Workshop Basic Arduino Class 1 – Arduino Fundamentals

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Arduino

What is?

- Open source electronics platform.
- Allows creation of electronics prototipes.
- Based on open source software.
- Ease of use.
- Allows to do sequences and mathematics operations.
- Used for automation.

Arduino Types









Arduino Yún



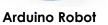
DIGITAL IN

ANALOG IN



COMMUNICATION (SERIAL)

CPU





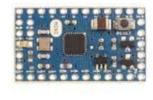
Arduino Uno



Arduino Leonardo



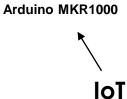
Arduino Due





Arduino Micro





SUPPLY (7V - 12V)

UNIVERSIDAD

DIGITAL OUT

PWM OUT

Arduino Mega 2560 Arduino Ethernet

Arduino Mini

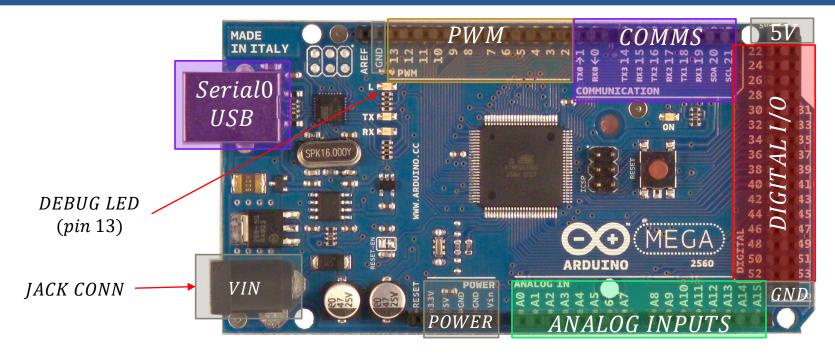
LilyPad Arduino

Arduino Nano



Arduino MEGA 2560 Pinout





- Based on the microcontroller ATMEGA 2560.
- **Supply:** Using Jack connecter with voltaje range from **7V to 12V**. Also it can be powered via USB but with low consumption.
- Maximum current per I/O digital pin: 40 mA.
- Maximum current for 3.3V supply pin: 50 mA.
- Digital Inputs and Outputs: 54 pins (OV or 5V).
- **Analog Inputs:** 16 pins (from **0V to 5V** of analog voltage).
- **PWM Outputs:** 15 pins (Considered in the 54 digital I/O pins).
- Oscilator frequency/Flash Memory/RAM/ROM: 16 MHz / Flash 256 Kb/ SRAM 8 Kb / EEPROM 4 Kb.
- Communications: USB CDC (Serial) + I2C + SPI.

Variables



NAME	SINTAX	SIZE	RANGE		EXAMPLE
NAME			WITHOUT SIGN	WITH SIGN	EXAMPLE
Boolean	boolean	1 bit	false True	N/A	boolean state = false;
Char ¹	char unsigned char	8 bits (1 byte)	0 a 255	-128 a 127	<pre>char myChar = 'A'; char myChar = 65; Both examples are equivalent</pre>
Byte	byte	8 bits (1 byte)	0 a 255	N/A	byte hello = B00000111; byte hello = 7; B indicates binary notation B00000111 is equal to 7 in decimal.
Integer	int unsigned int	16 bit (2 bytes)	0 a 65535	-32768 a 32767	unsigned int counter = 0;
Long	long unsigned long	32 bit	0 a 4,294,967,295	-2,147,483,648 a 2,147,483,647	unsigned long number = 20000;
Float ²	float	32 bit	N/A	-3.4028235E+38 a 3.4028235E+38	<pre>float temperature = 88.5;</pre>

EQUIVALENCIAS				
word	unsigned int			
short	int			

¹Check ASCII table (http://www.asciitable.com/index/asciifull.gif)

²Check Arduino documentation for more info (http://arduino.cc/en/Reference/Float#.UxOT7_I5Njl)

