Machine Learning Project-Exercise Band

Introduction

This report presents an analysis of a *FitBit-like* device used to monitor a specific exercise routine. Data is stored from the on-device accelerometer, when placed at three positions on the participants' body: belt, forearm and arm. An extra placement is recorded on the equipment-type used.

The motivation for the project is to predict how the exercises are performed. Questions answered concern: 1. how the software model was built 2. the use of cross-validation 3. expected out-of-sample error 4. why these choices

Data

The data for this assignment is from this location (http://groupware.les.inf.puc-rio.br/har), and contains information from the placement accelerometers. The data is split into a training and testing groups.

Method

Set the libraries and read the training test file. Split input training data into training and testing at 90%

```
library(lattice)
library(ggplot2)
library(caret)
library(gbm)
```

```
## Loading required package: survival
## Loading required package: splines
##
## Attaching package: 'survival'
##
## The following object is masked from 'package:caret':
##
## cluster
##
## Loading required package: parallel
## Loaded gbm 2.1
```

```
set.seed(9175)
fileLocation = "K:/COURSES/JHU_DataScience/PracticalMachineLearning/project/data/pml-training.csv"
pml.training <- read.csv(fileLocation)</pre>
```

Load data to memory

```
training <- read.csv(fileLocation, na.strings=c("NA","#DIV/0!",""))
testing <- read.csv(fileLocation, na.strings=c("NA","#DIV/0!",""))</pre>
```

Split the training data at the 90% point

```
inTrain <- createDataPartition(y=pml.training$classe, p=0.9, list=FALSE)
newTraining <- pml.training[inTrain,]
newTesting <- pml.training[-inTrain,]</pre>
```

Cleaning the data

Clean the data of NAs The following process was used to clean the data:

Mod 1: Cleaning NearZeroVariance Variables

(from Help - nearZeroVar diagnoses predictors that have one unique value (i.e. are zero variance predictors) or predictors that are have both of the following characteristics: they have very few unique values relative to the number of samples and the ratio of the frequency of the most common value to the frequency of the second most common value is large. checkConditionalX looks at the distribution of the columns of x conditioned on the levels of y and identifies columns of x that are sparse within groups of y.)

Inspect possible Non-Zero Variables:

```
myDataNZV < nearZeroVar(newTraining, saveMetrics=TRUE)
```

Run this code to create another training subset without NZV

```
myNZVvars <- names(newTraining) %in% c("new window", "kurtosis roll belt", "kurtosis picth belt",
"kurtosis yaw belt", "skewness roll belt", "skewness roll belt.1", "skewness yaw belt",
"max yaw belt", "min yaw belt", "amplitude yaw belt", "avg roll arm", "stddev roll arm",
"var roll arm", "avg pitch arm", "stddev pitch arm", "var pitch arm", "avg yaw arm",
"stddev yaw arm", "var yaw arm", "kurtosis roll arm", "kurtosis picth arm",
"kurtosis yaw arm", "skewness roll arm", "skewness pitch arm", "skewness yaw arm",
"max roll arm", "min roll arm", "min pitch arm", "amplitude roll arm", "amplitude pitch arm",
"kurtosis roll dumbbell", "kurtosis picth dumbbell", "kurtosis yaw dumbbell", "skewness roll dumbbel
1",
"skewness pitch dumbbell", "skewness yaw dumbbell", "max yaw dumbbell", "min yaw dumbbell",
"amplitude yaw dumbbell", "kurtosis roll forearm", "kurtosis picth forearm", "kurtosis yaw forearm",
"skewness_roll_forearm", "skewness_pitch_forearm", "skewness_yaw_forearm", "max_roll_forearm",
"max yaw forearm", "min roll forearm", "min yaw forearm", "amplitude roll forearm",
"amplitude yaw forearm", "avg roll forearm", "stddev roll forearm", "var roll forearm",
"avg pitch forearm", "stddev pitch forearm", "var pitch forearm", "avg yaw forearm",
"stddev_yaw_forearm", "var_yaw_forearm")
newTraining <- newTraining[!myNZVvars]
#To check the new N?? of observations
dim(newTraining)
```

```
## [1] 17662 100
```

