assume logical operators, bounded quantifiers, and typical set operations are defined.

In set theory, extensional functions are encoded as sets of input-output pairs; e.g. the increment function for the natural numbers is  $\{\langle 0,1\rangle,\langle 1,2\rangle,\langle 2,3\rangle,...\}$ . We call these **mappings** and intensional functions **lambdas**, and use **function** to mean either. As with lambdas, we use adjacency (e.g. (f x)) to apply mappings.

The set  $J \to X$  contains all the total mappings from J to X; equivalently, all the vectors of X indexed by J (which may be infinite). The function

$$\pi: J \Rightarrow (J \to X) \Rightarrow X$$

$$\pi \mid f := f \mid$$
(6)

produces projections. This is particularly useful when f is unnamed.

Any  $\lambda_{\rm ZFC}$  term e used as a truth statement means "e reduces to true." Therefore, the terms ( $\lambda$  a. a) 1 and 1 are (externally) unequal, but ( $\lambda$  a. a) 1 = 1.

Because of the way  $\lambda_{\rm ZFC}$ 's lambda terms are defined, lambda equality is alpha equivalence. For example,  $(\lambda a. a) = (\lambda b. b)$ , but not  $(\lambda a. 2) = (\lambda a. 1 + 1)$ .

If  $e_1 = e_2$ , then  $e_1$  and  $e_2$  both terminate, and substituting one for the other in an expression does not change its value. Substitution is also safe if both  $e_1$  and  $e_2$  do not terminate, leading to a coarser notion of equivalence.

**Definition 1 (observational equivalence).** For terms  $e_1$  and  $e_2$ ,  $e_1 \equiv e_2$  when  $e_1 = e_2$ , or both  $e_1$  and  $e_2$  do not terminate.

It might seem helpful to define basic equivalence even more coarsely. However, we want internal equality and external equivalence to be similar, and we want to be able to extend "\( \equiv \)" with type-specific rules.

To save space, we elide most proofs. The proofs, including the proof of program measurability, can be found at XXX.

### 2 Arrows and First-Order Semantics

Like monads [26] and idioms [18], arrows [8] thread effects through computations in a way that imposes structure. But arrow computations are always

- Function-like: An arrow computation of type  $x \rightsquigarrow y$  must behave like a corresponding function of type  $x \Rightarrow y$  (in a sense we explain shortly).
- First-order: There is no way to derive a computation  $app: \langle x \leadsto y, x \rangle \leadsto y$  from an arrow's minimal definition.

The first property makes arrows a good fit for a compositional translation from expressions to pure functions that operate on random sources. The second property makes arrows a good fit for a measure-theoretic semantics in particular, as app's corresponding function is generally not measurable [2].

#### 2.1 Alternative Arrow Definitions and Laws

To make applying measure-theoretic theorems easier, and to simplify interpreting let-calculus expressions as arrow computations, we do not give typical minimal arrow definitions. For each arrow a, instead of first<sub>a</sub>, we define (&&<sub>a</sub>). This combinator is typically called **fanout**, but its use will be clearer if we call it **pairing**. One way to strengthen an arrow a is to define an additional combinator left<sub>a</sub>, which can be used to choose an arrow computation based on the result of another. Again, we define a different combinator, ifte<sub>a</sub> ("if-then-else").

In a nonstrict  $\lambda$ -calculus, defining a choice combinator allows writing recursive functions using nothing but arrow combinators and lifted, pure functions. However, a strict  $\lambda$ -calculus needs an extra combinator lazy for deferring conditional branches. For example, define the **function arrow** with choice:

and try to define the following recursive function:

$$halt-on-true := ifte (arr id) (arr id) halt-on-true$$
 (8)

In a strict  $\lambda$ -calculus, the defining expression does not terminate. But if the "else" branch is lazy  $\lambda 0$ , halt-on-true, it loops only when applied to false.

All of our arrows are arrows with choice, so we simply call them arrows.

**Definition 2 (arrow).** Let  $1 := \{0\}$ . A binary type constructor  $(\leadsto_a)$  and

$$\operatorname{arr}_{a}: (x \Rightarrow y) \Rightarrow (x \leadsto_{a} y)$$

$$(\ggg_{a}): (x \leadsto_{a} y) \Rightarrow (y \leadsto_{a} z) \Rightarrow (x \leadsto_{a} z)$$

$$(\&\&_{a}): (x \leadsto_{a} y) \Rightarrow (x \leadsto_{a} z) \Rightarrow (x \leadsto_{a} \langle y, z \rangle)$$

$$\operatorname{ifte}_{a}: (x \leadsto_{a} \operatorname{Bool}) \Rightarrow (x \leadsto_{a} y) \Rightarrow (x \leadsto_{a} y) \Rightarrow (x \leadsto_{a} y)$$

$$\operatorname{lazy}_{a}: (1 \Rightarrow (x \leadsto_{a} y)) \Rightarrow (x \leadsto_{a} y)$$

$$(9)$$

define an arrow if certain monoid, homomorphism, and structural laws hold.

The arrow homomorphism laws can be put in terms of more general homomorphism properties that deal with distributing an arrow-to-arrow lift.

**Definition 3 (arrow homomorphism).** lift<sub>b</sub> :  $(x \leadsto_a y) \Rightarrow (x \leadsto_b y)$  is an arrow homomorphism from arrow a to arrow b if these distributive laws hold:

$$lift_b (arr_a f) \equiv arr_b f \tag{10}$$

$$lift_b (f_1 \ggg_a f_2) \equiv (lift_b f_1) \ggg_b (lift_b f_2)$$
(11)

$$lift_b (f_1 \&\& _a f_2) \equiv (lift_b f_1) \&\& _b (lift_b f_2)$$
(12)

$$lift_b (ift_a f_1 f_2 f_3) \equiv ift_b (lift_b f_1) (lift_b f_2) (lift_b f_3)$$
(13)

$$lift_h (lazy_a f) \equiv lazy_h \lambda 0. lift_h (f 0)$$
 (14)

```
p \ ::\equiv \ x := e; \ \dots \ ; \, e
                                                              e \ ::\equiv \ x \ e \mid \mathsf{let} \ e \ e \mid \mathsf{env} \ n \mid \langle e, e \rangle \mid \mathsf{fst} \ e \mid \mathsf{snd} \ e \mid \mathsf{if} \ e \ e \ e \mid v
                                                              v ::\equiv [\text{first-order constants}]
                                                                                      \llbracket x := e; \dots; e_{body} \rrbracket_{\mathbf{a}} :\equiv x := \llbracket e \rrbracket_{\mathbf{a}}; \dots; \llbracket e_{body} \rrbracket_{\mathbf{a}}
                                                                                                                                                                 \llbracket \mathsf{let}\ e\ e_{body} \rrbracket_{\mathsf{a}}\ :\equiv\ \big(\llbracket e \rrbracket_{\mathsf{a}}\ \&\&\&_{\mathsf{a}}\ \mathsf{arr}_{\mathsf{a}}\ \mathsf{id}\big) \ggg_{\mathsf{a}}\ \llbracket e_{body} \rrbracket_{\mathsf{a}}
               [\![x\ e]\!]_{\mathsf{a}}\ :\equiv\ [\![\langle e, \langle \rangle \rangle]\!]_{\mathsf{a}}\ \ggg_{\mathsf{a}} x
\llbracket \langle e_1, e_2 \rangle \rrbracket_{\mathsf{a}} \; :\equiv \; \llbracket e_1 \rrbracket_{\mathsf{a}} \; \& \& _{\mathsf{a}} \; \llbracket e_2 \rrbracket_{\mathsf{a}}
                                                                                                                                                                                   \llbracket \mathsf{env} \ 0 \rrbracket_{\mathsf{a}} \ :\equiv \ \mathsf{arr}_{\mathsf{a}} \ \mathsf{fst}
           \llbracket \mathsf{fst}\ e \rrbracket_{\mathsf{a}}\ :\equiv\ \llbracket e \rrbracket_{\mathsf{a}}\ \ggg_{\mathsf{a}} \mathsf{arr}_{\mathsf{a}}\ \mathsf{fst}
                                                                                                                                                            \llbracket \mathsf{env} \; (n+1) \rrbracket_{\mathsf{a}} \; :\equiv \; \mathsf{arr}_{\mathsf{a}} \; \mathsf{snd} \; \ggg_{\mathsf{a}} \; \llbracket \mathsf{env} \; n \rrbracket_{\mathsf{a}}
       [\![\mathsf{snd}\ e]\!]_{\mathsf{a}}\ :\equiv\ [\![e]\!]_{\mathsf{a}}\ \ggg_{\mathsf{a}}\mathsf{arr}_{\mathsf{a}}\mathsf{snd}
                                                                                                                                                                \llbracket \mathsf{if} \ e_c \ e_t \ e_f \rrbracket_{\mathsf{a}} \ :\equiv \ \mathsf{ifte_a} \ \llbracket e_c \rrbracket_{\mathsf{a}} \ \llbracket \mathsf{lazy} \ e_t \rrbracket_{\mathsf{a}} \ \llbracket \mathsf{lazy} \ e_f \rrbracket_{\mathsf{a}}
                      \llbracket v \rrbracket_{\mathsf{a}} :\equiv \mathsf{arr}_{\mathsf{a}} \; (\mathsf{const} \; v)
                                                                                                                                                                                 [[\mathsf{lazy}\ e]]_{\mathsf{a}} :\equiv \mathsf{lazy}_{\mathsf{a}}\ \lambda\,0.\,[[e]]_{\mathsf{a}}
                              id := \lambda a.a
                                                                                                                                                                            subject to [p]_a : \langle \rangle \leadsto_a y for some y
           const b := \lambda a. b
```