Typical Operators



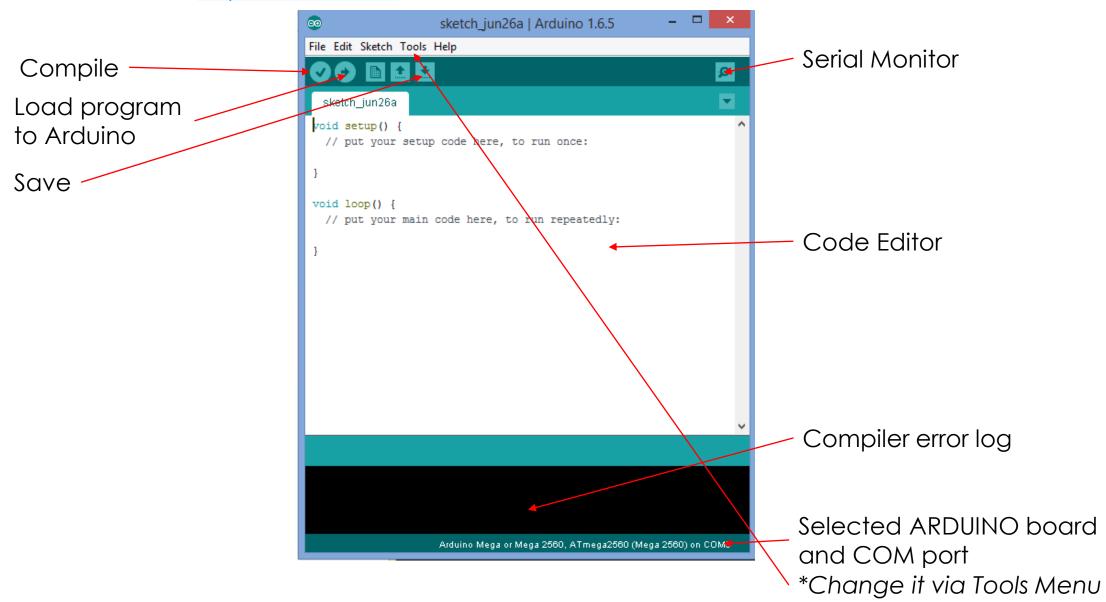
	SYMBOL	DESCRIPTION
	=	Assignment
ARITHMETIC	+	Addition
	-	Subtraction
	*	Multiplication
AF	/	Division
	%	Module
	==	Equal to: $x == y$ is equivalent to: x is equal to y ?
COMPARATIVE	<u>:</u>	Not equal to: $x! = y$ is equivalent: x is not equal to y ?
RAT	<	Less than
MPA	^	Greater than
CO	 	Less than or equal to
	 	Greater than or equal to
NS	&&	AND
BOOLEANS		OR
BO		Negation (NOT)
	++	Increment: $y = x + +$ is equivalent to: $y = x + 1$
ORS		Decrement: $y = x$ is equivalent to: $y = x - 1$
LAT	+=	Addition assignment: $y += x$ is equivalent to: $y = y + x$
JMU	-=	Subtraction assignment: $y = x$ is equivalent to: $y = y - x$
ACCUMULATORS	*=	Multiplication assignment: $y *= x$ is equivalent to: $y = y * x$
4	/=	Division assignment: $y/=x$ is equivalent to: $y=y/x$

Arduino Program Structure

```
Library declaration(e.g: #include <SFEMP3Shield.h>)
I/O Pin Labeling (e.g. #define LEDPIN 13)
Constant declaration (e.g. const unsigned int contMax = 10;)
Variable declaration (e.g: float temperature = 0;)
Subroutines or functions declaration:
Example for subroutine:
void readSens() {
                                  //Example of a subroutine that reads the analog value from 0 to 1023 and converts it
                                   //from 0 to 100 degrees storing it in the float variable named temperature.
     y = analogRead(1); //Analog read from pin A1
     temperature = y*100.0/1023.0; //Float to degree celcius conversion
Example for function:
int sum(int x, int y) { //Example of a function that sums two numbers "x" y "y" and returns the result as int
     return x + y;
Pin configuration and cleaning:
void setup() {
     //CONFIGURATION: Indicate which pins are inputs and which are outputs "pinMode(PIN,OUTPUT o INPUT);" without quotes.
     //CLEANING: For safety, it is important to clean used outputs with the purpose that they are turned off at the
     //beginning of the program. Use the function "digitalWrite(PIN, LOW);" without quotes.
     //COMMUNICATIONS: For example, for communications with the computer, use the function "Serial.begin(BAUDIOS);"
     //without quotes.
Infinite loop (Main program - Execution):
void loop() {
     //Main program
```

