

MESH GENERATION

Num2Ing TU Berlin

with Ali and Dirk (WS 2019/20)

Preparation

Get Julia/Python/MATLAB to work.

Plot a single triangle using triplot.

Download & compile triangle.

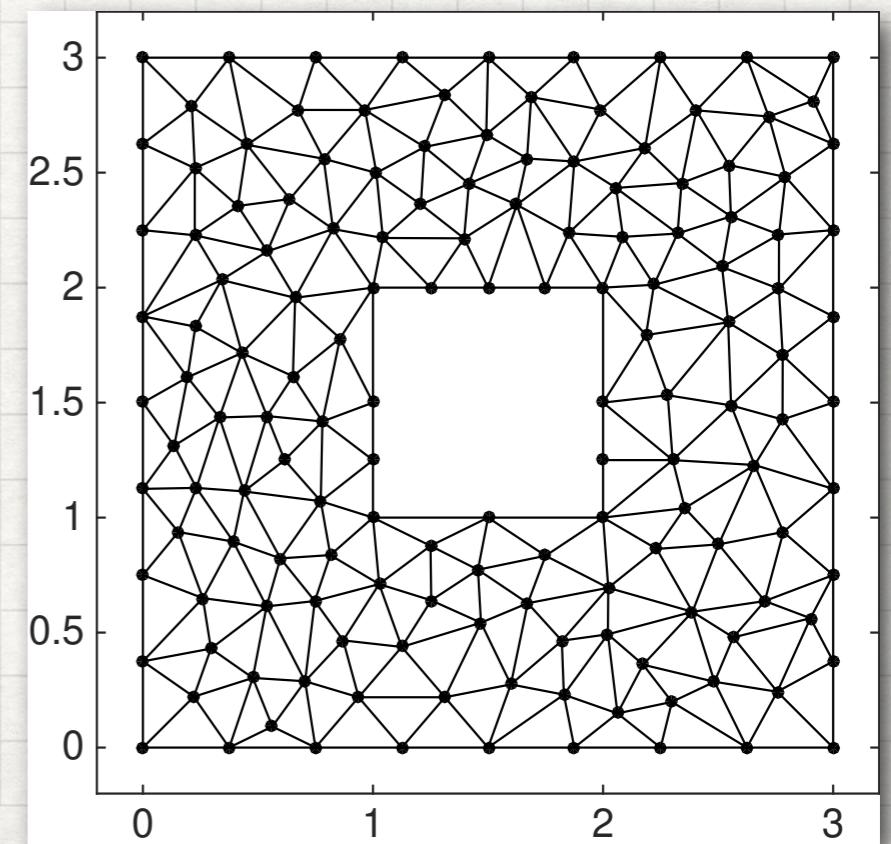
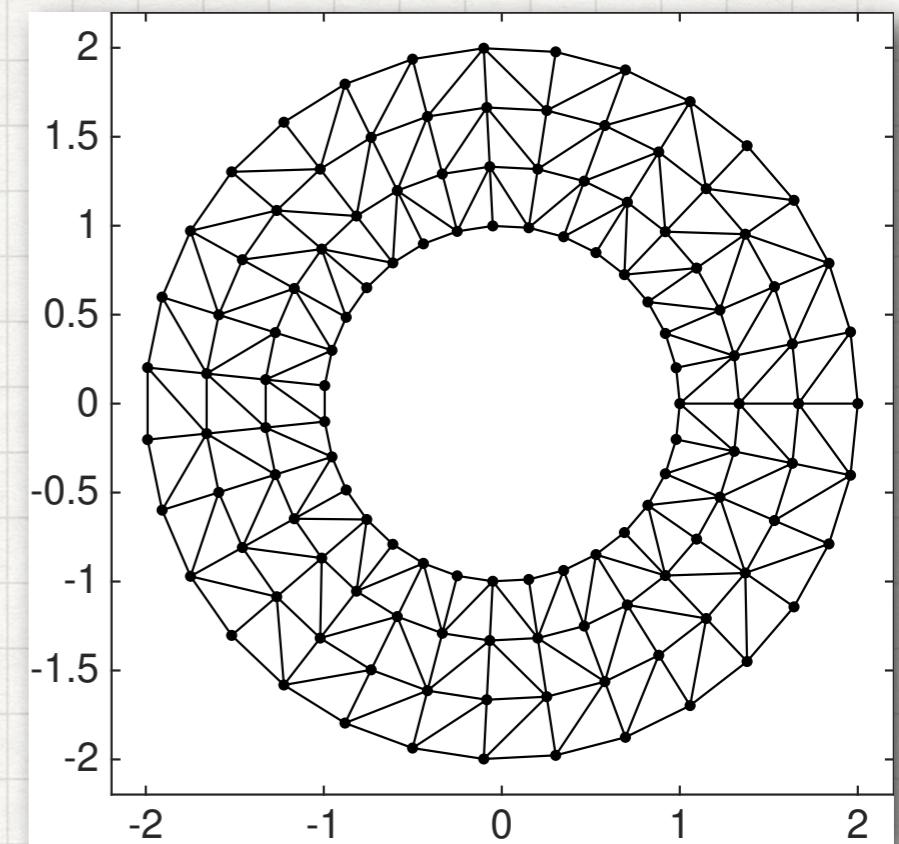
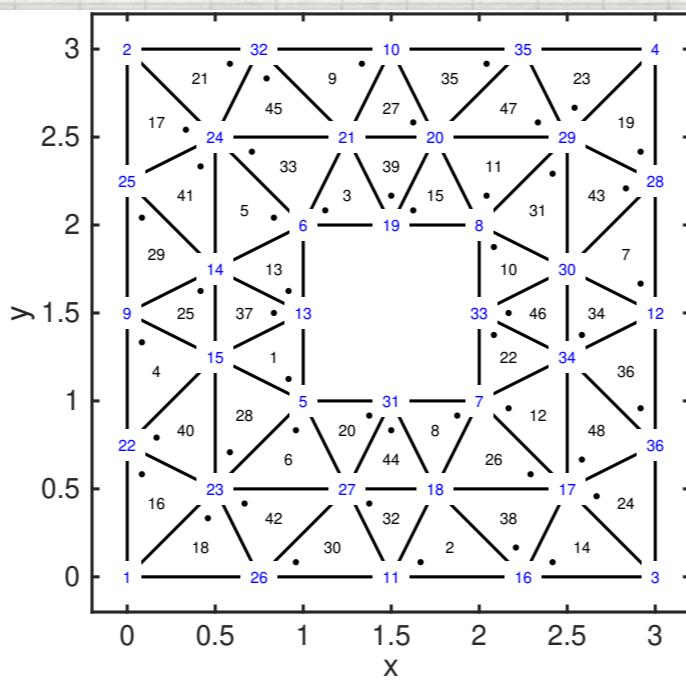
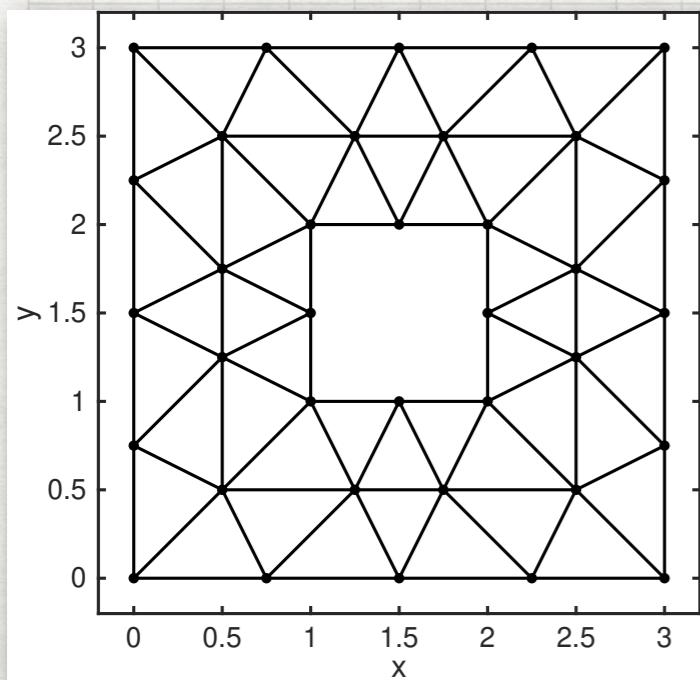
```
1 import matplotlib.pyplot as plt
2 import numpy as np
3
4 tri = np.array([[0,1,2]],dtype=np.int64)
5 x  = np.array([0,1,0],dtype=float)
6 y  = np.array([0,0,1],dtype=float)
7
8 plt.figure()
9 plt.triplot(x,y,triangles=tri)
10 plt.show()
```

```
>> x=[0 1 0];
>> y=[0 0 1];
>> tri=[1 2 3];
>> triplot(tri,x,y)
>>
```