Mod 2: remove first column of training (ID) Removing the variable (ID) so that it doesn't interfer with ML

```
newTraining < newTraining[c(1)]
```

Mod 3: Cleaning variables of too many NAs. For Variables that have >60% threshold of NA's

```
trainingMx <- newTraining
                                                   #make another subset to iterate over
 for(i in 1:length(newTraining))
                                                   #do next column in the training dataset
     if(sum( is.na( newTraining[, i] )) /nrow(newTraining) >= .6 )
                                                   #if number NAs >60% of total obs
     {
         for(j in 1:length(trainingMx))
             if(length( grep(names(newTraining[i]), names(trainingMx)[j])) ==1)
                                                   #if same columns
                  trainingMx <- trainingMx[ , -j] #remove column</pre>
         }
     }
 #check the new observations
 dim(trainingMx)
 ## [1] 17662
 #point back to our original training
 newTraining <- trainingMx
 rm(trainingMx)
adjust newTesting and testing data as above
 cleanUp1 <- colnames(newTraining)</pre>
 cleanUp2 <- colnames(newTraining[, -58]) #already with classe column removed
 newTesting <- newTesting[cleanUp1]
 testing <- testing[cleanUp2]
 #To check the new observations
 dim(newTesting)
 ## [1] 1960
              58
```

To ensure proper functioning of Decision Trees and RandomForest Algorithm with the test data (original data provided), we need to force to the same type.

#The last column (problem id) which is not equal to training sets, was removed

#To check the new observations

57

dim(testing)

[1] 19622

```
for (i in 1:length(newTesting))
{
    for(j in 1:length(newTraining))
    {
        if(length(grep(names(newTraining[i]), names(newTesting)[j]))==1)
        {
            class(newTesting[j]) <- class(newTraining[i])
        }
    }
}
#make sure coertion really worked
testing <- rbind(newTraining[2, -58], testing) #row 1,2 are useless and were be removed
testing <- testing[-1,]</pre>
```

```
names(newTraining)
```

```
## [1] "user name"
                                "raw_timestamp_part_1" "raw_timestamp_part_2"
## [4] "cvtd timestamp"
                               "num window"
                                                       "roll belt"
## [7] "pitch_belt"
                                                       "total accel belt"
                               "yaw belt"
## [10] "gyros belt x"
                               "gyros belt y"
                                                       "gyros belt z"
## [13] "accel_belt_x"
                               "accel_belt_y"
                                                       "accel_belt_z"
## [16] "magnet_belt_x"
                               "magnet_belt_y"
                                                       "magnet_belt_z"
## [19] "roll arm"
                               "pitch arm"
                                                       "yaw arm"
## [22] "total_accel_arm"
                               "gyros_arm_x"
                                                       "gyros_arm_y"
## [25] "gyros arm z"
                               "accel arm x"
                                                       "accel arm y"
## [28] "accel arm z"
                               "magnet_arm_x"
                                                       "magnet_arm_y"
## [31] "magnet arm z"
                               "roll dumbbell"
                                                       "pitch dumbbell"
## [34] "yaw_dumbbell"
                               "total_accel_dumbbell" "gyros_dumbbell_x"
## [37] "gyros dumbbell y"
                               "gyros dumbbell z"
                                                       "accel dumbbell x"
## [40] "accel dumbbell y"
                               "accel dumbbell z"
                                                       "magnet dumbbell x"
## [43] "magnet dumbbell y"
                               "magnet dumbbell z"
                                                       "roll forearm"
## [46] "pitch_forearm"
                                                       "total accel forearm"
                               "yaw forearm"
## [49] "gyros_forearm_x"
                               "gyros_forearm_y"
                                                       "gyros forearm z"
## [52] "accel forearm x"
                               "accel forearm y"
                                                       "accel forearm z"
## [55] "magnet_forearm_x"
                               "magnet_forearm_y"
                                                       "magnet_forearm_z"
## [58] "classe"
```

```
smt <- summary(newTraining)
write.table(smt, file="K:/COURSES/JHU_DataScience/PracticalMachineLearning/project/data/summary.txt"
, sep=',')</pre>
```

Reasons for process: 1. 90 percent subsample is used to train the module 2. 10 percent sample is used for cross-validation.

