Dimension Reduction for Big Data

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25th June 2018

Overview

- Introduction
 - Motivation
- Goal
- Implementation
- Results
- Conclusion

Applications

Analytics



Business Intelligence





Infrastructure



Other Technologies





Curse of Dimensionality

1. Data isolation

Curse of Dimensionality

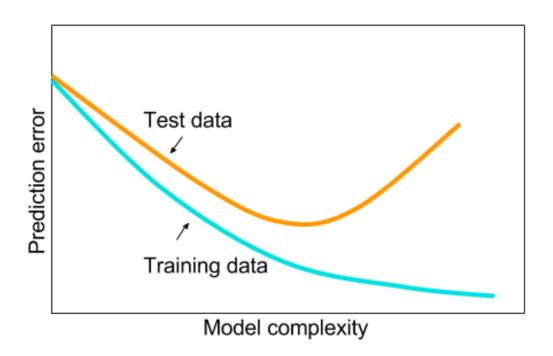
1. Data isolation

 Number of training samples required for a K-Nearest Neighbour search algorithm

Dimension size	10	15	20	30	50	100	150
Number of samples required	1	3	39	45,378	5.76×10^{12}	4.22×10^{39}	1.28×10^{72}

Curse of Dimensionality

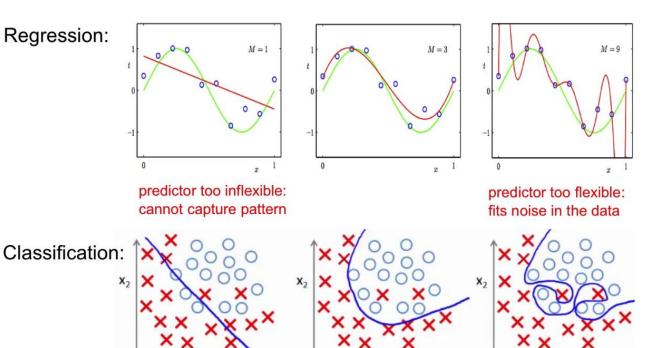
- Data isolation
- 2. Overfitting



 X_1

Curse of Dimensionality

- Data isolation
- 2. Overfitting
- 3. False Structure

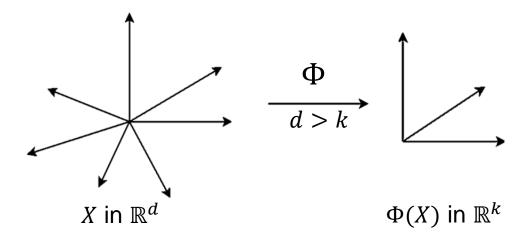


 X_1

Curse of Dimensionality

- 1. Data isolation
- 2. Overfitting
- 3. False Structure
- 4. Computation difficulty
 - Time
 - Complexity

Random Projection (1)



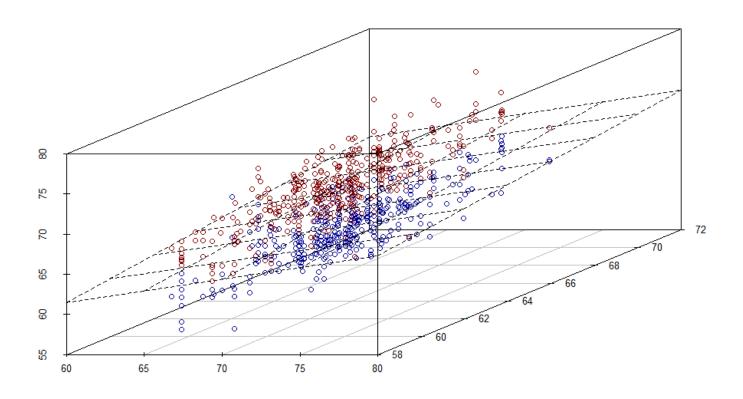
 Assist applications whose data is represented geometrically in high dimensional vector spaces

X – Data matrix

d – Euclidean space dimension

k – Reduced space dimension

Random Projection (2)



Johnson-Lindenstrauss Transform

- Fundemental method for dimension reduction.
- Theorem:

For any
$$(x, y) \in X$$
,
$$(1 - \epsilon) \|x - y\|_2 \le \|\Phi(x - y)\|_2 \le (1 + \epsilon) \|x - y\|_2$$

