TECHNICAL UNIVERSITY OF BERLIN

Faculty II - Mathematics and Natural Sciences

Institute of Mathematics

Dr. D. Peschka, A. Selahi

Numerical Mathematics II for Engineers

Homework Assignment 1: Submitted on October 28th, 2019

Submitted by Group 5

Kagan Atci	338131	Phyiscal Engineering, M.Sc.
Daniel V. Herrmannsdoerfer		
Navneet Singh		

Exercise 1

a & b)

• Common PDE: Kaup-Kupershmidt equation

$$\frac{\partial u}{\partial t} = \frac{\partial^5 u}{\partial x^5} + 10 \frac{\partial^3 u}{\partial x^3} u + 25 \frac{\partial^2 u}{\partial x^2} \frac{\partial u}{\partial x} + 20 u^2 \frac{\partial u}{\partial x}$$
 (1)

is a PDE fifth order.

• Member 1 PDE: Hunter-Saxton equation

$$\frac{\partial}{\partial x} \left(\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} \right) = \frac{1}{2} \frac{\partial^2 u}{\partial x^2} \tag{2}$$

is a PDE second order.

• Member 2 PDE: Liouville equation

$$\nabla^2 u + e^{\lambda u} = 0 \tag{3}$$

is a PDE second order.

• Member 3 PDE: φ^4 - Equation

$$\frac{\partial^2 \varphi}{\partial t^2} - \frac{\partial^2 \varphi}{\partial r^2} - \varphi + \varphi^3 = 0 \tag{4}$$

is a PDE second order.

Numerical Mathematics II for Engineers

c) The Navier-Stokes-Equation describes the motion of the viscous fluid substances and is expressed for compressible fluid as

$$\rho(\partial_t u + u \cdot \nabla u) = -\nabla p + \mu \nabla^2 u + f \tag{5}$$

with ρ the density, u velocity vector, p pressure, and μ kinematic viscosity of the fluid. Equation (5) is expressed in homogenous form by setting f = 0 as follows

$$\rho(\partial_t u + u \cdot \nabla u) + \nabla p - \mu \nabla^2 u = 0 \tag{6}$$

For $u(t,x) = (u_0x_2(H-x_2),0)^T$ with $u_0 \in \mathbb{R}$, $x = (x_1,x_2) \in \Omega = \mathbb{R} \times (0,H)$, and $t \in (0,\infty)$, the partial differentiations result

$$\frac{\partial u}{\partial t} = (0,0)^T \tag{7}$$

$$\nabla u = (0,0)^T \tag{8}$$

$$\nabla^2 u = (0,0)^T \tag{9}$$

since u is not t-dependent and u_1 and u_2 are not effected by x_1 and x_2 , respectively. Equations 7, 8 and 9 show that u is a twice differentiable function, satisfying the homogenous Navier-Stokes PDE with a boundary condition in a domain $\Omega \in \mathbb{R}^2$, which is reffered to as the classical solution for second order PDEs. For the given conditions, Equation (6) can be expressed as

$$\nabla p = 0 \tag{10}$$

This can be referred to a 2D-flow model of a fluid in a tube with a width of H at any certain height, which is observed along the gravity axis. Therefore, the pressure in the domain Ω is described as $p = const. \in [0, \infty)$.

Exercise 2

Given is the Toeplitz-Matrix

$$\underline{\underline{K_4}} = \begin{bmatrix} 2 & -1 & 0 & 0 \\ -1 & 2 & -1 & 0 \\ 0 & -1 & 2 & -1 \\ 0 & 0 & -1 & 2 \end{bmatrix} \in \mathbb{R}^{4 \times 4} \tag{11}$$

and $f(x) = \frac{1}{2} \underline{x}^T \underline{\underline{K_4}} \underline{x} : \mathbb{R}^4 \to R$.