- 3. used this simple cross-validation rather than using K-fold with the [cv.folds] option to decrease run time, which was already rather long
- 4. implement a Stochastic Gradient Boosting algorithm via the gbm package.

```
ptm <- proc.time()
modFitAl <- train(classe ~ user_name + pitch_arm + yaw_arm + roll_arm + roll_belt + pitch_belt + yaw
_belt + gyros_belt_x + gyros_belt_y + gyros_belt_z + accel_belt_x + accel_belt_y + accel_belt_z + ma
gnet_belt_x + magnet_belt_y + magnet_belt_z + gyros_arm_x + gyros_arm_y + gyros_arm_z + accel_arm_x
+ accel_arm_y + accel_arm_z + magnet_arm_x + magnet_arm_y + magnet_arm_z + roll_dumbbell + pitch_dum
bbell + yaw_dumbbell, method="gbm", data=newTraining, verbose=FALSE)</pre>
```

```
## Loading required package: plyr

tm <- proc.time() - ptm

tm

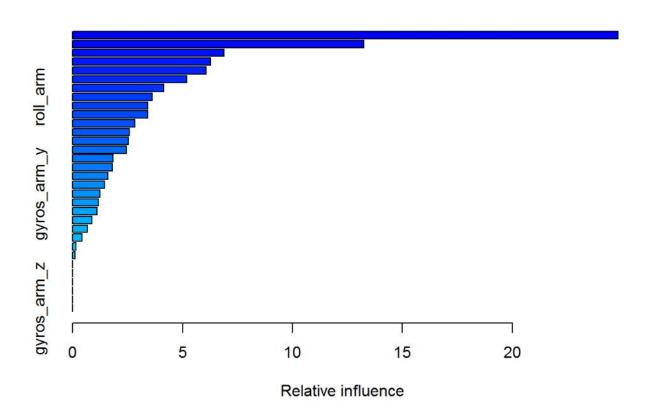
## user system elapsed
## 1265.75    2.16 1273.98

ptm <- proc.time()
modFitA2 <- train(classe ~ user_name + pitch_arm + yaw_arm + roll_arm + roll_belt + pitch_belt + yaw</pre>
```

```
ptm <- proc.time()
modFitA2 <- train(classe ~ user_name + pitch_arm + yaw_arm + roll_arm + roll_belt + pitch_belt + yaw
_belt + gyros_belt_x + gyros_belt_y + gyros_belt_z + accel_belt_x + accel_belt_y + accel_belt_z + ma
gnet_belt_x + magnet_belt_y + magnet_belt_z + gyros_arm_x + gyros_arm_y + gyros_arm_z + accel_arm_x
+ accel_arm_y + accel_arm_z + magnet_arm_x + magnet_arm_y + magnet_arm_z + roll_dumbbell + pitch_dum
bbell + yaw_dumbbell, method="gbm", data=newTesting, verbose=FALSE)
tm <- proc.time() - ptm
tm</pre>
```

```
## user system elapsed
## 126.97 0.42 136.05
```

```
summary(modFitA1)
```



```
##
                                  var
                                         rel.inf
## roll_belt
                            roll belt 24.8004549
## yaw_belt
                             yaw_belt 13.2581575
## magnet belt z
                       magnet belt z 6.8879286
## roll_dumbbell
                       roll_dumbbell 6.2670735
## pitch belt
                           pitch belt 6.0828479
## magnet_arm_x
                        magnet_arm_x 5.1978168
## magnet arm z
                         magnet arm z 4.1531520
## roll_arm
                             roll_arm 3.6326962
## gyros belt z
                         gyros belt z 3.4184291
## accel arm x
                         accel arm x 3.4133532
## user nameeurico
                     user_nameeurico 2.8309509
## yaw_dumbbell
                         yaw dumbbell 2.5753052
## pitch dumbbell
                      pitch dumbbell 2.5310924
## accel arm z
                        accel arm z 2.4527768
## yaw arm
                              yaw arm 1.8361944
## accel_belt_z
                        accel_belt_z 1.8160015
## magnet_belt_x
                       magnet_belt_x 1.6058697
## pitch_arm
                          pitch_arm 1.4446081
## gyros arm y
                        gyros_arm_y 1.2518722
## magnet_belt_y
                       magnet_belt_y 1.1788608
## magnet arm y
                        magnet arm y 1.1150757
## user_namecharles user_namecharles 0.8853653
## gyros_belt_y
                        gyros belt_y 0.6747000
## gyros_arm_x
                        gyros_arm_x 0.4252966
## accel arm y
                         accel arm y 0.1545834
## gyros belt x
                         gyros belt x 0.1095373
## user namecarlitos user namecarlitos 0.0000000
## user_namejeremy
                     user_namejeremy 0.0000000
                      user_namepedro 0.0000000
## user namepedro
## accel belt x
                        accel belt x 0.0000000
## accel_belt_y
                        accel belt y 0.0000000
## gyros_arm_z
                          gyros_arm_z 0.0000000
predictTraining <- predict(modFitAl, newTraining)</pre>
table(predictTraining, newTraining$classe)
##
## predictTraining
                     A
                               C
                                         E
                          В
                                    D
                A 4725 151
                                   47
                                        36
##
                              56
```