- Projecting any point in the data set (X) on to a random low dimensional subspace should, up to a distortion of $1 \pm \epsilon$, preserve pairwise distances
- Classic JL Transform (FJLT):
 - Runtime: 0(kd)

Goal

- Implement structured random matrices to speed up the JL transform
 - Fast JL Transforms (FJLT)

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Design Methods

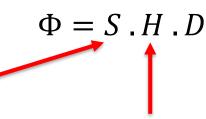
- 1. FJLT projection method 1
 - Sparse matrices
- 2. FJLT projection method 2
 - Methods from coding theory

FJLT Method 1

$$\Phi = S.H.D$$

- $(k \times d)$ Sparse matrix.
 - $S_{ij} \sim N(0, 1/q)$, with probability q
 - $S_{ij} = 0$, with probability (1 q)
 - $q = \min\left\{\frac{\log^2 n}{d}, 1\right\}$

FJLT Method 1



- $(k \times d)$ Sparse matrix
 - S_{ij} non zero with probability q
 - $q = \min\left\{\frac{\log^2 n}{d}, 1\right\}$

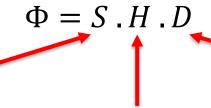
- $(d \times d)$ Walsh-Hadamard matrix
 - Fourier transform matrix
 - Simple to compute; runtime of $O(d \log d)$

$$- H_2 = \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}$$

$$- H_{2^{2n}} = \begin{pmatrix} H_{2^n} & H_{2^n} \\ H_{2^n} & -H_{2^n} \end{pmatrix}$$

FJLT Method 1

- $(k \times d)$ Sparse matrix
 - S_{ij} non zero with probability q
 - $q = \min\left\{\frac{\log^2 n}{d}, 1\right\}$



- $(d \times d)$ Walsh-Hadamard matrix
 - Fourier transform matrix
- $(d \times d)$ Random diagonal matrix
 - $D_{ii} = \{-1,1\}$ with probability 1/2

$$\begin{pmatrix} \pm 1 & 0 & 0 \\ 0 & \ddots & 0 \\ 0 & 0 & \pm 1 \end{pmatrix}$$

FJLT Method 1

- $(k \times d)$ Sparse matrix
 - S_{ij} non zero with probability q
 - $q = \min\left\{\frac{\log^2 n}{d}, 1\right\}$

• $(d \times d)$ Walsh-Hadamard matrix

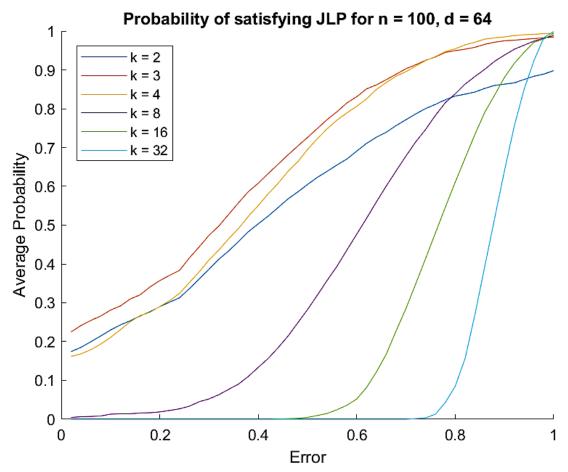
 $\Phi = S \cdot H \cdot D$

- Fourier transform matrix
- $(d \times d)$ Random diagonal matrix
 - $D_{ii} = \{-1,1\}$ with probability 1/2

