

Question 3

$$V(s) = \frac{\sum_{t \in \tau(s)} p_{t:T(t)-1} G_t}{\sum_{t \in \tau(s)} p_{t:T(t)-1}}$$

Given that we are ^{at} state s_t and perform action A_t , probability of the action trajectory $s_{t+1}, A_{t+1}, \dots, s_T$ occurring under any policy π is

$$Pr \{s_{t+1}, A_{t+1}, \dots, s_T \mid s_t, A_t, A_{t+1:T-1} \sim \pi\}$$

$$\Rightarrow \prod_{k=t}^{T-1} \pi(A_k | s_k) p(s_{k+1} | s_k, A_k)$$

$$p'_{t:T-1} = \left[\prod_{k=t}^{T-1} \left(\pi(A_k | s_k) / b(A_k | s_k) \right) \right] \times \frac{1}{\pi(A_t | s_t)} \times b(A_t | s_t)$$

$$\Rightarrow \boxed{p'_{t:T-1} = \prod_{k=t+1}^{T-1} \frac{\pi(A_k | s_k)}{b(A_k | s_k)}}$$

~~Q(s,a) =~~

$\tau(s,a) \rightarrow$ all time steps where state s is visited and action a is performed

$$Q(s,a) = \frac{\sum_{t \in \tau(s,a)} p'_{t:T(t)-1} G_t}{\sum_{t \in \tau(s,a)} p'_{t:T(t)-1}}$$