Fig. 1: Transformation from a let-calculus with first-order definitions and De-Bruijn-indexed bindings to computations in arrow a.

The arrow homomorphism laws state that  $arr_a : (x \Rightarrow y) \Rightarrow (x \leadsto_a y)$  must be a homomorphism from the function arrow (7) to arrow a. Roughly, arrow computations that do not use additional combinators can be transformed into  $arr_a$  applied to a pure computation. They must be *function-like*.

To prove arrow laws, we usually prove arrows are *epimorphic* to arrows for which the laws are known to hold. (Isomorphism is sufficient but not necessary.)

**Definition 4 (arrow epimorphism).** An arrow homomorphism lift<sub>b</sub>:  $(x \leadsto_a y) \Rightarrow (x \leadsto_b y)$  that has a right inverse is an **arrow epimorphism** from a to b.

**Theorem 1.** If lift<sub>b</sub>:  $(x \leadsto_a y) \Rightarrow (x \leadsto_b y)$  is an arrow epimorphism and the combinators of a define an arrow, then the combinators of b define an arrow.

#### 2.2 First-Order Let-Calculus Semantics

Fig. 1 defines a transformation from a first-order let-calculus to arrow computations for any arrow a. A program is a sequence of definition statements followed by a final expression. The semantic function  $\llbracket \cdot \rrbracket_a$  transforms each defining expression and the final expression into arrow computations. Functions are named, but local variables and arguments are not. Instead, variables are referred to by De Bruijn indexes, with 0 referring to the innermost binding.

Perhaps unsurprisingly, the interpretation acts like a stack machine. The final expression has type  $\langle \rangle \leadsto_a y$ , where y is the type of the program's value, and  $\langle \rangle$  denotes an empty list. The let expression pushes values onto the stack. First-order functions have type  $\langle x, \langle \rangle \rangle \leadsto_a y$  where x is the argument type and y is the return type. Application sends a stack containing just an x.

We generally regard programs as if they were their final expressions. Thus, the following definition applies to both programs and expressions.

```
\begin{array}{llll} X \leadsto_{\perp} Y & ::= & X \Rightarrow Y_{\perp} & \text{ ifte}_{\perp} : (X \leadsto_{\perp} Bool) \Rightarrow (X \leadsto_{\perp} Y) \Rightarrow \\ & (X \leadsto_{\perp} Y) \Rightarrow (X \leadsto_{\perp} Y) \Rightarrow \\ & (X \leadsto_{\perp} Y) \Rightarrow (X \leadsto_{\perp} Y) \Rightarrow \\ & \text{ ifte}_{\perp} : (X \Rightarrow Y) \Rightarrow (X \leadsto_{\perp} Y) \Rightarrow \\ & \text{ ifte}_{\perp} : (X \bowtie_{\perp} Y) \Rightarrow (X \leadsto_{\perp} Y) \Rightarrow \\ & \text{ ifte}_{\perp} : (X \bowtie_{\perp} Y) \Rightarrow (X \leadsto_{\perp} Y) \Rightarrow \\ & \text{ ifte}_{\perp} : (X \bowtie_{\perp} Y) \Rightarrow (X \leadsto_{\perp} Y) \Rightarrow \\ & \text{ ifte}_{\perp} : (X \bowtie_{\perp} Y) \Rightarrow (X \leadsto_{\perp} Y) \Rightarrow \\ & \text{ ifte}_{\perp} : (X \bowtie_{\perp} Y) \Rightarrow (X \leadsto_{\perp} Y) \Rightarrow \\ & \text{ ifte}_{\perp} : (X \bowtie_{\perp} Y) \Rightarrow (X \leadsto_{\perp} Y) \Rightarrow \\ & \text{ ifte}_{\perp} : (X \bowtie_{\perp} Y) \Rightarrow (X \leadsto_{\perp} Y) \Rightarrow \\ & \text{ ifte}_{\perp} : (X \leadsto_{\perp} Y) \Rightarrow (X \leadsto_{\perp} Y) \Rightarrow \\ & \text{ ifte}_{\perp} : (X \leadsto_{\perp} Y) \Rightarrow (X \leadsto_{\perp} Y) \Rightarrow \\ & \text{ ifte}_{\perp} : (X \leadsto_{\perp} Y) \Rightarrow (X \leadsto_{\perp} Y) \Rightarrow \\ & \text{ ifte}_{\perp} : (X \leadsto_{\perp} Y) \Rightarrow (X \leadsto_{\perp} Y) \Rightarrow \\ & \text{ ifte}_{\perp} : (X \leadsto_{\perp} Y) \Rightarrow (X \leadsto_{\perp} Y) \Rightarrow \\ & \text{ ifte}_{\perp} : (X \leadsto_{\perp} Y) \Rightarrow (X \leadsto_{\perp} Y) \Rightarrow \\ & \text{ ifte}_{\perp} : (X \leadsto_{\perp} Y) \Rightarrow (X \leadsto_{\perp} Y) \Rightarrow \\ & \text{ ifte}_{\perp} : (X \leadsto_{\perp} Y) \Rightarrow (X \leadsto_{\perp} Y) \Rightarrow \\ & \text{ ifte}_{\perp} : (X \leadsto_{\perp} Y) \Rightarrow (X \leadsto_{\perp} Y) \Rightarrow \\ & \text{ ifte}_{\perp} : (X \leadsto_{\perp} Y) \Rightarrow (X \leadsto_{\perp} Y) \Rightarrow \\ & \text{ ifte}_{\perp} : (X \leadsto_{\perp} Y) \Rightarrow (X \leadsto_{\perp} Y) \Rightarrow \\ & \text{ ifte}_{\perp} : (X \leadsto_{\perp} Y) \Rightarrow (X \leadsto_{\perp} Y) \Rightarrow \\ & \text{ ifte}_{\perp} : (X \leadsto_{\perp} Y) \Rightarrow (X \leadsto_{\perp} Y) \Rightarrow \\ & \text{ ifte}_{\perp} : (X \leadsto_{\perp} Y) \Rightarrow (X \leadsto_{\perp} Y) \Rightarrow \\ & \text{ ifte}_{\perp} : (X \leadsto_{\perp} Y) \Rightarrow (X \leadsto_{\perp} Y) \Rightarrow \\ & \text{ ifte}_{\perp} : (X \leadsto_{\perp} Y) \Rightarrow (X \leadsto_{\perp} Y) \Rightarrow \\ & \text{ ifte}_{\perp} : (X \leadsto_{\perp} Y) \Rightarrow (X \leadsto_{\perp} Y) \Rightarrow \\ & \text{ ifte}_{\perp} : (X \leadsto_{\perp} Y) \Rightarrow (X \leadsto_{
```

Fig. 2: Bottom arrow definitions.