a) f(x) can be expressed by executing the matrix multiplication as

$$f(x) = x_1^2 + (x_1 - x_2)^2 + (x_2 - x_3)^2 + (x_3 - x_4)^2 + x_4^2$$
(12)

2 Assignment 1

and the gradient of f(x) is

$$\nabla f(x) = \begin{bmatrix} \frac{\partial f}{\partial x_1} \\ \frac{\partial f}{\partial x_2} \\ \frac{\partial f}{\partial x_3} \\ \frac{\partial f}{\partial x_4} \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 4x_1 - x_2 \\ -x_1 + 4x_2 - x_3 \\ -x_2 + 4x_3 - x_4 \\ -x_3 + 4x_4 \end{bmatrix} = \begin{bmatrix} 2x_1 - \frac{x_2}{2} \\ \frac{-x_1}{2} + 2x_2 - \frac{x_3}{2} \\ \frac{-x_2}{2} + 2x_3 - \frac{x_4}{2} \\ \frac{-x_3}{2} + 2x_4 \end{bmatrix}$$
(13)

and $K_4\underline{x}$ gives

$$\underline{\underline{K_4x}} = \begin{bmatrix} 2 & -1 & 0 & 0 \\ -1 & 2 & -1 & 0 \\ 0 & -1 & 2 & -1 \\ 0 & 0 & -1 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 2x_1 - \frac{x_2}{2} \\ \frac{-x_1}{2} + 2x_2 - \frac{x_3}{2} \\ \frac{-x_2}{2} + 2x_3 - \frac{x_4}{2} \\ \frac{-x_3}{2} + 2x_4 \end{bmatrix}$$
(14)

Hence, the statement $\nabla f(x) = \underline{\underline{K_4}}\underline{x}$ is verified, since Equation (13) and Equation (14) portray equal functionals.

- **b)** A real symmetric matrix $\underline{\underline{K_n}} \in \mathbb{R}^{n \times n}$ is considered as positive definite, if $\underline{x}^T \underline{\underline{K_n}} \underline{x} > 0$, $\forall x \in \mathbb{R}^n \setminus \{0\}$. f(x) is a good example for fulfilment of this condition, since the $\underline{x}^T \underline{\underline{K_4}} \underline{x}$ is already expanded in Equation (12) that consists of sum of square terms, and therefore non-negative for all $x \in \mathbb{R}^n \setminus \{0\}$.
- c) In the first step of the induction $det(K_1)$ for n=1 is investigated. With

$$\det(\underline{K_1}) = \det(2) = 2 \tag{15}$$

the statement $det(K_n) = n + 1$ is fulfilled.

In the second step, we prove a statement for a general n, assuming that the relation holds for every value up to n-1. The determinant $\det(\underline{K}_n)$ for $n \in \mathbb{N}$ is written

Numerical Mathematics II for Engineers

with the Laplace expansion as follows

The minor determinant in the second term on the right hand-side of Equation (16) is further expanded as

$$\begin{vmatrix} 2 & -1 & 0 & \cdots & 0 \\ -1 & & & & & \\ & \ddots & \ddots & \ddots & & \\ 0 & \cdots & 0 & -1 \end{vmatrix}_{n-1} = (-1) \cdot (-1)^{n-1+n-1} \begin{vmatrix} 2 & -1 & 0 & \cdots & 0 \\ -1 & & & & \\ & \ddots & \ddots & \ddots & \\ & & & & -1 \\ 0 & \cdots & 0 & -1 & 2 \end{vmatrix}_{n-2}$$
(17)

With Equation (17) plugged in Equation (16), and assuming that stated relation holds, $det(K_n)$ can be expressed as

$$\det(\underline{\underline{K_n}}) = 2 \det(\underline{\underline{K_{n-1}}}) - \det(\underline{\underline{K_{n-2}}})
= 2n - (n-1) = n+1$$
(18)

$$=2n - (n-1) = n+1 \tag{19}$$

4 Assignment 1