The model correctly classifies 93.6% of the observations in the training data with 150 trees. The *roll_belt* and *yaw_belt* features were by far the most important

##

##

##

В

E

57

40

D 113

87 3128 125

10

12

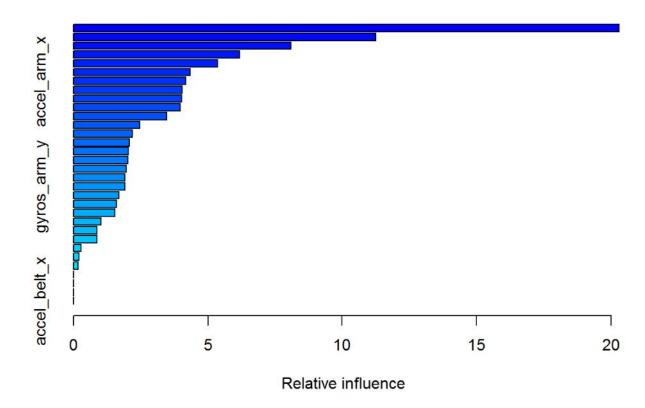
117 2830 129

17

62 2679 7 23 33

23

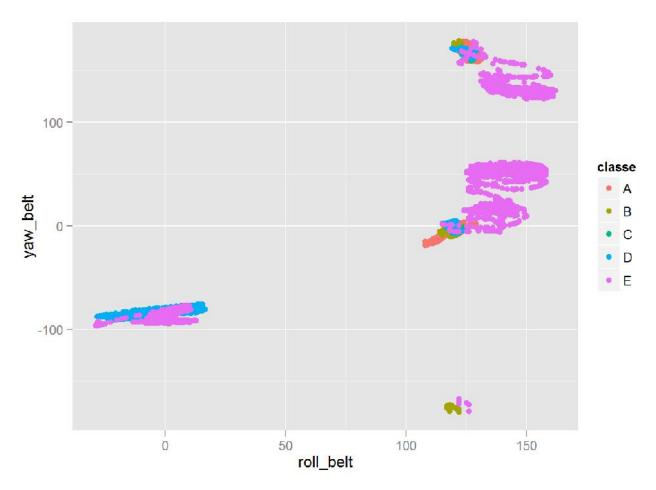
23 3137



```
##
                                var
                                       rel.inf
## roll_belt
                         roll_belt 20.2945582
## yaw_belt
                           yaw_belt 11.2603480
## roll dumbbell
                    roll dumbbell 8.0878723
## pitch_belt
                         pitch_belt 6.1718943
## magnet belt z
                    magnet belt z 5.3493030
## yaw_arm
                            yaw_arm 4.3351289
                       accel_arm_x 4.1733592
## accel arm x
                      magnet_arm_z 4.0399129
## magnet arm z
                    pitch_dumbbell 4.0193920
## pitch dumbbell
## magnet arm x
                      magnet_arm_x 3.9627574
## gyros belt z
                      gyros belt z 3.4699891
## magnet_arm_y
                     magnet_arm_y 2.4762284
## roll arm
                          roll arm 2.1975738
## pitch arm
                         pitch arm 2.0843119
                     accel_arm_z 2.0346517
## accel arm z
## magnet_belt_y
                     magnet_belt_y 2.0290223
## yaw_dumbbell
                      yaw_dumbbell 1.9648800
## user_nameeurico user_nameeurico 1.9048732
## gyros arm y
                       gyros_arm_y 1.9023023
                     magnet_belt_x 1.6857479
## magnet belt x
## gyros arm x
                       gyros arm x 1.6000038
## accel_arm_y
                       accel_arm_y 1.5463860
## accel belt z
                     accel_belt_z 1.0177495
## gyros_belt_x
                      gyros_belt_x 0.8740361
## gyros belt y
                      gyros belt y 0.8646887
## user namepedro
                    user namepedro 0.2764315
## accel belt y
                      accel belt y 0.2126767
## gyros_arm_z
                        gyros_arm_z 0.1639205
## user_namecarlitos user_namecarlitos 0.0000000
## user namecharles user namecharles 0.0000000
## user_namejeremy user_namejeremy 0.0000000
## accel_belt_x
                       accel belt x 0.0000000
```