**Definition 5 (well-defined expression).** An expression e is **well-defined** under arrow a if  $[e]_a$ :  $x \leadsto_a y$  for some x and y, and  $[e]_a$  terminates.

From here on, we assume all expressions are well-defined. (The arrow a will be clear from context.) Well-definedness does not guarantee that *running* an interpretation terminates. It just simplifies statements about expressions, such as the following theorem, on which most of our semantic correctness results rely.

Theorem 2 (homomorphisms distribute over expressions). Let lift<sub>b</sub>:  $(x \leadsto_a y) \Rightarrow (x \leadsto_b y)$  be an arrow homomorphism. For all e,  $[\![e]\!]_b \equiv \text{lift}_b$   $[\![e]\!]_a$ .

If we assume  $lift_b$  defines correct behavior for arrow b in terms of arrow a, and prove that  $lift_b$  is a homomorphism, then by Theorem 2,  $[\![\cdot]\!]_b$  is correct.

## 3 The Bottom and Preimage Arrows

To use Theorem 2 to prove correct the interpretations of expressions as preimage arrow computations, we need the preimage arrow to be homomorphic to a simpler arrow whose behavior is well-understood. One obvious candidate is the function arrow (7). However, we will need to explicitly handle nontermination as an error value, so we need a slightly more complicated arrow.

Fig. 2 defines the **bottom arrow**. Its computations are of type  $X \leadsto_{\perp} Y ::= X \Rightarrow Y_{\perp}$ , where  $Y_{\perp} ::= Y \cup \{\bot\}$  and  $\bot$  is an error value. To prove the arrow laws, we need a coarser notion of equivalence.

**Definition 6 (bottom arrow equivalence).** Two computations  $f_1: X \leadsto_{\perp} Y$  and  $f_2: X \leadsto_{\perp} Y$  are equivalent, or  $f_1 \equiv f_2$ , when  $f_1 = f_2$  a for all  $a \in X$ .

Using bottom arrow equivalence, it is easy to show that  $(\sim_{\perp})$  is epimorphic to the Maybe monad's Kleisli arrow. By Theorem 1, the arrow laws hold.

```
X \xrightarrow{\sim} Y ::= \langle Set Y, Set Y \Rightarrow Set X \rangle
                                                                                                                                                         \langle \cdot, \cdot \rangle_{\mathsf{pre}} : (\mathsf{X} \xrightarrow{\mathsf{nre}} \mathsf{Y}_1) \Rightarrow (\mathsf{X} \xrightarrow{\mathsf{nre}} \mathsf{Y}_2) \Rightarrow (\mathsf{X} \xrightarrow{\mathsf{nre}} \mathsf{Y}_1 \times \mathsf{Y}_2)
                                                                                                                                                          \langle \langle \mathsf{Y}_1', \mathsf{p}_1 \rangle, \langle \mathsf{Y}_2', \mathsf{p}_2 \rangle \rangle_{\mathsf{pre}} \; := \;
pre : (X \leadsto_{\perp} Y) \Rightarrow (X \xrightarrow[nre]{} Y)
                                                                                                                                                                 \begin{array}{c} \text{let } Y' := Y_1' \times Y_2' \\ p := \lambda B. \bigcup_{\langle b_1, b_2 \rangle \in B} (p_1 \{b_1\}) \cap (p_2 \{b_2\}) \end{array}
\mathsf{pre}\;\mathsf{f}\;\mathsf{A}\;:=\;
         \langle \mathsf{image}_{\perp} \mathsf{f} \mathsf{A}, \lambda \mathsf{B}. \mathsf{preimage}_{\perp} \mathsf{f} \mathsf{A} \mathsf{B} \rangle
 \varnothing_{\mathsf{pre}} := \langle \varnothing, \lambda \, \mathsf{B}. \, \varnothing \rangle
                                                                                                                                                          (\circ_{\mathsf{pre}}): (\mathsf{Y} \underset{\mathsf{nre}}{\rightharpoonup} \mathsf{Z}) \Rightarrow (\mathsf{X} \underset{\mathsf{nre}}{\rightharpoonup} \mathsf{Y}) \Rightarrow (\mathsf{X} \underset{\mathsf{nre}}{\rightharpoonup} \mathsf{Z})
ap_{pre} : (X \xrightarrow{pre} Y) \Rightarrow Set Y \Rightarrow Set X
                                                                                                                                                           \langle \mathsf{Z}', \mathsf{p}_2 \rangle \circ_{\mathsf{pre}} \mathsf{h}_1 := \langle \mathsf{Z}', \lambda \, \mathsf{C}. \, \mathsf{ap}_{\mathsf{pre}} \, \mathsf{h}_1 \, \, (\mathsf{p}_2 \, \, \mathsf{C}) \rangle
ap_{pre} \langle Y', p \rangle B := p (B \cap Y')
                                                                                                                                                          (\uplus_{\mathsf{pre}}) : (\mathsf{X} \xrightarrow{\mathsf{pre}} \mathsf{Y}) \Rightarrow (\mathsf{X} \xrightarrow{\mathsf{pre}} \mathsf{Y}) \Rightarrow (\mathsf{X} \xrightarrow{\mathsf{pre}} \mathsf{Y})
range_{pre} : (X \xrightarrow[pre]{} Y) \Rightarrow Set Y
                                                                                                                                                          \mathsf{h}_1 \uplus_{\mathsf{pre}} \mathsf{h}_2 \ := \ \mathsf{let} \ \mathsf{Y}' := (\mathsf{range}_{\mathsf{pre}} \ \mathsf{h}_1) \cup (\mathsf{range}_{\mathsf{pre}} \ \mathsf{h}_2)
\mathsf{range}_{\mathsf{pre}}\ \langle \mathsf{Y}',\mathsf{p}\rangle\ :=\ \mathsf{Y}'
                                                                                                                                                                                                                                 p := \lambda B. (ap_{pre} h_1 B) \cup (ap_{pre} h_2 B)
\mathsf{image}_{\bot} : (\mathsf{X} \leadsto_{\bot} \mathsf{Y}) \Rightarrow \mathsf{Set} \; \mathsf{X} \Rightarrow \mathsf{Set} \; \mathsf{Y}
                                                                                                                                                           \mathsf{preimage}_{\bot} : (\mathsf{X} \leadsto_{\bot} \mathsf{Y}) \Rightarrow \mathsf{Set} \ \mathsf{X} \Rightarrow \mathsf{Set} \ \mathsf{Y} \Rightarrow \mathsf{Set} \ \mathsf{X}
image_{\perp} f A := (image f A) \setminus \{\bot\}
                                                                                                                                                           \mathsf{preimage}_{\bot} \ f \ A \ B \ := \ \{ \mathsf{a} \in \mathsf{A} \mid \mathsf{f} \ \mathsf{a} \in \mathsf{B} \}
```

Fig. 3: Lazy preimage mappings and operations.

## 3.1 Lazy Preimage Mappings

Implementation will be smoother if we have an abstraction that makes it easy to replace computation on concrete sets with computation on abstract sets. Therefore, we confine preimage set computation to instances of

$$X \xrightarrow{re} Y ::= \langle Set Y, Set Y \Rightarrow Set X \rangle$$
 (15)

Like a mapping, an  $X \xrightarrow[pre]{} Y$  has an observable domain—which is critical to defining preimage arrow composition further on—but computing the input-output pairs is delayed. We therefore call these *lazy preimage mappings*.