- Gmsh (mesh generation) <http://gmsh.info/>
- Triangle (2D mesh generation) <https://www.cs.cmu.edu/~quake/triangle>
- TetGen (3D mesh generation) <http://www.tetgen.org/>

MATLAB functions

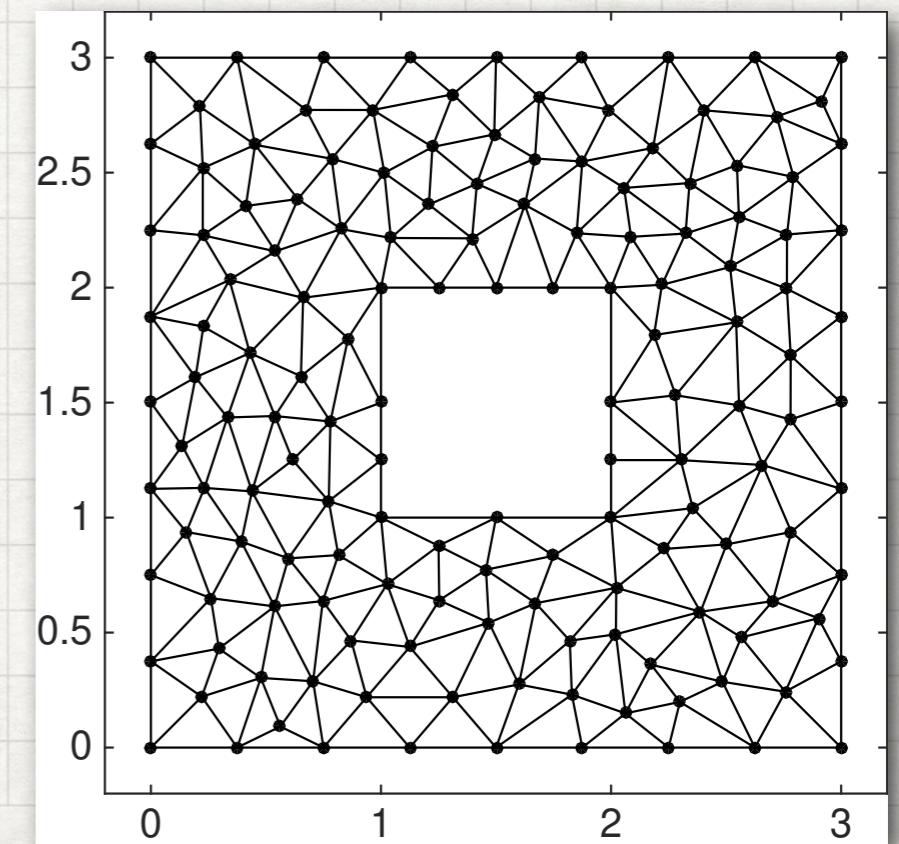
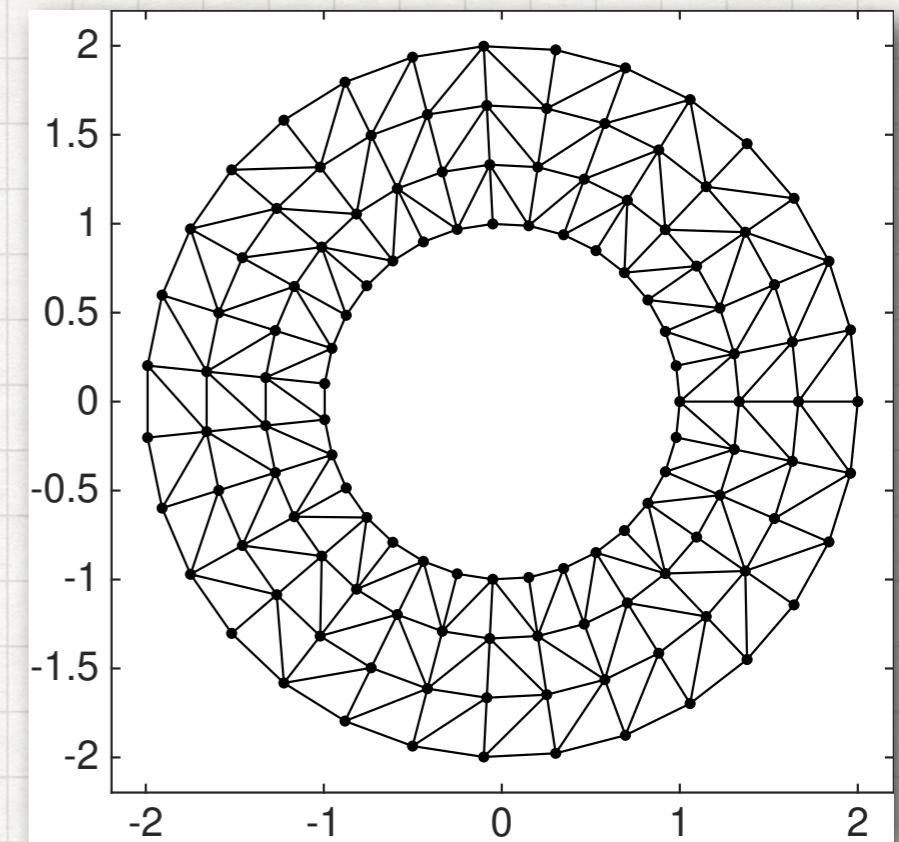
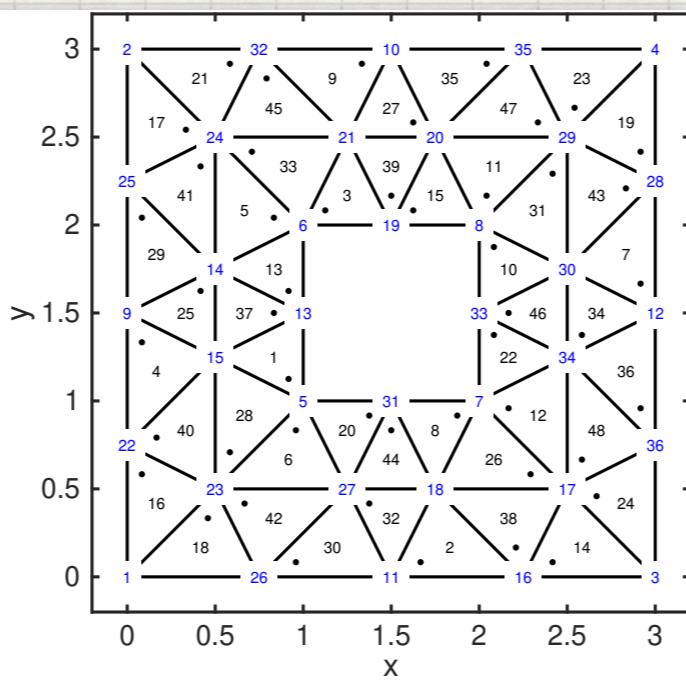
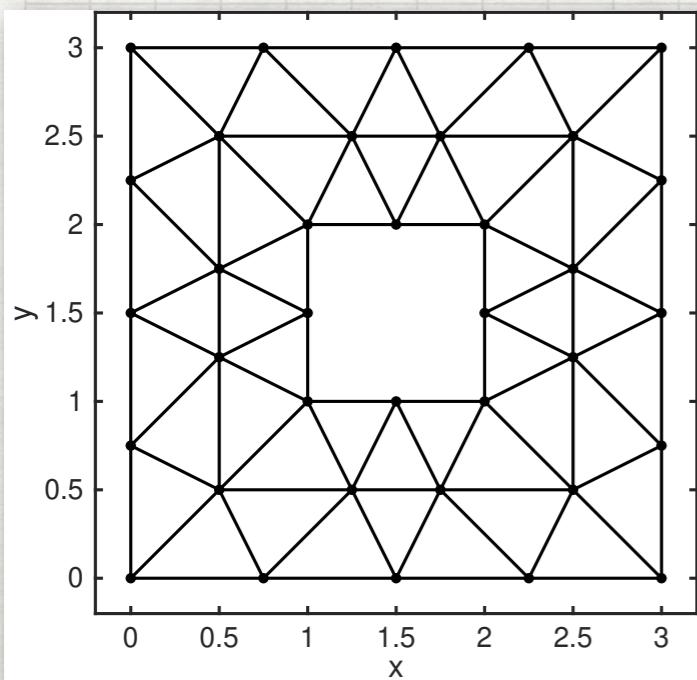
- `trisurf`, `trisurf` (Plotting)
- `delaunay` (Mesh generation)
- `readtri` (Read triangle file)
- `meshgrid` (Point arrays)



Python functions

```
import matplotlib.pyplot as plt  
import matplotlib.tri as tri  
import numpy as np
```

- **triplot, trisurf (Plotting)**
- **delaunay (Mesh generation)**
- **readtria (Read triangle file)**
- **meshgrid (Point arrays)**



Definition III.27 (k -simplex): Let $x_k \in \mathbb{R}^n$ be a set of $k + 1$ distinct points so that $x_r - x_0$ for $r = 1, \dots, k$ are linearly independent. Then the convex hull of points

$$C(x_0, \dots, x_k) = \{\xi_0 x_0 + \xi_1 x_1 + \dots + \xi_k x_k : \sum_{i=0}^k \xi_i = 1 \text{ and } \xi_i \geq 0\} \subset \mathbb{R}^n, \quad (\text{III.15})$$

