Workshop Basic Arduino Class 2 – Sensors

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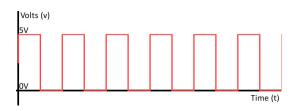


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Introduction – Types of sensors



Digital

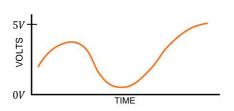


- 2 States (Binary):
 - "HIGH" or "5V" or "0N".
 - "LOW" or "0V" or "0FF".
- Follow the static discipline.
- Works as a switch.



Arduino function: digitalRead(PIN)

Analog

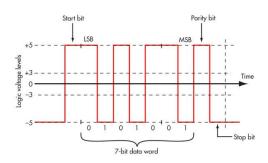


- Multiple values (0 to 5V).
- Requires Analog to Digital Conversor (ADC).
 - Arduino ADC has 10 bit.
 - Arduino ADC range is 0~1023.



Arduino function: analogRead(PIN)

Specialized



- Usually work as a digital sensor with fast pulses.
- The data is "encoded" in a bit stream.
- Commonly used with **libraries** to interpret data.
- Usually include a microprocessor handling encoding.
- Most used protocols: UART, I2C, One-wire.

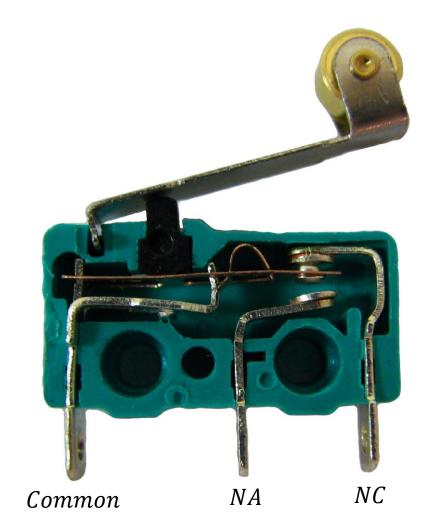


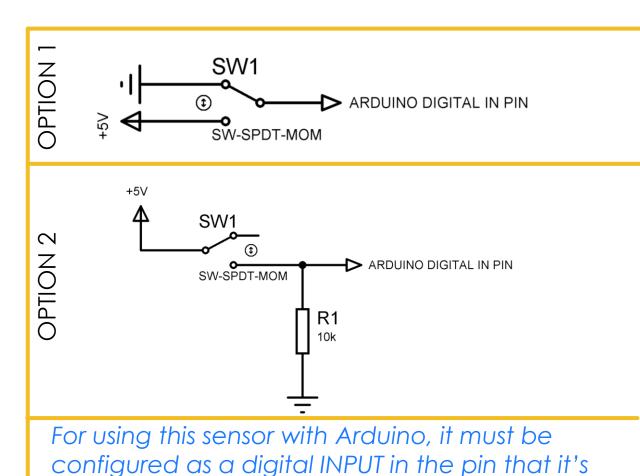




Digital Sensors – Limit Switch

- Works as a button in SPDT configuration (Single Pole Dual Throw).
- Normally, it possess 3 terminals (Common, Normally Open, Normally Closed).
- Commonly used as Limit Switch for a path (security stops).

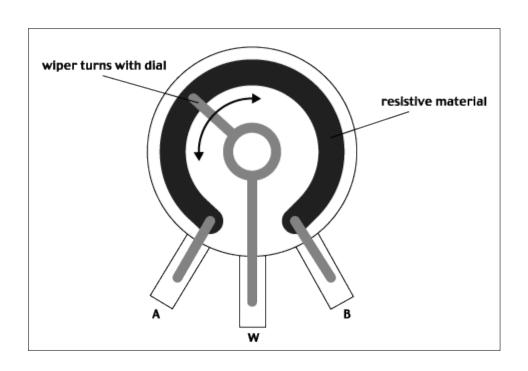




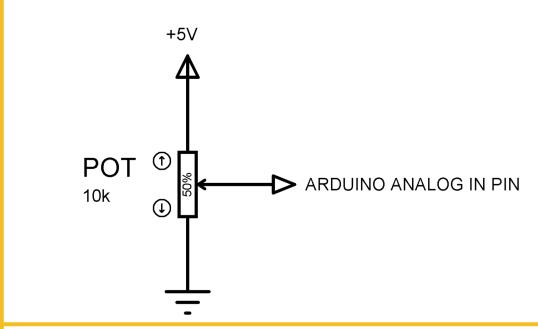
connected.