Converting a bottom arrow computation to a lazy preimage mapping requires computing its range and constructing a delayed preimage computation:

pre : 
$$(X \leadsto_{\perp} Y) \Rightarrow Set X \Rightarrow (X \xrightarrow{pre} Y)$$
  
pre f A :=  $\langle image_{\perp} f A, \lambda B. preimage_{\perp} f A B \rangle$  (16)

Fig. 3 defines  $image_{\perp}$ ,  $preimage_{\perp}$ , and operations on preimage mappings:  $\langle \cdot, \cdot \rangle_{pre}$  returns preimage mappings that compute preimages under pairing, and  $(\circ_{pre})$  and  $(\uplus_{pre})$  do the same for compositions and for unions of functions with disjoint domains. The  $ap_{pre}$  function applies a preimage mapping to a Set Y. Preimage arrow correctness depends on  $ap_{pre}$  and pre together behaving like  $preimage_{\perp}$ .

**Theorem 3** (ap<sub>pre</sub> computes preimages). Let  $f : X \leadsto_{\perp} Y$ . For all  $A \subseteq X$  and  $B \subseteq Y$ , ap<sub>pre</sub> (pre f A)  $B \equiv \text{preimage}_{\perp} f A B$ .

```
\begin{array}{lll} X \underset{\text{pre}}{\leadsto} Y ::= Set \ X \Rightarrow (X \underset{\text{pre}}{\leadsto} Y) & & & & & & & & & & & & & \\ \text{ifte}_{\text{pre}} : (X \underset{\text{pre}}{\leadsto} Y) \Rightarrow (X \underset{\text{pre}}{\leadsto} Y) \Rightarrow \\ (X \underset{\text{pre}}{\leadsto} Y) \Rightarrow (X \underset{\text{pre}}{\leadsto} Y) \Rightarrow \\ (X \underset{\text{pre}}{\leadsto} Y) \Rightarrow (X \underset{\text{pre}}{\leadsto} Y) \Rightarrow \\ (X \underset{\text{pre}}{\leadsto} Y) \Rightarrow (X \underset{\text{pre}}{\leadsto} Y) \Rightarrow \\ (X \underset{\text{pre}}{\leadsto} Y) \Rightarrow (X \underset{\text{pre}}{\leadsto} Y) \Rightarrow \\ (X \underset{\text{pre}}{\leadsto} Y) \Rightarrow (X \underset{\text{pre}}{\leadsto} Y) \Rightarrow \\ (X \underset{\text{pre}}{\leadsto} Y) \Rightarrow (X \underset{\text{pre}}{\leadsto} Z) \Rightarrow (X \underset{\text{pre}}{\leadsto} Z) \\ (X \underset{\text{pre}}{\leadsto} Z) \Rightarrow (X \underset{\text{pre}}{\leadsto} Z) \Rightarrow (X \underset{\text{pre}}{\leadsto} Z) \\ (X \underset{\text{pre}}{\leadsto} Y) \Rightarrow (X \underset{\text{pre}}{\leadsto} Y
```

Fig. 4: Preimage arrow definitions.

#### 3.2 The Preimage Arrow

If we define the **preimage arrow** type constructor as

$$X \underset{\text{pre}}{\leadsto} Y ::= \text{Set } X \Rightarrow (X \underset{\text{pre}}{\rightharpoonup} Y)$$
 (17)

then we already have a lift lift<sub>pre</sub>:  $(X \leadsto_{\perp} Y) \Rightarrow (X \leadsto_{pre} Y)$  from the bottom arrow to the preimage arrow: pre. By Theorem 3, lifted bottom arrow computations compute correct preimages, exactly as we should expect them to.

Fig. 4 defines the preimage arrow in terms of preimage mapping operations (Fig. 3). For these definitions to make lift<sub>pre</sub> a homomorphism, we need preimage arrow equivalence to mean "computes the same preimages."

**Definition 7** (preimage arrow equivalence). Two preimage arrow computations  $h_1: X \underset{pre}{\sim} Y$  and  $h_2: X \underset{pre}{\sim} Y$  are equivalent, or  $h_1 \equiv h_2$ , when  $ap_{pre} (h_1 A) B \equiv ap_{pre} (h_2 A) B$  for all  $A \subseteq X$  and  $B \subseteq Y$ .

Theorem 4 (preimage arrow correctness). lift<sub>pre</sub> is a homomorphism.

Corollary 1 (semantic correctness). For all e,  $[e]_{pre} \equiv lift_{pre}$   $[e]_{\perp}$ .

The type  $X \underset{\text{ore}}{\sim} Y$  does not constrain its inhabitants to behave intuitively; e.g.

unruly : Bool 
$$\underset{\text{pre}}{\leadsto}$$
 Bool unruly A :=  $\langle \text{Bool} \backslash A, \lambda B. B \rangle$  (18)

So  $\operatorname{ap}_{\operatorname{pre}}$  (unruly  $\{\operatorname{true}\}$ )  $\{\operatorname{false}\}=\{\operatorname{false}\}\cap(\operatorname{Bool}\setminus\{\operatorname{true}\})=\{\operatorname{false}\}$ —a "preimage" that does not even intersect the given domain  $\{\operatorname{true}\}$ . Other examples show preimage computations are not necessarily monotone, and lack other desirable properties. Those with desirable properties obey the following law.

**Definition 8 (preimage arrow law).** Let  $h: X_{pre} Y$ . If there exists an  $f: X \leadsto_{\perp} Y$  such that  $h \equiv lift_{pre} f$ , then h obeys the **preimage arrow law**.

By homomorphism of lift<sub>pre</sub>, preimage arrow combinators preserve the preimage arrow law. From here on, we assume all  $h: X \underset{pre}{\leadsto} Y$  obey it. Thus, lift<sub>pre</sub> is an epimorphism; by Theorem 1, the arrow laws hold.

## 4 Preimages Under Partial Functions

We have defined the top of our roadmap:

$$\begin{array}{ccc}
\mathsf{X} \leadsto_{\perp} \mathsf{Y} & \xrightarrow{\mathsf{lift}_{\mathsf{pre}}} & \mathsf{X} \underset{\mathsf{pre}}{\leadsto} \mathsf{Y} \\
\eta_{\perp^*} \downarrow & & & \downarrow \eta_{\mathsf{pre}^*} \\
\mathsf{X} \leadsto_{\perp^*} \mathsf{Y} & \xrightarrow{\mathsf{lift}_{\mathsf{pre}^*}} & \mathsf{X} \underset{\mathsf{pre}^*}{\leadsto} \mathsf{Y}
\end{array} \tag{19}$$

so that  $lift_{pre}$  is a homomorphism. Now we move down each side and connect the bottom, in a way that makes every morphism a homomorphism.

Probabilistic functions that may not terminate, but terminate with probability 1, are common. For example, suppose every use of random retrieves a number in [0,1] from an implicit random source. The following probabilistic function, which defines the well-known **geometric distribution**, counts the number of times random < p is false:

geometric 
$$p := if (random < p) 0 (1 + geometric p)$$
 (20)

For any p > 0, geometric p may not terminate, but the probability of never taking the "then" branch is  $1 - (1 - p) \cdot (1 - p) \cdot (1 - p) \cdot \cdots = 1$ .

Suppose we interpret geometric p as  $h: R \underset{pre}{\leadsto} \mathbb{N}$ , a preimage arrow computation from random sources to naturals, and we have a probability measure  $P: Set R \Rightarrow [0,1]$ . The probability of  $N \subseteq \mathbb{N}$  is P (ap<sub>pre</sub> (h R) N). To compute this, we must

- 1. Ensure ap<sub>pre</sub> (h R) N terminates.
- 2. Ensure each  $r \in R$  contains enough random numbers.
- 3. Determine how random indexes numbers in r.

Ensuring  $ap_{pre}$  (h R) N terminates is the most difficult, but doing the other two will provide structure that makes it much easier.

#### 4.1 Threading and Indexing

We clearly need bottom and preimage arrows that thread a random source. To ensure random sources contain enough numbers, they should be infinite.