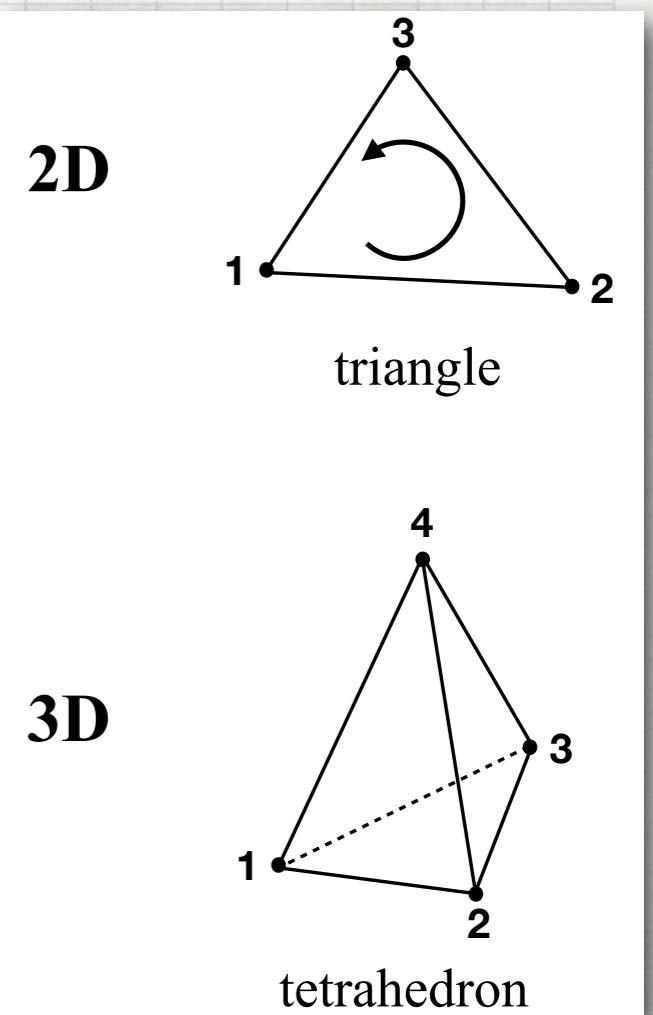
is a k -simplex. For a point $x \in C$ we call (ξ_0, \dots, ξ_k) its barycentric coordinates. A 0-simplex is a vertex, a 1-simplex is a line, a 2-simplex is a triangle, a 3-simplex is a tetrahedron and linear independency requires $n \geq k$. By removing the i th vertex each k -simplex is composed of $k + 1$ $(k - 1)$ -simplices $C(x_0, \dots, \widehat{x_{i+1}}, \dots, x_k)$ for $i = 0, \dots, k$. E.g., each tetrahedron (3-simplex) is composed of 4 triangles (2-simplex), which are the faces/boundaries of the tetrahedron, each triangle (2-simplex) is composed of 3 lines (1-simplex), which are the edges/boundaries of the triangle. Each line (2-simplex) is composed of 2 vertices (0-simplex), which are the boundaries of the line.

Definition III.28 (Mesh representation with simplices): Let $x_k \in \mathbb{R}^n$ for $k = 1, \dots, n_p$ be a set of $n_p \in \mathbb{N}$ distinct points and $e_k \in \mathbb{N}^{n_e \times (k+1)}$ such that

$$\Omega_l = C(x_{e_k(l,1)}, \dots, x_{e_k(l,k+1)}),$$

using (III.15) is a k -simplex for all $l = 1, \dots, n_e$. We say n_p is the *number of points* and n_e is the *number of elements*. As before we require the set Ω_l to form an admissible decomposition of $\bar{\Omega} = \bigcup_{l=1}^{n_e} \bar{\Omega}_l$. The mesh is represented using the vertex positions $x_k \in \mathbb{R}^n$ and using the element description encoded in $e_k \in \mathbb{N}^{n_e \times (k+1)}$.

$$\bar{\Omega} = \bigcup_{l=1}^{n_e} \bar{\Omega}_l$$

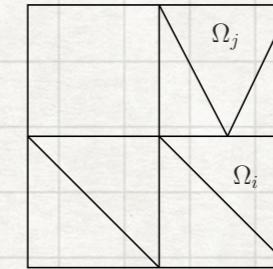
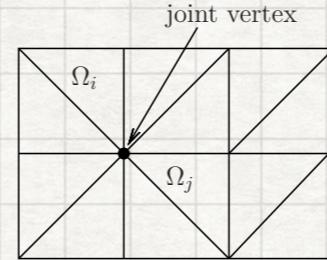
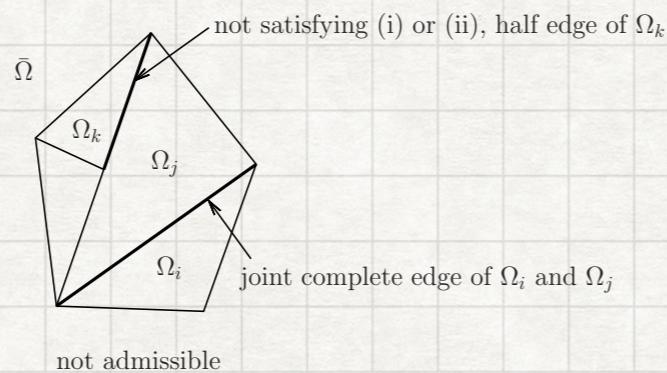


Definition III.24 (Admissible decomposition): Assume a given domain $\Omega \subset \mathbb{R}^d$ with polygonal boundary and let

$$\bar{\Omega} = \bigcup_{i=1}^{n+1} \bar{\Omega}_i,$$

be a decomposition of $\bar{\Omega}$ into elements $\{\bar{\Omega}_i\}_{i=1,\dots,n+1}$.

- $n = 1$: If $\Omega = (a, b) \subset \mathbb{R}$, then an admissible decomposition is given by a union of non-overlapping but adjacent intervals, i.e., $\Omega_i = (x_{i-1}, x_i)$, $i = 1, \dots, n + 1$ and $a = x_0 < x_1 < \dots < x_n < x_{n+1} = b$.
- $n = 2$: A decomposition of Ω into triangles (or convex quadrilaterals etc) $\{\Omega_i\}_{i=1}^n$ is admissible, if for each i and j exactly one of the following cases is true:
 - $\Omega_i = \Omega_j$;
 - $\bar{\Omega}_i \cap \bar{\Omega}_j$ is a joint complete edge of both Ω_i and Ω_j ;
 - $\bar{\Omega}_i \cap \bar{\Omega}_j$ is a joint vertex of Ω_i and Ω_j ;
 - $\bar{\Omega}_i \cap \bar{\Omega}_j = \emptyset$.