Analog Sensors- Potentiometer

- Variable resistance.
- Allows the user to graduate certain variable.
- Can be used as angular sensors.
- Types:
 - Logarithmic: Less precision.
 - Linear: High precision.







For using this sensor with Arduino, it must be connected to an Analog Pin (Voltaje will vary from 0V to 5V) and using the analogRead function

Example 2.1 - Potentiometer



 Do an Arduino program that monitors the value of the potentiometers and shows it on the Serial Monitor

```
//I/O Pin Labeling
#define POT1 0 //Potentiometer POT1 connected to pin A0
//Variable declaration
unsigned int valuePOT = 0; //Variable to store the value of the potentiometer (valuePOT)
void setup() {
 //I/O Pin Configuration
 //Note: The analog inputs are not declared as INPUTS, they come like this as default
 //Communications
  Serial.begin (9600); //Begin Serial communications with the computer using the Serial O
ports (TX0 RX0) and 9600 speed bauds rate
void loop() {
  valuePOT = analogRead(POT1); //Read the ADC value of POT1 pin and store it on valuePOT
  Serial.print("POT value: "); //Print result on Serial monitor
  Serial.println(valuePOT); //Print result on Serial monitor
```

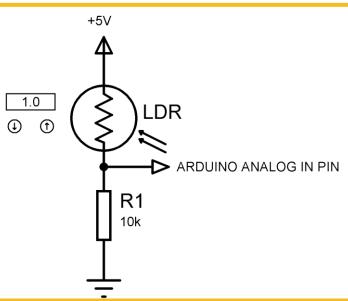
Sensores análogos - LDR

- Light Dependent Resistor (LDR).
- Changes its resistance depending on the light intensity.
 - Lowers its resistance if there is more light.
 - Increases its resistance if There is less light.

Used for applications where the brightness level needs to be measured in order to be controlled

(e.g. Smartphone screen brightness)





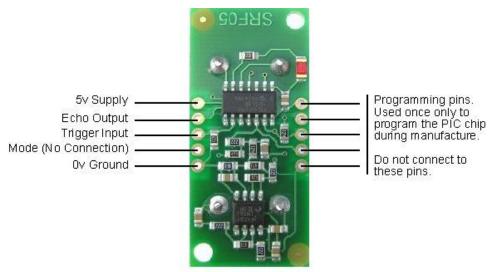
For using this sensor on the Arduino, the sensor must be connected in voltaje divider configuration (see picture). The output of the divider goest to an analog pin of the Arduino, where the analogRead function must be used. The voltage will vary depending on the resistance that is selected as Pull Down on the divider

Digital/Analog Sensor – Ultrasonic Sensor



- Used in order to measure a distance to an object
- They reach large distances (approximately 5 meters)
- Works as a bat
- Returns the time (on microseconds) that the sound signal took in order to go to an objet and return to the sensor

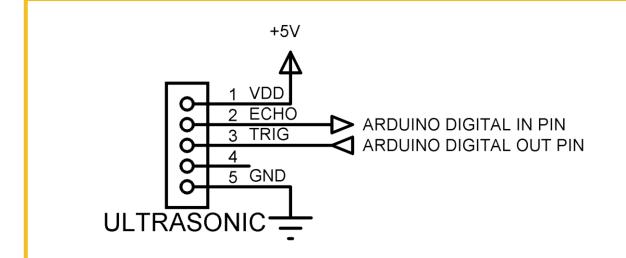




Connections for 2-pin Trigger/Echo Mode (SRF04 compatible)

$$x(cm) = 343 \frac{m}{s} \cdot \frac{100 \ cm}{1 \ m} \cdot \frac{t(\mu secs)}{2} \cdot \frac{1 \ s}{10^6 \mu secs}$$

$$x(cm) \approx \frac{t(\mu secs)}{58}$$



For using this sensor on the Arduino, the ECHO pin must be connected to a digital input pin of the Arduino, the TRIG pin to a digital output pin and finally the VDD and GND pins must be supplied with a power supplyPara utilizarlo en el ARDUINO.

