# **Dami Thomas**

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#### **EDUCATION**

#### Massachusetts Institute of Technology (MIT)

Exp. May 2026

Candidate for B.S in Artificial Intelligence and Decision Making & Minor in Mechanical Engineering

• Relevant Coursework: Introduction to Robotics, Robotic Manipulation, Introduction to Machine Learning, Advances in Computer Vision, Introduction to Autonomous Machines, Dynamics and Controls I & II, Design and Manufacturing

### **EXPERIENCE**

#### Rockwell Automation | AI Engineer Intern

June 2025 - August 2025 | Milwaukee, WI

- Built a RAG re-ranking pipeline for a pharmaceutical recipe generation product with Streamlit, ChromaDB, LangChain, Azure OpenAI, and Python, boosting chatbot quality with an 84% user preference rate.
- Engineered data preprocessing pipelines on product failure and warranty datasets using Scikit-learn, NumPy, and Pandas to enable causal AI modeling and improve reliability insights.

# NASDAQ | AI Engineer Intern

January 2025 - February 2025 | Boston, MA

- Created a Year-End Review Synthesizer using AWS Bedrock, Python, and LLMs, reducing employees' evaluation data collection time from multiple days to 2 minutes.
- Implemented map-reduce and LangGraph for parallel processing of Jira tickets, emails, and GitHub commits, enabling automated generation of data-driven performance summaries and optimized managerial review processes.

# Elinta Robotics | Assembly and Design Engineer Intern

June 2023 - August 2023 | Kaunas, Lithuania

- Spearheaded the design and implementation of automated systems using aluminum profiles, stainless steel components, and FESTO pneumatic technology for assembling a Milk Packaging Line.
- Engineered **pneumatic-powered actuators** with integrated **computer vision algorithms** to optimize efficiency and quality control in manufacturing processes for building a PCB Tester.

#### NASA Lunar Autonomy Challenge | Team Member

October 2024 - May 2025 | Cambridge, MA

- Applied SciPy interpolation to model and estimate lunar surface elevations (75–90% confidence) and visualized terrain with Matplotlib heatmaps; built a PID controller for rover path following and boulder avoidance.
- Achieved 2nd place nationally among 31 U.S. university teams for autonomous rover performance.

# **PROJECTS**

#### Semantic Navigation Robot

July 2025 - August 2025

- Built a Semantic Visual Navigation Robot with ROS 2 Humble, SLAM Toolbox, Nav2, YOLOv11, Whisper, and RViz2, leveraging the NVIDIA R2B bag dataset for mapping, object detection, and speech-driven navigation without simulation.
- **Designed modular ROS 2 architecture** using CycloneDDS and rosbag2 playback to integrate perception, planning, and natural language commands.

Fit Classifier

May 2025 - July 2025

- Built an end-to-end fashion recognition pipeline with YOLOv8, CLIP embeddings, and FAISS, deployed via Python-Docker on Google Cloud with Firestore for embeddings/metadata; achieved 2–3s detection speed, 80%+ match accuracy.
- Designed a **React frontend** with an integrated AI-powered chatbot via **Google Gemini API**, enabling photo uploads, real-time visualization, natural language queries, category classification, and product recommendations with purchase links for users.

#### Yu-Gi-Oh! Deck Builder

August 2024

• Built a Yu-Gi-Oh! deck builder website with Node.js, Express.js, and EJS, integrating the YuGiOhProDeck API and Axios to filter 12,000+ cards with efficient RESTful data handling.

#### **Autonomous Competition Robot**

August 2023 - December 2023

 Built an Arduino-powered robot integrating IMU, encoders, and line-tracking sensors, and implemented PID and Bang-Bang control for reliable maze navigation and line following.

#### **SKILLS**

Software: TensorFlow | PyTorch | Python | Linux | MATLAB | SQL | Javascript | Arduino | Adobe Illustrator | Hugging Face React.js | HTML | CSS | Postgres | Git | ROS2 | Numpy | Pandas | Node.js | Express.js | YOLO | Docker

Maker: SolidWorks | 3D Printing | Woodworking | CNC Lathe & Mill | Laser Cutter | Waterjet | Welding | Plasma Cutter | Drill Press