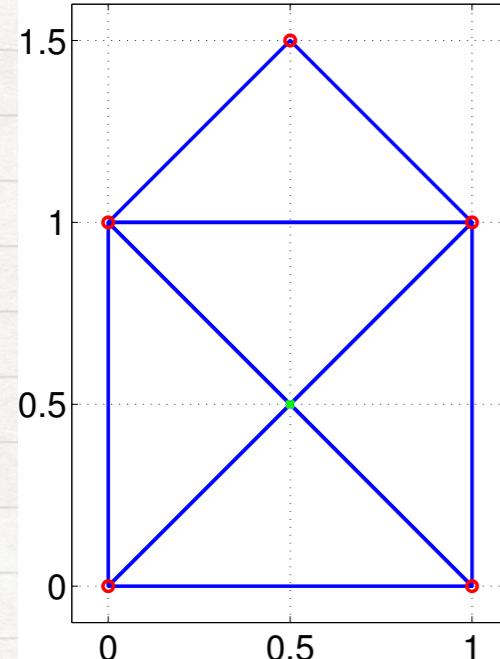


- $n = 3$: A decomposition into tetrahedrons (or hexahedrons, pyramids, wedges, etc) is called admissible, if for each i and j exactly one of the following cases is true:

- $\Omega_i = \Omega_j$;
- $\bar{\Omega}_i \cap \bar{\Omega}_j$ is a joint complete face of both Ω_i and Ω_j (triangle, quadrilateral, ...);
- $\bar{\Omega}_i \cap \bar{\Omega}_j$ is a joint complete edge of both Ω_i and Ω_j ;
- $\bar{\Omega}_i \cap \bar{\Omega}_j$ is a joint vertex of Ω_i and Ω_j ;
- $\bar{\Omega}_i \cap \bar{\Omega}_j = \emptyset$.

Structured mesh-Task 1: Generate and plot via triplot (by hand)

Example III.30 (House mesh): The mesh shown below can be represented as follows:



$$x_1 = (0, 0)^\top, \quad x_2 = (1, 0)^\top, \quad x_3 = (0.5, 0.5)^\top,$$
$$x_4 = (0, 1)^\top, \quad x_5 = (1, 1)^\top, \quad x_6 = (0.5, 1.5)^\top,$$

$$e_2 = \begin{pmatrix} 1 & 2 & 3 \\ 1 & 3 & 4 \\ 2 & 5 & 3 \\ 3 & 5 & 4 \\ 4 & 5 & 6 \end{pmatrix} \in \mathbb{N}^{5 \times 3}, \quad n_p = 6, \quad n_e = 5, \quad k = 2.$$

The domain consists of $n_p = 6$ vertices, 10 lines, $n_e = 5$ triangles.

Structured mesh-Task 2: Generate and plot via triplot

Listing III.1: MATLAB code tensor mesh generation

```
% generate points
k = 10; l = 20;
xx = linspace(0,1,k);
yy = linspace(0,1,l).^(1.3);
[x,y]=meshgrid(xx,yy);
x = x'; y = y';

% lexicographical ordering
ix = reshape(1:(k*l),[k l]);
ix1 = ix(1:k-1,1:l-1); ix1 = ix1(:);
ix2 = ix(2:k ,1:l-1); ix2 = ix2(:);
ix3 = ix(1:k-1,2:l ); ix3 = ix3(:);
ix4 = ix(2:k ,2:l ); ix4 = ix4(:);

% connectivity (2 triangles per quad)
e2 = [ix1 ix2 ix3; ix3 ix2 ix1];
% plot
triplot(e2,x(:),y(:), 'k-')
```

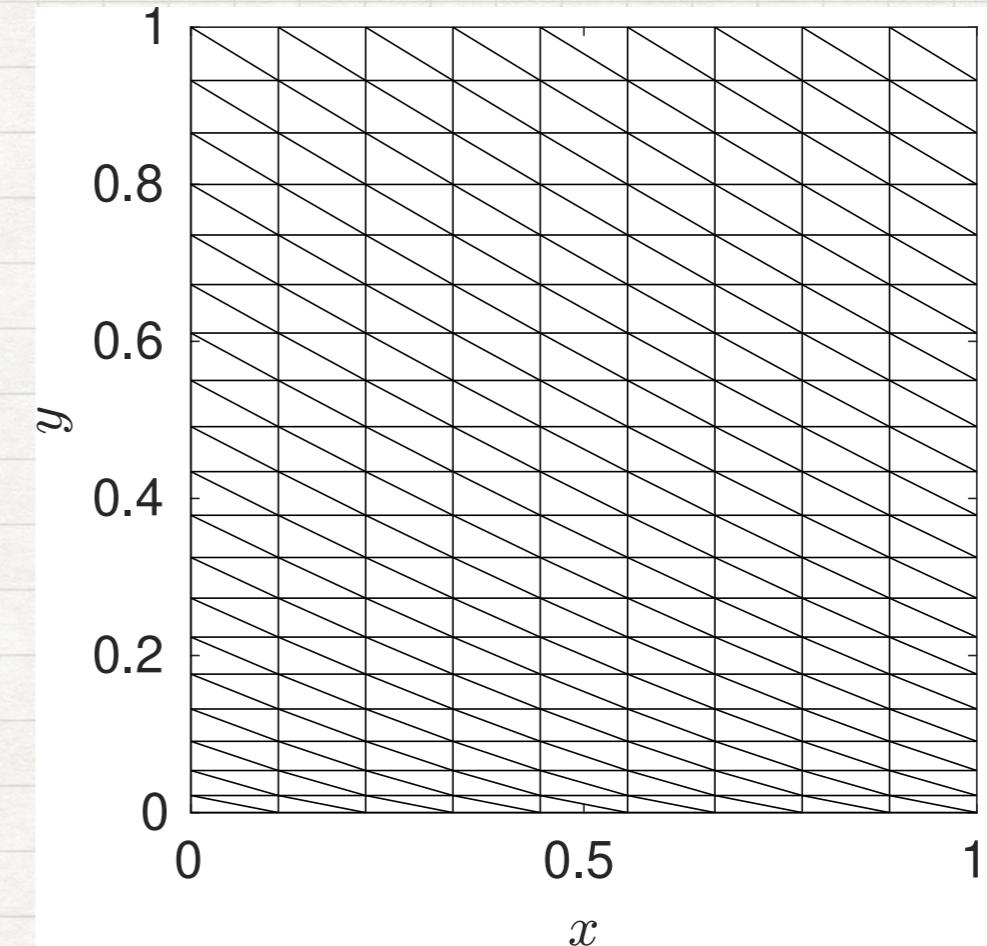


Figure III.5.: Structured tensor mesh.

```
1 # A box with eight vertices in 2D, no attributes, one boundary marker.  
2 8 2 0 1  
3 # Outer box has these vertices:  
4 1 0 0 0  
5 2 0 3 0  
6 3 3 0 0  
7 4 3 3 33 # A special marker for this vertex.  
8 # Inner square has these vertices:  
9 5 1 1 0  
10 6 1 2 0  
11 7 2 1 0  
12 8 2 2 0  
13 # Five segments with boundary markers.  
14 5 1  
15 1 1 2 5 # Left side of outer box.  
16 # Square hole has these segments:  
17 2 5 7 0  
18 3 7 8 0  
19 4 8 6 10  
20 5 6 5 0  
21 # One hole in the middle of the inner square.  
22 1  
23 1 1.5 1.5
```