Example 2.2 – Ultrasonic Sensor

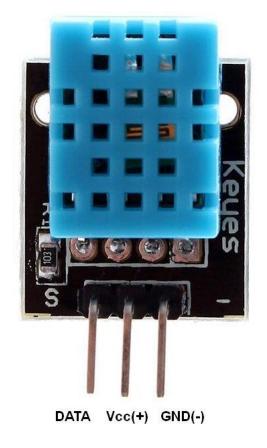
```
EAFIT ...
```

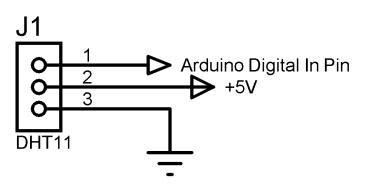
```
//I/O Pin Labeling
#define ECHO 2 //Ultrasonic ECHO pin connected to
                                                     //Physical Output Cleaning
Arduino pin 2
                                                      digitalWrite(TRIG, LOW);
#define TRIG 3 //Ultrasonic TRIG pin connected t
Arduino pin 3
                                                      //Communications
                                                      Serial.begin (9600); //Begin Serial Communications
//Variable declaration
                                                    with the computer by the Serial O port (TXO RXO) at
unsigned int distance = 0; //Variable for storing 9600 bauds
the value of the potentiometer (distance)
//Subroutines and functions
                                                    void loop() {
unsigned int ultraMeas (unsigned int ECHOPIN,
                                                      distance = ultraMeas(ECHO, TRIG); //Measure
unsigned int TRIGPIN) {
                                                    distance
  delay(50); //Delay of 50 ms before the next
                                                      Serial.print("Distance (cm): ");
ranging
                                                      Serial.println(distance);
  digitalWrite(TRIGPIN, HIGH); //Turn ON the TRIG
for measuring the distance
  delayMicroseconds (10); //Wait 10uSecs with the
TRIG ON
  digitalWrite (TRIGPIN, LOW); //Turn OFF the TTRUG
 return pulseIn (ECHOPIN, HIGH) /58.0; //Return the
distance on centimeters
void setup() {
  //I/O Pin Definition
  pinMode(ECHO, INPUT); //ECHO Pin as input
  pinMode(TRIG, OUTPUT); //TRIG Pin as output
```

Specialized sensors – DHT11



- Allows to measure temperature and humidity.
- Can be used for weather telemetry.
- Very usefull for Green houses.
- Sends a data stream via One-Wire protocol that can be interpreted with a Library.





For using this sensor with Arduino, a library that allows to interpret data stream from sensor must be used

Example 2.3 – DHT11



 Do a program on Arduino that monitors the temperature and humidity of the DHT11 and prints each values on the Serial Monitor every second. If the temperature rises 25 °C, turn a LED L1.

```
//Library Declaration
                                                        pinMode(L1, OUTPUT); //LED L1 as a digital output
#include <DHT.h>
                                                        //Physical Outputs Cleaning
                                                        digitalWrite(L1, LOW); //Turn off L1
//I/O Pin Labeling
#define L1 13 //LED L1 connected on pin 13
#define DHTPIN 2 //DHT11 sensor connected to pin 2
                                                      //Communications
                                                        Serial.begin (9600); //Begin Serial Communications
//Constants declaration
                                                      with the computer by the Serial O port (TXO RXO) at
const int Tmax = 25; //Max temperature constants
                                                      9600 bauds
                                                        dht.begin(); //Initialize communications with DHT11
initiliazed
//on 25 °C.
                                                      sensor
//Variable declaration
float temperature = 0; //Variable to store the
                                                      //Run-time
temperature
float humidity = 0; //Variable to store humidity
                                                      void loop() {
                                                          readDHT();
//Library Vars
                                                          Serial.print("Temperature: ");
#define DHTTYPE DHT11 //Use DHT11 sensor variant
                                                          Serial.print(temperature);
DHT dht(DHTPIN, DHTTYPE); //DHT object var
                                                          Serial.print(" Humidity: ");
                                                          Serial.println(humidity);
                                                          if (temperature >= Tmax) {
//Subroutines & Functions
                                                            digitalWrite(L1, HIGH);
void readDHT() {
 temperature = dht.readTemperature();
 humidity = dht.readHumidity();
                                                          delay(1000);
//Configuration
void setup() {
  //Pin Configuration
```



Thanks!