• For $k \le d^{1/3}$, the runtime is $O(d \log d)$

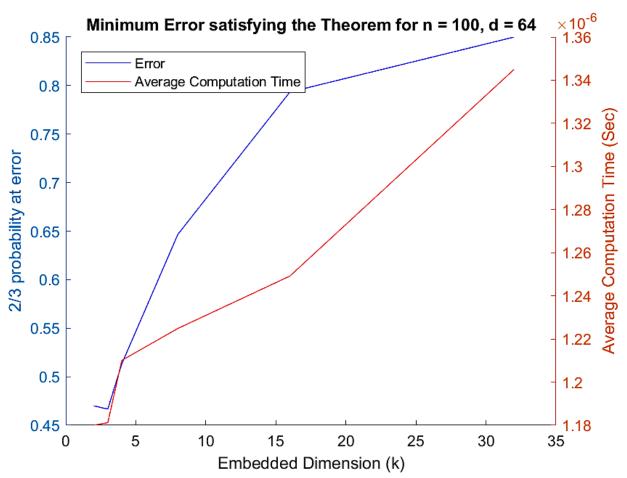
Results

- FJLT 1
 - Test 1
 - $-k \leq 4$



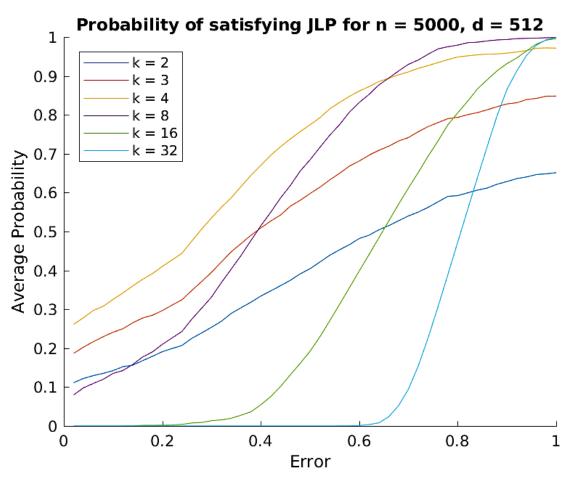
Results

- FJLT 1
 - Test 1
 - $-k \leq 4$



Results

- FJLT 1
 - Test 2
 - $-k \leq 8$

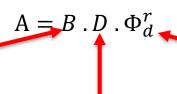


Design Methods

- 1. FJLT projection method 1
 - Sparse matrices
 - Computation time: $O(d \log d)$
 - Reduced dimension: $k \le d^{1/3}$
- 2. FJLT projection method 2
 - Methods from coding theory

FJLT Method 2

- $(k \times d)$ code matrix
 - Matrix containing unit norm vector columns



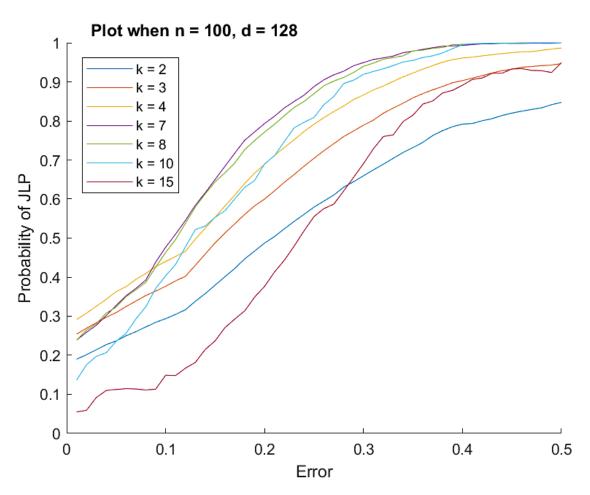
- $(d \times d)$ Random diagonal matrix
 - $D_{ii} = \{-1,1\}$ with probability 1/2
- $(d \times d)$ matrix
 - Combination of H_d and D_d

