## Numerical Mathematics II for Engineers Homework assignment 3: Rise of the stencil.

Programming assignments can be solved in MATLAB/Python/Julia. Use sparse matrices where appropriate!

**Deadline**: submit before/during the lecture on November 11, 2019.

1. Exercise: Implementation of higher-order difference stencils

7 points

For given  $m \in \mathbb{N}_0$ , let  $\bar{\Omega} = [0,1]$  and  $\bar{\Omega}_h = \{0,h,2h,\ldots,(N+1)h\}$  with h = 1/(N+1) the corresponding grid. Consider  $x_n = nh \in \bar{\Omega}_h$  with sufficiently many neighbors to either side, i.e., for any j with  $n-m \leq j \leq n+m$  we require  $x_j = jh \in \bar{\Omega}_h$ . We abbreviate  $u_n = u(x_n)$  with  $u : \bar{\Omega} \to \mathbb{R}$  being r-times continously differentiable.

- a) Perform Taylor expansions for  $u_j$  for  $n-m \leq j \leq n+m$  in terms of  $u(x_n)$  and derivatives  $u^{(k)}(x_n)$  for  $k \geq 0$ . Expand and, by neglecting the remainders, invert this relationship to find symmetric difference stencils for arbitrary derivatives and arbitrary desired consistency level. What are k, r and the remainders R?
- b) Based on a) write a function S=a03ex01getstencil(m) which returns the 2m+1 stencils for  $u^{(k)}(x_n)$  for k=0...2m and compare the symmetric stencils here: https://en.wikipedia.org/wiki/Finite\_difference\_coefficient
- c) Write a function [xh,Lh]=a03ex01getlaplace(m,N) which returns the reduced sparse matrix for the Laplace operator  $L_h \in \mathbb{R}^{(N+1)\times (N+1)}$  based on the stencil S from b) with periodic boundary conditions and the corresponding mesh  $x_h = (x_0,..,x_N)$  for given  $N,m\in\mathbb{N}$ .
  - Hint: Assume  $u: \mathbb{R} \to \mathbb{R}$  is 1-periodic u(x+1) = u(x). Discretize u on [0,1) or  $u_h$  on  $\{0,h,2h,\ldots,Nh\}$  with h=1/(N+1) and identify  $u_{N+1+i}=u_i$  for  $i\in\mathbb{Z}$ .
- d) For  $u(x) = \sin(2\pi x)$  plot the error  $\max_j |(L_h u_h)(x_j) u''(x_j)|$  as a function of h doubly logarithmically for m = 1, ..., 4 and  $N = 2^p 1$  for p = 2, ..., 15 and discuss.

2. Exercise: Difference formulas for non-uniform grids

7 points

Consider a domain  $\Omega = (0,1)$ , its closure  $\overline{\Omega} = [0,1]$ , and a grid  $\overline{\Omega}_h = \{x_0, \dots, x_{N+1}\}$ , where the grid points satisfy  $0 = x_0 < x_1 < \dots < x_{N+1} = 1$  with step sizes  $h_i := x_i - x_{i-1}$  and maximal step size  $h := \max_{i \in \{1,\dots,N+1\}} h_i$ . If  $h_i = h_j$  for all  $i, j \in \{1,\dots,N+1\}$  we say that  $\overline{\Omega}_h$  is a uniform grid, otherwise a non-uniform grid. For  $i \in \{1,\dots,N\}$  and  $u \in C^4(\overline{\Omega})$  we define the adapted differences

$$(D^{-}u)_{i} := \frac{u(x_{i}) - u(x_{i-1})}{x_{i} - x_{i-1}} = \frac{u(x_{i}) - u(x_{i-1})}{h_{i}},$$

$$(D^{+}u)_{i} := \frac{u(x_{i+1}) - u(x_{i})}{x_{i+1} - x_{i}} = \frac{u(x_{i+1}) - u(x_{i})}{h_{i+1}},$$

$$(D^{0}u)_{i} := \frac{u(x_{i+1}) - u(x_{i-1})}{x_{i+1} - x_{i-1}} = \frac{u(x_{i+1}) - u(x_{i-1})}{h_{i} + h_{i+1}}.$$

a) Determine  $\alpha_i, \beta_i, \gamma_i, R_i \in \mathbb{R}$  depending on  $h_i, h_{i+1}$  such that

$$u''(x_i) = \alpha_i u(x_{i-1}) + \beta_i u(x_i) + \gamma_i u(x_{i+1}) + R_i,$$

with  $\lim_{h\to 0} R_i = 0$ . Hint: Use u'' = au'' + bu'' with a+b=1 and use suitable Taylor expansions to express the two terms. Choose a and b properly.

- **b)** Determine the order of the remainder  $R_i$  for general  $h_i, h_{i+1}$ , i.e., find the largest p > 0 such that  $|R_i| = \mathcal{O}(h^p)$ . Is  $u \in C^4(\overline{\Omega})$  necessary to obtain this rate?
- c) Under which special conditions on  $h_i, h_{i+1}$  does the order of  $R_i$  improve? Is it necessary that  $u \in C^4(\overline{\Omega})$  to obtain the improved rate?
- 3. Programming exercise: 1D FDM

7 points

Consider the following boundary value problem (BVP) :

$$\begin{cases} -u''(x) - 4u'(x) + u(x) = f(x), & \text{for all } x \in \Omega = (0, 1), \\ u(0) = 1, \ u(1) = 2. \end{cases}$$

The exact solution is given by  $u(x)=1+4x^2-3x^3$ . Discretize this BVP with finite differences on  $\overline{\Omega}_h=\{ih\in\mathbb{R}:i=0,\ldots,N+1\}$  with mesh size  $h=\frac{1}{N+1}$ , where  $N=2^p-1$  for some integer p>1. Use the standard scheme

$$u_h(0) = 1, u_h(1) = 2,$$
  
 $(-D^-D^+ - 4D^0 + I)u_h(ih) = f(ih),$   $i = 1, ..., N,$ 

so that you get a discrete equation  $L_h u_h = f_h$  with  $L_h \in \mathbb{R}^{N \times N}$ .

a) Determine the right hand side of the BVP analytically.

- b) Write a function [xh,Lh,fh] = a03ex03getBVP(p) that sets up the grid xh, the sparse matrix Lh, and the right hand side fh of the corresponding linear system for the refinement level n=2^p-1. Hint: Useful MATLAB commands are speye, spdiags, linspace, etc. (useful Python functions are numpy.linspace, scipy.sparse.diags, etc.).
- c) Write a function error = a03ex03solve() that solves the discretized problem for  $p \in \{1, ..., 15\}$ . For each p determine the error between the approximation and the restricted exact solution in the maximum norm, i.e. error(p) =  $\max_i |u_h(ih) u(ih)|$ . Plot the errors versus the grid size using loglog(h,error) (in Python matplotlib.pyplot.loglog(h,error)). How fast does error(p)  $\rightarrow 0$  as  $h \rightarrow 0$ ?

total sum: 21 points