In a pure  $\lambda$ -calculus, random sources are typically infinite streams, threaded monadically: each computation receives and produces a random source. A little-used alternative is for the random source to be a tree, threaded applicatively: each computation receives, but does not produce, a random source. Combinators split the tree and pass subtrees to subcomputations.

```
\begin{array}{c} \mathsf{ifte_{a^*}} : (\mathsf{x} \leadsto_{\mathsf{a^*}} \mathsf{Bool}) \Rightarrow (\mathsf{x} \leadsto_{\mathsf{a^*}} \mathsf{y}) \Rightarrow \\ (\mathsf{x} \leadsto_{\mathsf{a^*}} \mathsf{y}) \Rightarrow (\mathsf{x} \leadsto_{\mathsf{a^*}} \mathsf{y}) \end{array}
\mathsf{x} \leadsto_{\mathsf{a}^*} \mathsf{y} \ ::= \ \mathsf{AStore} \ \mathsf{s} \ \big( \mathsf{x} \leadsto_{\mathsf{a}} \mathsf{y} \big) \ ::= \ \mathsf{J} \Rightarrow \big( \langle \mathsf{s}, \mathsf{x} \rangle \leadsto_{\mathsf{a}} \mathsf{y} \big)
arr_{a^*}: (x \Rightarrow y) \Rightarrow (x \leadsto_{a^*} y)
                                                                                                                                                                                           \mathsf{ifte}_{\mathsf{a}^*} \ \mathsf{k}_1 \ \mathsf{k}_2 \ \mathsf{k}_3 \ \mathsf{j} \ := \\
\operatorname{arr}_{\operatorname{a}^*} \ := \ \eta_{\operatorname{a}^*} \circ \operatorname{arr}_{\operatorname{a}}
                                                                                                                                                                                                  ifte<sub>a</sub> (k_1 (left j))
                                                                                                                                                                                                                 (k_2 (left (right j)))
\left(\ggg_{a^*}\right):\left(x\rightsquigarrow_{a^*}y\right)\Rightarrow\left(y\rightsquigarrow_{a^*}z\right)\Rightarrow\left(x\rightsquigarrow_{a^*}z\right)
                                                                                                                                                                                                                 (k3 (right (right j)))
(k_1 \ggg_{a^*} k_2) j :=
                                                                                                                                                                                           \mathsf{lazy}_{\mathsf{a}^*}: (1 \Rightarrow (\mathsf{x} \leadsto_{\mathsf{a}^*} \mathsf{y})) \Rightarrow (\mathsf{x} \leadsto_{\mathsf{a}^*} \mathsf{y})
       (arr_a fst \&\& a k_1 (left j)) >>> a k_2 (right j)
                                                                                                                                                                                           lazy_{a^*} k j := lazy_a \lambda 0. k 0 j
(\&\&\&_{a^*}): (x \leadsto_{a^*} y_1) \Rightarrow (x \leadsto_{a^*} y_2) \Rightarrow (x \leadsto_{a^*} \langle y_1, y_2 \rangle)
                                                                                                                                                                                            \eta_{a^*}: (x \leadsto_a y) \Rightarrow (x \leadsto_{a^*} y)
(k_1 \&\&\&_{a^*} k_2) j := k_1 (left j) \&\&\&_a k_2 (right j)
                                                                                                                                                                                            \eta_{a^*} f j := arr<sub>a</sub> snd \gg<sub>a</sub> f
```

Fig. 5: AStore (associative store) arrow transformer definitions.

With either alternative, for arrows, the resulting definitions are large, conceptually difficult, and hard to manipulate. Fortunately, assigning each subcomputation a unique index into a tree-shaped random source, and passing the random source unchanged, is relatively easy. To do this, we need an indexing scheme.

**Definition 9 (binary indexing scheme).** Let J be an index set,  $j_0 \in J$  a distinguished element, and left:  $J \Rightarrow J$  and right:  $J \Rightarrow J$  be total, injective functions. If for all  $j \in J$ ,  $j = \text{next } j_0$  for some finite composition next of left and right, then J,  $j_0$ , left and right define a binary indexing scheme.

For example, let J be the set of lists of  $\{0,1\}$ ,  $j_0 := \langle \rangle$ , and left  $j := \langle 0,j \rangle$  and right  $j := \langle 1,j \rangle$ . In any case, J is countable, and can be thought of as a set of indexes into an infinite binary tree. Values of type  $J \to A$  encode an infinite binary tree of A values as an infinite vector (i.e. total mapping).

We thread infinite binary trees through bottom and preimage arrow computations by defining an **arrow transformer**: a type constructor that receives and produces an arrow type, and combinators for arrows of the produced type.

The AStore arrow type constructor takes a store type s and an arrow  $x \leadsto_a y$ :

AStore s 
$$(x \leadsto_a y) ::= J \Rightarrow (\langle s, x \rangle \leadsto_a y)$$
 (21)

Reading the type, we see that computations receive an index  $j \in J$  and produce a computation that receives a store as well as an x. Lifting extracts the x from the input pair and sends it on to the original computation, ignoring j:

$$\eta_{\mathsf{a}^*} : (\mathsf{x} \leadsto_{\mathsf{a}} \mathsf{y}) \Rightarrow \mathsf{AStore} \ \mathsf{s} \ (\mathsf{x} \leadsto_{\mathsf{a}} \mathsf{y})$$

$$\eta_{\mathsf{a}^*} \ \mathsf{f} \ \mathsf{j} \ := \ \mathsf{arr}_{\mathsf{a}} \ \mathsf{snd} \ggg_{\mathsf{a}} \mathsf{f}$$
(22)

Fig. 5 defines the remaining combinators. Each subcomputation receives left j, right j, or some other unique binary index. We thus think of programs interpreted as AStore arrows as being completely unrolled into an infinite binary tree, with each expression labeled with its tree index.

### 4.2 Partial, Probabilistic Programs

To interpret probabilitic programs, we put an infinite random tree in the store.

**Definition 10 (random source).** Let  $R := J \rightarrow [0,1]$ . A random source is any infinite binary tree  $r \in R$ .

To interpret partial programs, we need to ensure termination. An utimately implementable way is to have the store dictate which branch of each conditional, if any, is taken.

**Definition 11 (branch trace).** A branch trace is any  $t \in J \to \mathsf{Bool}_\perp$  such that  $t \ j = \mathsf{true}$  or  $t \ j = \mathsf{false}$  for no more than finitely many  $j \in J$ .

Let  $T \subset J \to \mathsf{Bool}_{\perp}$  be the largest set of branch traces.

Let  $X \leadsto_{a^*} Y ::= AStore (R \times T) (X \leadsto_a Y)$  be an AStore arrow type that threads both random stores and branch traces. For probabilistic programs, we define a combinator  $random_{a^*}$  that returns the number at its tree index in the random source, and extend  $\llbracket \cdot \rrbracket_{a^*}$  for arrows  $a^*$  for which  $random_{a^*}$  is defined:

$$\begin{array}{lll} \operatorname{random}_{\mathsf{a}^*}: \mathsf{X} \leadsto_{\mathsf{a}^*} [0,1] \\ \operatorname{random}_{\mathsf{a}^*} \mathsf{j} &:= \operatorname{arr}_{\mathsf{a}} \left( \operatorname{fst} \ggg \operatorname{fst} \ggg \pi \mathsf{j} \right) \end{array} \qquad \begin{bmatrix} \operatorname{random}_{\mathsf{a}^*} &:= \operatorname{random}_{\mathsf{a}^*} & (23) \\ \operatorname{random}_{\mathsf{a}^*$$

