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- · <u>Subject</u>: Design and Analysis of Algorithms
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Tutorial - 5

- 0.1 What is the difference between DFS and BFS? Write the applications of both the algorithms.
- > BFS (Breadth First Search) DFS (Depth First Search)
 - for finding the shortest structure.
 - 2) BFS can be used to find single source shortest path in an unweighted graph, because in BFS, we reach a revotese with minimum no. of edges from source.
 - 3) Siblings are visited before the children.

- 1) BFS uses Queue data structure 1) DFS uses Stack ducta
 - 2) In DFS, we might traverse through more edges to neach a destination votex from a source.
 - 3) Children are visited before the siblings.

Applications

- · Shortest path & minimum spanning tree for unweighted graph
- · Peer to peer networks
- · Cycle detection in undirected
- · Path finding
- · Topological Sorting
- · To test if a graph is sipartite.
- Q. 2 Which data structures are used to implement BFS and DFS? Why?
- → BFS does the search for nodes level-by-level, i.e., it searches the nodes w.r.t. their distance prom noot. Here, siblings are visited before children. So, we use Queue as

- it is FIFO (First In First Out) data structure, we visit the node which is discovered first from the root.
- For DFS, we retrieve nodes from root to the farthest node as much as possible, same idea as LIFO (Last In First Out). So, we use Stuk data staucture; children are visited before the siblings.
- 0.3 What do you mean by sparse and dense graph; Which suppresentation of graph is better for sparse and dense graphs?
- \rightarrow A graph with relatively few edges is <u>Sparse</u>. Sparse graph is a graph G(V, E) in which |E| = O(|V|) where E = Edge & V = Vertex.
 - A graph with many edges is <u>Dense</u>. Dense graph is a graph G(V, E) in which $|E| = O(IV^2I)$ where E = Edge & V = Verotex.
 - For Sparse graphs, Adjacency List com be used for representation.
 - For Dense graphs, Adjacency Matrix can be used for suppresentation.
- Q.4 How can you detect a cycle in a graph using BFS and DFS?

- -> # Detecting a cycle in Directed graph using BFS
 - 1) Compute in-degree (no. of incoming edges) for each of the vertex present in the graph & initialize the count of visited nodes as O.
 - 2) Rich all the vertices with in-degree as zero & add them into a queue (Enqueue operation)
- 3) Removee a revoten from the queue (Dequeue operation) and then s

 - (a) Increment count of reisited nodes by 1.
 (b) Decrease in-degree by 1 for all its neighboring
 - (c) If in-degree of a neighbowing node is reduced to zero, then add it to the queue.
- 4) Repeat Step 3 until the queue is empty.
- 5) If count of reisited nodes is not equal to the no. of nodes in the graph, the graph has cycle, otherwise not.
- # Detecting a cycle in Directed graph using DFS
- 1) Create a graph using the given no. of edges &
- 2) Orecte a recursive function that initializes the current index ou vertex, visited & recursion stack.
- 3) Movek the current node as visited and also mark the index in succuesion stack.
- 4) Find all the vectices which are not visited & are adjacent to the coverent node. Recursively call the function for those reedices, if the recursive function exturns tome, return tome.

5) If the adjacent rectices are already marked in the recursion stack, then return tome.

6) Crecte a werapper class, that calls the recursing function for all the receptives and if any function returns tome, else if for all rectices the function returns false, return false.

Q.5 What do you mean by disjoint set data stoudy? Explain I operations along with examples, which can be performed on disjoint sets.

→ Disjoint set is basically a group of sets where no item can be in more than one set. It supports Union and Find operations on subsets.

Assume that you have a set of 'N' elements that are divided into further subsets and you have to torack the connectiveity of each element in a specific subset or connectivity of subsets with each other. You can use the Union-Find algorithm (Disjoint set union) to achieve this.

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Operations on Disjoint set

Let $S_1 = \{1, 2, 3\}$ and $S_2 = \{4, 5, 6\}$



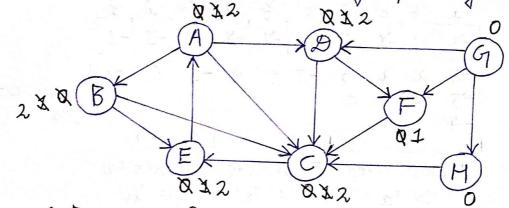
• Jind(): It is used to find in which subset a particular element is present & vetwins the representative of that particular set.

e.g.
$$find(1) = 51$$
, $find(5) = 52$

union(): It merges two different subsets into a single subset & representative of one set becomes representative of the other.

