

# DENNIS WAI

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## EDUCATION

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### University of California, Berkeley

*2013-Present*

PhD. in Mechanical Engineering

Advisor: Professor Masayoshi Tomizuka

Overall GPA: 3.910

### University of California, Berkeley

*Completed May 2013*

B.S. in Mechanical Engineering

Overall GPA: 3.817

## RESEARCH EXPERIENCE

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### Mechanical Systems Laboratory

Aug 2013 - Present

*Graduate Student Researcher*

*Berkeley, CA*

- Stochastic estimation techniques for attitude estimation
- Model-based control coupled with stochastic estimation on a quadcopter testbed.

### CiBER Lab

May 2011 - May 2013

*Undergraduate Researcher*

*Berkeley, CA*

- Designed and manufactured a novel tail backpack for a remote controlled car to demonstrate pitch-correcting abilities in midair.
- Created and designed various PCBs for controller purposes in Tailbot, a robot with inertial assisted control by an active tail inspired by lizards; Tailbot was also a featured robot on the front page of Nature magazine

### Mechanical Systems Laboratory

May 2010-May 2011

*Undergraduate Researcher*

*Berkeley, CA*

- Created a small, wireless Arduino inertial measurement unit as part of a wireless body sensor network that will relay kinematic information to a local networked computer for analysis in a clinical setting.
- Developed in LabVIEW packet loss compensation methods to account for incomplete sensor readings as well as graphical methods to translate the kinematic data into easily understood animations of a virtual human.

## WORK EXPERIENCE

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### **Jet Propulsion Laboratory**

*Mechanical Engineer*

Jun 2014 - Aug 2014

*Pasadena, CA*

- Kinematic analysis of a 3/4 degree of freedom robotic arm to determine workspace accessibility in the Mars Sample Transfer Chain, which involves transferring a cache from one rover to another so that the cache can be returned from Mars to Earth

### **Jet Propulsion Laboratory**

*Electrical Engineer*

Jun 2013 - Aug 2013

*Pasadena, CA*

- Assisted in the prototyping of a novel comet sampling tool for a future comet surface sample return mission, which can help provide answers to the origin of water in our solar system
- Architected and manufactured the electrical and pneumatic control system for the autonomous sampling system. The system successfully retrieved samples with high reliability and will represent JPL's candidate solution for the mission.

### **Space Science Laboratory**

*Mechanical Engineer*

May 2012 - Aug 2012

*Berkeley, CA*

- Drafted and designed the optical layout for an externally dispersed interferometer attachment for the Lick Observatories in order to improve its spectral resolution by four folds
- Prepared weekly presentations to update fellow astronomers in hardware developments

### **Pioneers in Engineering**

*Mentorship Coordinator*

May 2011 - May 2012

*Berkeley, CA*

- Spearheaded efforts to recruit Berkeley undergraduates to become robotics mentors for underprivileged high school students in our annual 300+ robotics competition.
- Managed a 10-person committee in robotics curriculum development for 90+ UC Berkeley undergraduates
- Hosted the inaugural and well-received Robots vs Dinosaur Science Festival, a 100+ event, complete with 8 novel science activities in cooperation with the Lawrence Hall of Science

## TEACHING EXPERIENCE

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### **UC Berkeley EECS Department**

*Teaching Assistant*

May 2012 - Aug 2012

*Berkeley, CA*

- Taught *Electronic Techniques for Engineering* to 100+ UC Berkeley undergraduates over the summer
- Prepared discussion, exam reviews, and other curriculum material for students
- Led weekly discussions, instructional labs, and office hours and was rated as the best Teaching Assistant

### **Academic Service Center at UC Berkeley**

*Physics Tutor*

May 2011 - May 2012

*Berkeley, CA*

- Assisted undergraduates in mastery of basic and advanced physics concepts through 1-on-1 tutoring

## PUBLICATIONS

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### Conference Proceedings

1. Joonbum Bae; Haninger, K.; **Wai, D.**; Garcia, X.; Tomizuka, M., "A network-based monitoring system for rehabilitation," *Advanced Intelligent Mechatronics (AIM), 2012 IEEE/ASME International Conference on* , vol., no., pp.232,237, 11-14 July 2012 [IEEE Link](#)

## RELEVANT SKILLS

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<b>Computer Languages</b>	Python, MATLAB, C++, C, LabVIEW, OSX, Ubuntu
<b>Tools</b>	Solidworks, EAGLE, AutoCAD, Inkscape, Illustrator
<b>Cantonese</b>	Fluent

## HONORS AND EXTRACURRICULARS

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<b>Pioneers in Engineering Scholarship Committee</b>	Aug 2013 - Present
<b>Pioneers in Engineering Advisor</b>	May 2012 - Present
<b>Pioneers in Engineering Mentorship Coordinator</b>	May 2011 - May 2012
<b>Tau Beta Pi Service Chair - Officer of the Semester</b>	Aug 2012 - Dec 2012
<b>Pi Tau Sigma Student Relations Officer</b>	Jan 2011 - Dec 2011
<b>Charles and Daisee Seffens Scholarship Recipient</b>	Aug 2009 - Aug 2012
<b>Cal Band Trombonist</b>	Aug 2010 - Aug 2012