$$\Phi_d^{(r)} = HD^{(r)}HD^{(r-1)}\dots HD^{(1)}$$

• For $k < d^{1/2}$, the runtime is $O(d \log k)$

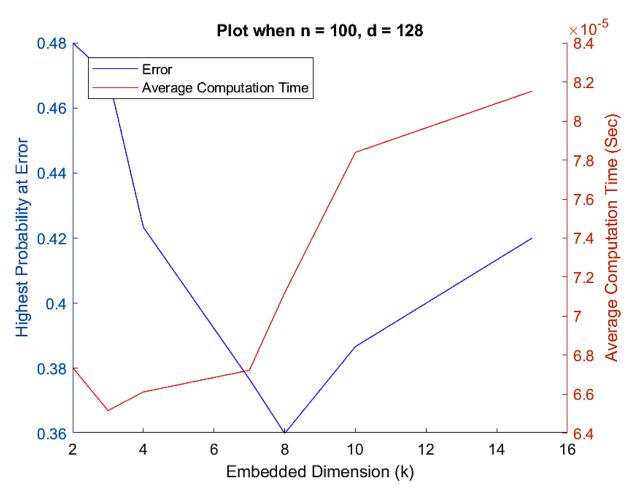
Results

- FJLT 2
 - Test 1
 - k < 12



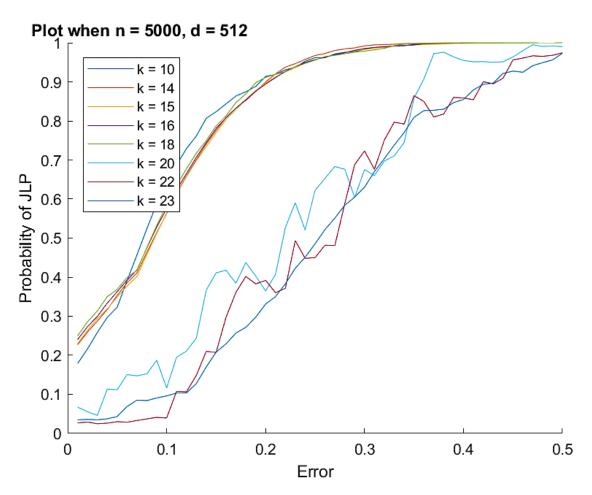
Results

- FJLT 2
 - Test 1
 - k < 12



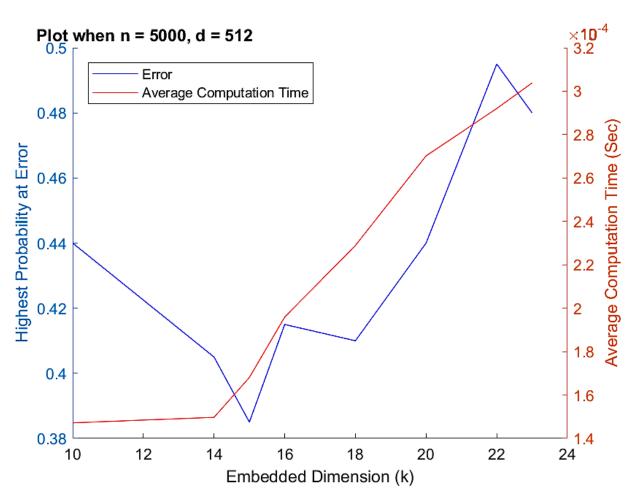
Results

- FJLT 2
 - Test 2
 - k < 23



Results

- FJLT 2
 - Test 2
 - k < 23

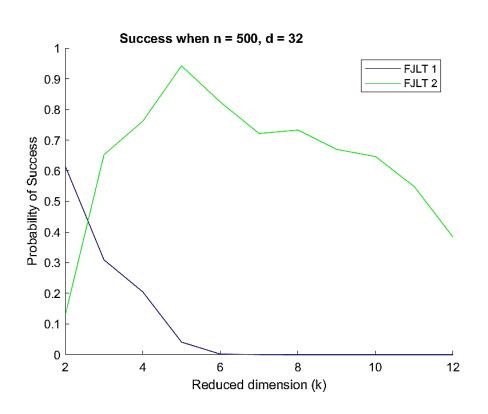


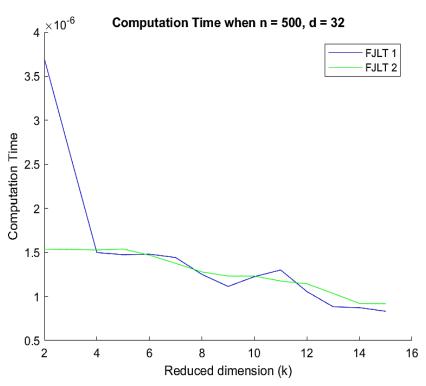
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Summary

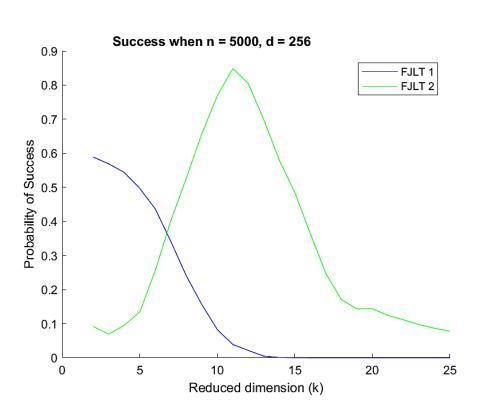
- 1. FJLT projection method 1
 - Sparse matrices
 - Computation time: $O(d \log d)$
 - Reduced dimension: $k \le d^{1/3}$
- 2. FJLT projection method 2
 - Methods from coding theory
 - Computation time: $O(d \log k)$
 - Reduced dimension: $k < d^{1/2}$