Triangle: box.poly example

```
1 # A box with eight vertices in 2D, no attributes, one boundary marker.  
2 8 2 0 1  
3 # Outer box has these vertices:  
4 1 0 0 0  
5 2 0 3 0  
6 3 3 0 0  
7 4 3 3 33 # A special marker for this vertex.  
8 # Inner square has these vertices:  
9 5 1 1 0  
10 6 1 2 0  
11 7 2 1 0  
12 8 2 2 0  
13 # 8 segments with boundary markers.  
14 8 1  
15 1 1 2 0  
16 2 2 4 0  
17 3 4 3 0  
18 4 3 1 0  
19 5 5 6 0  
20 6 6 8 0  
21 7 8 7 0  
22 8 7 5 0  
23 # One hole in the middle of the inner square.  
24 1  
25 1 1.5 1.5
```

Triangle: box_v1.poly example

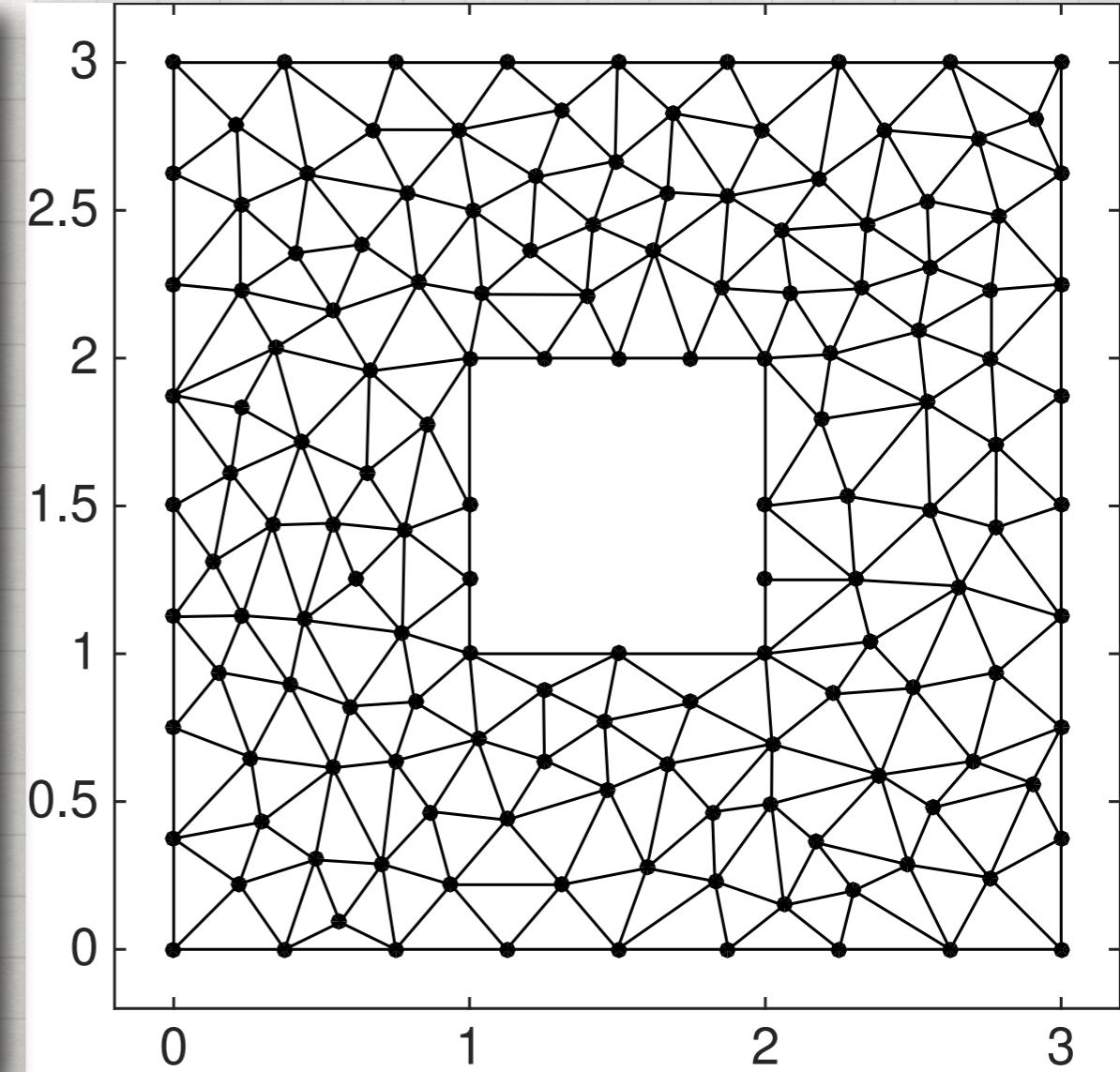
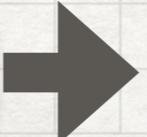
Unstructured mesh-Task 3: Generate using triangle and plot via triplot

```
1 # A box with eight vertices in 2D, no attributes, one boundary marker.  
2 8 2 0 1  
3 # Outer box has these vertices:  
4 1 0 0 0  
5 2 0 3 0  
6 3 3 0 0  
7 4 3 3 33 # A special marker for this vertex.  
8 # Inner square has these vertices:  
9 5 1 1 0  
10 6 1 2 0  
11 7 2 1 0  
12 8 2 2 0  
13 # 8 segments with boundary markers.  
14 8 1  
15 1 1 2 0  
16 2 2 4 0  
17 3 4 3 0  
18 4 3 1 0  
19 5 5 6 0  
20 6 6 8 0  
21 7 8 7 0  
22 8 7 5 0  
23 # One hole in the middle of the inner square.  
24 1  
25 1 1.5 1.5
```

box_v1.poly



[./triangle](#) -qpca0.1 box_v1.poly



```
>> [x,y,npoin,nelement,tri,idp,ide] = readtria('box_v1.1');  
read mesh file: box_v1.1  
>> triplot(tri,x,y)
```