For partial programs, we define a combinator that reads branch traces, and an if-then-else combinator that ensures its test expression agrees with the trace:

$$\begin{array}{lll} \mathsf{branch}_{\mathsf{a}^*} : \mathsf{X} \leadsto_{\mathsf{a}^*} \mathsf{Bool} \\ \mathsf{branch}_{\mathsf{a}^*} \ \mathsf{j} \ := \ \mathsf{arr}_{\mathsf{a}} \ (\mathsf{fst} \ggg \mathsf{snd} \ggg \pi \ \mathsf{j}) \\ \mathsf{ifte}_{\mathsf{a}^*}^{\Downarrow} : (\mathsf{x} \leadsto_{\mathsf{a}^*} \mathsf{Bool}) \Rightarrow (\mathsf{x} \leadsto_{\mathsf{a}^*} \mathsf{y}) \Rightarrow (\mathsf{x} \leadsto_{\mathsf{a}^*} \mathsf{y}) \Rightarrow (\mathsf{x} \leadsto_{\mathsf{a}^*} \mathsf{y}) \\ \mathsf{ifte}_{\mathsf{a}^*}^{\Downarrow} \ \mathsf{k}_1 \ \mathsf{k}_2 \ \mathsf{k}_3 \ \mathsf{j} \ := \ \mathsf{ifte}_{\mathsf{a}} \ ((\mathsf{k}_1 \ (\mathsf{left} \ \mathsf{j}) \ggg_{\mathsf{a}} \mathsf{arr}_{\mathsf{a}} \mathsf{agrees}) \\ & (\mathsf{k}_2 \ (\mathsf{left} \ (\mathsf{right} \ \mathsf{j}))) \\ & (\mathsf{k}_3 \ (\mathsf{right} \ (\mathsf{right} \ \mathsf{j}))) \end{array}$$

where agrees  $\langle b_1, b_2 \rangle :=$  if  $(b_1 = b_2)$   $b_1 \perp$ . Thus, if the branch trace does not agree with the test expression, it returns an error. We define a new semantic function  $[\![\cdot]\!]_{a^*}^{\Downarrow}$  by replacing the if rule in  $[\![\cdot]\!]_{a^*}$ :

$$[\![\mathsf{if}\ e_c\ e_t\ e_f]\!]_{\mathsf{a}^*}^{\Downarrow} :\equiv \mathsf{ifte}_{\mathsf{a}^*}^{\Downarrow}\ [\![e_c]\!]_{\mathsf{a}^*}^{\Downarrow}\ [\![\mathsf{lazy}\ e_f]\!]_{\mathsf{a}^*}^{\Downarrow}\ [\![\mathsf{lazy}\ e_f]\!]_{\mathsf{a}^*}^{\Downarrow}$$

For an AStore computation k, we obviously must run k on every branch trace in T and filter out  $\bot$ , or somehow find inputs  $\langle \langle r, t \rangle, a \rangle$  for which agrees never returns  $\bot$ . Preimage AStore arrows do the former by first computing an image, and the latter by computing preimages of sets that cannot contain  $\bot$ .

Definition 12 (terminating, probabilistic arrows). Define

$$\begin{array}{lll} X \leadsto_{\perp^*} Y & ::= & \mathsf{AStore} \; (\mathsf{R} \times \mathsf{T}) \; (\mathsf{X} \leadsto_{\perp} \mathsf{Y}) \\ X \leadsto_{\mathsf{pre}^*} \mathsf{Y} & ::= & \mathsf{AStore} \; (\mathsf{R} \times \mathsf{T}) \; (\mathsf{X} \leadsto_{\mathsf{pre}} \mathsf{Y}) \end{array} \tag{26}$$

as the type constructors for the **bottom\*** and **preimage\*** arrows.

Suppose  $f := [\![e]\!]_{\perp^*}^{\downarrow} : X \leadsto_{\perp^*} Y$ . Its domain is  $X' := (R \times T) \times X$ . We assume each  $r \in R$  is random, but not  $t \in T$  nor  $a \in X$ ; therefore, neither T nor X should affect the probabilities of output sets. The probability of  $B \subseteq Y$  is therefore

P (image (fst 
$$\gg$$
 fst) (preimage <sub>$\perp$</sub>  f X' B))  
= P (image (fst  $\gg$  fst) (ap<sub>pre</sub> (h X') B)) (27)

where  $h := [e]_{pre^*}^{\downarrow}$ , if f and h always terminate and  $[\cdot]_{pre^*}^{\downarrow}$  is correct.

### 4.3 Correctness and Termination

For correctness, we have two arrow lifts to prove homomorphic: one from pure computations to effectful (i.e. from those that do not access the store to those that do), and one from effectful computations to effectful. For both, we need AStore arrow equivalence to be more extensional.

**Definition 13** (AStore arrow equivalence). Two AStore arrow computations  $k_1$  and  $k_2$  are equivalent, or  $k_1 \equiv k_2$ , when  $k_1 \neq k_2$  if or all  $j \in J$ .

Theorem 5 (pure AStore arrow correctness).  $\eta_{a^*}$  is a homomorphism.

Corollary 2 (pure semantic correctness). For all pure e,  $[\![e]\!]_{a^*} \equiv \eta_{a^*}$   $[\![e]\!]_a$ .

We need a lift between AStore arrows. Let  $x \leadsto_{a^*} y ::= AStore s (x \leadsto_a y)$ ,  $x \leadsto_{b^*} y ::= AStore s (x \leadsto_b y)$ , and lift<sub>b</sub> :  $(x \leadsto_a y) \Rightarrow (x \leadsto_b y)$ . Define

$$\begin{aligned}
& \text{lift}_{b^*} : (\mathsf{x} \leadsto_{\mathsf{a}^*} \mathsf{y}) \Rightarrow (\mathsf{x} \leadsto_{\mathsf{b}^*} \mathsf{y}) \\
& \text{lift}_{b^*} \mathsf{f} \mathsf{j} := \mathsf{lift}_{\mathsf{b}} (\mathsf{f} \mathsf{j})
\end{aligned} \tag{28}$$

Theorem 6 (effectful AStore arrow correctness). If lift<sub>b</sub> is an arrow homomorphism from a to b, then lift<sub>b\*</sub> is an arrow homomorphism from  $a^*$  to  $b^*$ .

Corollary 3 (preimage\* arrow correctness). lift<sub>pre\*</sub> is a homomorphism.

Corollary 4 (effectful semantic correctness). For all expressions e,  $\llbracket e \rrbracket_{\mathsf{pre}^*} \equiv \mathsf{lift}_{\mathsf{pre}^*}$   $\llbracket e \rrbracket_{\perp^*}$  and  $\llbracket e \rrbracket_{\mathsf{pre}^*}^{\Downarrow} \equiv \mathsf{lift}_{\mathsf{pre}^*}$   $\llbracket e \rrbracket_{\perp^*}^{\Downarrow}$ .

For termination, we need to define the largest domain on which  $\llbracket e \rrbracket_{\mathsf{a}^*}^{\downarrow}$  and  $\llbracket e \rrbracket_{\mathsf{a}^*}$  computations should agree.

**Definition 14 (maximal domain).** Let  $f: X \leadsto_{\perp^*} Y$ . Its **maximal domain** is the largest  $A^* \subseteq (R \times T) \times X$  for which  $A^* = \{a \in A^* \mid f \mid_D a \neq \bot\}$ .

Because  $f j_0 a \neq \bot$  implies termination, all inputs in  $A^*$  are terminating.

Theorem 7 (correct termination everywhere). Let  $[e]_{\perp^*}^{\downarrow}: X \leadsto_{\perp^*} Y$  have maximal domain  $A^*$ , and  $X' := (R \times T) \times X$ . For all  $a \in X'$ ,  $A \subseteq X'$  and  $B \subseteq Y$ ,

$$\begin{bmatrix} e \end{bmatrix}_{\perp^*}^{\downarrow} \quad j_0 \quad a \qquad = \quad \text{if} \quad (a \in A^*) \quad (\llbracket e \rrbracket_{\perp^*} \quad j_0 \quad a) \perp \\
ap_{\text{pre}} \quad (\llbracket e \rrbracket_{\text{pre}^*}^{\downarrow} \quad j_0 \quad A) \quad B \quad = \quad ap_{\text{pre}} \quad (\llbracket e \rrbracket_{\text{pre}^*} \quad j_0 \quad (A \cap A^*)) \quad B$$
(29)

In other words, preimages computed using  $\llbracket \cdot \rrbracket_{\mathsf{pre}^*}^{\Downarrow}$  always terminate, never include inputs that give rise to errors or nontermination, and are correct.

```
\begin{array}{lll} id_{pre}\;A\;:=\;\langle A,\lambda B.B\rangle & const_{pre}\;b\;A\;:=\;\langle \{b\},\lambda B.\, if\;(B=\varnothing)\;\varnothing\;A\rangle \\ fst_{pre}\;A\;:=\;\langle proj_1\;A,unproj_1\;A\rangle & \pi_{pre}\;j\;A\;:=\;\langle proj\;j\;A,unproj\;j\;A\rangle \\ \hline snd_{pre}\;A\;:=\;\langle proj_2\;A,unproj_2\;A\rangle & \hline \\ proj_1:=image\;fst & proj\;j\;A\;:=\;image\;(\pi\;j)\;A \\ proj_2:=image\;snd & unproj_1\;A\;B\;:=\;A\cap(B\times proj_2\;A) \\ unproj_2\;A\;B\;:=\;A\cap(proj_1\;A\times B) & unproj\;j\;A\;B\;:=\;A\cap\prod_{i\in J}if\;(j=i)\;B\;(proj\;j\;A) \end{array}
```

Fig. 6: Preimage arrow lifts needed to interpret probabilistic programs.