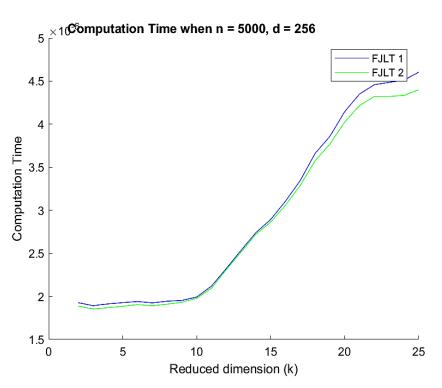
Comparison (1)





Comparison (2)

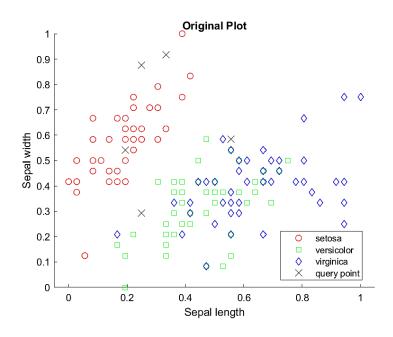




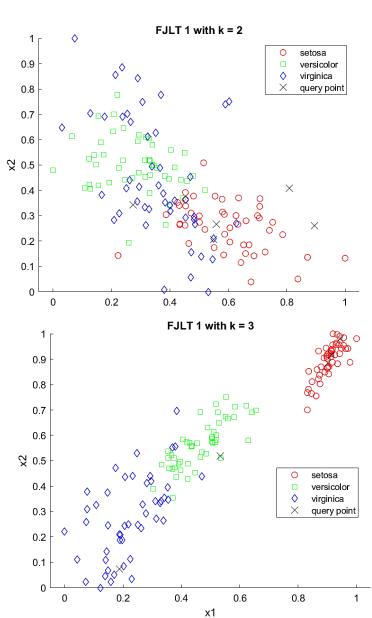
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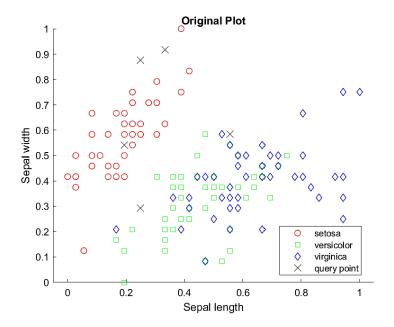
FJLT 1 on ML



k: reduced dimension; d: original dimension;



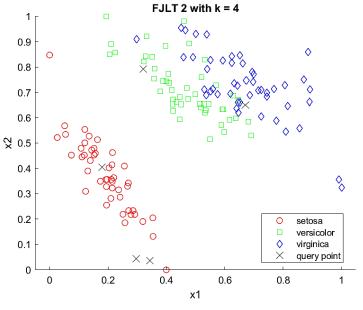
FJLT 2 on ML

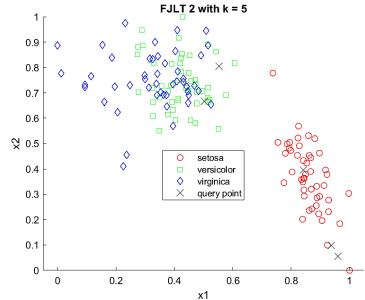


k: reduced dimension; d: original dimension;

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FJLT on ML

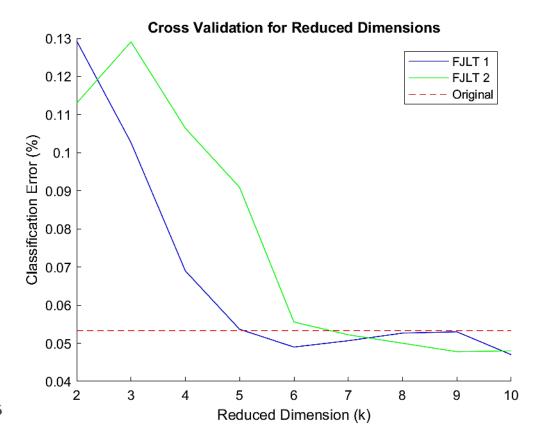
Cross-validation test

		Actual Class			
		setosa	versicolor	virginica	
Predicted Class	setosa	50	0	0	
	versicolor	0	48	6	
	virginica	0	2	44	
	undefined	0	0	0	