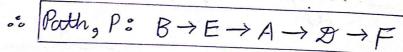
$$e \cdot 9 \cdot S_1 \cup S_2 \Rightarrow S_3 = \{1, 2, 3, 4, 5, 6\}$$

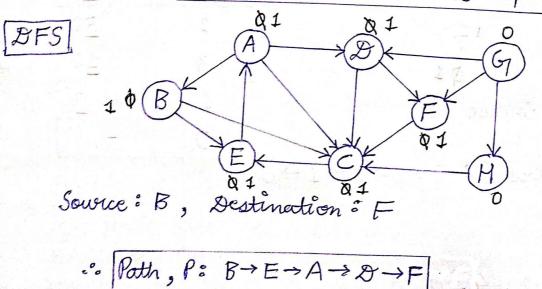
Q. 6 Run BFS and DFS on graph given below:



Source: B, Destination: F

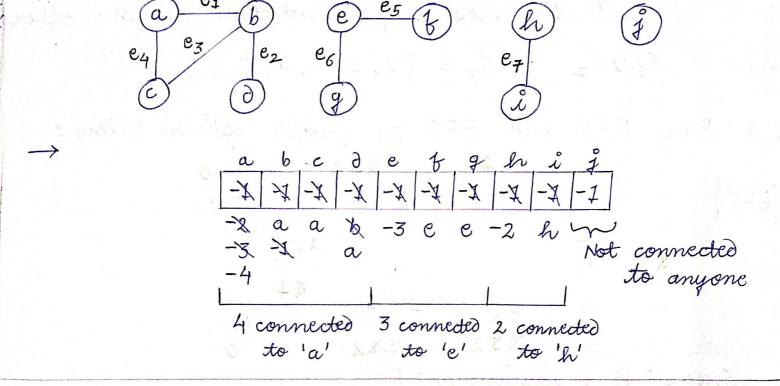
				Princip	TO IN	Rear	\rightarrow	
Queue	Node	B	E	C	A	2	F	
	Parient	-	B	B	E	A	2	





Node processed	Stack
_	B
B	EC
Ę	AC
A	DCC
D	CFCC
C	FCC
F	CC

Q.7 Find out the no. of connected components & vertices in each component using disjoint set data stouctures in the given graphs:



Q.8 Apply topological sorting & DFS on the given graph: __01____

DFS

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		(5)		(4)	
			7 87		× 91
Ø	(2)		(0)	1 - 2	(1)
1					
		0 7	3	(
			01		
e i grad	\	2	9 F	_	
	2	Source	2:5		

Node	Stack
-	<u>5</u>
5	20
2	<u>3</u> 0
3	10
1) \$ 1 O
0	

... DFS towersal: 5→2→3→1→0

Topological sort

5, 2, 4, 5, 3, 1

- Q.9 Heap data structure can be used to implement periority queue. Name few graph algorithms where you need to use priority queue and why?
- Heaps one great for implementing a priority queue because of the largest and smallest element being at the root of tree for a max heap and a min heap respectively.

We use a man heap for a man-priority queue.

Applications of Briority queue

- 1) Dijkotera's shortest path algorithm: When the graph is stored in the form of adjacency list or matrix, priority queue can be used to esdract minimum weighted path efficiently when implementing the algorithm.
- 2) <u>Peim's algorithm</u>: Periority queue is used to implement Perim's algorithm to store keys of nodes & esotoract minimum key node at every step.
- 3) <u>Data compression</u>: Periority queue is used in Huffman codes which is used to compress data.
- 0.10 What is the difference between Man heap & Min heap?
 - → Min heap
 - 1) In a min heap, key present at the scoot node must be less thorn or equal to the keys present at all of its children.
 - 2) The minimum key element is present at the most.
 - 3) It uses the ascending priority.

Max heap

- 1) In a max heap, key present at the scoot node must be greater than or equal to the keys present at all of its children.
- 2) The maximum key element is present at the most.
- 3) It uses the descending