

(n=2)

1 = "L"

2 = "R"

3 = "O"

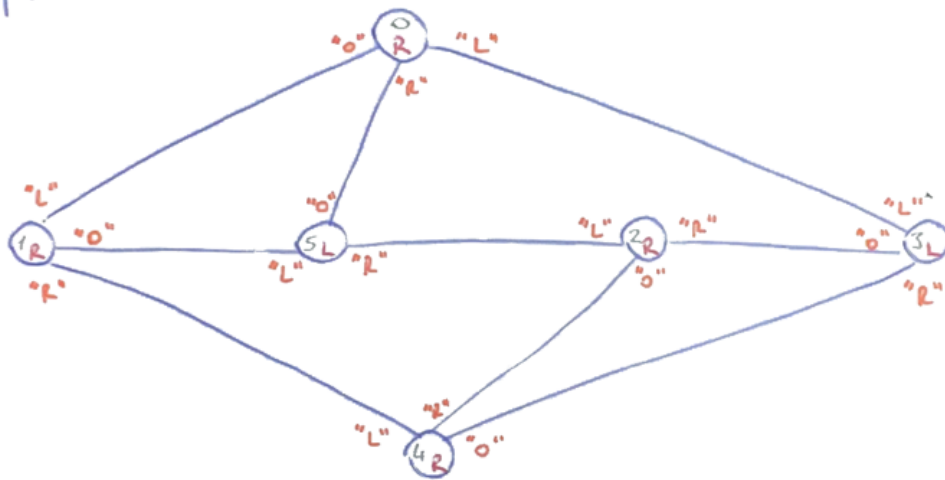
Adjacency Matrix:

| | V_0 | V_1 | V_2 | V_3 | V_4 | V_5 |
|-------|---------------------------|---------------------------|---------------------------|---------------------------|---------------------------|---------------------------|
| V_0 | 0 | $\overset{3}{\text{"O"}}$ | 0 | $\overset{1}{\text{"L"}}$ | 0 | $\overset{2}{\text{"R"}}$ |
| V_1 | $\overset{1}{\text{"L"}}$ | 0 | 0 | 0 | $\overset{2}{\text{"R"}}$ | $\overset{3}{\text{"O"}}$ |
| V_2 | 0 | 0 | 0 | $\overset{2}{\text{"R"}}$ | $\overset{3}{\text{"O"}}$ | $\overset{1}{\text{"L"}}$ |
| V_3 | $\overset{1}{\text{"L"}}$ | 0 | $\overset{3}{\text{"O"}}$ | 0 | $\overset{2}{\text{"R"}}$ | 0 |
| V_4 | 0 | $\overset{1}{\text{"L"}}$ | $\overset{2}{\text{"R"}}$ | $\overset{3}{\text{"O"}}$ | 0 | 0 |
| V_5 | $\overset{3}{\text{"O"}}$ | $\overset{1}{\text{"L"}}$ | $\overset{2}{\text{"R"}}$ | 0 | 0 | 0 |

Vertex Settings:

| V_0 | $\overset{2}{\text{"R"}}$ |
|-------|---------------------------|
| V_1 | $\overset{2}{\text{"R"}}$ |
| V_2 | $\overset{2}{\text{"R"}}$ |
| V_3 | $\overset{1}{\text{"L"}}$ |
| V_4 | $\overset{2}{\text{"R"}}$ |
| V_5 | $\overset{1}{\text{"L"}}$ |

Map:



Simulation 1:

| | Vertex | Direction |
|-------|--------|-----------|
| 1/s : | 0 | 2 "R" |
| 2/s : | 5 | 1 "L" |
| 3/s : | 1 | 2 "R" |
| 4/s : | 4 | 3 "O" |
| 5/s : | 3 | 3 "O" |

Simulation 2:

| | Vertex | Direction |
|-------|--------|-----------|
| 1/s : | 5 | 3 "O" |
| 2/s : | 0 | 3 "O" |
| 3/s : | 1 | 3 "O" |
| 4/s : | 5 | 3 "O" |
| 5/s : | 0 | 3 "O" |

Signals:

Real: $\begin{bmatrix} \overset{R}{2}, \overset{L}{1}, \overset{R}{2}, \overset{O}{3}, \overset{O}{3} \end{bmatrix}$
 Obs: $\begin{bmatrix} \overset{R}{2}, \overset{L}{1}, \overset{R}{3}, \overset{O}{3}, \overset{O}{3} \end{bmatrix}$

Signals:

Real: $\begin{bmatrix} 3, 3, 3, 3, 3 \end{bmatrix}$
 Obs: $\begin{bmatrix} 3, 3, 2, 1, 3 \end{bmatrix}$