Table 5.9: Confusion matrix for FJLT 2 projection with k=4

		Actual Class		
		setosa	versicolor	virginica
Predicted Class	setosa	50	0	0
	versicolor	0	47	2
	virginica	0	3	48
	undefined	0	0	0

Table 5.10: Confusion matrix for FJLT 2 projection with $\mathbf{k}=5$



Conclusions

- 1. FJLT projection method 1
 - Sparse matrices
 - Computation time: $O(d \log d)$; Reduced dimension: $k \le d^{1/3}$
- 2. FJLT projection method 2
 - Methods from coding theory
 - Computation time: $O(d \log k)$; Reduced dimension: $k < d^{1/2}$
- 3. For very complex datasets, the computation time is similar.
 - Better probability of success achieved by FJLT 2
- 4. Great performance in standard ML techniques

Future Work

- Simulations of FJLT on large pixel image datasets
 - Emotion/face recognition
- Restriction on reduced dimension
 - Current $k < d^{1/2}$
 - Use of techniques such as Restricted Isometry Property and sparse dimension reduction
- Improving the computation time
 - Better than $O(d \log k)$

Thank you

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APPENDIX

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FJLT Method 1

Theorem:

Given a fixed set of X of n points in \mathbb{R}^d , and $\epsilon < 1$, draw a matrix Φ from FJLT 1. With probability at least $\frac{2}{3}$, the following 2 events occur:

- 1. For any $x \in X$, $(1 - \epsilon)k||x||_2 \le ||\Phi x||_2 \le (1 + \epsilon)k||x||_2$
- 2. The mapping $\Phi: \mathbb{R}^d \to \mathbb{R}^k$ requires, $O(d \log d + \min\{d\epsilon^{-2} \log n, \epsilon^{-2} \log^3 n\})$ operations.

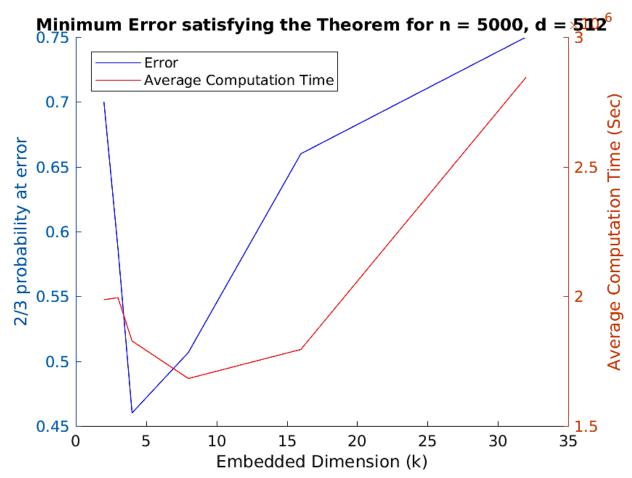
FJLT Method 1

			k							
d	$d^{1/3}$	n	2	3	4	8	16	32		
64	4	1000	0.540	0.540	0.640	0.760	0.880	0.940		
		5000	0.460	0.540	0.680	0.820	0.880	0.940		
		10000	0.580	0.600	0.720	0.800	0.880	0.940		
	5	1000	0.520	0.420	0.380	0.680	0.800	0.900		
128		5000	0.500	0.500	0.600	0.740	0.840	0.920		
		10000	0.520	0.560	0.620	0.760	0.880	0.920		
	6	1000	0.680	0.520	0.400	0.580	0.720	0.860		
256		5000	0.600	0.380	0.400	0.640	0.780	0.880		
		10000	0.540	0.380	0.440	0.640	0.820	0.900		
512	8	1000	NaN	0.740	0.480	0.380	0.620	0.780		
		10000	0.780	0.480	0.360	0.520	0.720	0.840		
1024	10	10000	NaN	0.840	0.500	0.340	0.600	0.720		

Table 5.1: Error at which 2/3 probability is reached for different tests.