Examples

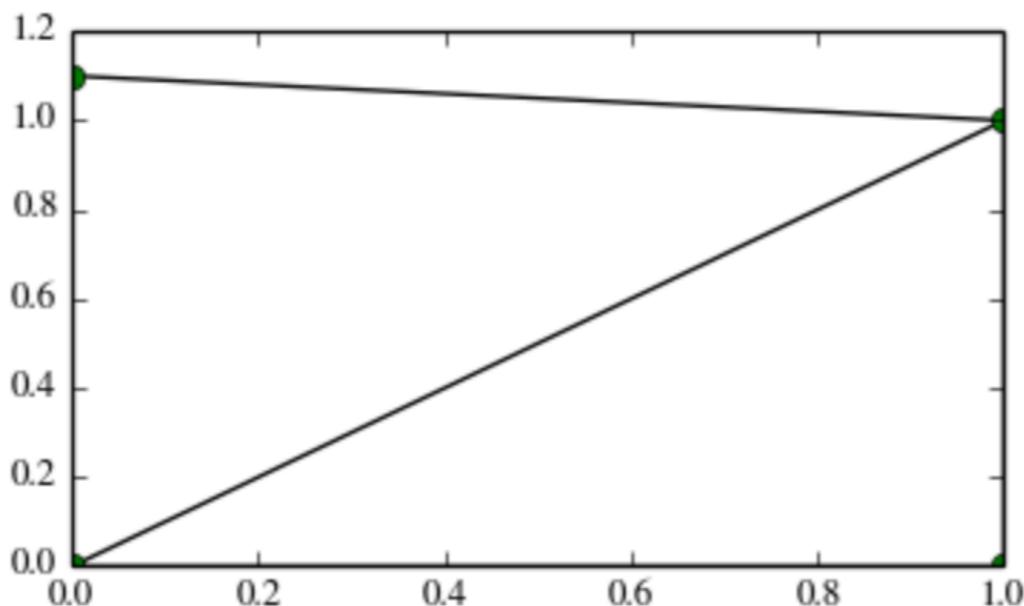
Triangulation of a set of points:

```
>>> points = np.array([[0, 0], [0, 1.1], [1, 0], [1, 1]])>>>
>>> from scipy.spatial import Delaunay
>>> tri = Delaunay(points)
```

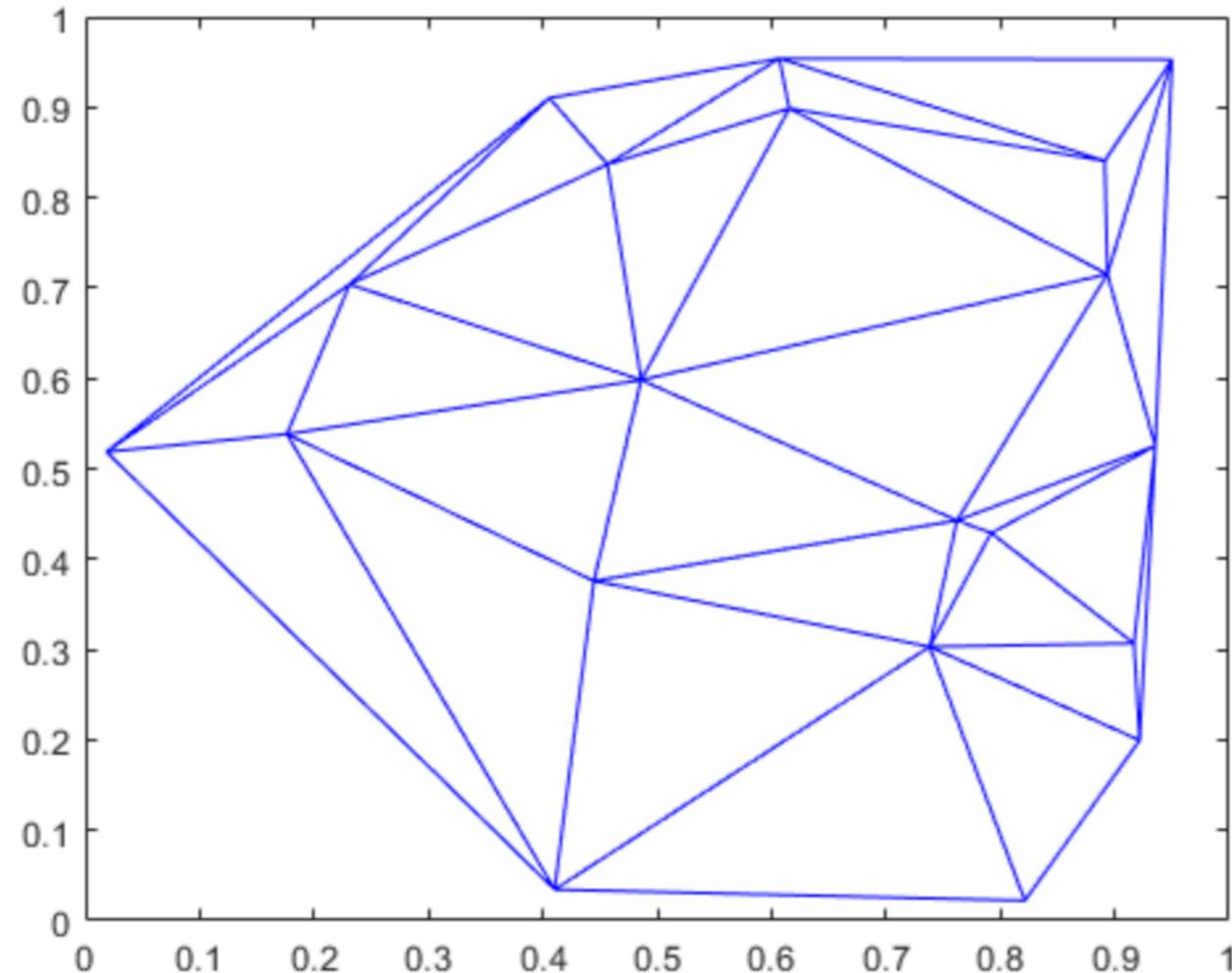
We can plot it:

```
>>> import matplotlib.pyplot as plt
>>> plt.triplot(points[:,0], points[:,1], tri.simplices.copy())
>>> plt.plot(points[:,0], points[:,1], 'o')
>>> plt.show()
```

([Source code](#))