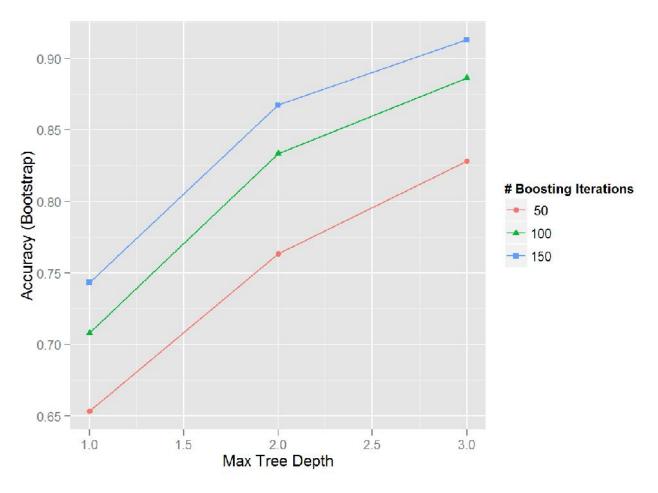
A plot of these top two features colored by outcome demonstrates their relative importance.

```
qplot(roll_belt, yaw_belt,colour=classe,data=newTraining)
```



Although these are the top observations, however, not great predictors. Obviously, some bunching can be seen in this plot. The choice of a boosting algorithm is a good choice given the large number of weak predictors. The next plot shows the improved performance using boosting iterations.

ggplot(modFitA1)



Next, I check the performance on the 10 percent subsample to get an estimate of the algorithm's out-of-sample performance.

```
predictTesting <- predict(modFitA2, newTesting) #newTesting chaged to testing
table(predictTesting, newTesting$classe)
  predictTesting
                         8
                     2 365
                             6
                                     1
                C
                         6 332
                                 5
                                     0
                             3 314
                                      2
                D
                         0
                                 1 356
```

The algorithm actually performs only does slightly worse on the testing subset than it did on the full training set, correctly classifying 93.4 percent of the observations.

Prediction Phase

Finally, predict using the original testing set. The results go to the <code>pml_write_files()</code> function and stored.

```
pml.testing <- read.csv("K:/COURSES/JHU_DataScience/PracticalMachineLearning/project/data/pml-testin
g.csv")
answers <- as.character(predict(modFitA1, pml.testing))
pml_write_files = function(x) {
    n = length(x)
    for(i in 1:n) {
        filename = paste0("problem_id_",i,".txt")
        write.table(x[i],file=filename,quote=FALSE,row.names=FALSE,col.names=FALSE)
    }
}
pml_write_files(answers)</pre>
```

The algorithm correctly predicted the outcome for 20/20 observations, in agreement with its strong out-of-sample classification accuracy.