Results

- FJLT 1
 - Test 2
 - $-k \leq 8$



FJLT Method 2

Theorems:

Theorem 3.2 For any code matrix A of size $k \times d$ for k < d, the mapping $x \mapsto Ax$ can be computed in time $O(d \log k)$.

Theorem 3.3 Let $\delta > 0$ be some arbitrarily small constant. For any d, k satisfying $k < d^{\frac{1}{2}-\delta}$, there exists an algorithm constructing a random matrix A of size $k \times d$ satisfying Johnson-Lindenstrauss properties $(0 \le \epsilon \le 1/2)$, such that the time to compute $x \mapsto Ax$ for any $x \in \mathbb{R}^d$ is $O(d \log k)$. The constriction uses O(d) random bits and applies to both the Euclidean (p = 2) and the Manhattan (p = 1) cases.

FJLT Method 2

$$A = B \cdot D \cdot \Phi_d^r$$

$$B_{k \times d} = [B_k \quad B_k \quad B_k \dots B_k]$$

$$BD = \underbrace{(B_k \quad B_k \quad B_k \dots B_k)}_{d/\beta \text{ copies of } k \times \beta \text{ blocks}} \begin{bmatrix} D_\beta & 0 & \cdots & 0 \\ 0 & D_\beta & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & D_\beta \end{bmatrix}$$

$$\frac{d/\beta \text{ copies of } \beta \times \beta \text{ blocks}}{d/\beta \text{ copies of } \beta \times \beta \text{ blocks}}$$

FJLT Method 2

$$A = B \cdot D \cdot \Phi_d^r$$

$$BD = \underbrace{(B_k \quad B_k \quad B_k \dots B_k)}_{d/\beta \text{ copies of } k \times \beta \text{ blocks}} \underbrace{\begin{pmatrix} D_\beta & 0 & \cdots & 0 \\ 0 & D_\beta & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & D_\beta \end{pmatrix}}_{d/\beta \text{ copies of } \beta \times \beta \text{ blocks}}$$

$$HD' = \underbrace{\begin{pmatrix} H_{\beta} & 0 & \cdots & 0 \\ 0 & H_{\beta} & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & H_{\beta} \end{pmatrix}}_{d/\beta \text{ copies of } \beta \times \beta \text{ blocks}} \underbrace{\begin{pmatrix} D_{\beta}^{(1)} & 0 & \cdots & 0 \\ 0 & D_{\beta}^{(2)} & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & D_{\beta}^{(r)} \end{pmatrix}}_{d/\beta \text{ copies of } \beta \times \beta \text{ blocks}} \bullet \text{For } k < d^{1/2}, \text{ the runtime is } O(d \log k)$$

FJLT Method 2 (1)

Theorem 3.2 For any code matrix A of size $k \times d$ for k < d, the mapping $x \mapsto Ax$ can be computed in time $O(d \log k)$.

Theorem 3.3 Let $\delta > 0$ be some arbitrarily small constant. For any d, k satisfying $k < d^{\frac{1}{2}-\delta}$, there exists an algorithm constructing a random matrix A of size $k \times d$ satisfying Johnson-Lindenstrauss properties $(0 \le \epsilon \le 1/2)$, such that the time to compute $x \mapsto Ax$ for any $x \in \mathbb{R}^d$ is $O(d \log k)$. The constriction uses O(d) random bits and applies to both the Euclidean (p = 2) and the Manhattan (p = 1) cases.

Lemma 3.1 There exists a 4-wise independent code matrix of size $k \times f_{BCH}(k)$, where $f_{BCH}(k) = \Theta(k^2)$.

Lemma 3.2 Assume B is a $k \times d$ 4-wise independent code matrix.

