Ay190 - Worksheet 10 David Vartanyan

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1

We use the shooting method code template to solve our BVP. We guess a z = y'(a) and use an integrator (FE or RK2) to extend to boundary b. We calculate the error between y(z) and our endpoint B = y(b). We then use a rootfinder to improve our guess of z and iterate until desired accuracy. Even with extreme values of *z*, the process takes 2 iterations (see ws10.py and ws10b.py).

To test for convergence, we run using 10 and 10000 steps. FE converges, see 1 and 2; interestingly, RK2 doesn't. See 3 and 4.

The top figure shows the exact and FE or RK2 solution to our BVP; the subplot shows the error. RK2 is accurate but divergent.

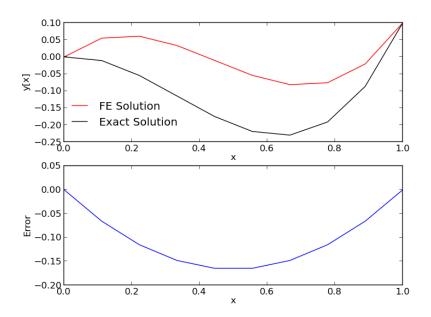


Figure 1: FE, npoints=10

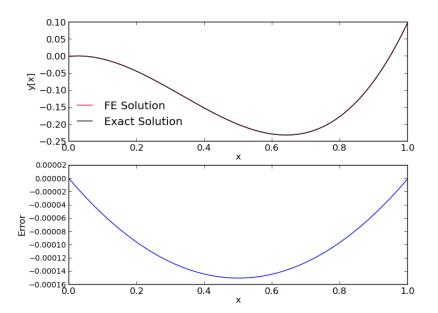


Figure 2: FE, npoints=10000

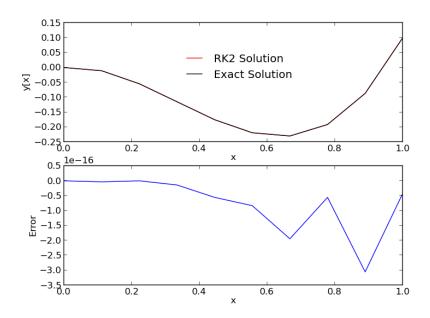


Figure 3: RK2, npoints=10

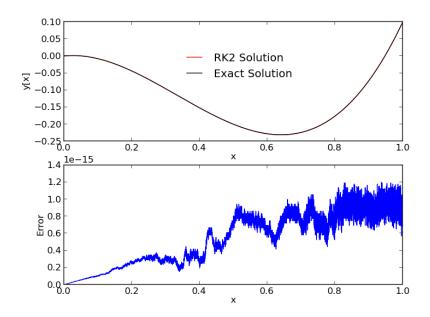


Figure 4: RK2, npoints=10000