Arduino IDE

Software download: http://arduino.cc



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Arduino common used commands



pinMode

- Configures the specified pin as input or output
- Sintax: pinMode (pin, mode);
 - pin: The pin # that will be configured
 - mode: Determines if the pin is an input or an output. Receives INPUT or OUTPUT

digitalWrite

- Writes a logical state to an output pin: a HIGH logic state (5V) or a LOW logic state (0V)
- Sintax: digitalWrite (pin, value);
 - pin: The pin # that will be written
 - value: HIGH or LOW

digitalRead

- Reads and returns the logic state value of a digital input pin
- Sintax: digitalRead (pin)
 - pin: The input pin # that will be read
 - Returns HIGH or LOW depending on the logic state value of the input pin that was read

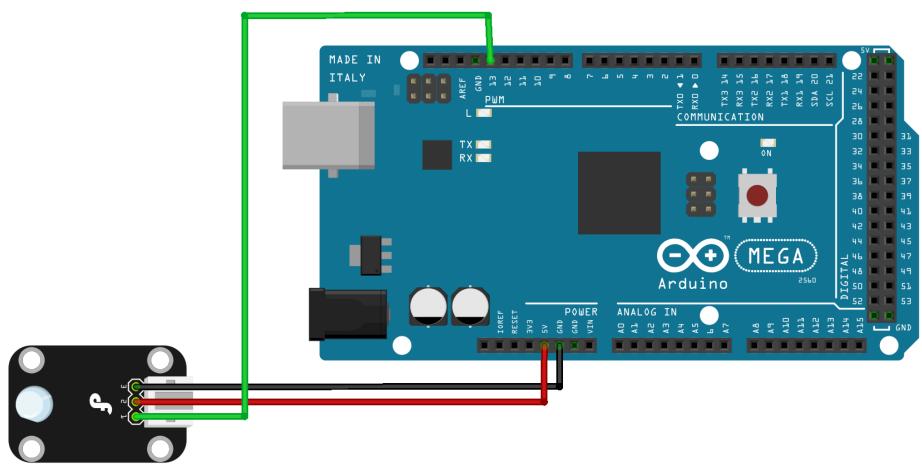
delay

- Pauses the program execution for a desired time (in miliseconds)
- Not recommended to use because it pauses the whole program execution for the input time
- Sintax: delay (ms);
 - ms: The number of miliseconds that is desired to pause the program (var type: unsigned long)

Example 1.1 – Arduino common used commands



Example: In PIN 13 there is a LED (L1) connected. Blink the LED $\frac{1}{2}$ second ON and $\frac{1}{2}$ second OFF.



Example 1.1 – Arduino common used commands



```
//I/O pin labeling
#define L1 13 //Label LED connected in pin 13 as "L1"
//Constant declaration
unsigned long TBLINK = 500; //Blink constant TBLINK initialized on
                            //500 \text{ ms}
void setup() {
 //I/O Pin Configuration
 pinMode(L1, OUTPUT); //Set pin L1 as Output
 //Output cleaning
 digitalWrite(L1, LOW); //Turn OFF L1
void loop() {
 digitalWrite(L1, HIGH); //Turn ON L1
 delay(TBLINK); //Delay of TBLINK miliseconds(500 ms)
 digitalWrite(L1, LOW); //Turn OFF L1
 delay(TBLINK); //Delay of TBLINK miliseconds(500 ms)
```

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If statement

- Used in conjunction with a comparison operator.
- Tests if a condition is met, and in the positive case, executes desired actions and then it continues with the program.
- Sintax:

```
if (condition) {
    //Do something here
}
else if (othercondition) {
    //Do something else if the first condition wasn't met but the othercondition was met
}
else {
    //Do something here in other case
}
```