FJLT Method 2 (2)

$$B_{k \times d} = [B_k \quad B_k \quad B_k \dots B_k]$$

$$D' = D^{(1)}, D^{(2)}, D^{(3)}, \dots, D^{(r)}$$

$$\Phi_d^{(r)} = HD^{(r)}HD^{(r-1)}\dots HD^{(1)}$$

$$BD = \underbrace{(B_k \quad B_k \quad B_k \dots B_k)}_{d/\beta \text{ copies of } k \times \beta \text{ blocks}} \underbrace{\begin{pmatrix} D_\beta & 0 & \cdots & 0 \\ 0 & D_\beta & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & D_\beta \end{pmatrix}}_{d/\beta \text{ copies of } \beta \times \beta \text{ blocks}}$$

$$HD' = \underbrace{\begin{pmatrix} H_{\beta} & 0 & \cdots & 0 \\ 0 & H_{\beta} & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & H_{\beta} \end{pmatrix}}_{d/\beta \text{ copies of } \beta \times \beta \text{ blocks}} \underbrace{\begin{pmatrix} D_{\beta}^{(1)} & 0 & \cdots & 0 \\ 0 & D_{\beta}^{(2)} & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & D_{\beta}^{(r)} \end{pmatrix}}_{d/\beta \text{ copies of } \beta \times \beta \text{ blocks}}$$

FJLT Method 2 (3)

d	$d^{1/2}$	n	k	β	error
32	5.7	50	5	16	0.380
64	8	50	6	32	0.350
128	11.3	500	3	8	0.310
120	11.5	5000	3	8	0.330
	16	50	8	64	0.340
256		500	8	64	0.330
		10000	8	64	0.360
512	22.6	1000	18	256	0.330
012		10000	18	256	0.300

Table 5.2: Best performing reduced dimension solution for different tests

Comparison Tests

		F.	JLT 1	FJLT 2				
n	n d		min e	k	beta	min e		
50	32	3	0.40	5	16	0.40		
	64	4	0.44	6	32	0.38		
	128	4	0.40	7	32	0.35		
	256	8	0.32	9	64	0.25		
	512	16	0.30	16	256	0.25		
	32	2	0.50	5	16	0.38		
	64	3	0.40	7	32	0.37		
100	128	4	0.40	6	32	0.34		
	256	8	0.32	10	128	0.34		
	512	8	0.36	15	256	0.28		
	32	2	0.52	5	16	0.42		
	64	2	0.50	7	32	0.40		
500	128	3	0.44	7	32	0.37		
	256	4	0.40	9	64	0.35		
	512	8	0.30	14	256	0.32		
	32	2	4.80	5	16	0.46		
	64	2	0.54	7	32	0.41		
1000	128	4	0.38	7	32	0.38		
	256	4	0.40	9	64	0.35		
	512	8	0.38	18	256	0.33		
	32	2	0.58	5	16	0.45		
	64	2	0.46	7	32	0.42		
5000	128	3	0.50	7	32	0.39		
	256	3	0.38	9	64	0.35		
	512	4	0.36	14	256	0.33		
	32	2	0.50	5	16	0.45		
	64	2	0.60	7	32	0.41		
10000	128	2	0.52	7	32	0.39		
10000	256	3	0.38	9	64	0.34		
	512	4	0.36	18	256	0.32		
	1024	8	0.34	25	512	0.30		

Table 1: Optimal reduced dimension and error for different parameters

FJLT on ML

Summary of correctness tests

Type	Test Size	Accuracy (as per dataset) %									
		Original	k								
		Original	2	3	4	5	6	7	8	9	10
FJLT 1	5	80.0	78.0	84.0	88.0	86.0	90.0	92.0	90.0	84.0	92.0
FJLT 2	5	80.0	86.0	86.0	84.0	88.0	86.0	90.0	90.0	86.0	86.0
FJLT 1	10	90.0	89.0	88.0	92.0	90.0	91.0	93.0	94.0	92.0	91.0
FJLT 2	10	90.0	92.0	87.0	85.0	87.0	94.0	92.0	93.0	94.0	92.0
FJLT 1	15	100.0	94.0	94.0	100.0	99.3	100.0	100.0	100.0	100.0	100.0
FJLT 2	15	100.0	90.0	95.3	98.0	97.3	100.0	100.0	99.3	99.3	100.0

l_p -norm

$$||x_p|| = \left(\sum_{i=1}^n |x_i|^p\right)^{\frac{1}{p}}$$

ℓ₂ Regression

- Least square fit of an overdetermined linear system
- Old method:
 - Solution obtained by down sampling
- Problem:
 - Complex solution
 - Down sampling distribution depends on norms of rows of the left singular vector matrix of the original system
- Solution:
 - Multiply the equation matrix on the left by HD
 - The resulting left singular matrix have almost uniform sampling

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