## 5 Approximating Semantics

We would like to be able to compute preimages of uncountable sets, such as real intervals—but  $preimage_{\perp}$  f A B is uncomputable for most uncountable sets A and B no matter how cleverly they are represented. Further, because pre,  $lift_{pre}$  and  $arr_{pre}$  are defined in terms of  $preimage_{\perp}$ , we cannot implement them.

Fortunately, we need only certain lifts. Fig. 6 gives explicit definitions for  $arr_{pre}$  id,  $arr_{pre}$  fst,  $arr_{pre}$  snd,  $arr_{pre}$  (const b) and  $arr_{pre}$  ( $\pi$  j). To implement them, we need to model sets in a way that makes  $A = \emptyset$  is decidable, and the following representable and finitely computable:

• 
$$A \cap B$$
,  $\varnothing$ , {true}, {false} and {b} for every const b  
•  $A_1 \times A_2$ ,  $proj_1 A$  and  $proj_2 A$   
•  $J \to X$ ,  $proj j A$  and  $unproj j A B$ 

We first need to define families of sets under which these operations are closed.

**Definition 15 (rectangular family).** Rect X denotes the **rectangular family** of subsets of X. Rect X must contain  $\varnothing$  and X, and be closed under finite intersections. Products must satisfy the following rules:

$$Rect \langle X_1, X_2 \rangle = (Rect X_1) \boxtimes (Rect X_2)$$
 (31)

$$Rect (J \to X) = (Rect X)^{\boxtimes J}$$
 (32)

where the following operations lift cartesian products to sets of sets:

$$\mathcal{A}_1 \boxtimes \mathcal{A}_2 := \{ \mathsf{A}_1 \times \mathsf{A}_2 \mid \mathsf{A}_1 \in \mathcal{A}_1, \mathsf{A}_2 \in \mathcal{A}_2 \} \tag{33}$$

$$\mathcal{A}^{\boxtimes J} := \bigcup_{J' \subset J} \left\{ \prod_{j \in J} A_j \mid A_j \in \mathcal{A}, j \in J' \iff A_j \subset \bigcup \mathcal{A} \right\}$$
(34)

We additionally define Rect Bool  $:= \mathcal{P}$  Bool. It is easy to show the collection of all rectangular families is closed under products, projections, and unproj.

Further, all of the operations in (30) can be exactly implemented if finite sets are modeled directly, sets in an ordered space (such as  $\mathbb{R}$ ) are modeled by intervals, and sets in Rect  $\langle X_1, X_2 \rangle$  are modeled by pairs of type  $\langle \text{Rect } X_1, \text{Rect } X_2 \rangle$ . By (34), sets in Rect (J  $\rightarrow$  X) have no more than finitely many projections that are proper subsets of X. They can be modeled by *finite* binary trees, where unrepresented projections are implicitly X.

The set of branch traces T is nonrectangular, but we can model T subsets by  $J \to \mathsf{Bool}_\perp$  rectangles, implicitly intersected with T.

**Theorem 8** (T model). If  $T' \in \text{Rect } (J \to \text{Bool}_{\perp})$  and  $j \in J$ , then proj j  $(T' \cap T) = \text{proj j } T'$ . If  $B \subseteq \text{Bool}_{\perp}$ , then unproj j  $(T' \cap T)$  B = unproj j T'  $B \cap T$ .

Rectangular families are not closed under ( $\cup$ ). For conditionals, then, we need a lattice join ( $\vee$ ) with respect to ( $\subseteq$ ) with the following additional properties:

$$(A_1 \times A_2) \vee (B_1 \times B_2) = (A_1 \vee B_1) \times (A_2 \vee B_2)$$

$$(\prod_{i \in J} A_j) \vee (\prod_{i \in J} B_j) = \prod_{i \in J} A_j \vee B_j$$

$$(35)$$

If for every nonproduct type X, Rect X is closed under  $(\lor)$ , then rectangular families are clearly closed under  $(\lor)$ . Further, for any A and B,  $A \cup B \subseteq A \lor B$ .

Fig. 7 defines approximating preimage arrows. Approximating preimage mapping operations (Fig. 7a) are defined in terms of lattice operations on rectangular families. Every approximating preimage arrow combinator (Fig. 7b) is defined the same way as its corresponding exact preimage arrow combinator, but using approximating preimage mapping operations instead of exact. Fig. 7c defines  $\mathsf{random'}_{\mathsf{pre^*}}$  and  $\mathsf{branch'}_{\mathsf{pre^*}}$  without using the uncomputable  $\mathsf{arr'}_{\mathsf{pre^*}}$ , and  $\mathsf{ifte^{\Downarrow'}}_{\mathsf{pre^*}}$ , for interpreting expressions using  $\mathsf{rec}_{\mathsf{pre^*}}$  for guaranteed termination.

Let 
$$h := [e]_{pre^*}^{\Downarrow} : X_{\stackrel{\sim}{pre^*}} Y$$
 and  $h' := [e]_{pre^*}^{\Downarrow'} : X_{\stackrel{\sim}{pre^*}} Y$  for any expression  $e$ .

**Theorem 9 (sound, terminating, decreasing).** For all  $A \in \text{Rect } \langle \langle R, T \rangle, X \rangle$  and  $B \in \text{Rect } Y$ ,  $\text{appre } (h \ j_0 \ A) \ B \subseteq \text{ap}'_{\text{pre}} (h' \ j_0 \ A) \ B \subseteq A$ .

Theorem 10 (monotone).  $ap'_{pre}$  (h'  $j_0$  A) B is monotone in both A and B.

Given these properties, we might try to compute preimages of B by computing preimages with respect to increasingly fine discretizations of A.

Definition 16 (preimage refinement algorithm). Let  $B \in Rect \ Y$  and

refine : Rect 
$$\langle \langle R, T \rangle, X \rangle \Rightarrow \text{Rect } \langle \langle R, T \rangle, X \rangle$$
  
refine A := ap'<sub>pre</sub> (h' j<sub>0</sub> A) B (36)

Define partition : Rect  $\langle\langle R,T\rangle,X\rangle\Rightarrow$  Set (Rect  $\langle\langle R,T\rangle,X\rangle$ ) to produce positive-measure, disjoint rectangles, and define

$$\begin{array}{l} \text{refine}^*: \mathsf{Set} \; \big(\mathsf{Rect} \; \langle \langle \mathsf{R}, \mathsf{T} \rangle, \mathsf{X} \rangle \big) \Rightarrow \mathsf{Set} \; \big(\mathsf{Rect} \; \langle \langle \mathsf{R}, \mathsf{T} \rangle, \mathsf{X} \rangle \big) \\ \\ \mathsf{refine}^* \; \mathcal{A} := \mathsf{image} \; \mathsf{refine} \; \left(\bigcup_{\mathsf{A} \in \; \mathsf{A}} \mathsf{partition} \; \mathsf{A} \right) \\ \end{array}$$

For any  $A \in \text{Rect } \langle \langle R, T \rangle, X \rangle$ , iterate refine\* on  $\{A\}$ .