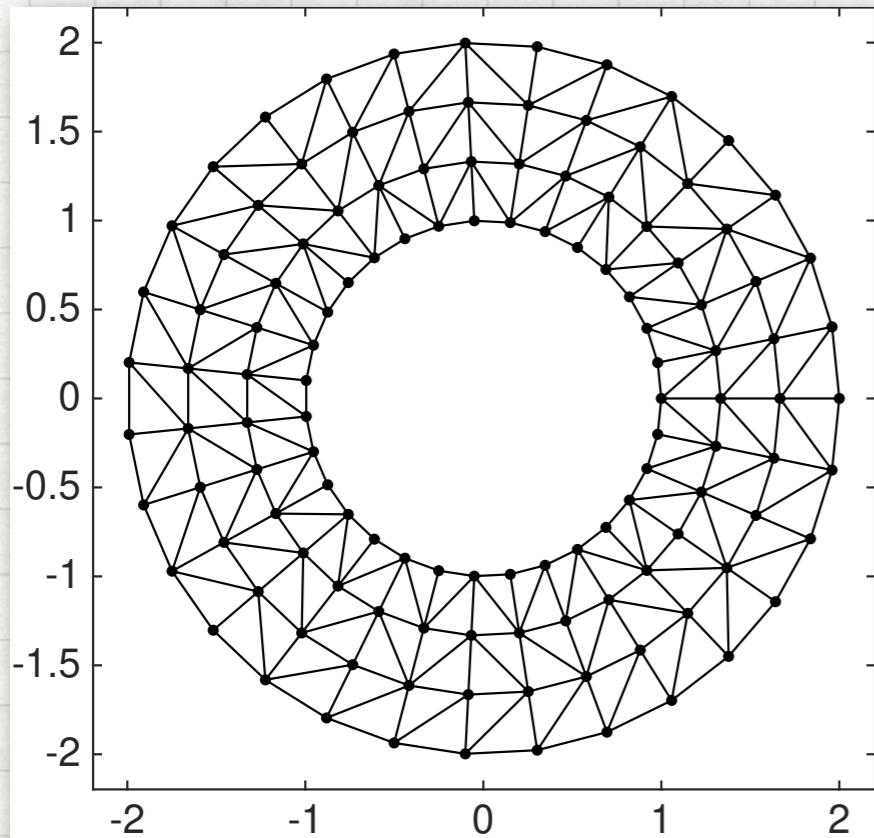


```
x = gallery('uniformdata',[20,1],0);
y = gallery('uniformdata',[20,1],1);
DT = delaunay(x,y);
triplot(DT,x,y);
```



Structured or Unstructured Mesh-Task 4:

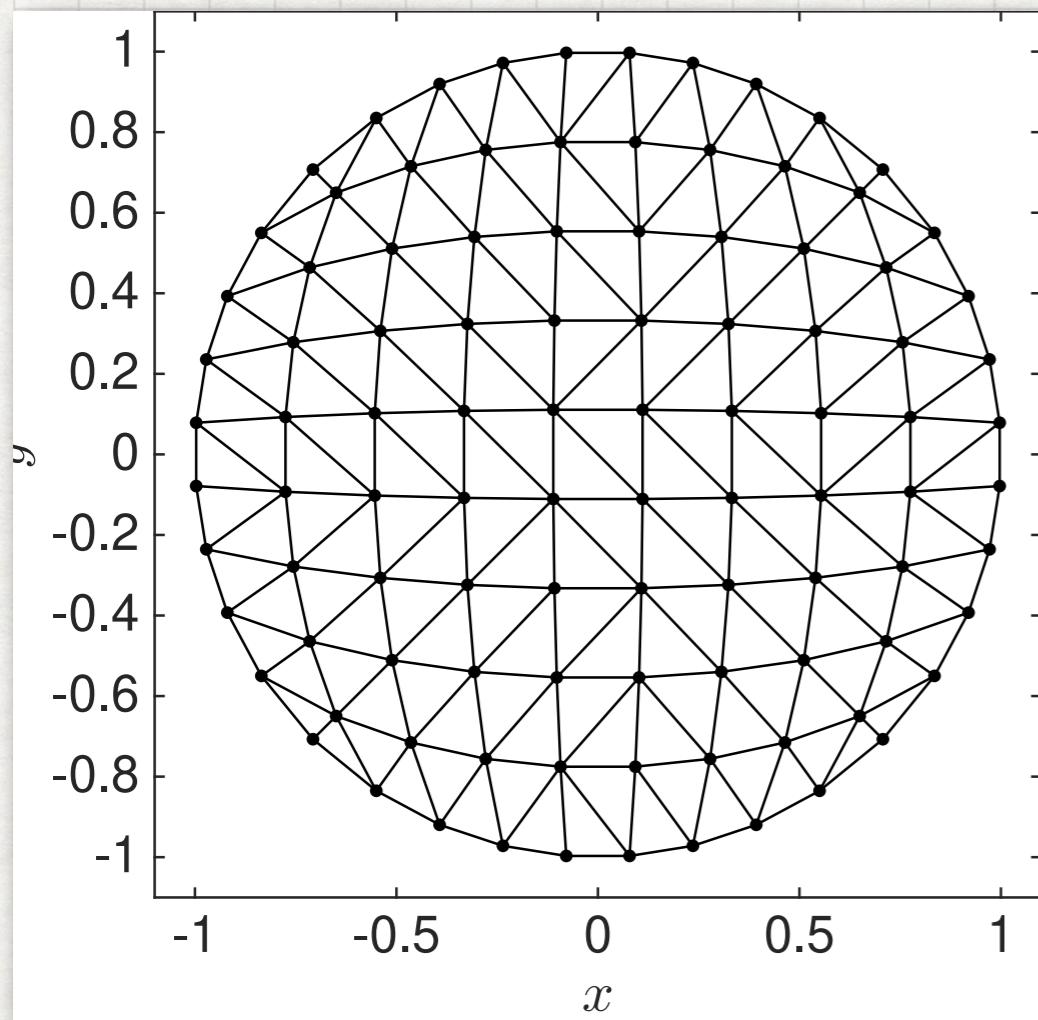
Generate using delaunay and/or triangle and plot via triplot



**Generate domain where either
(cumbersome) e2 takes care identification
of vertices for $\phi=0$ and 2π using a
deformed structured mesh or
(better) from triangle using
an inner/outer circular boundary.**

Structured or Unstructured Mesh Task 5:

Generate using delaunay and/or triangle and plot via triplot



**Generate disc domain using triangle
or alternatively using Delaunay or ...**