Example with digital input pins

```
if (digitalRead(pin) == HIGH) {
    //Do something here if the current pin
    //logic state is HIGH
}
```

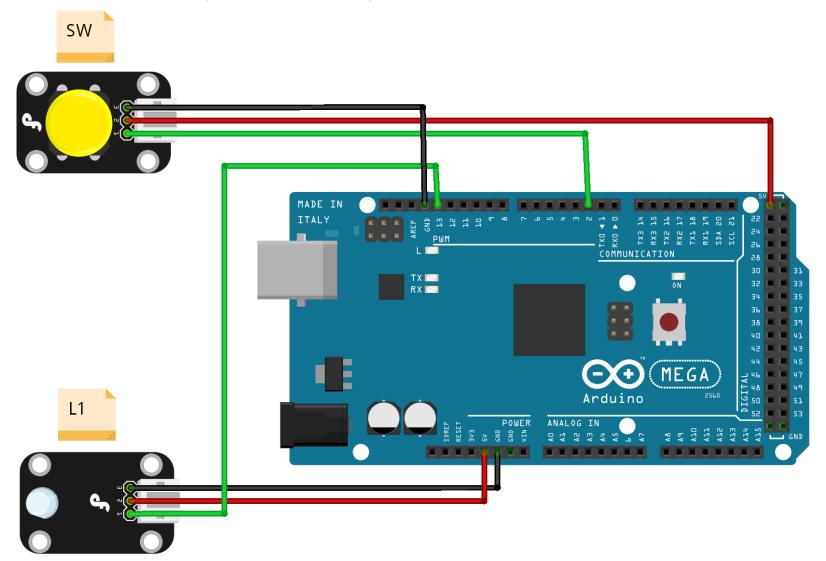
Example with internal variables

```
if (temperature > 25) {
    //Do something here if temperature is
    //greater than 25 degree Celcius
}
```

Example 1.2 – If statement with digital input



Example: In the PIN 2 there is a switch (SW) and in the PIN 13 there is a LED (L1). Turn ON the LED if the switch is activated, in other case, turn off the LED



Example 1.2 – If statement with digital input



```
//I/O pin labeling
#define SW 2 //Switch "SW" connected on pin 2
#define L1 13 //LED "L1" connected on pin 13
void setup() {
 //I/O Pin Configuration
 pinMode(SW, INPUT); //SW as INPUT
 pinMode(L1, OUTPUT); //L1 as OUTPUT
 //Output cleaning
 digitalWrite(L1, LOW); //Turn OFF L1
void loop() {
 if (digitalRead(SW) == HIGH) { //Check if SW is in logic state HIGH
   digitalWrite(L1, HIGH); //If it is, turn ON L1
 else { //In other case
   digitalWrite(L1, LOW); //If the SW is OFF, turn OFF L1
```

Switch statement



- Allows to do different actions depending of different variable values.
- Similar to do multiple if..else if statements for the same var but with different values.
- Each case is the posible value that the variable can have and it's ended with a break;
- Sintax:

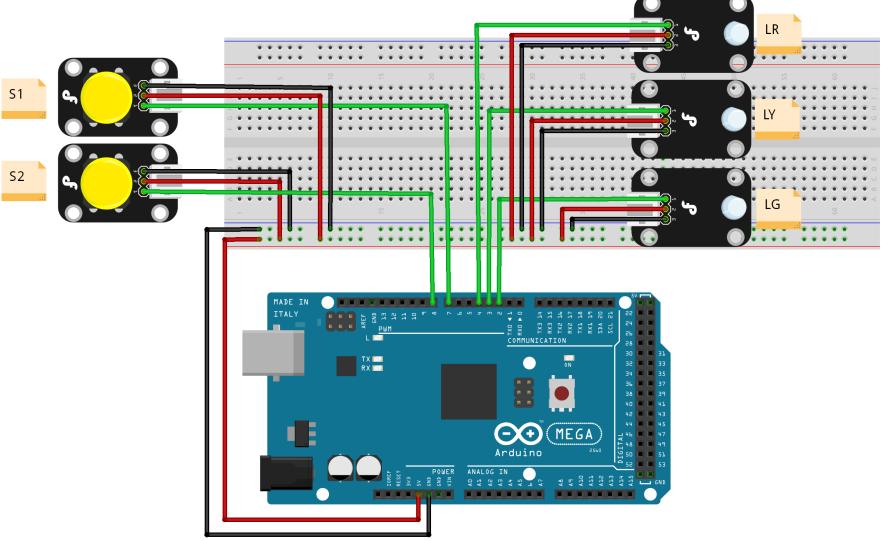
It is posible to check the case with labels instead of raw numbers predefined at the beginning of the program with #define.

```
switch (var) {
   case label1:
        //Do something here if var is equal to the label1
   break;
   case label2:
        //Do something here if var is equal to the label2
   break;
}
```

Example 1.3 – Traffic light



Write a program that controls a traffic light with 2 maintenance switches. If both switches are activated, the Red light will blink. In other case the traffic light will work normally (Red, Yellow, Green).



Example 1.3 – Traffic light



```
//I/O pin labeling
                                                                               void loop() {
#define LR 4 //Red LED "LR" connected on digital pin 4
                                                                                if (digitalRead(S1) == HIGH && digitalRead(S2) == HIGH) { //If both
#define LY 3 //Yellow LED "LY" connected on digital pin 3
                                                                               maintenance switchs are ON, blink
#define LG 2 //Green LED "LG" connected on digital pin 2
                                                                                  //Turn OFF all LEDs
#define S1 7 //Switch "S1" connected on digital pin 7
                                                                                   digitalWrite(LR, LOW);
#define S2 8 //Switch "S2" connected on digital pin 8
                                                                                   digitalWrite(LY, LOW);
                                                                                   digitalWrite(LG, LOW);
//Constant declaration
                                                                                   delay(TIT); //Delay of TIT mseqs (5000msecs)
const unsigned long TRV = 5000; //Time constant from Red to Green
initialized on 5000 ms
                                                                                   //Turn ON red led
const unsigned long TVA = 2500; //Time constant from Green to Yellow
                                                                                   digitalWrite(LR, HIGH);
initialized on 2500 ms
                                                                                   digitalWrite(LY, LOW);
const unsigned long TAR = 1000; //Time constant from Yellow to Red
                                                                                   digitalWrite(LG, LOW);
initialized on 1000 ms
                                                                                   delay(TIT); //Delay of TIT msegs (5000msecs)
const unsigned long TIT = 5000; //Time constant for blinking initialized on
                                                                                 else {//In other case
5000 ms
                                                                                   //Normal traffic light secuence
                                                                                   digitalWrite(LR, HIGH);
void setup() {
                                                                                   digitalWrite(LY, LOW);
 //Pin configuration
                                                                                   digitalWrite(LG, LOW);
 pinMode(LR, OUTPUT); //LR as output
                                                                                   delay(TRV); //Delay of TRV msecs (5000msecs)
 pinMode(LY, OUTPUT); //LY as output
  pinMode(LG, OUTPUT); //LG as output
                                                                                   digitalWrite(LR, LOW);
 pinMode(S1, INPUT); //S1 as intput
                                                                                   digitalWrite(LY, LOW);
  pinMode(S2, INPUT); //S2 as intput
                                                                                   digitalWrite(LG, HIGH);
                                                                                   delay(TVA); //Delay of TVA mseqs (2500msecs)
  //Physical Output Cleaning
  digitalWrite(LR, LOW); //Turn off LR
                                                                                   digitalWrite(LR, LOW);
  digitalWrite(LY, LOW); //Turn off LY
                                                                                   digitalWrite(LY, HIGH);
  digitalWrite(LG, LOW); //Turn off LG
                                                                                   digitalWrite(LG, LOW);
                                                                                   delay(TAR); //Delay of TAR mseqs (1000msecs)
```



Thanks!