$$\begin{array}{lll} X \underset{\text{pre}}{\rightharpoonup}' Y ::= \langle \text{Rect } Y, \text{Rect } Y \Rightarrow \text{Rect } X \rangle & \langle \cdot, \cdot \rangle_{\text{pre}}' : (X \underset{\text{pre}}{\rightharpoonup}' Y_1) \Rightarrow (X \underset{\text{pre}}{\rightharpoonup}' Y_2) \Rightarrow (X \underset{\text{pre}}{\rightharpoonup}' Y_1 \times Y_2) \\ & \langle (Y_1', p_1), \langle (Y_2', p_2) \rangle_{\text{pre}}' := \\ & \langle (Y_1' \times Y_2', \lambda B. \, p_1 \, (\text{proj}_1 \, B) \cap p_2 \, (\text{proj}_2 \, B) \rangle \\ & \text{ap}_{\text{pre}}' : (X \underset{\text{pre}}{\rightharpoonup}' Y) \Rightarrow \text{Rect } Y \Rightarrow \text{Rect } X \\ & \text{ap}_{\text{pre}}' \cdot (Y', p) \, B := p \, (B \cap Y') \\ & \langle (Y_1', p_1) \oplus_{\text{pre}}' \cdot (Y_2', p_2) := \\ & \langle (P_1', p_1) \oplus_{\text{pre}}' \cdot (Y_2', p_2) := \\ & \langle (P_1', p_1) \oplus_{\text{pre}}' \cdot (Y_2', p_1) \otimes (X \underset{\text{pre}}{\rightharpoonup}' Y) \otimes$$

(a) Definitions for preimage mappings that compute rectangular covers.

(b) An approximating preimage arrow, defined using approximating preimage mappings.

$$\begin{array}{lll} X \underset{\text{pre}^*}{\sim} Y ::= \mathsf{AStore} \ (\mathsf{R} \times \mathsf{T}) \ (X \underset{\text{pre}^*}{\sim}' Y) & \text{ ifte}^{\Downarrow_{\mathsf{pre}^*}} : (X \underset{\text{pre}^*}{\sim}' \mathsf{Bool}) \Rightarrow (X \underset{\text{pre}^*}{\sim}' Y) \Rightarrow (X \underset{\text{pre$$

(c) Preimage\* arrow combinators for probabilistic choice and guaranteed termination. Fig. 5 (AStore arrow transformer) defines  $\eta'_{pre^*}$ ,  $(\ggg'_{pre^*})$ ,  $(\ggg'_{pre^*})$ , ifte'\_{pre^\*} and lazy'\_{pre^\*}.

Fig. 7: Implementable arrows that approximate preimage arrows. Because  $\mathsf{arr}_{\mathsf{pre}}$  is generally uncomputable, there is no corresponding  $\mathsf{arr}'_{\mathsf{pre}}$  combinator. However, specific lifts such as  $\mathsf{fst}_{\mathsf{pre}} := \mathsf{arr}_{\mathsf{pre}}$  fst are computable, and are defined in Fig. 6.

Theorem 10 guarantees refining a partition of A never does worse than refining A itself. Theorem 9 guarantees termination, that refine A is never larger than A, and that the algorithm is **sound**: the preimage of B is always contained in the covering partition refine\* returns.

We would like it to be **complete** in the limit, up to null sets: covering partitions' measures should converge to the true preimage measure. Unfortunately, preimage refinement appears to compute the Jordan outer measure of a preimage, which is not always its measure. We leave completeness conditions for future work, and for now, use algorithms that depend only on soundness.

## 6 Implementations

We have four implementations: one of the exact semantics, two direct implementations of the approximating semantics, and a less direct but more efficient implementation of the approximating semantics, which we call **Dr. Bayes**.

If sets are restricted to be finite, the exact semantics can be implemented directly in any practical  $\lambda$ -calculus. Computing exact preimages is very inefficient, even under the interpretations of very small programs. Still, we have found our Typed Racket [23] implementation useful for finding theorem candidates.

Given a rectangular set library, the approximating preimage arrows defined in Figs. 6 and 7 can be implemented with few changes in any practical  $\lambda$ -calculus. We have done so in Typed Racket and Haskell [1]. Both implementations' arrow combinator definitions are almost line-for-line transliterations from the figures.

All three direct implementations can currently be found at XXX: URL.

Our main implementation,  $Dr.\ Bayes$ , is written in Typed Racket. It consists of the semantic function  $[\cdot]_{a^*}$  from Fig. 1 and its extension  $[\cdot]_{a^*}^{\downarrow}$ , the bottom\* arrow as defined in Figs. 2 and 5, the approximating preimage and preimage\* arrows as defined in Figs. 6 and 7, and algorithms to compute approximate probabilities. We use it to test the feasibility of solving real-world problems by computing approximate preimages.

Dr. Bayes's arrows operate on a monomorphic rectangular set data type. For data types and ad-hoc polymorphism, it includes tagged rectangles and disjoint unions. To overapproximate real intervals, it includes floating-point intervals. Finding the smallest covering rectangle for images and preimages under add, sub:  $\langle \mathbb{R}, \mathbb{R} \rangle \Rightarrow \mathbb{R}$  and other monotone functions is straightforward. Given sub<sub>pre</sub> and negative?<sub>pre</sub>, inequalities such as  $(\leq_{pre})$  are trivial. For the piecewise monotone mul, div:  $(\mathbb{R}, \mathbb{R}) \Rightarrow \mathbb{R}$ , we distinguish monotone cases using ifte<sub>pre</sub>.

Section ?? outlines preimage refinement: a discretization algorithm that seems to converge for programs that halt with probability 1, consisting of repeatedly shrinking and repartitioning a program's domain. We do not use this algorithm directly in Dr. Bayes because it is inefficient: good accuracy requires fine discretization, which is exponential in the number of discretized axes.

Instead of enumerating partitions, Dr. Bayes samples from partitions of the random source, with time complexity linear in the number of samples and discretized axes. It uses expressions interpreted as bottom\* arrow computations to

reject samples that fall outside the true preimage set, and thus relies only on preimage refinement's soundness.

XXX: specific problems: thermometer, stochastic ray tracing

#### 7 Related Work

Computing a preimage also computes an overapproximation of a subdomain's image, which generalizes interval arithmetic [11] to all first-order algebraic types.

Our approximating semantics can be regarded as an abstract interpretation [6] with a concrete domain of arbitrary sets and an abstract domain of rectangular sets. In some ways, it is quite typical: it is sound, the abstract domain is a lattice, and the exact semantics it approximates performs infinite computations. However, it is far from typical in other ways. It is used to run programs, not for static analysis. The abstraction boundaries are the if branches of completely unrolled, infinite programs, and are not fixed. There is no Kleene iteration. Infinite computations are done in a library of  $\lambda_{\rm ZFC}$ -computable combinators, not by a semantic function. This cleanly separates the syntax from the semantics, and allows us to prove the exact semantics correct mostly by proving simple categorical properties.

Probabilistic languages can be approximately placed into two groups: those defined by an implementation, and those defined by a semantics.

Some languages defined by an implementation are probabilistic Scheme [14], BUGS [17], BLOG [19], BLAISE [4], Church [7], and Kiselyov's embedded language for O'Caml [12]. The reports on these languages generally describe interpreters, compilers, and algorithms for sampling with probabilistic conditions. Recently, Wingate et al [27] have defined the semantics of nonstandard interpretations that enable efficient inference, but do not define the languages.

Early work in probabilistic language semantics is not motivated by Bayesian concerns, and thus does not address conditioning. Examples are Kozen [15], Hurd [9], Jones [10], Ramsey and Pfeffer [22], and Park [20]. Recent semantics work tackles conditioning, such as IBAL [21] and Fun [5]. While Fun's original measure-theoretic semantics in particular looks promising, its implementations are so far based on probability densities. Thus, they cannot handle recursion, discontinuous programs, or aribtrary conditions.

### 8 Conclusions and Future Work

XXX: todo

Understanding the exact semantics, and implementing the approximating semantics, requires little more than basic set theory and some experience using combinator libraries in a pure  $\lambda$ -calculus.

the conditions under which the approximating semantics is complete in the limit, up to null sets

relation to type systems

constraints sampling algorithms different abstract domains

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